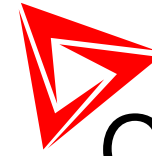


Compact Controller for Stand-by and Parallel Operating Gen-sets



ComAp

LEADER IN GEN-SET
COMMUNICATION SOLUTION

Inteli New Technology Modular Gen-set Controller

Multiple Internal engines application – SW configuration
MINT

IG-NT, IG-NTC, IG-EE, IG-EEC, IS-NT, IG-NT-BB, IG-NTC-BB, IS-NTC-BB

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REFERENCE GUIDE



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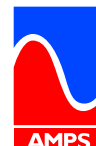


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Document information

IGS-NT® – MINT Reference guide

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1	3.1.0	31.8.2014



Pressing F1 in the GenConfig and IntelliMonitor setpoint, values or configuration window will open the help with the context of currently selected setpoint, value and binary input or output function.

Available related documentation

PDF files	Description
IGS-NT-SPTM-3.1.0 Reference Guide.pdf	General description of SPTM applications for IntelliGen NT and IntelliSys NT. Contains description of engine and generator control, control of power in parallel to mains operation, list of all Setpoints, Values, Logical Binary Inputs and Logical Binary Output.
IGS-NT-SPI-3.1.0 Reference Guide.pdf	General description of SPI applications for IntelliGen NT and IntelliSys NT. Contains description of engine and generator control, control of power in parallel to mains operation, list of all Setpoints, Values, Logical Binary Inputs and Logical Binary Output.
IGS-NT-MINT-3.1.0 Reference Guide.pdf	General description of MINT applications for IntelliGen NT and IntelliSys NT. Contains description of engine and generator control, powermanagement, list of all Setpoints, Values, Logical Binary Inputs and Logical Binary Output.
IGS-NT-Combi-3.1.0 Reference Guide.pdf	General description of Combi applications for IntelliGen NT and IntelliSys NT. Contains description of engine, and generator control in SPTM, SPI and MINT mode, powermanagement, list of all Setpoints, Values, Logical Binary Inputs and Logical Binary Output.
IGS-NT-COX-3.1.0 Reference Guide.pdf	General description of COX applications for IntelliGen NT and IntelliSys NT. Contains description of engine and generator control, powermanagement, list of all Setpoints, Values, Logical Binary Inputs and Logical Binary Output.
IGS-NT Application Guide 05-2013.pdf	Applications of IntelliGen NT, IntelliSys NT and IntelliMains NT, examples of connection, description of PLC functions, Virtual and Shared peripheries.
IGS-NT Operator Guide 01-2014.pdf	Operator Guide for all hardware variation of IntelliGen NT and IntelliSys NT, IntelliVision 5 and IntelliVision 8.
IGS-NT Installation Guide 08-2014.pdf	Thorough description of installation and technical information about IntelliGen NT, IntelliSys NT and IntelliMains NT and related accessories.
IGS-NT Communication Guide 05-2013.pdf	Thorough description of connectivity and communication for IntelliGen NT, IntelliSys NT and IntelliMains NT and related accessories.
IGS-NT Troubleshooting Guide 08-2014.pdf	How to solve most common troubles with IntelliGen NT and IntelliSys NT controllers. Including the list of alarm messages.
IGS-NT & ID-DCU Accessory Modules 07-2014.pdf	Thorough description of accessory modules for IGS-NT family, technical data, information about installation of the modules, how to connect them to controller and set them properly.

General guidelines

What is described in this manual?

This manual describes „MINT“ software configuration. The software configuration is designed for multiple sets applications with internal load sharer and synchronizer.

What is the purpose of this manual?

This manual provides general information on how to configure and operate the controller.

This manual is intended for use by:

Operators of gen-sets

Gen-set control panel builders

For everybody who is concerned with installation, operation and maintenance of the gen-set

!! Warnings !!

The NT controller can be remotely controlled. In the event that maintenance needs to be done to the gen-set, check the following to ensure that the engine cannot be started.

To be sure:

Disconnect remote control via RS232 line

Disconnect input REMOTE START/STOP

or

Disconnect output STARTER and outputs GCB CLOSE/OPEN and MCB CLOSE/OPEN

The controller contains a large number of configurable setpoints, because of this it is impossible to describe all of its functions. These are subject to change from SW version to SW version. This manual only describes the product and is not guaranteed to be set for your application on arrival.

Text

ESC

(Capital letters in the frame) buttons on the front panel

Break Return

(Italic) set points

Generator protections

(Bold) Set point group

Cyan background

Valid for IS-NT only

Conformity declaration



Following described machine complies with the appropriate basic safety and health requirement of the EC Low Voltage Directive No: 73/23 / EEC and EC Electromagnetic Compatibility Directive 89/336 / EEC based on its design and type, as brought into circulation by us.

Note:

ComAp believes that all information provided herein is correct and reliable and reserves the right to update at any time. ComAp does not assume any responsibility for its use unless otherwise expressly undertaken.

WARNING – VERY IMPORTANT !!!

Be aware that the binary outputs can change state during and after software reprogramming (before the controller is used again ensure that the proper configuration and setpoint settings are set in the controller).

Every time you want to disconnect following NT controller terminals:

- Mains voltage measuring and / or
- Binary output for MCB control and / or
- MCB feedback

Be aware that the MCB can be switched off and gen-set can start !!!

Switch the controller to MAN mode and disconnect the Binary outputs Starter and Fuel to avoid unexpected automatic start of gen-set and GCB closing.

!!! CAUTION !!!***Dangerous voltage***

The terminals for voltage and current measurement should never be touched.
Properly connect the grounding terminals.
Do not disconnect the CT terminals for any reason.

Adjust set points

All setpoints are preadjusted to their typical values. But the set points in the “**Basic settings**” settings group **!!must!!** be adjusted before the first startup of the gen-set.

**!!! WRONG ADJUSTMENT OF BASIC PARAMETERS
CAN DESTROY THE GEN-SET !!!**

The following instructions are for qualified personnel only. To avoid personal injury do not perform any action not specified in this User guide !!!

Clarification of notation

HINT

This type of paragraph points out details to help user installation/configuration.

NOTE:

This type of paragraph calls readers' attention to a notice or related theme.

CAUTION!

This type of paragraph highlights a procedure, adjustment, etc. which may cause damage or improper functioning of the equipment if not carried out correctly and may not be clear at first sight.

WARNING!

This type of paragraph indicates things, procedures, adjustments, etc. which demand a high level of attention, otherwise personal injury or death may occur.

EXAMPLE:

This type of paragraph indicates examples of usage for illustrational purposes.

Available Firmware and Archive sets

For suitable firmware for your controller please consult this table:

Firmware (*.mhx)

InteliGen NT GC InteliGen NTC GC	InteliGen NT BaseBox InteliGen NTC BaseBox	InteliSys NT BaseBox InteliSys NTC BaseBox
IG-NT-GC-3.1.0	IG-NT-BB-3.1.0	IS-NT-3.1.0

Archives (*.ant)

InteliGen NT GC InteliGen NTC GC	InteliGen NT BaseBox InteliGen NTC BaseBox	InteliSys NT BaseBox InteliSys NTC BaseBox
IG-GC-SPTM-3.1.0	IG-BB-SPTM-3.1.0	IS-SPTM-3.1.0
IG-GC-SPI-3.1.0	IG-BB-SPI-3.1.0	IS-SPI-3.1.0
IG-GC-MINT-3.1.0	IG-BB-MINT-3.1.0	IS-MINT-3.1.0
IG-GC-COMBI-3.1.0	IG-BB-COMBI-3.1.0	IS-COMBI-3.1.0
IG-GC-COX-3.1.0	IG-BB-COX-3.1.0	IS-COX-3.1.0
IG-GC-MINT-Marine-3.1.0		IS-MINT-Marine-3.1.0

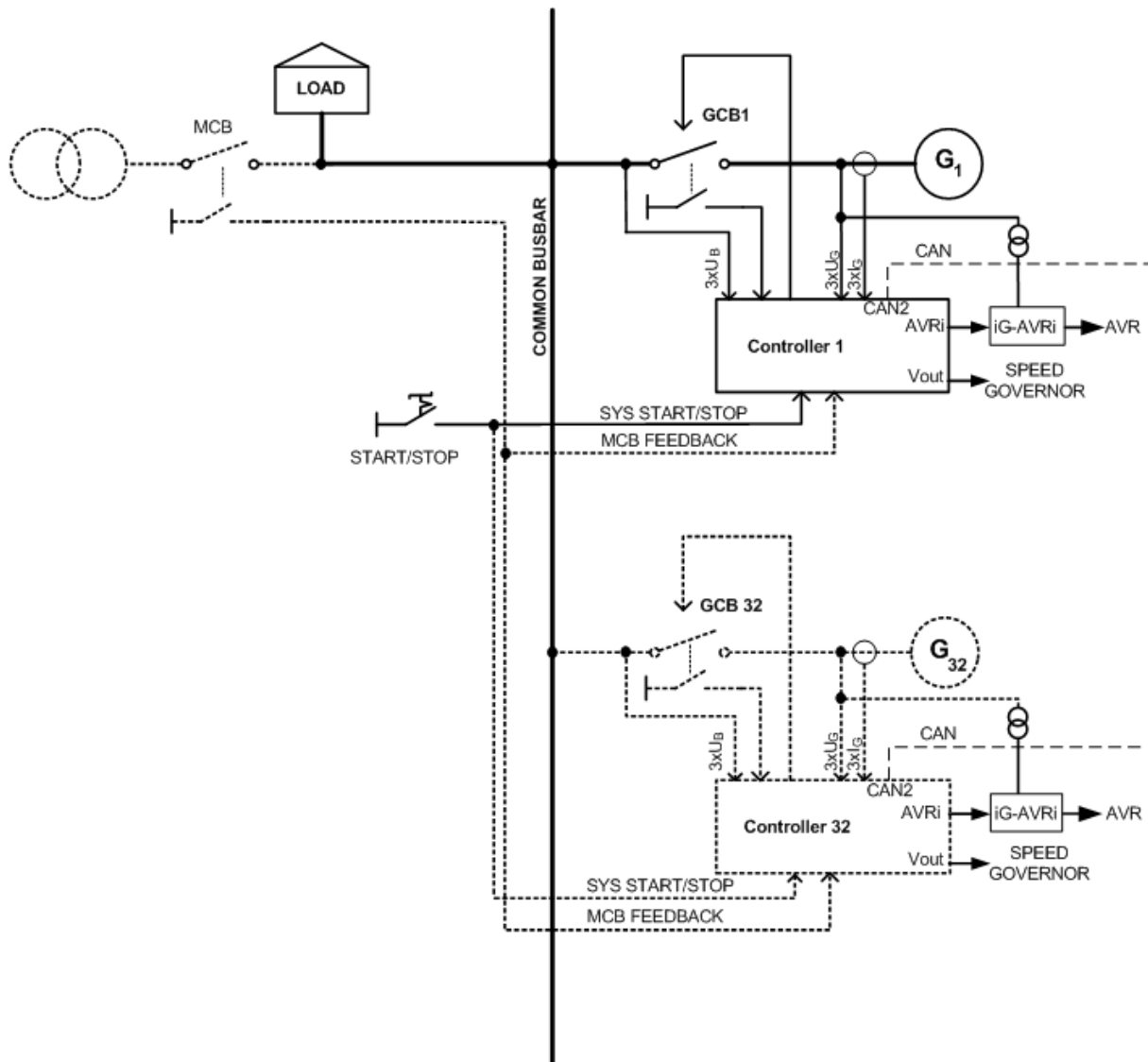
Some features are available only in InteliGen NT Basebox, InteliGen NTC Basebox and InteliSys NT. These features are highlighted by green background.

General description

Basic description of MINT application

The MINT application is intended for sites where up to 32 gen-sets cooperate with each one. It includes following main features:

- Automatic startup and stop sequences with adjustable timing
- Wide range of generator and engine protections, additional freely configurable protections
- **Multiple island operation with digital active and reactive load sharing**
- **Parallel to the mains operation**
- **One breaker control (GCB)** including **synchronizing** to the busbar.
- Soft loading and unloading
- **Power management** - automatic starting and stopping of gen-sets according to the load demand, running hours equalization and other optimization features



Functions

OFF-MAN-AUT mode

OFF mode

Outputs STARTER, GCB CLOSE/OPEN and FUEL SOLENOID are not energized.

Gen-set cannot be started. If **START**, **STOP**, **GCB ON/OFF** buttons are pressed the controller will not respond.

When the gen-set is running it is not possible to switch directly to OFF mode. First you have to stop the engine.

MAN mode

- 1) **START** - starts the gen-set.
- 2) **GCB ON/OFF**
 - If generator voltage is out of the limits (adjusted in the set point group **Gener protect**) controller does not respond to the **GCB ON/OFF**
 - a) controller closes GCB to dead bus.
 - b) controller starts GCB synchronizing when bus voltage is OK and MCB is closed or when other gen-set(s) provide healthy voltage to the bus. Closes the GCB when synchronized and stays running in parallel (island or mains parallel).
 - c) Unloads gen-set and opens the GCB if gen-set was running in parallel to the mains or to other gen-set(s).
- 3) **STOP**
 - a) When gen-set is running in parallel: transfers the load to the mains or to other gen-set(s), opens GCB, goes into cooling state and stops the engine.
 - b) When gen-set is running in single island (or in general there is no mains and no other gen-set(s) to transfer the load to): opens GCB, goes into cooling state and stops the engine.
 - c) When engine is running unloaded: activates cooling sequence and then stops the engine.
 - d) During cooling state causes immediate engine stop.

HINT

The gen-set is permitted to run unloaded for unlimited time.

Controller does not automatically start the gen-set when SYS START/STOP input is closed.

Load control type in mains parallel depends on **ProcessControl**: #SysLdCtrlPtM = BASELOAD or LDSHARING setpoint.

SEM

In SEM mode, pressing of **START** or **STOP** buttons performs a predefined sequence:

- 1) **START** – starts the engine, synchronizes and runs in parallel.
- 2) **STOP** – softly unloads the gen-set, opens GCB, provides cooldown and stops the engine.

AUT mode

- 1) All gen-sets necessary to cover selected *LoadRes strt* are started when binary input SYS START/STOP is closed and *Pwr management* is ENABLED. Power management can be based on kW, kVA or on relative % reserve.
 - a) 1 sec delayed when MCB FEEDBACK binary input is closed (mains parallel)
 - b) delayed #SysAMFstrt del when MCB FEEDBACK binary input is opened – start to island parallel (multi AMF) situation
- 2) The first gen-set closes the GCB to the dead bus, the rest are synchronized to the bus.
- 3) When all necessary gen-sets are connected to the bus and *LoadRes strt* is achieved, SYST RES OK output is closed. Output could be used to close the MGCB (Master GCB).
- 4) Total load and power factor are shared between parallel operating gen-sets.
- 5) Close input LOAD RESERVE 2 (or 3 or 4) and use setpoint *LoadRes strt2*(or 3 or 4) to switch to another load reserve setting. E.g. high load reserve during system start to be able to switch-on big devices, then during normal operation lower reserve to save engines (and fuel).

- 6) If total load increases and selected *LoadRes strt* is no more fulfilled, after a *Next start del* next ready gen-set with the highest priority (lowest priority number) is started and synchronized to the bus.
- 7) If load decreases and selected *LoadRes stp* is exceeded, after a *Next stop del* the running gen-set with the lowest priority is unloaded, got off line, cooled and stopped.
- 8) Complete gen-sets group stops when binary input SYS START/STOP opens. If the input MCB FEEDBACK is closed (gen-sets are in parallel to mains) controllers softly transfer the load to the mains. When gen-set is unloaded (see *GCB open level* or *GCB open del*) opens the output GCB CLOSE/OPEN.
- 9) The Running hours balancing or Load demand engines swap can be activated in power management.

HINT

Controller does not respond to **GCB ON/OFF**, **STOP**, **START** buttons and corresponding remote IntelliMonitor or Modbus commands in AUT mode.

Set **Basic setting**: *FltRes GoToMAN* = ENABLED to avoid automatic engine start when pressing **FAULT** **RESET** after any 2nd level alarm (Shutdown, Slow stop, Breaker Open&Cooldown).

Active and Reactive Power control modes in MINT

System Base load

Gen-set group is controlled on constant (or adjustable) power. The Baseload value can be changed by setpoint or via analog input.

Important setpoints: **ProcessControl**: *#SysLdCtrlPtM* = BASELOAD; *#SysBaseload*; *SysBaseLdMode*.

Local Baseload

Selected gen-set from island or mains parallel running group can be loaded to constant *LocalBaseload* value. This engine is taken out from Load sharing and Power management. *LocalBaseload* value is reduced only when common group (actual) load is lower than this value. The gen-sets in the group will try to match their *LocalBaseloads* (when more than one) based on their controller addresses, so the first limited would be the one with the highest CAN address. I.e. this function will switch-off automatically in one or more controllers if there is not enough load to cover all the requested *LocalBaseloads*.

Important setpoints: **ProcessControl**: *LocalBaseload*.

System Base power factor

Gen-set group is controlled in mains parallel to keep a constant (or adjustable) power factor.

Important setpoints: **ProcessControl**: *#SysPFCtrlPtM* = BASEPF; *#SysPwrFactor*.

Import-Export

Gen-set group is controlled to keep constant (or adjustable) Import or Export value. The external controller IntelliMains NT must be connected on the CAN2 to control gen-set group kW I/E.

Important setpoints: **ProcessControl**: *#SysLdCtrlPtM* = LDSHARING.

Import/Export power factor

Gen-set group is controlled to keep constant (or adjustable) Import or Export power factor.

Important setpoints: **ProcessControl**: *#SysLdCtrlPtM* = VSHARING. The external IntelliMains NT controller must be connected on the CAN2 to control gen-set group PF I/E.

Power management

The Power management function decides how many gen-sets should run and selects particular gen-sets to run. The power management is applicable in cases multiple gen-sets run in parallel to mains or in the island operation. The function is based on the load evaluation in order to provide enough of available running power. Since it allows the system to start and stop gen-sets based on the load demand, it can vastly improve the system fuel efficiency. In other words, an additional gen-set starts when the load of the system raises above certain level. The additional gen-set stops, when the load of the system drops down below a certain level. The process of determining gen-set start and stop is done in each controller; there is no "master slave"

system. Therefore, the system is very robust and resistant to failures of any unit in the system. Each of the controllers can be switched off without influencing the whole system. Except the situation the respective gen-set is not available for the power management.

The power management evaluates so called load reserve. The load reserve is calculated as difference between actual load and nominal power of running gen-sets. The reserve is calculated as absolute value (in kW / kVA) or relatively to the nominal power of gen-set(s) (in %). The setpoint **Pwr management: #Pwr mgmt mode** is used to select the absolute or relative mode.

The automatic priority swapping function focuses on efficient run of gen-set in regards to running hours and gen-set size.

NOTE:

The power management is related to MINT application only.

CAUTION!

The function of the controller is designed to handle the maximum sum of nominal power at 32000kW (3200.0kW, 320.00MW depending on the power format in the controller). If the sum of nominal power of all gen-sets connected to the intercontroller CAN exceeds these values the power format needs to be changed accordingly.

Example: There are 20 gen-sets each with 2000kW of nominal power. The sum of the nominal power is 40000kW. Therefore the power format in kW cannot be used because the sum exceeds 32767. Therefore power format in MW needs to be chosen because the sum in MW is 40MW (it does not exceeds 320.00MW).

1.1. Basic Power management

The setpoint **Pwr management: Pwr management** enables and disables the gen-set to be active within the power management and makes automatic load dependent starts and stops. If the power management is disabled, the start and stop of the gen-set do not depend on the load of the group. If the gen-set remains in AUT mode, the running condition depends only on the binary input *Sys start/stop*.

The binary input *Sys start/stop* requests the gen-set to start or stop. If the input is not active, the gen-set stops with delay **Pwr management: #SysAMFstopDel** after the input has been deactivated and will not start again if in AUT mode. If the input is activated again, the delay **Pwr management: #SysAMFstrtdel** starts to count down. Once the delay elapsed, the gen-set is activated and can be started by the power management. In other words, the power management is activated only if the binary input *Sys start/stop* is activated, the option of setpoint **Pwr management: Pwr management = ENABLED** and the AUT mode are selected.

NOTE:

The gen-set takes part of the power management (= is active) only if the controller is in AUT mode!

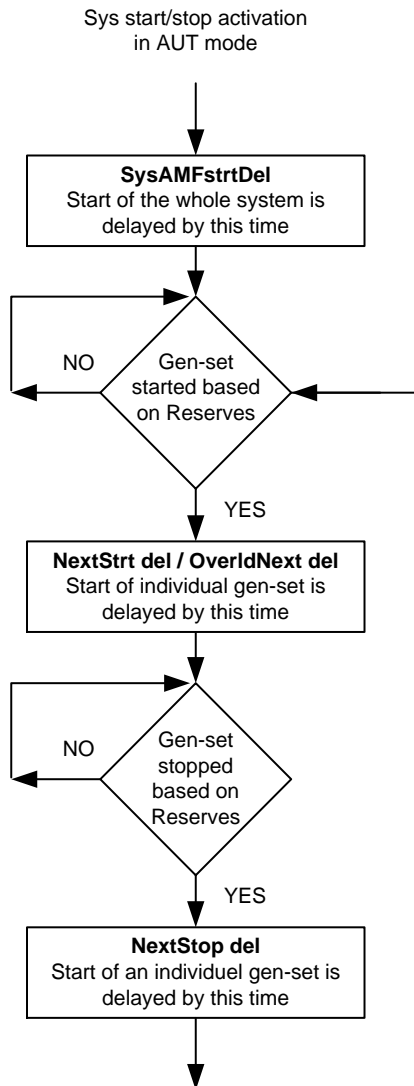
NOTE:

The gen-set performs load and VAR sharing whenever it is connected to the bus bar i.e. it is independent on whether the controller is in AUT or MAN mode or whether the power management is active or not. Do not confuse power management with load sharing.

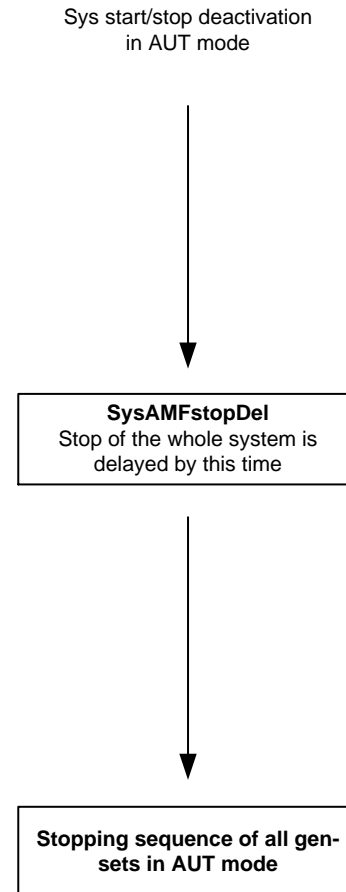
1.1.1 Principles of Power management

Internal conditions based on remaining load reserves and priorities are evaluated once a delay is elapsed. If the load reserve is insufficient the gen-set is started after delay given by the setpoint **Pwr management: #NextStrt del** is elapsed. Once the gen-set runs the controller evaluates stopping conditions based on load reserves and priorities. If the reserve is sufficient enough to stop a particular gen-set, it is stopped after delay given by the setpoint **Pwr management: #NextStopDel** is elapsed. All the time the system stop condition – i.e. the binary input *Sys start/stop* deactivated – is evaluated as well. Once the delay given by the setpoint

System activation



System deactivation



Pwr management: #SysAMFstopDel has elapsed all gen-sets in AUT mode are stopped. Following figure depicts the system activation and deactivation logic.

NOTE:

The setpoint **Pwr management: OverldNext del** is used in the case gen-sets are running at 90% or more of their nominal power. The setpoint **Pwr management: OverldNext del** should be generally shorter than the setpoint **Pwr management: NextStrtdel**. The shorter time always applies in such a case (counting in that part of NextStrtdel may have already been elapsed).

1.1.2 Load reserve

The power management is based on the load reserve concept. The load reserve is defined as a difference of the running nominal power of the group within power management and the total load of the system. There are two ways how to determine the load reserve. The absolute power management allows the system to keep the load reserve higher or equal to value in kW or kVA given by a relevant setpoint. The relative power management assures that load reserve is kept higher or equal to relative portion in % of the nominal power of group (i.e. running gen-sets active in power management) given by a relevant set-point. Depending of the situation, load reserves are calculated differently in two cases:

Case #1:

- island operation
- or parallel to mains operation, **ProcessControl**: #SysLdCtrl PtM = LDSHARING

Reserve	Actual Reserve	Start condition	Stop condition
Absolute kW / kVA	$AR_{strt} = \Sigma P_{g_{Nom}} - \Sigma P_{g_{Act}}$ $AR_{stp} = \Sigma P_{g_{Nom}^*} - \Sigma P_{g_{Act}}$	$AR_{strt} < \#LoadResStrt$	$AR_{stp} > \#LoadResStop$
Relative %	$RR_{strt} = [(\Sigma P_{g_{Nom}} - \Sigma P_{g_{Act}}) / \Sigma P_{g_{Nom}}].100\%$ $RR_{stp} = [(\Sigma P_{g_{Nom}^*} - \Sigma P_{g_{Act}}) / \Sigma P_{g_{Nom}^*}].100\%$	$RR_{strt} < \\%LdResStrt$	$RR_{stp} > \\%LdResStop$

Case #2:

- parallel to mains operation, **ProcessControl**: #SysLdCtrl PtM = BASELOAD

Reserve	Actual Reserve	Start condition	Stop condition
Absolute kW / kVA	$AR_{strt} = \Sigma P_{g_{Nom}} - BaseLd$ $AR_{stp} = \Sigma P_{g_{Nom}^*} - BaseLd$	$AR_{strt} < \#LoadResStrt$	$AR_{stp} > \#LoadResStop$
Relative %	$RR_{strt} = [(\Sigma P_{g_{Nom}} - BaseLd) / \Sigma P_{g_{Nom}}].100\%$ $RR_{stp} = [(\Sigma P_{g_{Nom}^*} - BaseLd) / \Sigma P_{g_{Nom}^*}].100\%$	$RR_{strt} < \\%LdResStrt$	$RR_{stp} > \\%LdResStop$

Where

- ARstrt Actual Absolute reserve in kW or kVA - for engine start calculation.
- ARstp Actual Absolute reserves in kW or kVA - for engine stop calculation.
- RRstrt Actual Relative reserve in % - for engine start calculation.
- RRstp Actual Relative reserves in % - for engine stop calculation.
- $\Sigma P_{g_{Nom}}$ Sum of Nominal power of all gen-sets on the bus.
- $\Sigma P_{g_{Nom}^*}$ Sum of Nominal power of all gen-sets on the bus apart of the one, which is going to be stopped.
- $\Sigma P_{g_{Act}}$ Sum of Actual power of all gen-sets on the bus = system load.
- BaseLd Baseload is given by the setpoint **ProcessControl**: #SysBaseLoad

NOTE:

System starting sequences may be very different due to their complexity (i.e. gen-sets which do not take part in power management, various nominal powers etc.). Each system should be considered individually.

Optional functions in absolute or relative Power management are:

- Running hours balancing (equalization) – in absolute or relative pwr mgmnt
- Load demand (different size) engines swap – **in absolute pwr mgmnt only**
- Power management of two or more gen-set groups (bus tie support) – in absolute or relative power management

NOTE:

The parallel operation to the mains of multiple gen-sets requires use of the IntelliMains controller. The IntelliMains controller supervises the mains. For further information, please refer to the [IM-NT-MCB-MGCB 3.0 Reference Guide](#) or newer version of the guide.

1.1.2.1 Starting sequence

As written above, the power management is based on the load evaluation in order to provide enough of available running power. An additional gen-set starts when the load of the system raises above certain level to keep the load reserve big enough. Following figure depicts the situation when an additional gen-set is requested to join the already running gen-set(s) to the bus.

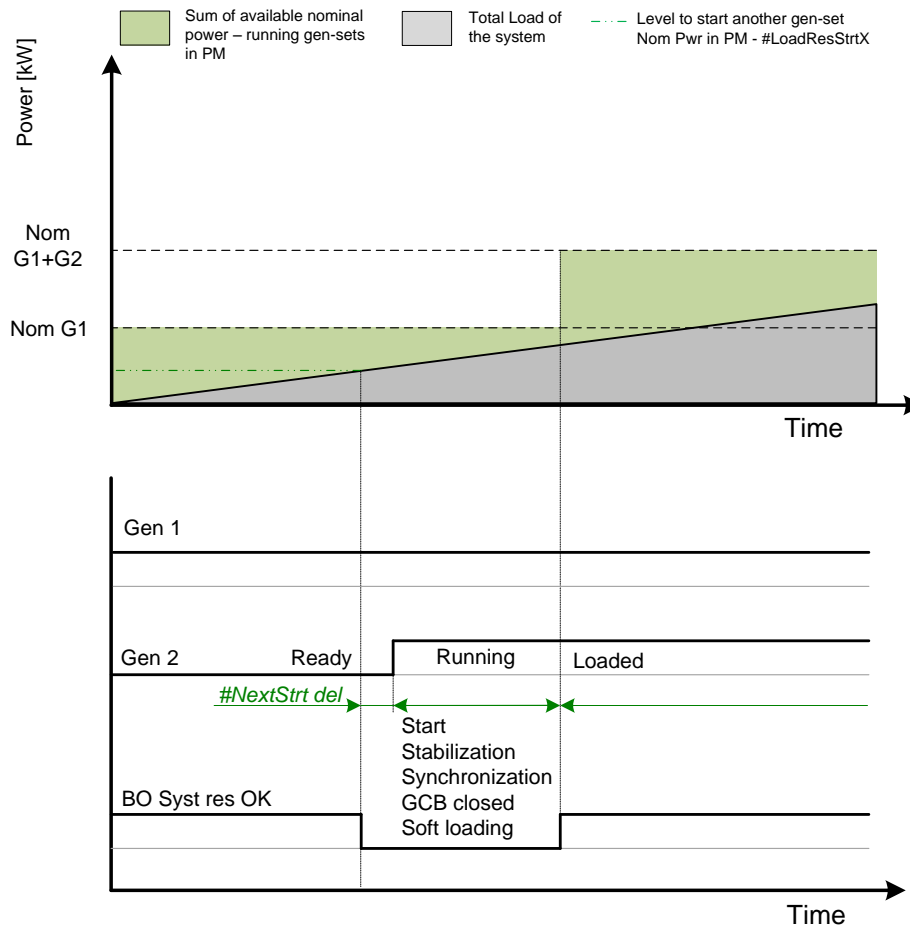


Figure: Starting sequence

As shown above, the load of the system has increased above the level defined by the start condition – i.e. the load reserve is not sufficient as required by the setpoint **Pwr management: #LoadResStrt**. Further explication is provided in chapters Absolute Power Management and Relative Power Management. The level is illustrated by the green dashed line. If the load reserve keeps insufficient for longer time than defined by the setpoint **Pwr management: #NextStrt del**, the next gen-set is actually started. The standard starting sequence follows. Please refer to the chapter Engine states for further information. Once the synchronization procedure is done, the GCB breaker is closed and the gen-set power is ramping up. Once loaded, the system load reserve is raised and becomes sufficient again. Please note the sum of nominal power of all gen-sets on the bus is increased by the nominal power of the additional gen-set.

1.1.2.2 Stopping sequence

As it is written above, the power management is based on the load evaluation in order to provide enough of available running power. An additional gen-set stops when the load of the system drops below certain level to avoid inefficient run of the gen-set. Following figure depicts the situation when a gen-set is requested to stop due to the power management.

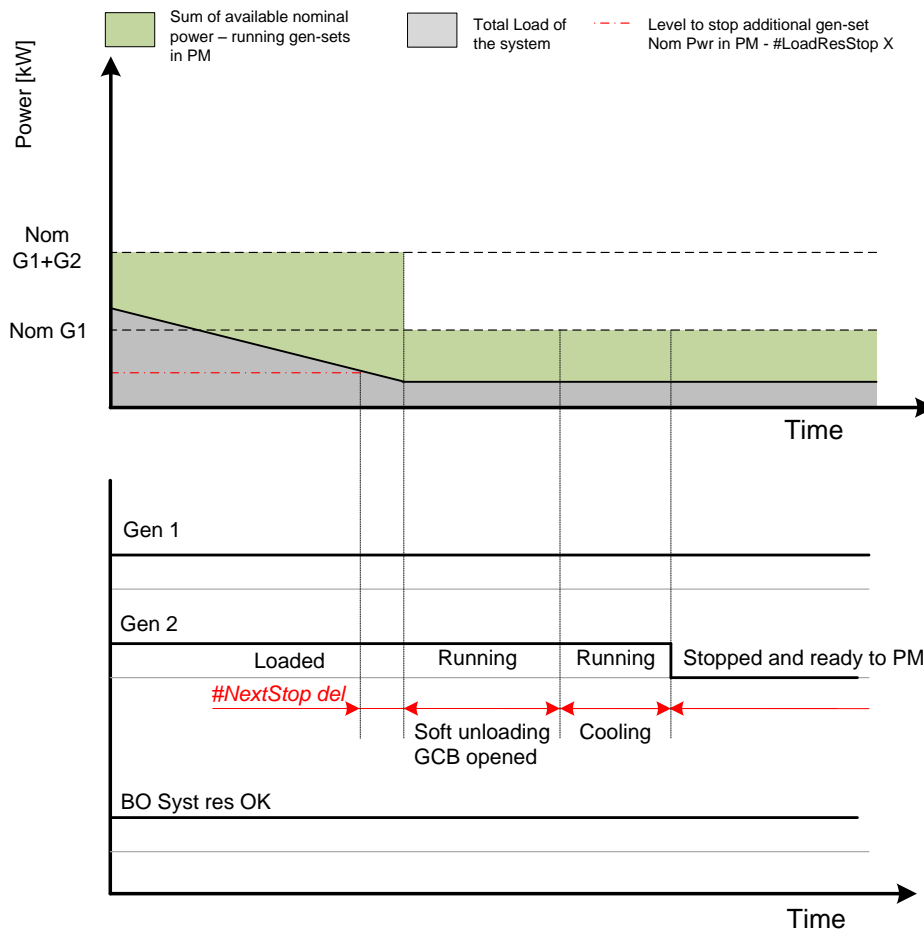


Figure: Stopping sequence

As shown above, the system load has decreased below the level defined by the stop condition – i.e. the load reserve is over a limit given by the setpoint **Pwr management: #LoadResStop**. Further explication is provided in chapters Absolute Power Management and Relative Power Management. The level is illustrated by the red dashed line. If the load reserve keeps over this limit for longer time than defined by setpoint **Pwr management: #NextStopDel del**, the next gen-set is actually requested to stop. Once the gen-set is unloaded, the GCB breaker is opened. Please note the sum of nominal power of all gen-sets on the bus is decreased by the nominal power of the stopped gen-set. The cooling sequence follows before the gen-set is actually stopped. The gen-set is ready to be started if the system load increases again.

1.1.2.3 Absolute Power Management

The power management based on absolute load reserves can be successfully used in cases the load portions are similar to the gen-set capacity or even bigger. The goal of the absolute reserve mode is to provide the same load reserve all the time independently on how many gen-sets are currently running. The mode perfectly fits for industrial plants with large loads.

The absolute power management guarantees adjustable load reserve in kVA or kW.

Activation:

Pwr management: #Pwr mgmt mode = ABS (kW) - Based on **active power** load reserve. Suitable for load demand-based optimization

Pwr management: #Pwr mgmt mode = ABS (kVA) - Based on **apparent power** load reserve. Suitable for generator or busbar dimensioning-based optimization.

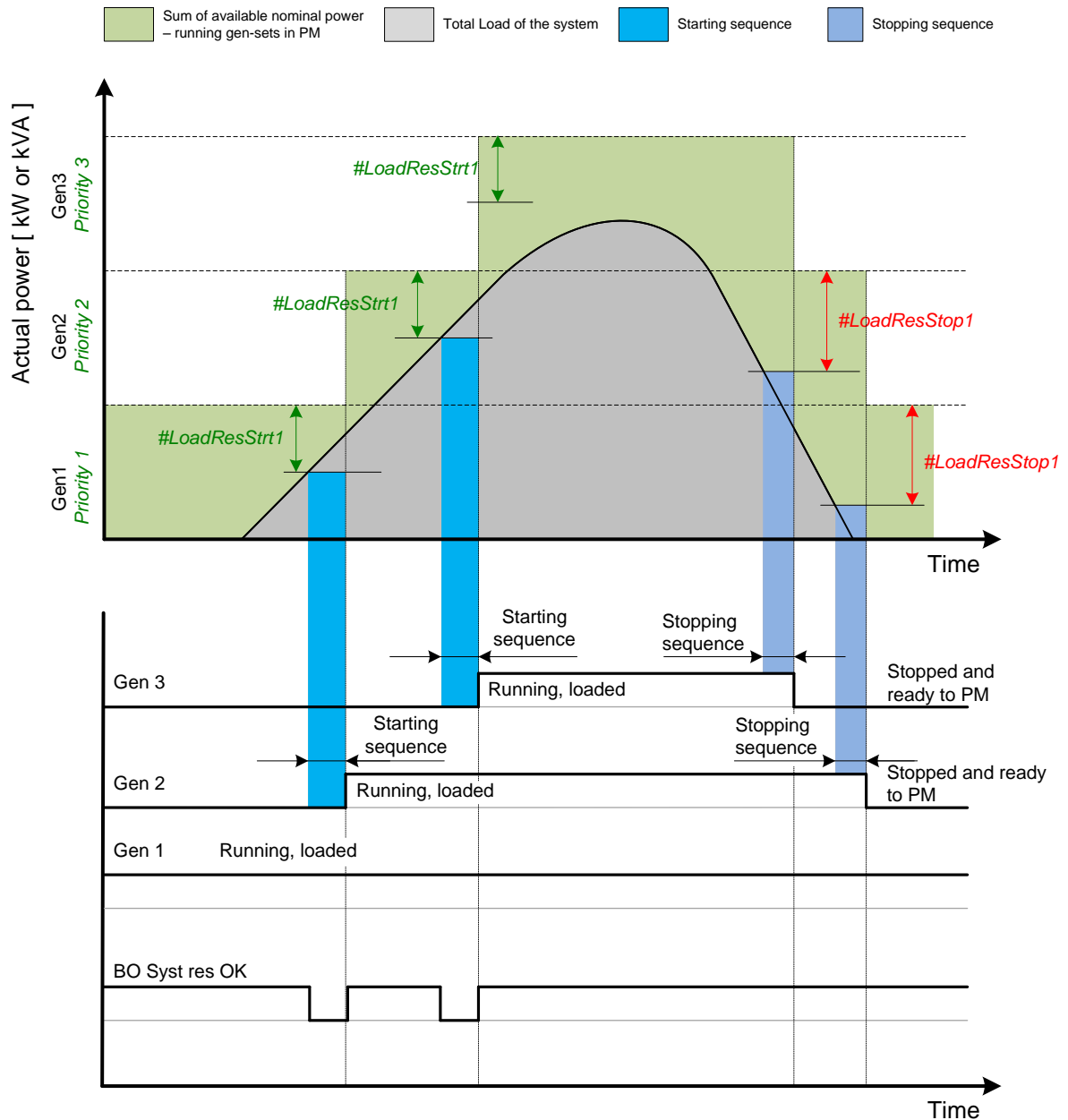


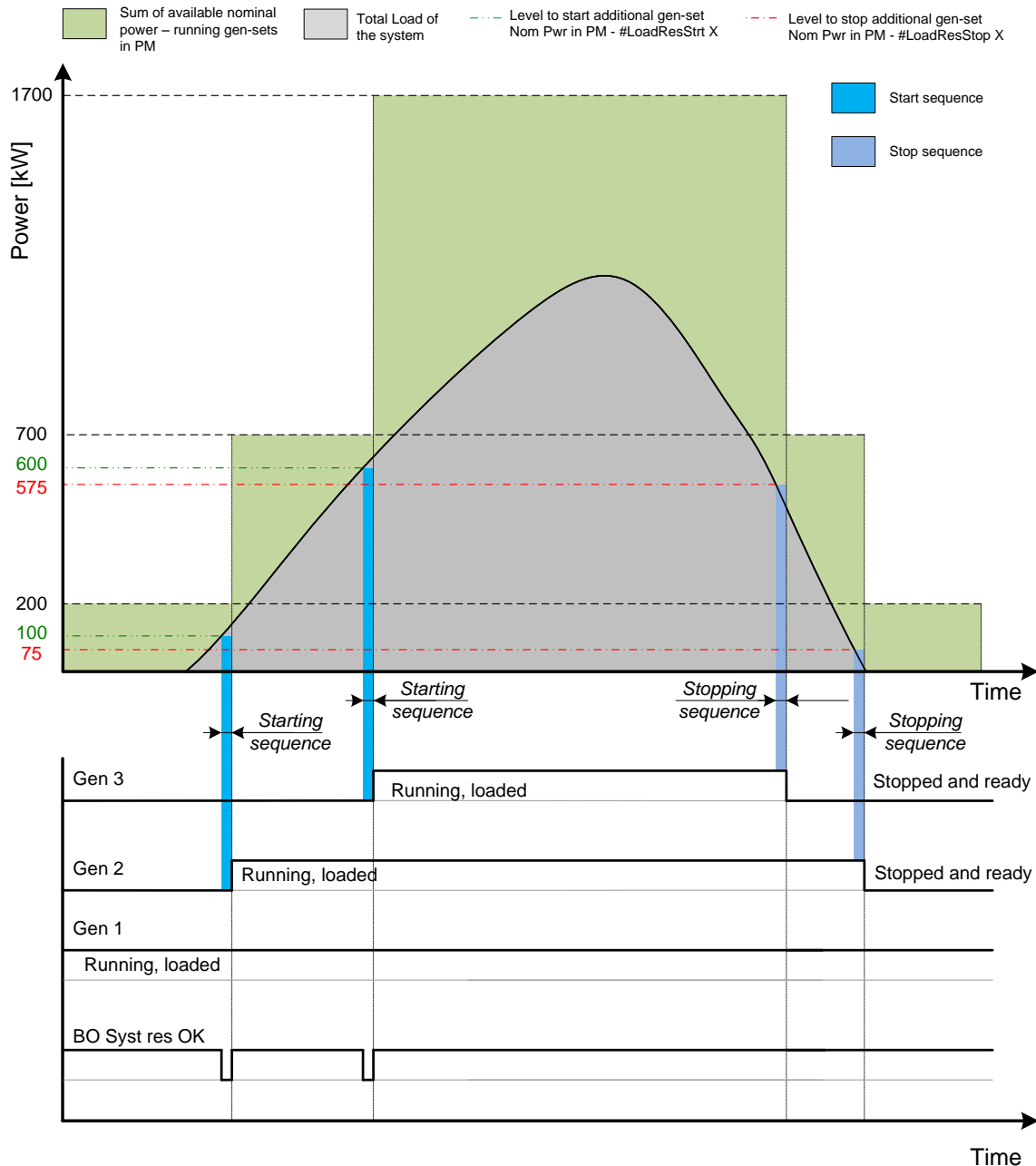
Figure: Power management based on absolute load reserve

An example of absolute power management is shown on the figure below. There are three gen-sets with following choice of setpoints:

Setpoint group	Basic settings	Pwr management					
Setpoint	Nomin power	Pwr management	#Pwr mgmt mode	Priority	#PriorityAuto Swap	#LoadRes Strt X	#LoadRes Stop X
Gen-set #1	200 kW	ENABLED	ABS (kW)	1	DISABLED	100 kW	125 kW
Gen-set #2	500 kW	ENABLED	ABS (kW)	2	DISABLED	100 kW	125 kW
Gen-set #3	1 000 kW	ENABLED	ABS (kW)	3	DISABLED	100 kW	125 kW

NOTE:

Gen-set #1 means that the CAN address of the controller is set to 1. The relevant setpoint is adjusted by **Comms settings: Contr. address.**



Absolute Power management example

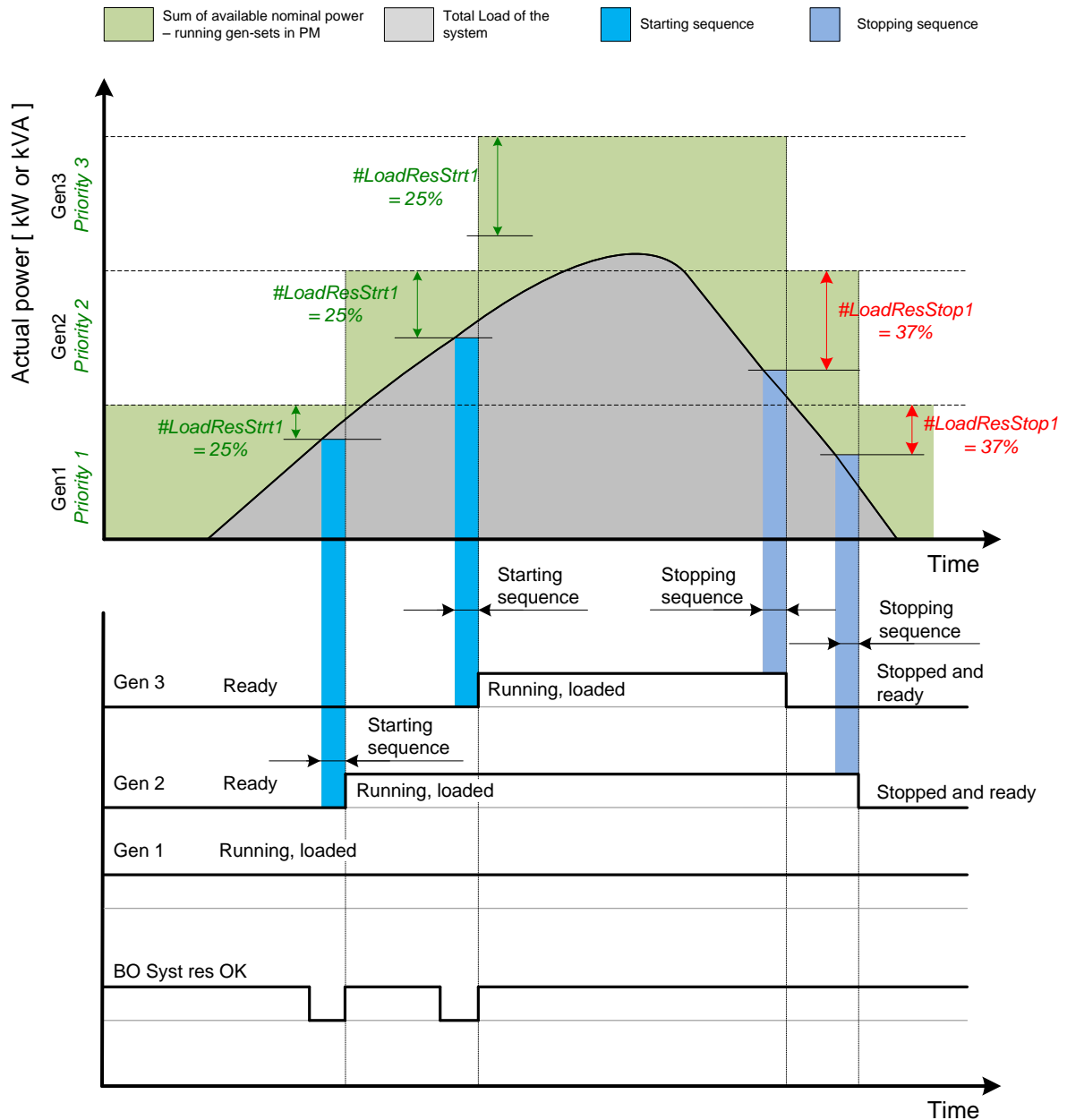
Figure:

As it is shown on both figures above, the additional gen-set is added once the actual load reserve is below the level given by the setpoint **Pwr management: #LoadResStrt X**. The additional gen-set is removed once the actual load reserve is above the level set by **Pwr management: #LoadResStop X**. The green dashed line depicts the value of load at which the additional gen-set is requested to start. This value of the load value is linked with the setpoint **Pwr management: #LoadResStrt X** in following way:

Sum of Nominal power - #LoadResStrt X = Value of load when additional gen-set requested to start
 E.g.: $700 \text{ kW} - 100 \text{ kW} = 600 \text{ kW}$

The red dashed line depicts the value of load at which the additional gen-set is requested to stop. This value of the load value is linked with the setpoint **Pwr management: #LoadRes Stop X** in following way:

Sum of Nominal power - #LoadResStop X = Value of load when additional gen-set requested to stop
 E.g.: $700 \text{ kW} - 125 \text{ kW} = 575 \text{ kW}$



Power management based on relative load reserve

Figure:

An example of relative power management is shown on the figure below. There are three gen-sets with following choice of setpoints:

Setpoint group	Basic settings	Pwr management					
Setpoint	Nomin power	Pwr management	#Pwr mgmt mode	Priority	#PriorityAuto Swap	##%LdRes Strt X	##%LdRes Stop X
Gen-set #1	200 kW	ENABLED	REL (%)	1	DISABLED	35 %	40 %
Gen-set #2	500 kW	ENABLED	REL (%)	2	DISABLED	35 %	40 %
Gen-set #3	1 000 kW	ENABLED	REL (%)	3	DISABLED	35 %	40 %

NOTE:

Gen-set #1 means that the CAN address of the controller is set to 1. The relevant setpoint is adjusted by **Comms settings: Contr. address.**

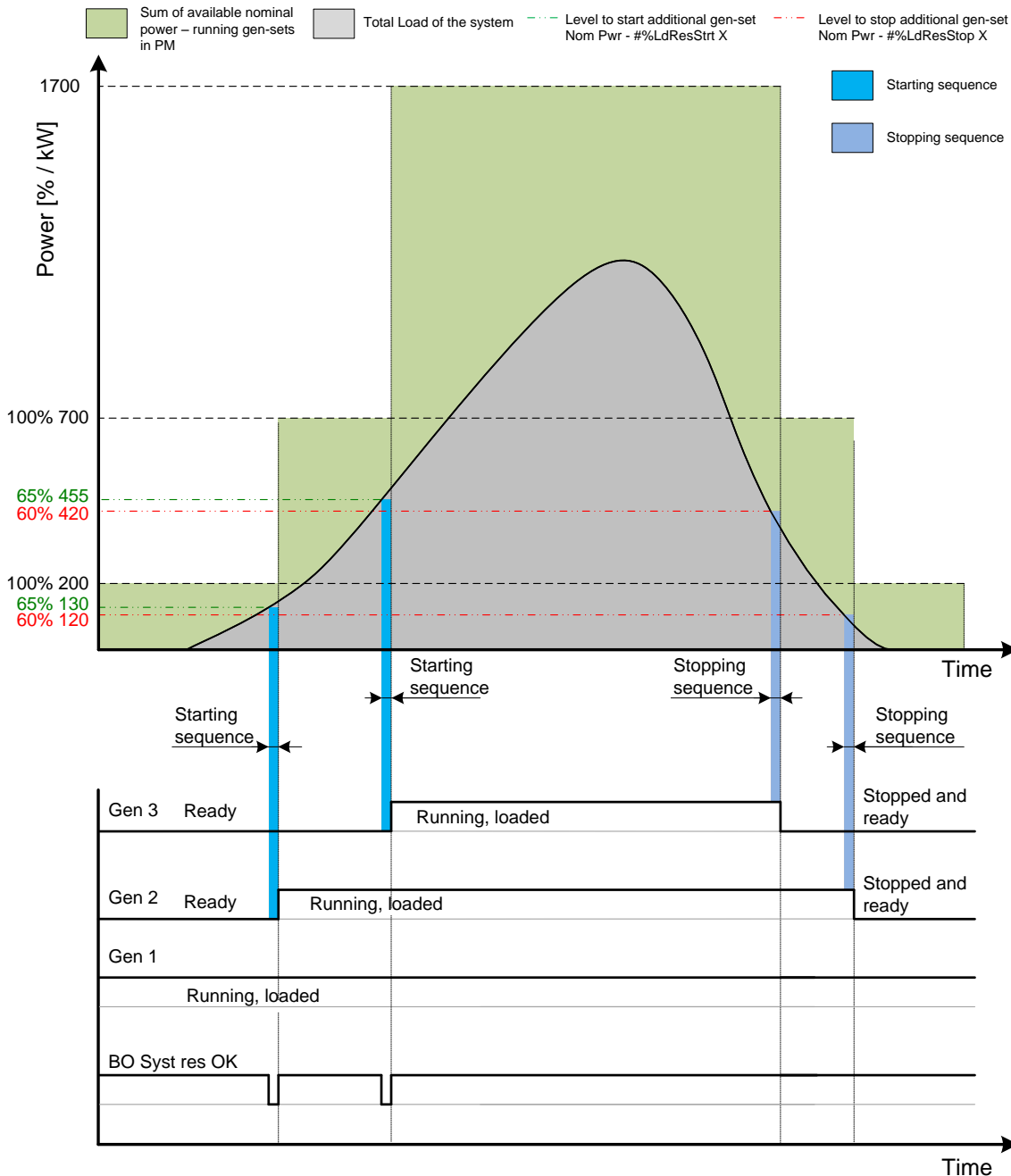


Figure:

Relative Power management example

As it is shown on both figures above, the additional gen-set is added once the actual load reserve is below the level given by the setpoint **Pwr management: $\#\%LdResStrt\ X$** . The additional gen-set is removed once the actual load reserve is above the level set by **Pwr management: $\#\%LdResStop\ X$** . The green dashed line depicts the value of load at which the additional gen-set is requested to start. This value of the load value is linked with the setpoint **Pwr management: $\#\%LdResStrt\ X$** in following way:

$$(100\% - \#\%LdResStrt\ X) * \text{Sum of Nominal power} = \text{Value of load when additional gen-set requested to start in kW (in \% of nominal power)}$$

E.g.: $(100\% - 35\%) * 700\text{ kW} = 455\text{ kW (65\% of nominal power)}$

The red dashed line depicts the value of load at which the additional gen-set is requested to stop. This value of the load value is linked with the setpoint **Pwr management: $\#\%LdResStop\ X$** in following way:

$$(100\% - \#\%LdResStop\ X) * \text{Sum of Nominal power} = \text{Value of load when additional gen-set requested to stop in kW (in \% of nominal power)}$$

E.g.: $(100\% - 40\%) * 700 \text{ kW} = 420 \text{ kW}$ (60 % of nominal power)

There are 4 levels for starting and stopping gen-sets.

- `##LdResStrt 1 / ##LdResStop 1` considered **by default**.
- `##LdResStrt 2 / ##LdResStop 2` considered if LBI: *Load res 2 activated*
- `##LdResStrt 3 / ##LdResStop 3` considered if LBI: *Load res 3 activated*
- `##LdResStrt 4 / ##LdResStop 4` considered if LBI: *Load res 4 activated*

NOTE:

All controllers cooperating together in Power management must have the same load reserve set selected.

It is possible to use virtual shared peripherals for distribution of the binary signal to activate LBI *Load res 2,3 or 4* among controllers over the CAN bus.

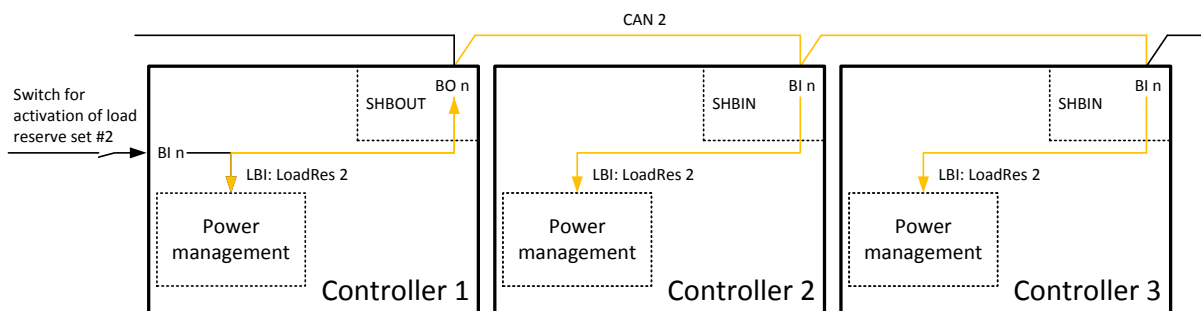


Figure: Example of using virtual shared peripherals for signal distribution

1.1.3 Priorities

The priority of the gen-set within the group is given by the setpoint **Pwr management: Priority**. Lower number represents "higher" priority, i.e. a gen-set with lower number starts before another one with higher number. In other words, the setpoint **Pwr management: Priority** means order in which gen-sets are started and connected to the bus. An example is shown on the figure below. There are four gen-sets with following choice of setpoints:

Setpoint group	Basic settings	Pwr management					
Setpoint	Nomin power	Pwr management	#Pwr mgmt mode	Priority	#PriorityAutoSwap	#LoadResStrt X	#LoadResStop X
Gen-set #1	200 kW	ENABLED	ABS (kW)	4	DISABLED	50 kW	70 kW
Gen-set #2	200 kW	ENABLED	ABS (kW)	3	DISABLED	50 kW	70 kW
Gen-set #3	200 kW	ENABLED	ABS (kW)	2	DISABLED	50 kW	70 kW
Gen-set #4	200 kW	ENABLED	ABS (kW)	1	DISABLED	50 kW	70 kW

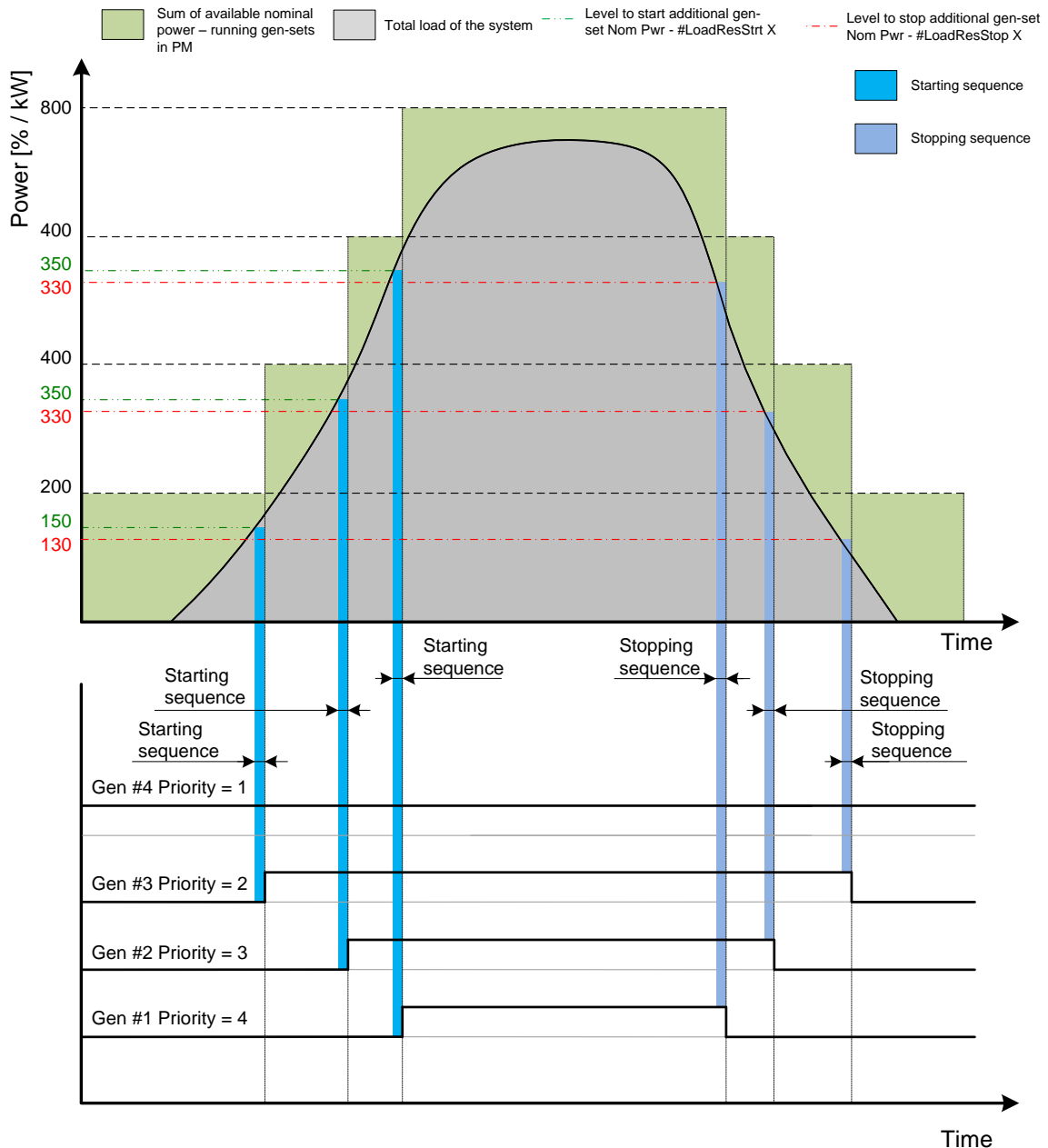


Figure: Power management example - Priorities

NOTE:

Gen-set #1 means that the CAN address of the controller is set to 1. The relevant setpoint is adjusted by **Comms settings: Contr. address.**

By choosing the setpoint **Pwr management: Priority = 1**, the gen-set #4 is running all the time in the example shown on the figure above (AUT mode selected, Pwr management enabled and LBI Sys start/stop activated).

The priority can be also adjusted by a set of logical binary inputs *Priority sw A*, *Priority sw B*, *Priority sw C* and *Priority sw D*. If at least one of these inputs is closed, the priority adjusted by the setpoint as mentioned above is overridden by the priority given by the combination (binary code) of the Priority SW inputs.

NOTE:

The inputs are intended for adjusting the priority by a rotary switch.

The force value function can be used to force priority 0 into the setpoint **Pwr management: Priority**. Priority 0 is the "highest" one, which means the gen-set will be running all the time while the power management is switched on.

If more than one gen-set have the same priority, they will act as "one big" gen-set. There are methods of automatic optimization of the priorities to achieve specific behavior of the group such as equalizing engine hours of the gen-sets or selection of optimal gen-sets to run according to their size and current load demand.

1.2. Automatic priority swapping

As stated in the chapter Priorities, the operator is able to select the order of gen-set starting. There is also the option of automatic priority selection. The controllers are sharing data concerning the running hours and all important information relevant to the actual load. Thanks to the Automatic priority swapping function the controllers choose the gen-set(s) to be running with consideration of their running hours and the actual load. The *Running hours equalization* (RHE) function keeps a constant maximal difference of gen-sets' running hours. The *Load demand swap* (LDS) function keeps running only the gen-sets with suitable nominal power to avoid inefficient fuel consumption or gen-set overload.

At least one gen-set in the group must be set as the master for priority optimization (**Pwr Management: Priority ctrl** = MASTER). It is possible to have more than one master, the one with lowest CAN address will play the role of the master and if it is switched off the next one will take the master role.

Important setpoint: Pwr management: #PriorAutoSwap

The Automatic priority swapping function does not change the setpoint **Pwr management: Priority**. The function sets the order of gen-sets by virtual values "engine priority".

1.2.1. Running hours equalization (RHE)

The gen-sets "engine priorities" are automatically swapped to balance engine running hours. In other words, the controllers compare Run hours of each gen-set and select gen-set(s) to run in order to maintain constant maximal difference of running hours. Up to 32 controllers are supported.

Activation: Pwr management: #PriorAutoSwap = RUN HOURS EQU

Important setpoints: RunHoursBase, #RunHrsMaxDiff, Priority ctrl, Control group

The actual values to be considered by the Running Hours Equalization are calculated from the following formula:

$$\underline{RHE_i = Runhours_i - RunHoursBase_i}$$

where **RHE** is considered value for Running hours equalization, **i** stands for a particular gen-set, **Runhours** is a cumulative sum of run hours available in statistic values of the controller, **RunHoursBase** is a setpoint. This setpoint may be used in the case of gen-sets with different runs hours are intended to be set at the same initial point (e.g. a new gen-set and a used gen-set after retrofit maintenance inspection).

The Running hours equalization function compares RHE value of each controller in the group. Once the difference between RHE of individual controllers is higher than **#RunHrsMaxDiff** (i.e. **#RunHrsMaxDiff + 1**), the gen-set(s) with the lowest is/are started.

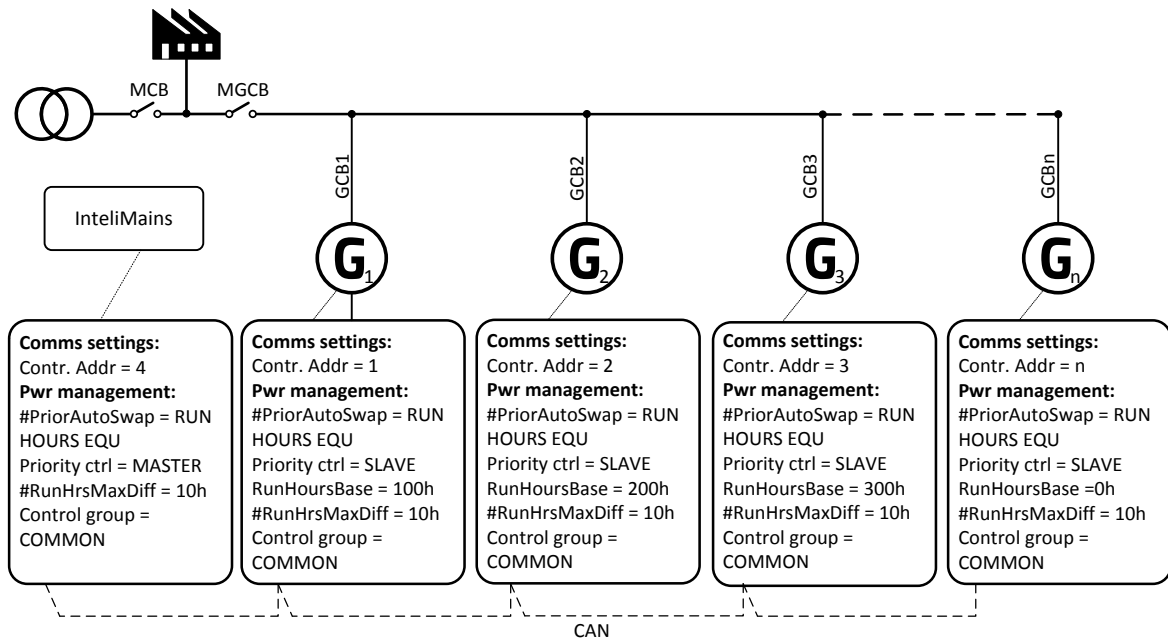


Figure: Running Hours Equalization example

EXAMPLE:

The system structure is shown on the figure above. The IntelliMains controller assumes the role of master in priority swapping and swaps priority of the engines based on their running hours.

3 cases are considered:

Case #1: 2 gen-gets available

Case #2: 3 gen-gets available with same initial RHE.

Case #3: 3 gen-gets available with different initial RHE.

Case #1:

Gen-set 1 running hours = 250 -> running hours considered in RHE = 100 (150-RunHoursBase)

Gen-set 2 running hours = 450 -> running hours considered in RHE = 200 (250-RunHoursBase)

Both gen-sets have the same nominal power of 700 kW. Originally, priority of gen-sets was $G1 = 2$, $G2 = 1$. Load demand in this example is constant and it is 500 kW (i.e. only one engine is running at any time). In this case, the IntelliMains controller sets the engine priority of the gen-set 1 to 1 because it has the lowest considered RHE and the difference between RHE2 (i.e. considered RHE of gen-set 2) and RHE1 is higher than #RunHrsMaxDiff that is set to 10h.

	Run hours	#RunHoursBase	RHE
Gen-set #1	250	150	100
Gen-set #2	450	250	200

The gen-set 1 runs for 100 hours to equalize the RHE of both gen-sets. The gen-set 1 keeps running until the difference between RHE1 and RHE2 exceeds #RunHrsMaxDiff (i.e. 10h). The gen-set 1 runs $100 + \text{\#RunHrsMaxDiff} + 1 = 100 + 10 + 1 = 111$ hours. After 111 hours the gen-sets 2 has the lowest RHE and the difference between RHE1 and RHE2 is higher than #RunHrsMaxDiff. The gen-set 2 runs 11 hours to equalize the RHE of both gen-sets and then additional #RunHrsMaxDiff + 1 hours (i.e. $11 + 10 + 1 = 22$ hours). The evolution of RHE1 and RHE2 is shown on the figure below.

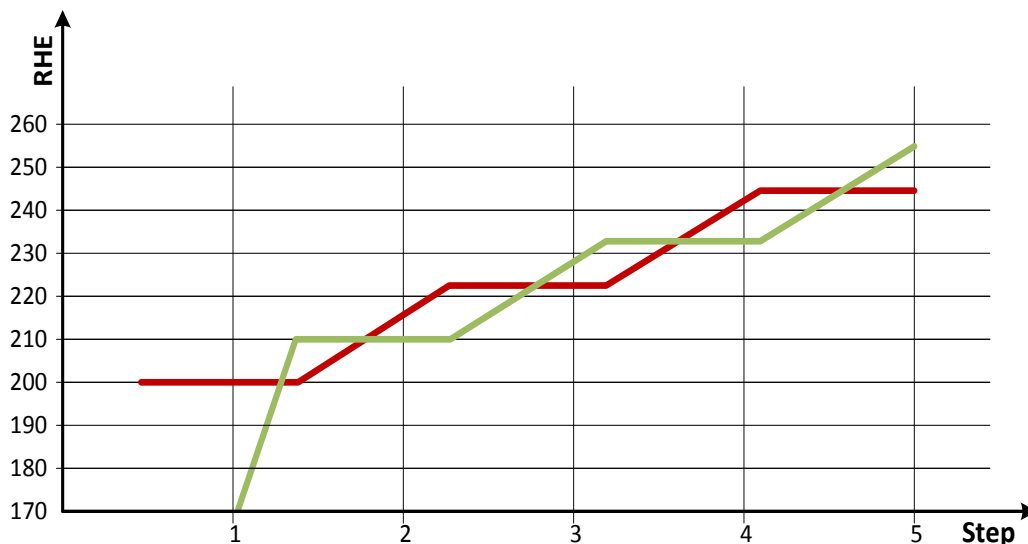




Figure: Running Hours Equalization example, 2 gen-sets

step	0	1	2	3	4	5
RHE1 	100	211	211	233	233	255
RHE2 	200	200	222	222	244	244
Run G1 (Δ RHE1)	0	111	0	22	0	22

Run G2 (Δ RHE2)	0	0	22	0	22	0
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From the example of the case #1, it can be concluded that the gen-sets are swapped after the duration determined by following formula:

SwapTime = Second lowest considered running hours – Current lowest considered running hours + #RunHrsMaxDiff +1

Case #2:

Gen-set 1 running hours = 0 -> running hours considered in RHE = 0 (0-RunHoursBase)
 Gen-set 2 running hours = 0 -> running hours considered in RHE = 0 (0-RunHoursBase)
 Gen-set 3 running hours = 0 -> running hours considered in RHE = 0 (0-RunHoursBase)

Each gen-set has the same RHE = 0 h. By applying the SwapTime formula, we get the run time of gen-set 1 before next swapping:

SwapTimeG1 = 0 – 0 + 10 + 1 = 11

Similar way, we get the run time of gen-set 2 before next swapping:

SwapTimeG2 = 11 – 11 + 10 + 1 = 11

Finally, we get the run time of gen-set 3 before next swapping:

SwapTimeG2 = 11 – 0 + 10 + 1 = 22

Please refer to figure below to understand the evolution of RHE of gen-sets in this particular case.

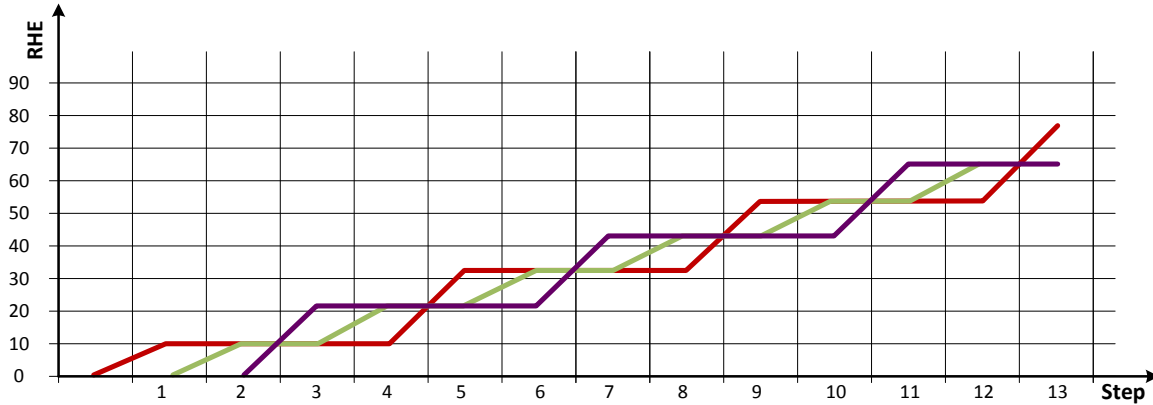





Figure: Running Hours Equalization example, 3 gen-sets with same initial RHE

step	0	1	2	3	4	5	6	7	8	9	10	11	12	13
RHE1 	0	11	11	11	11	33	33	33	33	55	55	55	55	77
RHE2 	0	0	11	11	22	22	33	33	44	44	55	55	66	66
RHE3 	0	0	0	22	22	22	22	44	44	44	44	66	66	66
Run G1 (Δ RHE1)	0	11	0	0	0	22	0	0	0	22	0	0	0	22
Run G2 (Δ RHE2)	0	0	11	0	11	0	11	0	11	0	11	0	11	0
Run G3 (Δ RHE3)	0	0	0	22	0	0	0	22	0	0	0	22	0	0

Case #3:

Gen-set 1 running hours = 250 -> running hours considered in RHE = 100 (150-RunHoursBase)
 Gen-set 2 running hours = 450 -> running hours considered in RHE = 200 (250-RunHoursBase)

Gen-set 3 running hours = 750 -> running hours considered in RHE = 250 (500-RunHoursBase)

The gen-set 1 has the lowest RHE1 = 100 h. By applying the SwapTime formula, we get the run time of gen-set 2 before next swapping:

$$\text{SwapTimeG1} = 200 - 100 + 10 + 1 = 111$$

Till the step 5, the evolution of the gen-set swapping is the same as in the case #1, just gen-set 1 and gen-set 2 involve. In the step 6 the gen-set 2 can run only 17 hours (previously 22 hours) because the gen-set 3 involves. The evolution of RHE1, RHE2 and RHE3 is shown on the figure below.

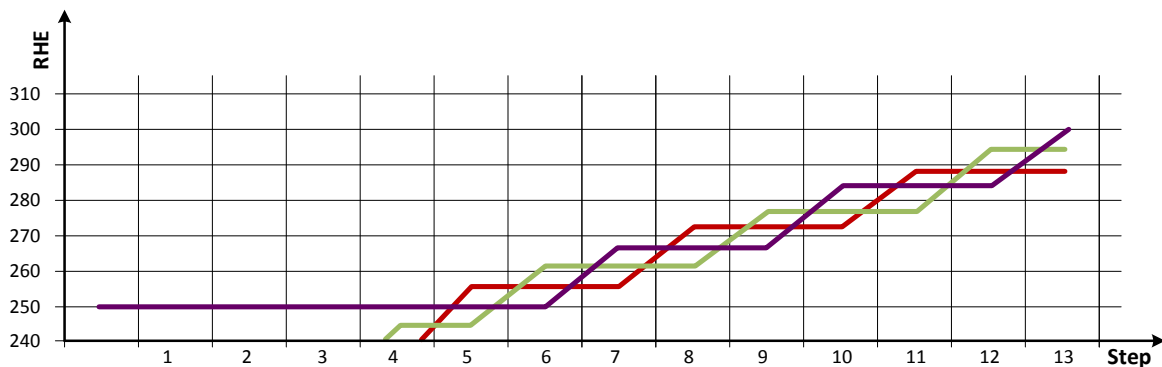


Figure: Running Hours Equalization example, 3 gen-sets with different initial RHE

step	0	1	2	3	4	5	6	7	8	9	10	11	12	13
RHE1 —	100	211	211	233	233	255	255	255	272	272	272	288	288	288
RHE2 —	200	200	222	222	244	244	261	261	261	277	277	277	294	294
RHE3 —	250	250	250	250	250	250	250	266	266	266	283	283	283	299
Run G1 (Δ RHE1)	0	111	0	22	0	22	0	0	17	0	0	16	0	0
Run G2 (Δ RHE2)	0	0	22	0	22	0	17	0	0	16	0	0	17	0
Run G3 (Δ RHE3)	0	0	0	0	0	0	0	16	0	0	17	0	0	16

NOTE:

Setting **Pwr management**: #RunHrsMaxDiff = 5 does not mean that gen-sets swap every 5 hours. The Swap time is determined by the formula stated above. Please read the entire chapter Running hours equalization for better understanding.

In the case **Pwr management**: #RunHrsMaxDiff is set to 0 and all gen-set in the group are at the same initial point (RHE are equal), the gen-set swapping happens every hour.

NOTE:

Core power management is still fully functional.

Priority setpoints are not actually changed. Virtual values “engine priority” are used. If changing of priority setpoints is required, they need to be changed and RHE needs to be disabled and enabled again for the changes to take place.

1.2.2. Load demand swap (LDS) – different sized engines

If there are gen-sets of different size at the site, it may be required always to run such gen-sets that best fit to the actual load demand. The *Load demand swap* function is intended for this purpose and can control up to 3 gen-sets (priorities). Up to three running engines (priorities) can be swapped based on load demand (e.g. one “small” engine may run on “small” load and swaps to another one, “big” engine that runs when load increases). This function is available **only in combination with absolute power management**.

Activation: Pwr management:#PriorAutoSwap = LD DEMAND SWAP

Important setpoints: #PwrBandContr1, #PwrBandContr2, #PwrBandContr3, #PwrBandContr4, #PwrBandChngDIUp, #PwrBandChngDIDn, Load reserve setpoints (depending on selected load reserve set), Priority ctrl, Control group.

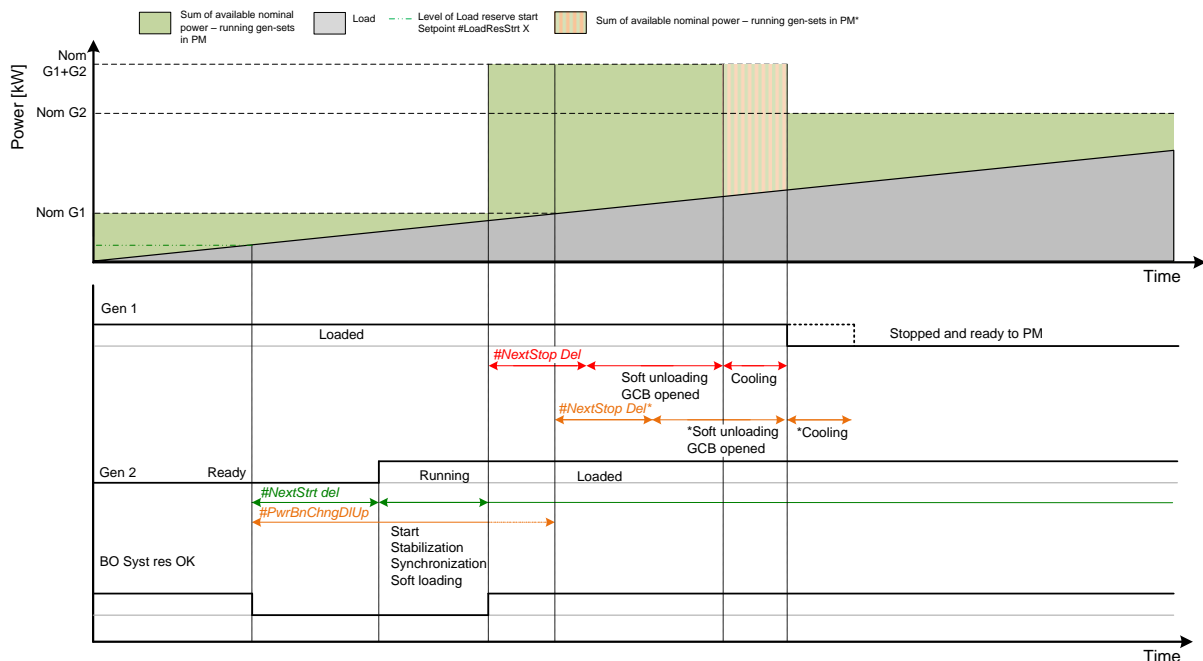
The gen-sets must have addresses 1, 2 and 3. There are four power bands; each of them has adjusted specific combination of gen-sets that run within it. Power bands are adjusted by setpoints #PwrBandContr1, #PwrBandContr2, #PwrBandContr3 and #PwrBandContr4. The load levels of the power bands are defined by sum of nominal powers of gen-sets that are adjusted to run in each particular power band, and the load reserve for start. The combinations of gen-sets must be created in the way the total nominal power of the Power band #1 < #2 < #3 < #4. If the load demand is above the power band #4 then all gen-sets are ordered to run. In fact there is power band #5, which has fixedly selected all the gen-sets to run.

The currently active power band is given by the actual load demand. If the load demand changes and gets out from the current power band, the next/previous power band is activated with delay **Pwr management:** #PwrBnChngDIUp or **Pwr management:** #PwrBnChngDIDn depending on the direction of the change. The gen-sets which are included in the current power band get engine priority 1, the others get priority 32. The setpoint **Pwr management:** Priority is not influenced by this function. Virtual values "engine priority" are used.

NOTE:
If the power band change delays (i.e. **Pwr management:** #PwrBnChngDIUp and **Pwr management:** #PwrBnChngDIDn) are adjusted to higher values than **Pwr management:** #NextStrt del and **Pwr management:** #OverldNextDel setpoints then it may occur, that also the gen-sets not belonging to the current power band will start. This is normal and it prevents the system from overloading. Priority setpoints are not actually changed. Virtual values "engine priority" are used.

1.2.2.1. Handover UP Swap sequence

As explain above, the automatic priority swapping evaluates the load of the system and assigns the most appropriate power band. The handover UP sequence describes the situation the gen-set with lower nominal power is swapped by the gen-set with higher nominal power. The gen-set with lower nominal capacity is stopped once the sequence is over. The stopped gen-set is in ready state and keeps available in power management.

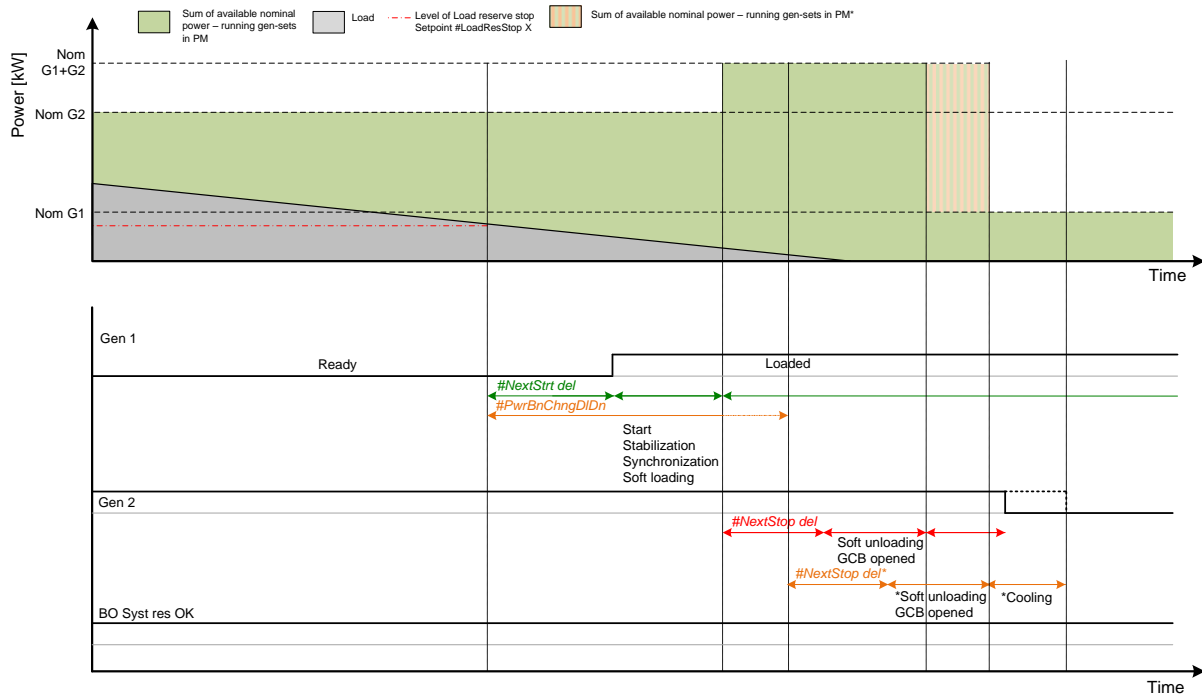


NOTE:

If the power band change delay **Pwr management: #PwrBnChngDIUp** is adjusted to that longer value than total time requiring start of other gen-set, stabilization, synchronization, GCB closing and soft loading, it postpones the soft unloading of the gen-set to be stopped. This delay is depicted by the dashed orange line. Consequently, the handover up swap sequence is postponed by this delay.

1.2.2.2. Handover DOWN Swap sequence

The handover DOWN sequence describes the opposite situation. The gen-set with higher nominal power is swapped by the gen-set with lower nominal power. The gen-set with higher nominal capacity is stopped once the sequence is over. The stopped gen-set is in ready state and keeps available in power management.



NOTE:

If the power band change delay **Pwr management: #PwrBnChngDIUp** is adjusted to that longer value than total time requiring start of other gen-set, stabilization, synchronization, GCB closing and soft loading, it postpones the soft unloading of the gen-set to be stopped. This delay is depicted by the dashed orange line. Consequently, the handover down swap sequence is postponed by this delay.

EXAMPLE:

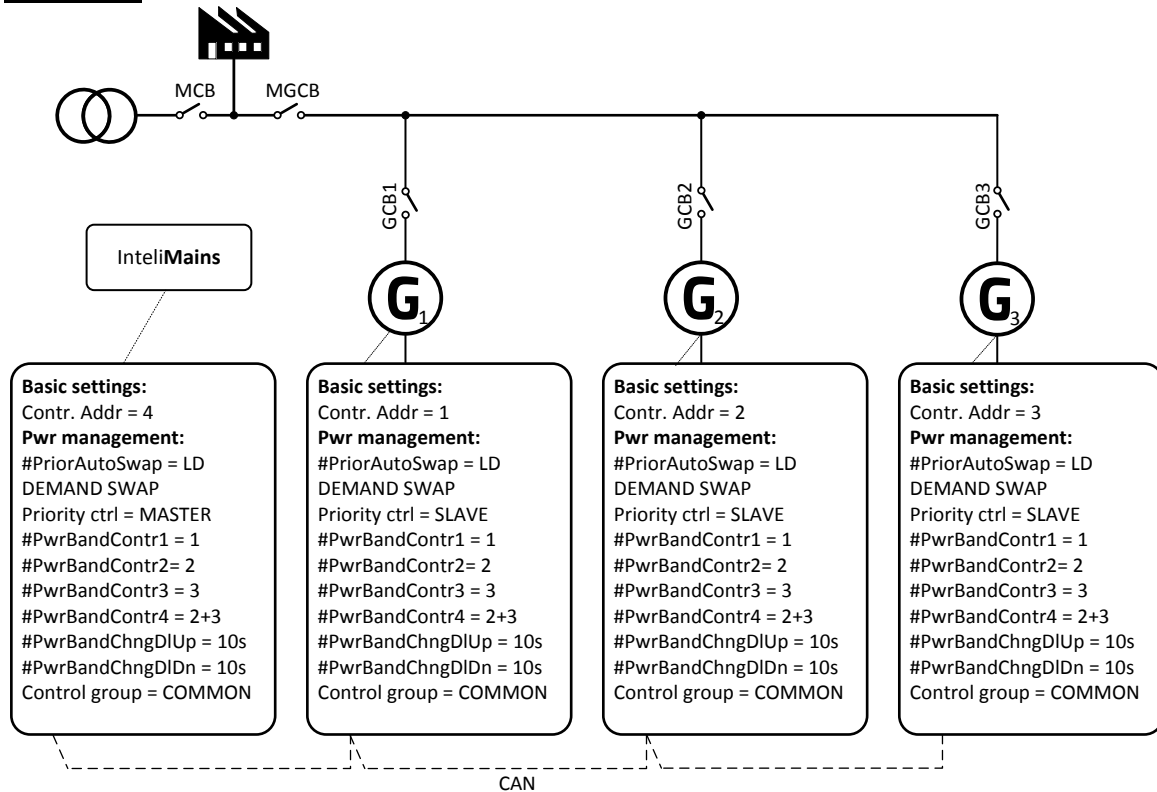


Figure: Load Demand Swapping example

The system is shown in previous figure. The IntelliMains controller assumes the role of master in priority swapping and swaps engine priority based on user defined power bands. There are 4 available customizable power bands. The power band #5 is fixed – all available gen-set in power gen-set are running.

Power bands are changed up if:

(Nominal power of all gen-sets in a particular band - Total generated power by gen-sets in power management) < Reserve for start

or down if:

(Nominal power of all gen-sets in next lower band - Total generated power by gen-sets in power management) > Reserve for stop

The site contains 3 gen-sets, G1 is 200kW, G2 is 500kW and G3 is 1000kW. The reserve for start is adjusted to 50kW and for stop to 70kW. Following table describes available power bands:

Gen-sets	Nominal power [kW]	Power band [kW]
G1	200	0 .. 150
G2	500	151 .. 450
G1+G2	700	451 .. 650
G3	1000	651 .. 950
G1+G3	1200	951 .. 1150
G2+G3	1500	1151 .. 1450
G1+G2+G3	1700	>1450

Following table describes selected power bands:

Power band	Gen-sets	Nominal power [kW]	Power band range [kW]
#PwrBandContr1	G1	200	0 .. 150
#PwrBandContr2	G2	500	151 .. 450
#PwrBandContr3	G3	1000	451 .. 950
#PwrBandContr4	G2+G3	1500	951 .. 1450
Fixed power band #5	G1+G2+G3	1700	>1450

Following figure illustrates the power bands swapping in function of load evolution.

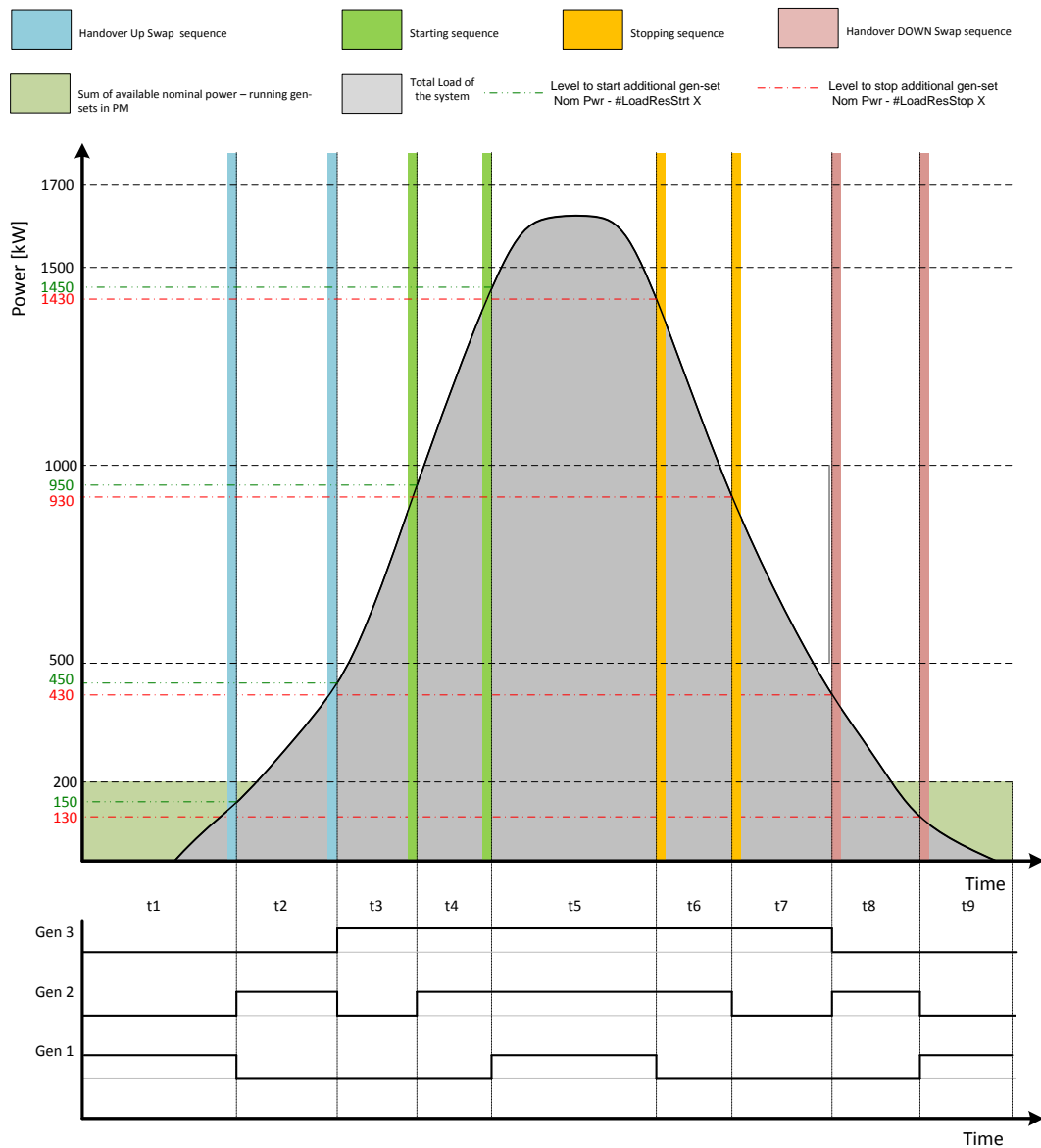


Figure: Load Demand Swapping example

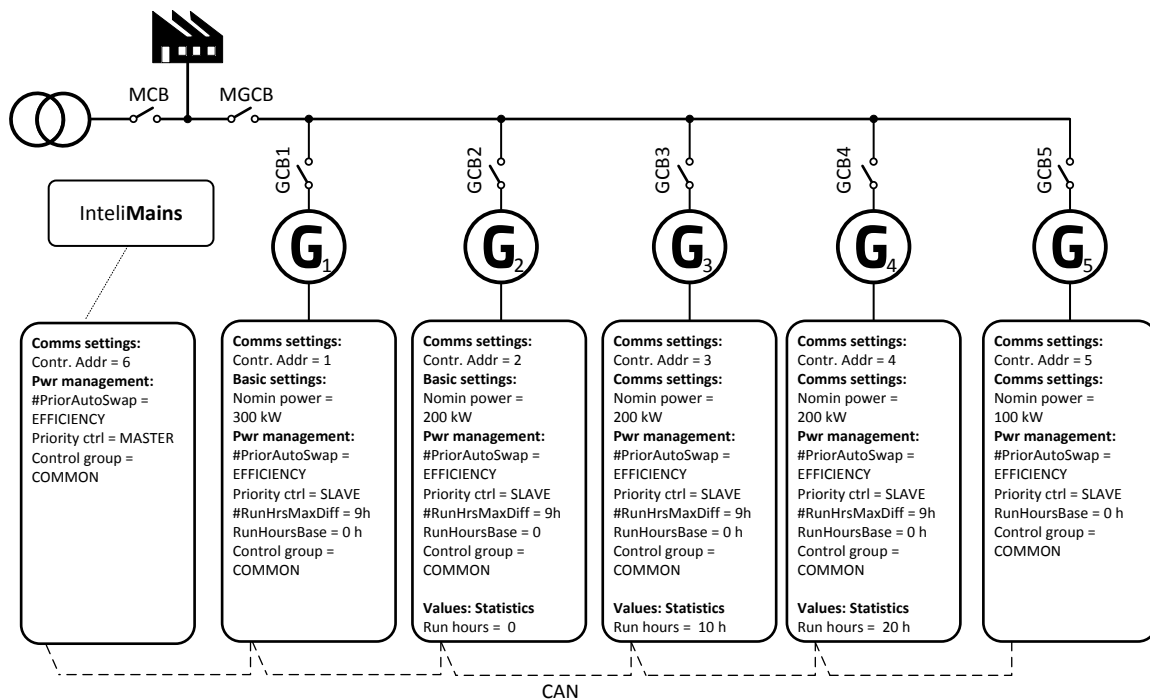
step		t1	t1 -> t2	t2	t2 -> t3	t3	t3 -> t4	t4	t4 -> t5	t5	t5 -> t6	t6	t6 -> t7	t7	t7 -> t8	t8	t8 -> t9	t9
Gen#1	200 kW	LOADED	handover UP	READY	handover UP	READY	starting of gen#2	READY	starting of gen#1	LOADED	stopping of gen#1	READY	stopping of gen#2	READY	handover DOWN	READY	handover DOWN	LOADED
Gen#2	500 kW	READY	handover UP	LOADED	handover UP	READY	starting of gen#2	LOADED	starting of gen#1	LOADED	stopping of gen#1	LOADED	stopping of gen#2	READY	handover DOWN	LOADED	handover DOWN	READY
Gen#3	1 000 kW	READY	handover UP	READY	handover UP	LOADED	starting of gen#2	LOADED	starting of gen#1	LOADED	stopping of gen#1	LOADED	stopping of gen#2	LOADED	handover DOWN	READY	handover DOWN	READY

1.2.3. Efficiency

The Efficiency mode is a combination of Running Hours Equalization and Load Demand Swap priority optimization modes. Please refer to chapters 1.2.1 and 1.2.2 for further information about RHE and LDS priority optimization function.

- In the first step, the controller sorts the gen-sets according to their nominal power.
- In the second step, the controller sorts the gen-sets with the same nominal power according to their RHE.
- The gen-set(s) their nominal power fits the most are chosen. From those with same nominal power, the gen-set(s) with lowest RHE are chosen.

EXAMPLE:



Setpoint group	Basic settings	Pwr management					
Setpoint	Nomin power / RHE	Pwr management	#Pwr mgmt mode	Priority	#PriorityAutoSwap	#LoadResStrt X	#LoadResStop X
Gen-set #1	300 kW	ENABLED	ABS (kW)	1	EFFICIENCY	20 kW	30 kW
Gen-set #2	200 kW / 0 h	ENABLED	ABS (kW)	2	EFFICIENCY		
Gen-set #3	200 kW / 10 h	ENABLED	ABS (kW)	3	EFFICIENCY		
Gen-set #4	200 kW / 20 h	ENABLED	ABS (kW)	4	EFFICIENCY		
Gen-set #5	100 kW	ENABLED	ABS (kW)	5	EFFICIENCY		

NOTE:

Gen-set #1 means that the CAN address of the controller is set to 1. The relevant setpoint is adjusted by **Comms settings: Contr. address**.

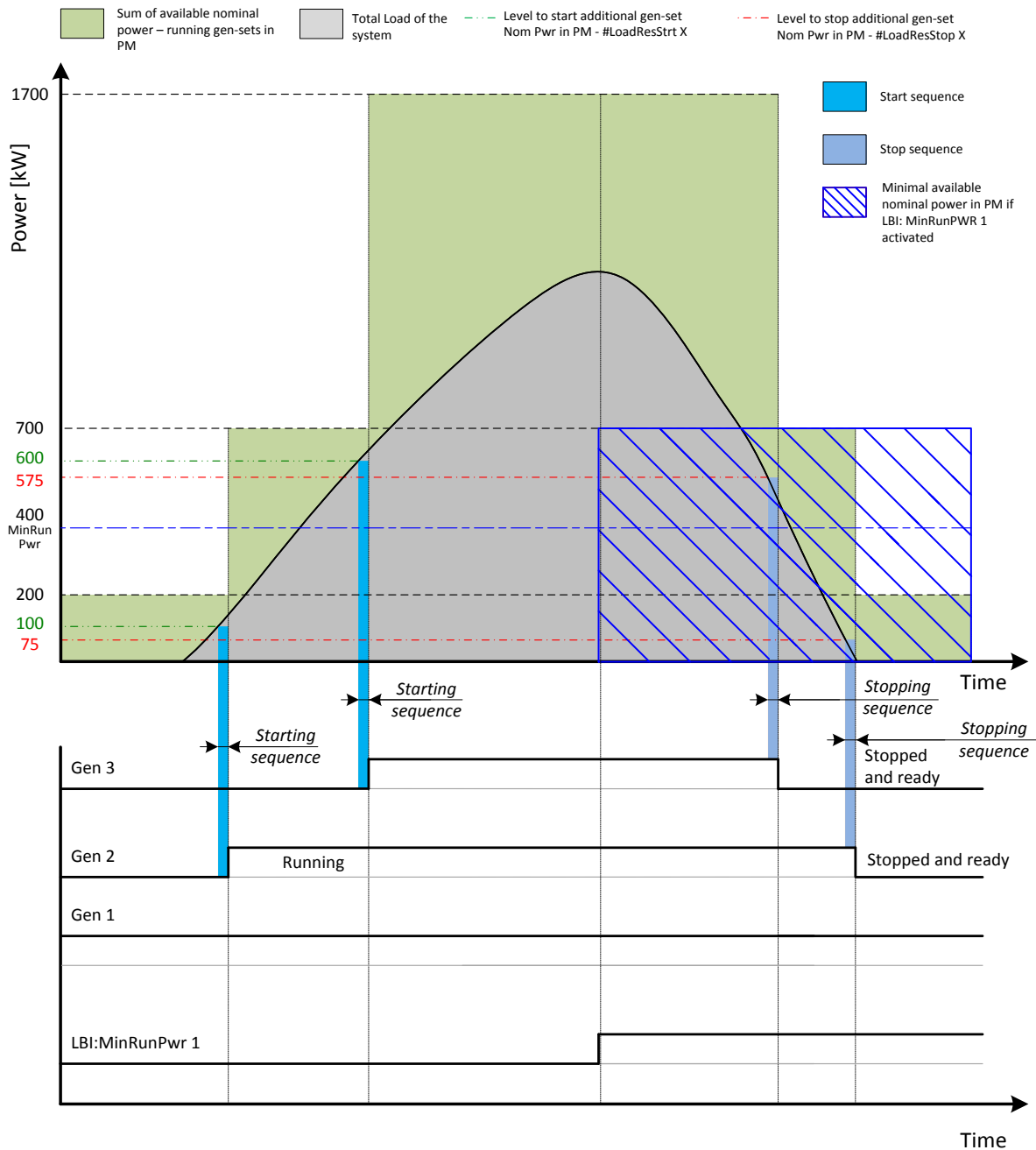
Following table provide an example of gen-set selection in function of system load evolution. The table is an example of Efficiency priority optimization function.

System Load [kW]	Running gen-sets	Description	Total Running power within PM [kW]	Relative load of gen-sets [%]	
40	5		100	40%	
60	5		100	60%	
80	5 2 [0h]	start stop	LDS Swap	300	26%
100	2 [10h]		200	50%	
120	2 [20h]		200	60%	
120	2 [30h] 3 [10h]	Start stop	RHE Swap	400	30%
120	3 [20h]		200	60%	
140	3 [30h]		200	70%	
180	3 [40h] 1	Start stop	LDS Swap	500	36%
200	1		300	67%	
240	1		300	80%	
280	1 5	Start	Gen#5 joins (LDS)	400	70%
340	1 5		400	85%	
380	1 5 4 [20h]	start stop	LDS + RHE Swap	600	63%
400	1 4		500	80%	
440	1 4		500	88%	
480	1 4 5	start	Gen#5 joins (LDS)	600	80%
540	1 4 5		600	90%	
580	1 4 5 2 [30h]	start stop	LDS Swap	800	73%
600	1 4 2		700	86%	
640	1 4 2		700	91%	
680	1 4 2 5	start	Gen#5 joins (LDS)	800	85%
740	1 4 2 5		800	93%	
780	1 4 2 5 3 [40h]	start stop	LDS Swap	1000	78%
800	1 4 2 3		900	89%	
840	1 4 2 3		900	93%	
880	1 4 2 3 5	start	Gen#5 joins (LDS)	1000	88%
940	1 4 2 3 5		1000	94%	

1.3. Minimum Running Power

Minimum Running Power function is used to adjust a minimum value of the sum of nominal power of all running gen-sets. If the function is active, then the gen-sets would not be stopped, although the reserve for stop is fulfilled.

EXAMPLE:



The setpoint **Pwr management: #MinRunPower 1** is adjusted to 400 kW. Once the LBI: *MinRunPwr 1* is activated, the available nominal running power has to be equal or higher to 400 kW. Even if the load reserve is big enough to stop the gen-set #2 (nominal power 500 kW), the gen-set keeps running as at least 400 kW has to be available. The gen-set#1 (nominal power 200 kW) is not enough.

There are 3 different *MinRunPower* setpoints.

- #*MinRunPower 1* considered if LBI *MinRun power 1* activated
- #*MinRunPower 2* considered if LBI *MinRun power 2* activated
- #*MinRunPower 3* considered if LBI *MinRun power 3* activated

NOTE:

If more than one binary input for *MinRunPower* activation is closed *MinRunPower* setpoint with higher number is used (i.e. binary inputs with higher number have higher priority). When no binary input is closed, then minimal running power is 0.

NOTE:

All controllers cooperating together in Power management must have the same Minimal Running Power set selected.

It is possible to use virtual shared peripherals for distribution of the binary signal activating LBI MinRun Power 1,2 or 3 among controllers over the CAN bus.

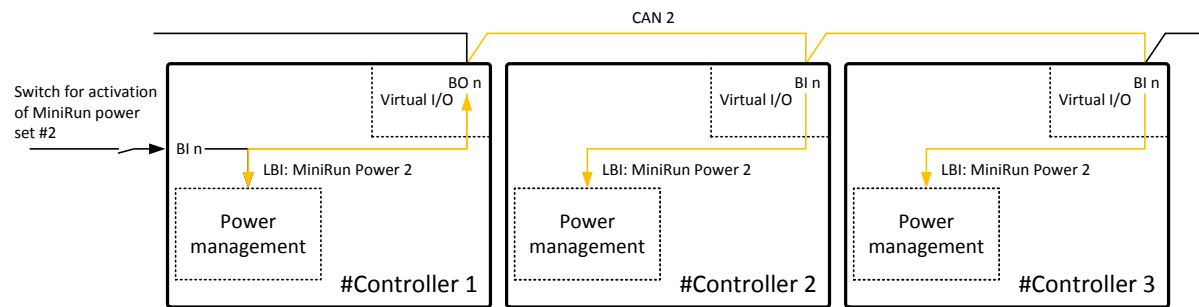


Figure: Example of using virtual shared peripherals for signal distribution

1.4. Control Groups

The physical group of the gen-sets (i.e. the site) can be separated into smaller logical groups, which can work independently even if they are interconnected by the CAN2 bus. The logical groups are intended to reflect the real topology of the site when the site is divided into smaller gen-set groups separated from each other by bus-tie breakers. If the bus-tie breakers are closed the sub-groups have to work as one large group and if the bus-tie breakers are open, the sub-groups have to work independently.

- The group which the particular controller belongs to is adjusted by the setpoint **Pwr management: Control group**. If there is only one group in the site, adjust the setpoint to 1 (=COMMON).
- The information which groups are currently linked together is being distributed via the CAN. Each controller can provide information about one BTB breaker. The breaker position is detected by the input *GroupLink* (i.e. this input is to be connected to the breaker feedback).
- The two groups which are connected together by the BTB breaker mentioned above are adjusted by setpoints **Pwr management: GroupLinkLeft** and **Pwr management: GroupLinkRight**.

NOTE:

The "group link" function is independent on the group, where the controller itself belongs to. The controller can provide "group link" information about any two groups.

- If the "group link" is opened the two groups act as two separated groups. If it is closed the groups act as one large group.

The picture below shows an example of a site with 4 gen-sets separated by a BTB breaker into two groups of 2. The BTB position is detected by the controllers 2 and 3. The reason, why there are 2 controllers used for detection of the BTB position, is to have a backup source of the group link information if the primary source (controller) is switched off.

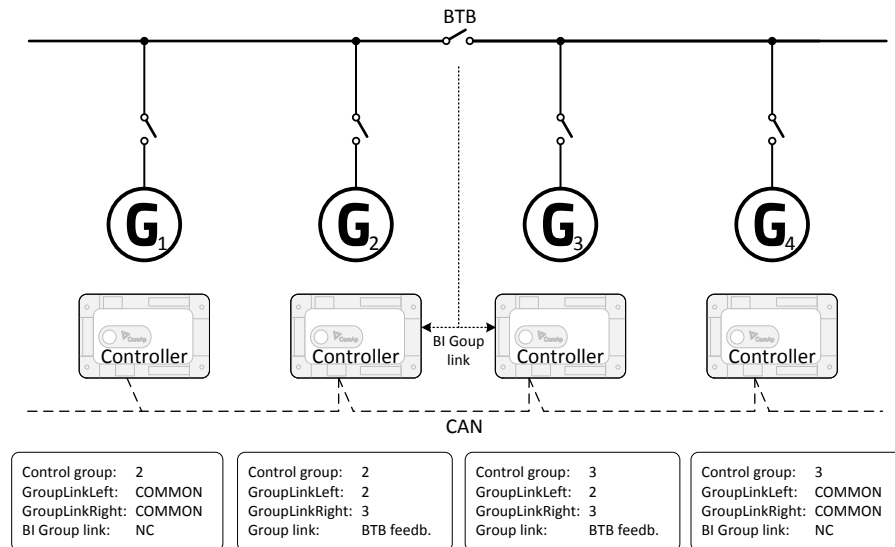


Figure: Example of control groups

Once the BTB breaker is closed, the control group 2 and 3 become new group 2+3. The closed BTB and the group link function influence the load reserve (i.e. increased by added gen-set of added gen-sets). Load sharing applies for all gen-sets.

Load shedding

All LOAD SHED outputs are activated (closed) to trip the unessential load when gen-set goes to island:

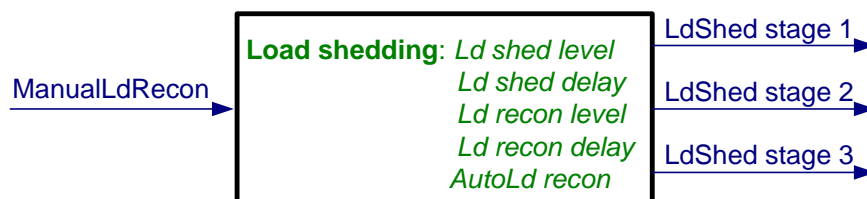
- When GCB is closed after mains fail and gen-set starts in SEM / AUT mode.
- When MCB opens from parallel to mains operation in SEM / AUT mode.
- Before MCB is opened in MAN mode by button.

The load shedding function is active in all controller modes except OFF.

Load shedding has three steps and each step is linked with its own Load shed x binary output. There is only one load shed level and delay for all three steps as well as recon level and delay. Load shed can only move from one step to the next, e.g. No LoadShed to LdShed S1 to LdShed S2 to LdShed S3 and vice versa.

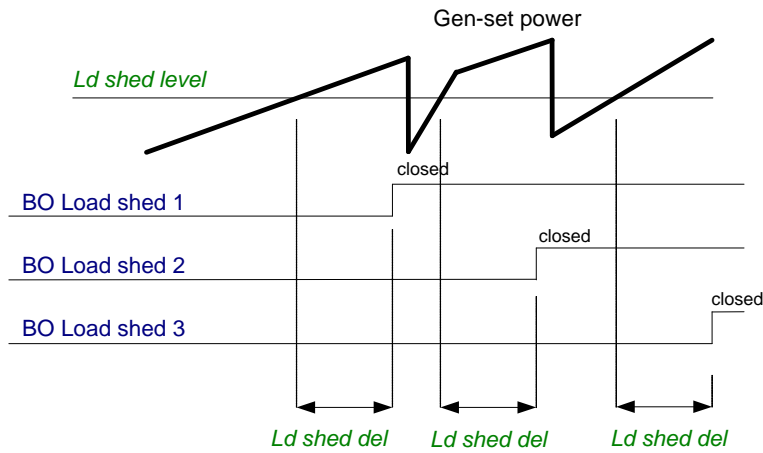
If manual reconnection of the load is desired, the AutoLd recon setpoint needs to be disabled (*AutoLd recon* = DISABLED) and the MAN load recon binary input needs to be configured.

Rising edge on this input resets the controller to a lower stage, but only if the load is under the *Ld recon level* at that moment.

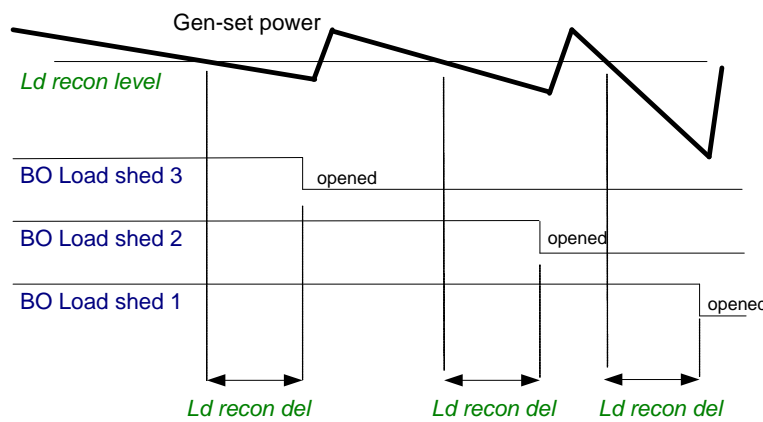


HINT

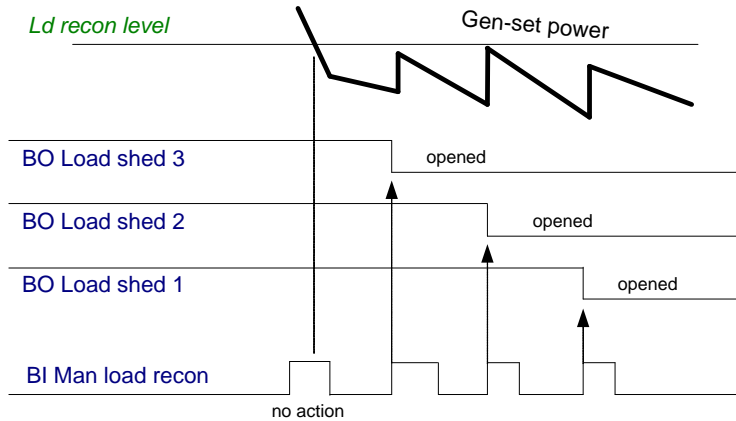
If no Load Shedding outputs are configured, there is no record to history and no screen timer indication of the activity of this function.



Load reconnection – automatic -> *AutoLd recon* = ENABLED



Load reconnection – manual -> *AutoLd recon* = DISABLED



Load shedding

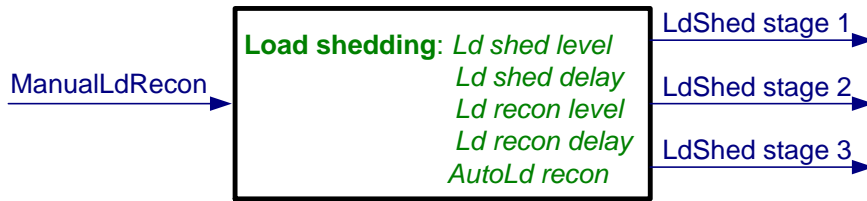
All LOAD SHED outputs are activated (closed) to trip the unessential load when gen-set goes to island:

- d) When GCB is closed after mains fail and gen-set starts in SEM / AUT mode.
- e) When MCB opens from parallel to mains operation in SEM / AUT mode.
- f) Before MCB is opened in MAN mode by button.

The load shedding function is active in all controller modes except OFF.

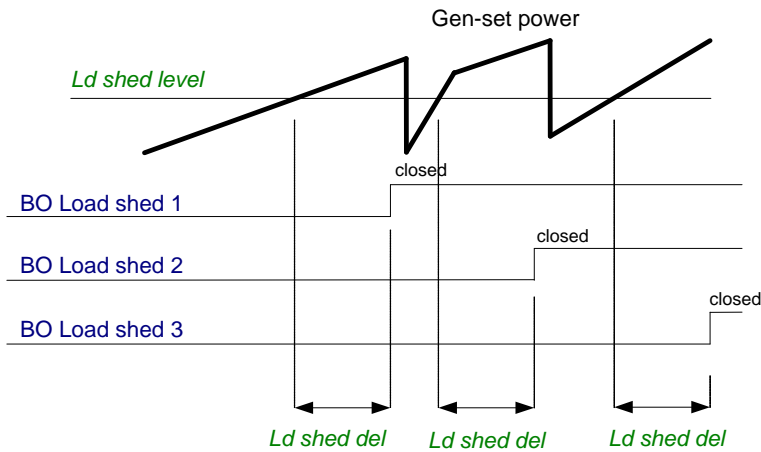
Load shedding has three steps and each step is linked with its own Load shed x binary output. There is only one load shed level and delay for all three steps as well as recon level and delay. Load shed can only move from one step to the next, e.g. No LoadShed to LdShed S1 to LdShed S2 to LdShed S3 and vice versa.

If manual reconnection of the load is desired, the *AutoLd recon* setpoint needs to be disabled (*AutoLd recon* = DISABLED) and the MAN load recon binary input needs to be configured. Rising edge on this input resets the controller to a lower stage, but only if the load is under the *Ld recon level* at that moment.

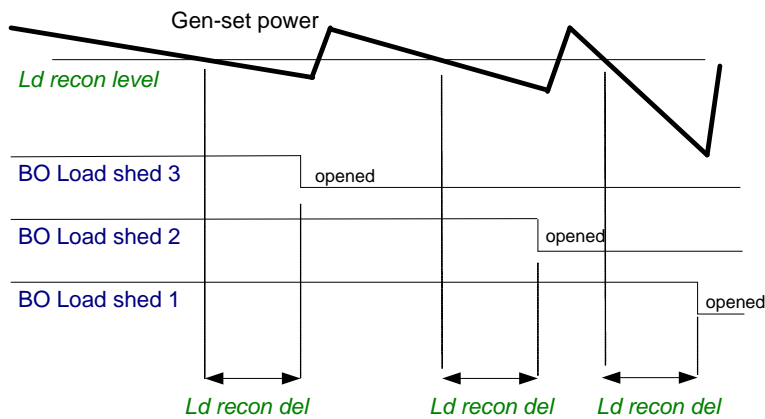


HINT

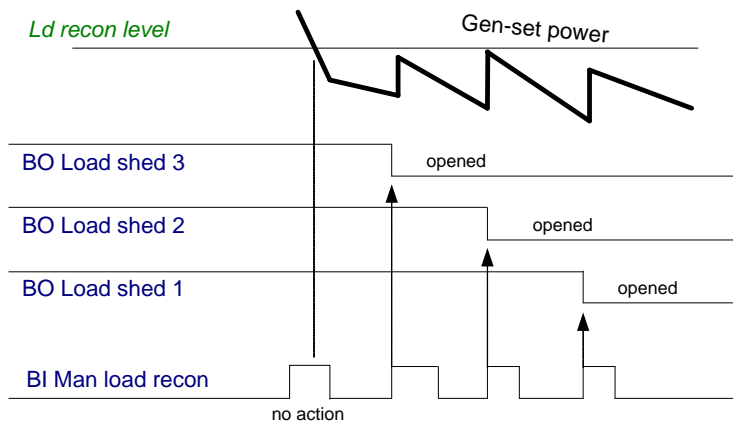
If no Load Shedding outputs are configured, there is no record to history and no screen timer indication of the activity of this function.



Load reconnection – automatic -> *AutoLd recon* = ENABLED



Load reconnection – manual -> *AutoLd recon* = DISABLED



Start up synchro (SUS) sequence description

Fast start of multiple gen-sets without standard synchronisation

Standard start sequence

Standard start sequence description: all gen-sets are started, first gen-set with voltage and frequency in limits is connected to common bus and other gen-sets are synchronised to bus. This can take several minutes according to type of gen-sets.

For some installation/application (data centers, hospitals) is necessary to have fast back up.

SUS - Start Up Synchro sequence

Start up synchro sequence description: all gen-sets are started with closed GCBs and without excitation (no voltage), when the required number of gen-set (according to their nominal power and condition #SUS min power) are in "RPM window with active LBO:ReadyToExcite, then all rest of gen-sets are disconnected (GCBs are opened) and gen-sets in "RPM window" with active LBO:ReadyToExcite are excited.

Because the gen-sets are rotating and they are connected together on the bus – and they are excited in the same moment – they are synchronized during voltage ramp.

We are strongly recommended to use exactly the same gen-sets for this application (the same engines, generators, AVRs....), - for elimination of currents floating between gen-sets (is necessary to have the same characteristic of starting RPM curves and voltage ramps).

Detailed description of process

For configuration of SUS sequence the setpoints from „SUS control“ group are used.

This function is available in MINT and COMBI application.

Setpoints

SUS sequence [ENABLED/DISABLED] - for activation/deactivation of SUS sequence

RPM window – it defines RPM window, where the gen-set can be excited.

RPM win TO – RPM window Time Out defines time for achieving RPM window and activation LBO:ReadyToExcite, if the gen-set doesn't activate LBO:ReadyToExcite in this time out, the GCB is opened and gen-set is started the standard way.

#ExcitationDel – delay is used in case that condition SUS min power is not met.

This delay is designed as time for waiting for gen-sets which are switched over to STANDARD start sequence. These gen-sets started STANDARD way should be in running state when the delay

#ExcitationDel is up. When the gen-sets (started SUS sequence) are excited – then the gen-sets (started STANDARD way) should immediately be synchronized to the bus.

#SUS min power - setpoint indicates the required power of gen-sets with activated LBO:ReadyToExcite. When the request/condition is met, gen-sets without active LBO:ReadyToExcite open their GCB and gen-sets with active LBO:ReadyToExcite are excited.

ExcitationCtrl – Excitation control settings [INTERNAL/EXTERNAL] – it is used for configuration of excitation control.

“**INTERNAL**” – controller activates/deactivates excitation based on setpoint #SUS min power

“**EXTERNAL**” – its determined for case, where request for excitation comes from external device (eg external PLC). External device gives request for excitation via LBI:SUS excit blk and controller activates/deactivates excitation based of LBI:SUS excit blk (its valid for SUS sequence only)

(Condition #SUS Min power is ignored, excitation is controlled via LBI:SUS excit blk.)

LBI:SUS excit blk must be activated before Start command come, if not – STANDARD start sequence is performed.

In case of using InteliMains^{NT} controller:

In IM-NT-MGCB application new setpoint is added:

MultiSoftStart [ENABLED/DISABLED]

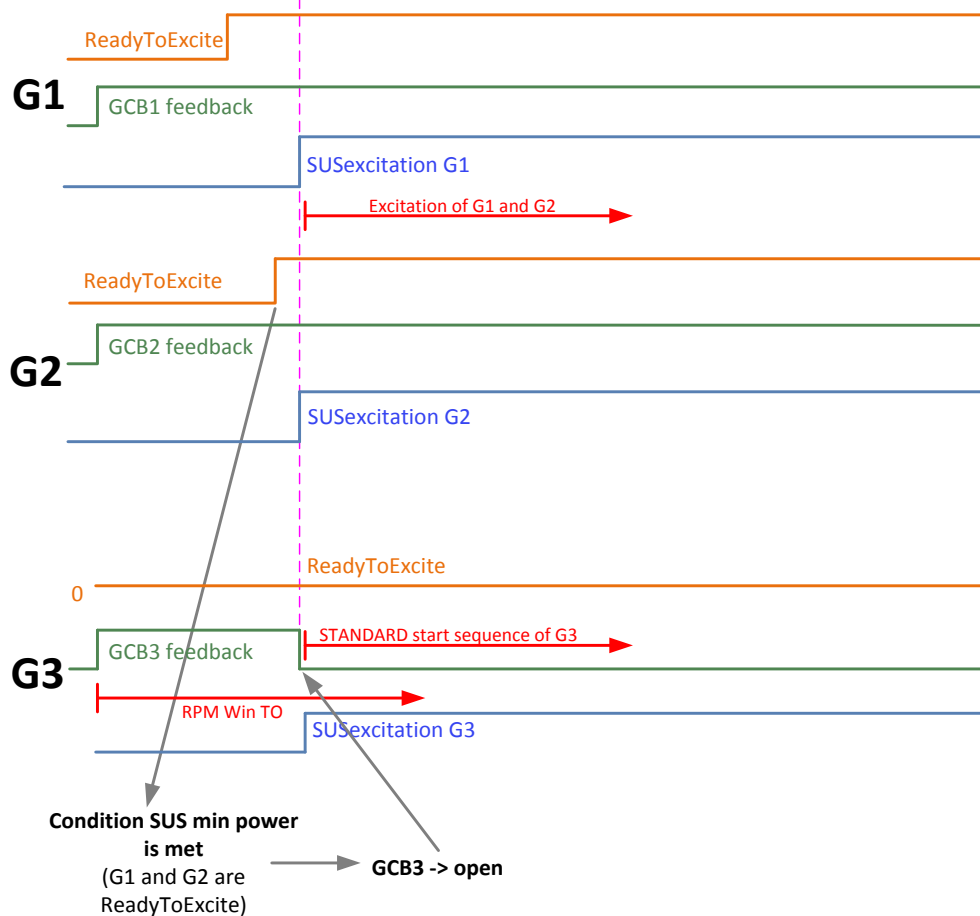
DISABLED – MGCB is closed standard way (when voltage and frequency on the bus are in limits)

ENABLED – MGCB is closed in the same time as GCBs (during SUS sequence)

It is determined for case, where is necessary to connect load before start of excitation (for example huge transformer).

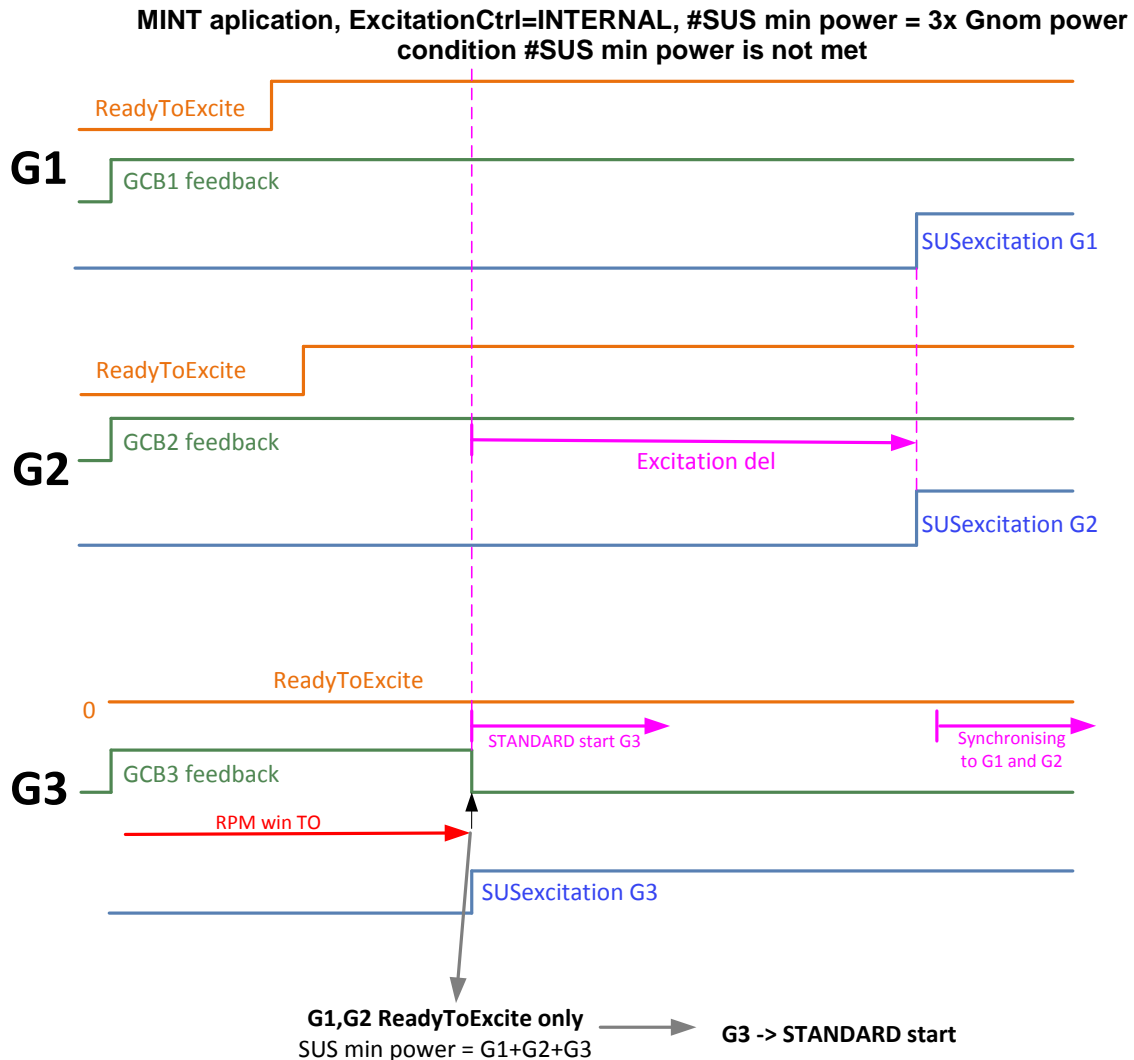
For more detail please read IM-NT-MGCB manual

MINT application, ExcitationCtrl=INTERNAL, #SUS min power = 2x Gnom power condition #SUS min power is met



The picture shows states of three gen-sets in SUS sequence.

First two gen-sets (G1 and G2) are in RPM window and with active LBO:ReadyToExcite – so the condition **#SUS min power** is met -> G3 opens the GCB3 and G1 and G2 are excited (LBO:SUS excitation is activated). (G3 opens the GCB, it is switched to STANDARD start and then will be synchronized to the bus standard way).

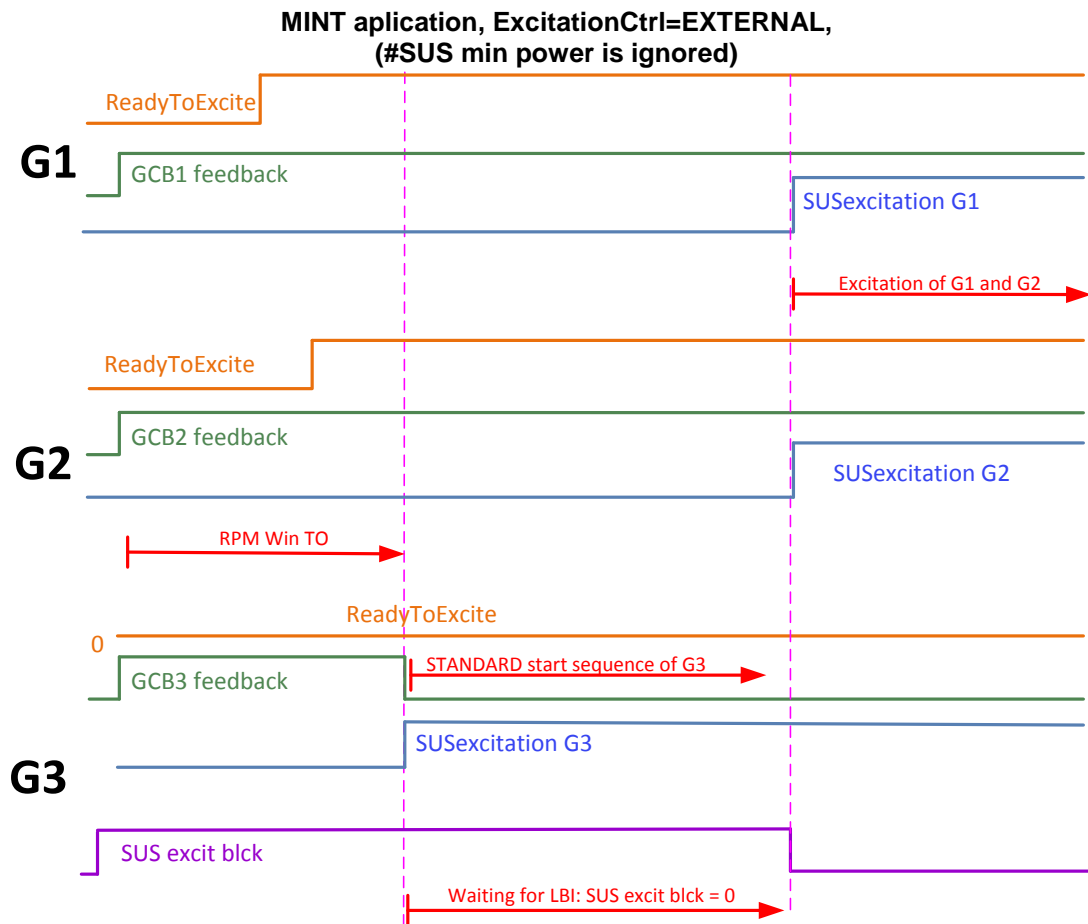


The picture shows states of three gen-sets in SUS sequence.

First two gen-sets (G1 and G2) are in RPM window and with active LBO:ReadyToExcite.

SUS min power is equal nominal power 3 gen-sets, but G3 doesn't activate LBO"ReadyToExcite in timer "RPM win TO" -> G3 opens the GCB3, it is switched over to standard start.

From opening the GCB3 is counted timer #ExcitationDel. When ExcitationDel is up, G1 and G2 are excited, then G3 can be synchronised to the bus by standard way.



In case of EXTERNAL control of excitation – all gen-sets start SUS sequence (based on the Load reserves). Gen-sets which activate LBO:ReadyToExcite in timer RPM win TO – stay non excite and wait for deactivation of LBI:SUS excit blk – then they are excited. Gen-sets which don't active LBO:ReadyToExcite in timer RPM win TO – are switched to STANDARD start and open their GCB – then they wait for voltage on the bus (excitation of group of gen-sets started SUS sequence) – after they are synchronized to the bus.

Conditions for performance of SUS sequence

- Setpoint "SUS Start (SUS control group) – ENABLED
- RPM pick-up is connected
- No voltage (voltage < 15V) on the bus
- MCB is opened
- LBI:GCB Disabled is not activated
- LBI: SUS excit blk – is activated before Start command (in case of configuration: setpoint ExcitationCtrl=EXTERNAL only (SUS control group)
- In case of enabled power management – the gen-sets are started based on actual Load reserves.
- GCB feedback must come during Prestart time (Engine params groups). If it doesn't come during Prestart time, then it is switched to STANDARD start sequence

Start of all gen-sets in combination with power management

In case of need fast start of all gen-sets (with different priority) by SUS sequence and power managements function – it is possible to achieve by activation of correct Load reserve (size of Load reserve responses Nominal power of all gen-sets).

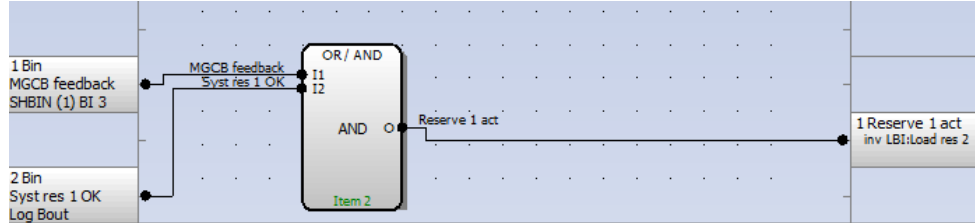
Solution:

Load reserve 2 is used for starting of all gen-sets. Load reserve 1 is default for standard running.

We need Load reserve 2 activates from start of all gen-sets until closing of MGCB.

After closing MGCB – Load reserve 1 is activated and some gen-sets are stopped based on this current reserve and priority.

Create in PLC



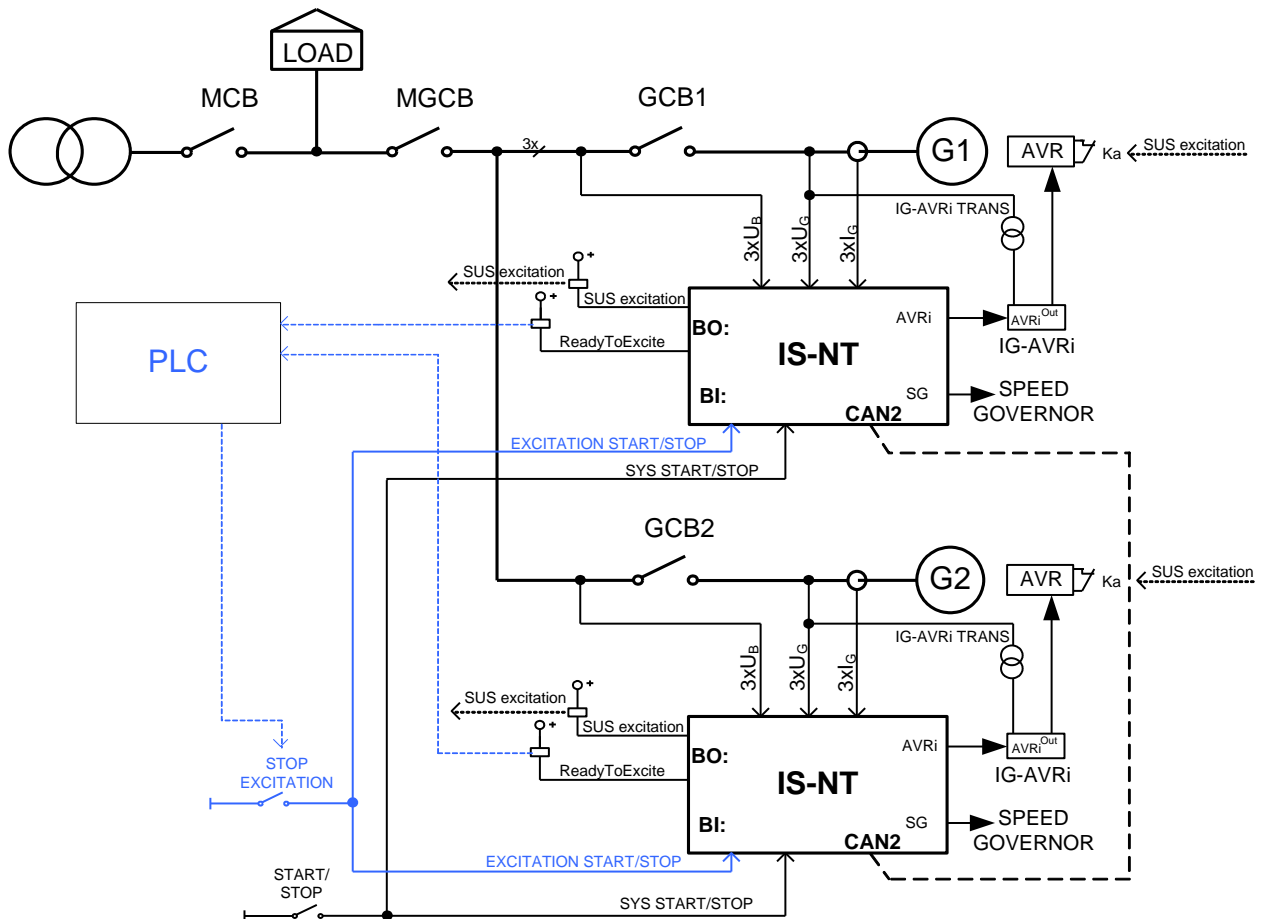
And in card LBI use for activation of Load Reserve 2 - signal from this PLC block above:



Load reserve 2 is activated until Load reserve 1 is OK and MGCB is closed – then system is switched over to Load reserve 1.

MGCB is closed when bus voltage and frequency are OK.

Recommended wiring for settings: StopExSource: EXTERNAL



HINT:

Blue wiring depicts solution for external control of excitation.

Engine states

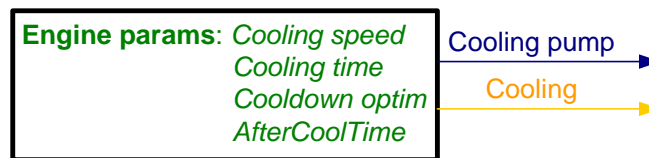
Engine prelubrication



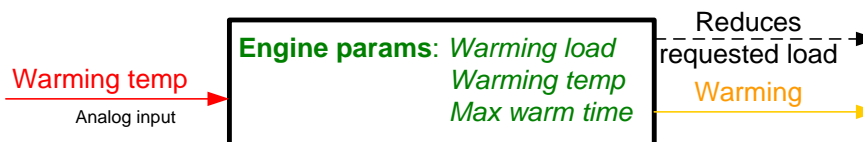
HINT

To use Prelubrication, configure Binary output PRELUBR PUMP first. Prelubrication is disabled in controller OFF mode or if *Prelubr time* is set to zero. Binary output PRELUBR PUMP is opened when engine is running. Prelubrication cycle starts with *PrelubrPause* after engine stop. Prelubrication cycle starts immediately when controller power supply is switched on or when mode changes from OFF to MAN or AUT or after Emergency stop was reset. An Alarmlist message “Not lubricated” is active until this first lubrication cycle has been completed.

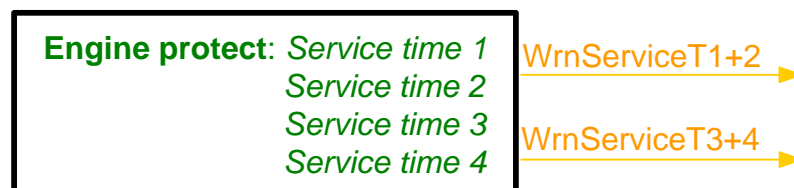
Engine cooling



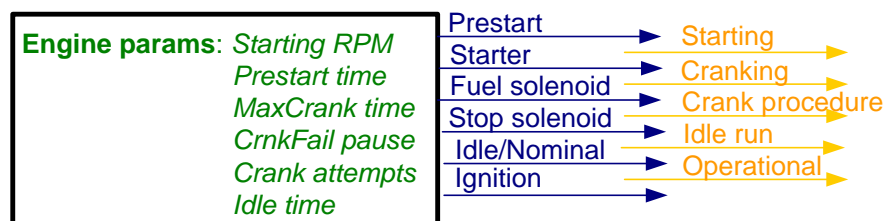
Engine warming



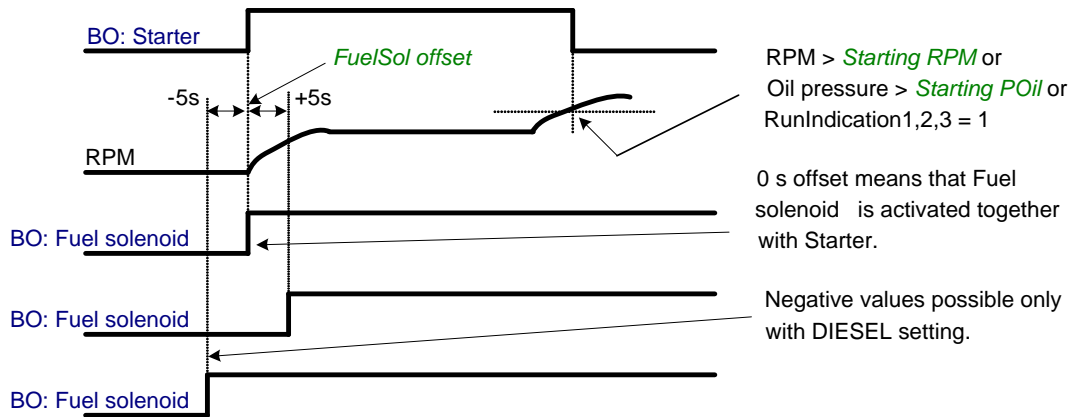
Service time alarm



Engine starting procedures



Engine starting procedure if **Engine params: Fuel solenoid = DIESEL ENGINE** with different setting of *FuelSol offset*.

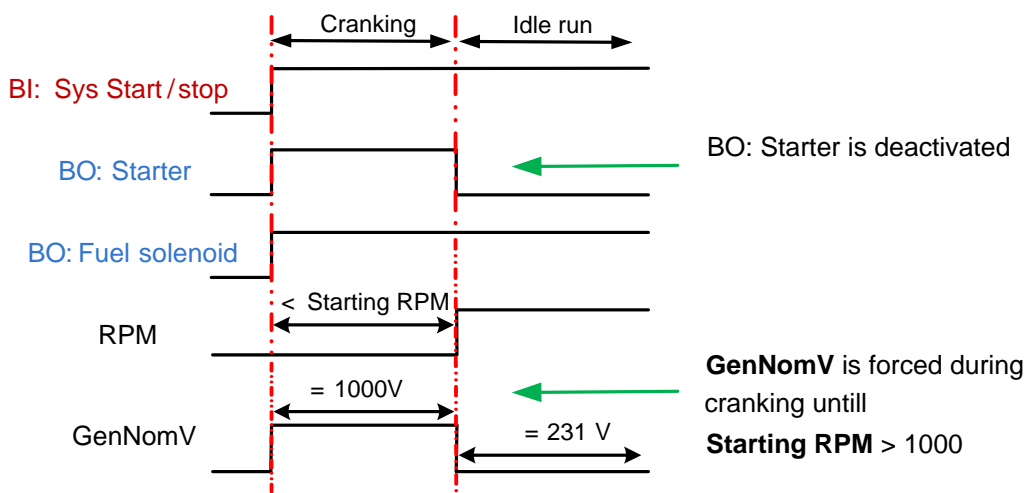


Engine starting procedure if **Engine params: Fuel solenoid = GAS ENGINE**



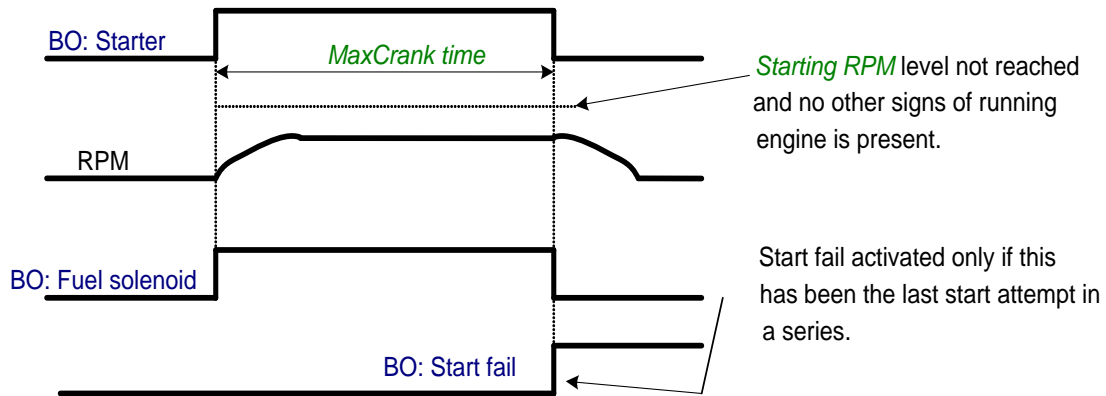
Engine starting procedure with **own starting procedure:**

Engine is started after **Starting RPM** reach starting level or other [condition](#). BO: Starter is deactivated only if one of those condition is fulfilled.

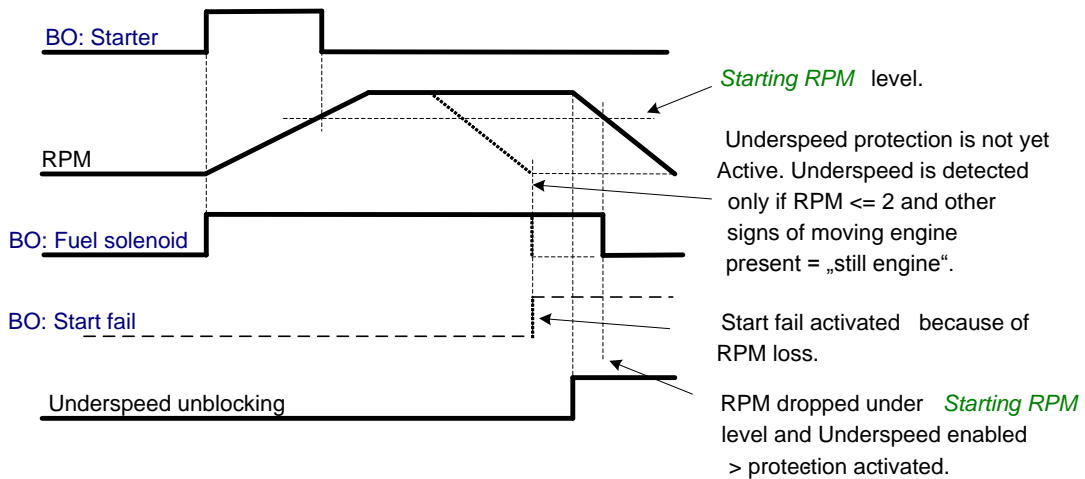


Generator nominal voltage is 231V but during *Cranking* is forced to 1000V until engine in *Idle state* (at least one of condition has to be fulfilled).

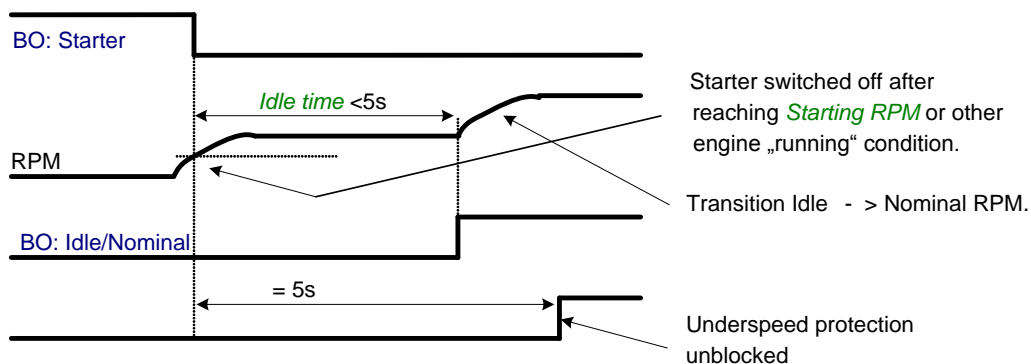
Unsuccessful start – no **Engine params**: *Starting RPM* reached



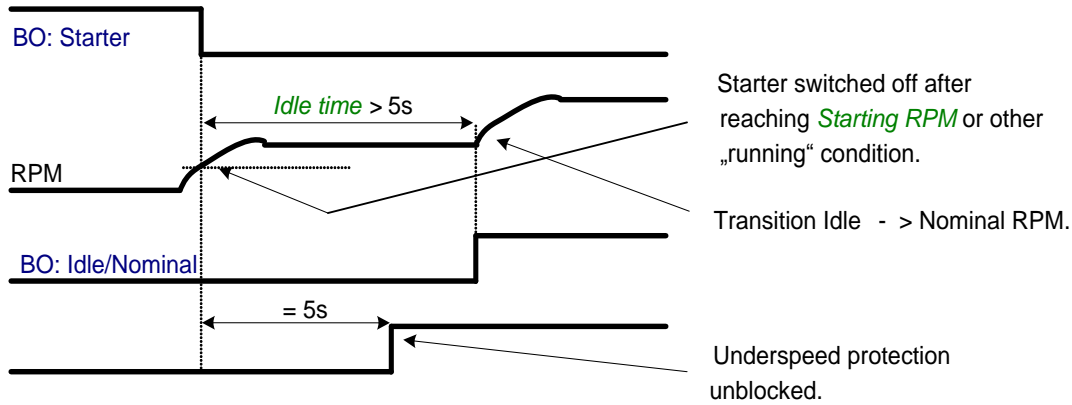
Unsuccessful start – RPM disappeared before/after Underspeed protection got active:



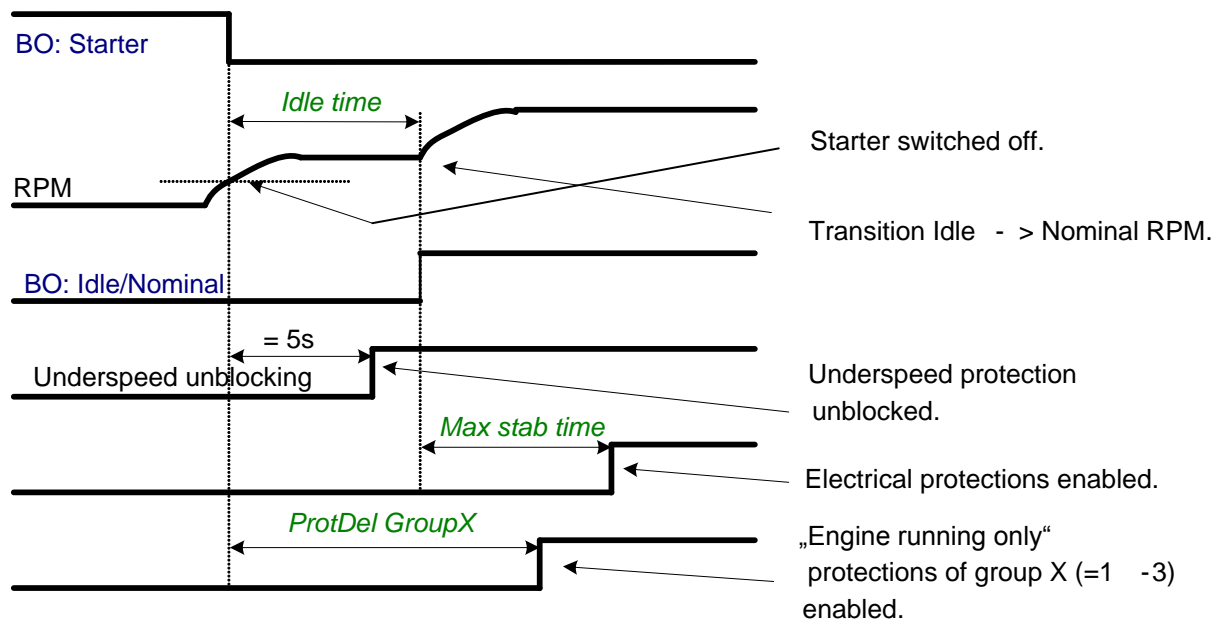
Underspeed protection unblocking if *Idle time* < 5s:



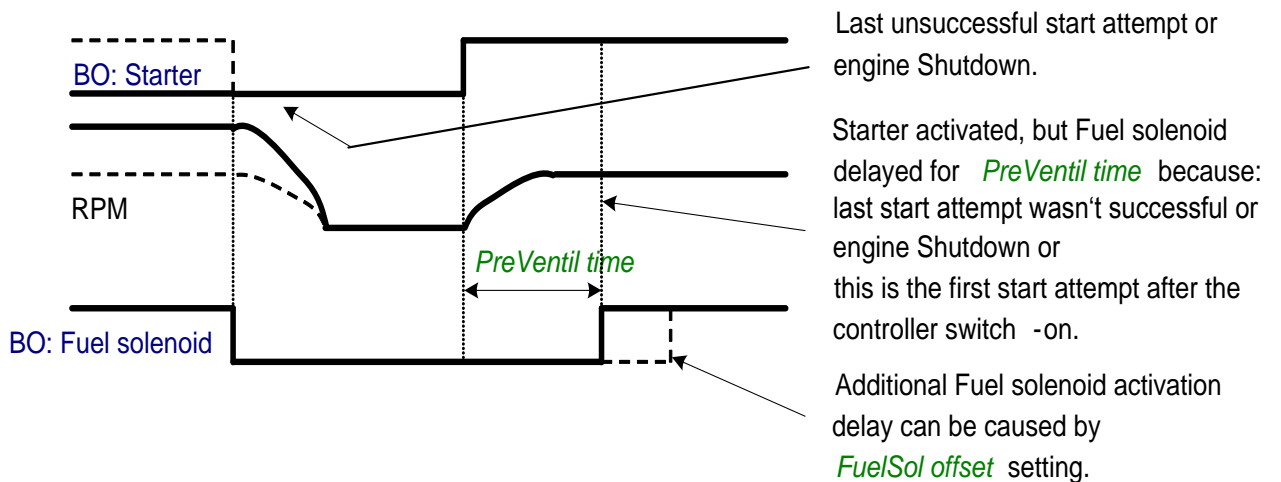
Underspeed protection unblocking if *Idle time* > 5s:



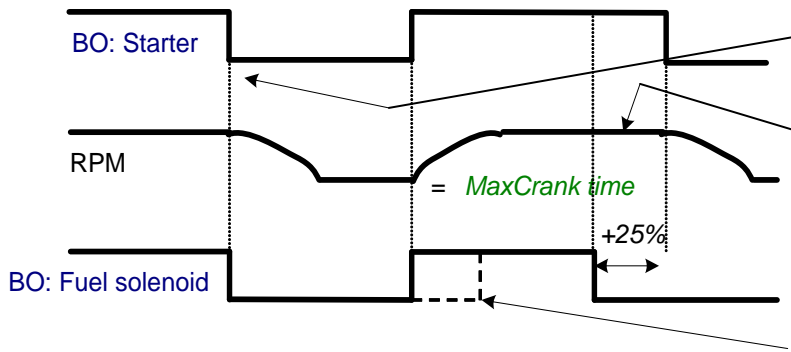
Transition Idle -> Nominal RPM, protections unblocking:



Preventilation (if *Fuel solenoid* = GAS):



Ventilation (if *Fuel solenoid* = GAS ENGINE):



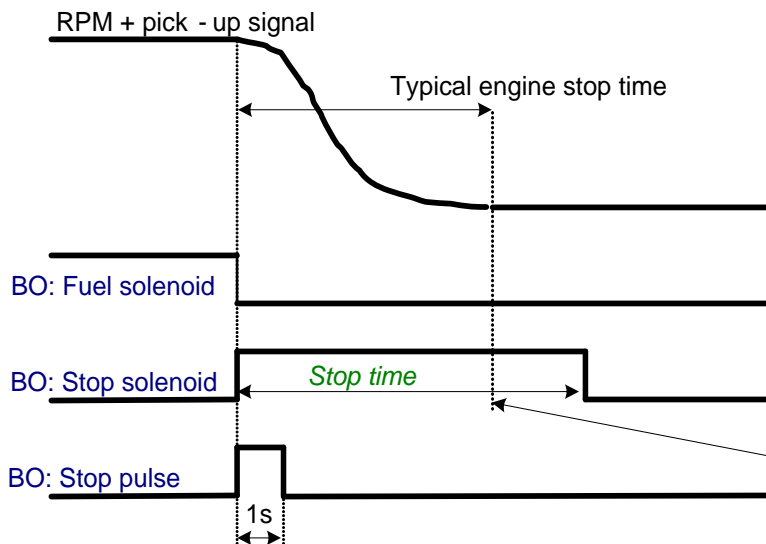
(*CrankAttempts* - 1) the attempt

The last crank attempt is extended by 25% of *MaxCrank* time, with Fuel solenoid closed, to ventilate the gas from the engine.

Fuel solenoid activation delay can be set using *FuelSol offset*

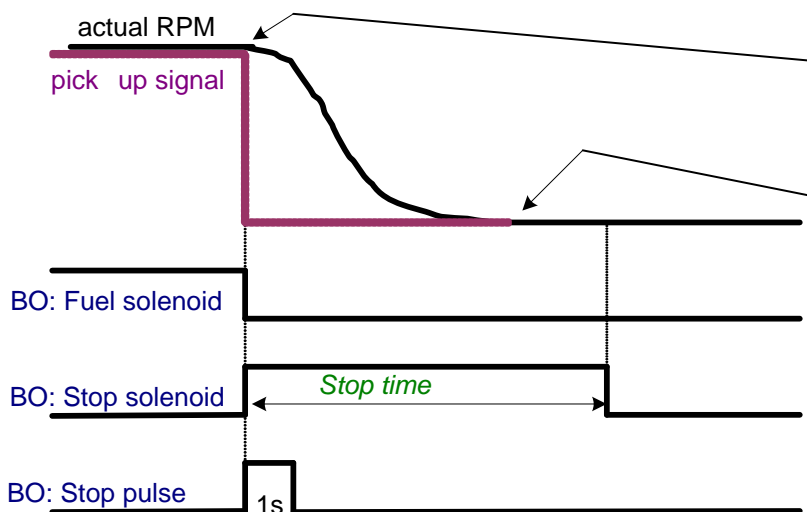
Engine stopping procedures

Normal engine stop:



Correct setting – *Stop time* setpoint is set to longer time than typical engine stop time.

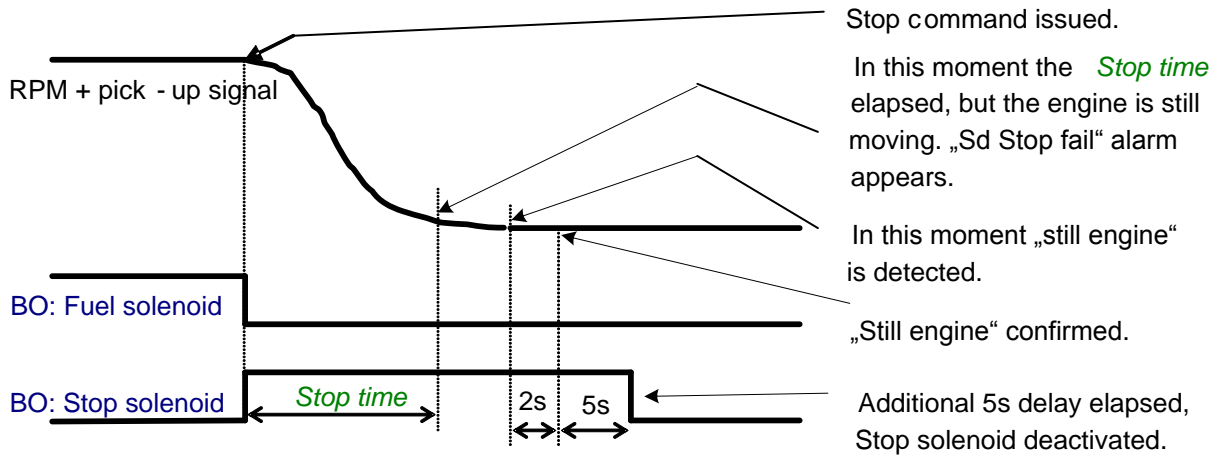
Pick-up sensor fault – forced engine stop:



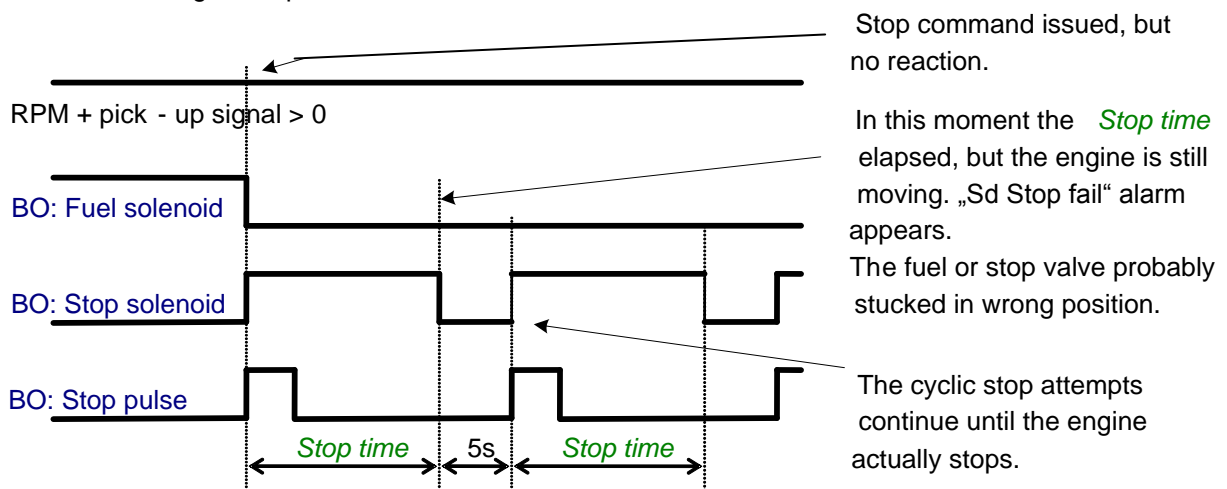
Moment of the pick up sensor fault – measured RPM=0.

In this moment „still engine“ is detected. If pick-up sensor failed, there may be other signals determining if engine is still moving or not.

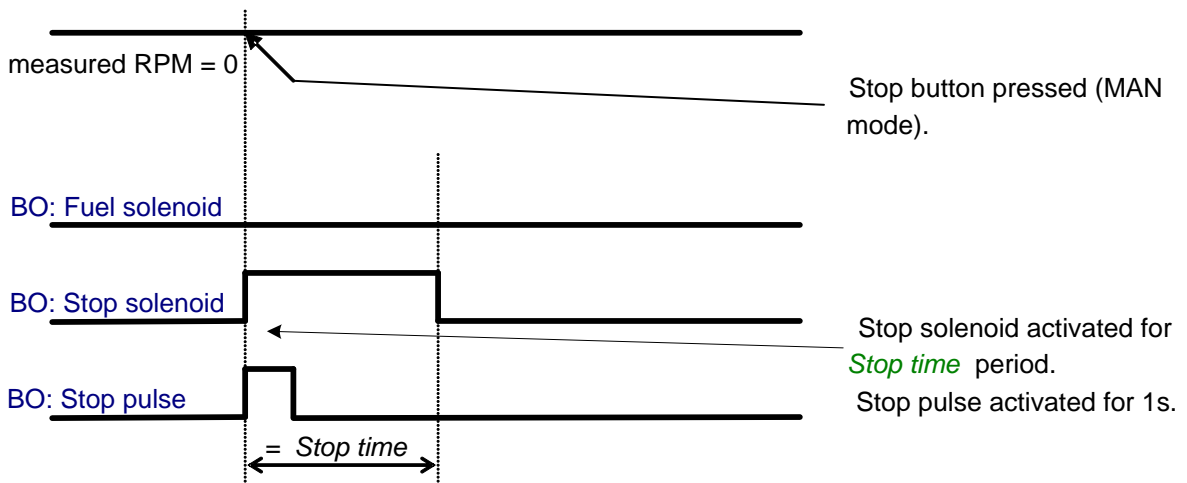
Normal engine stop, but *Stop time* is set too short:



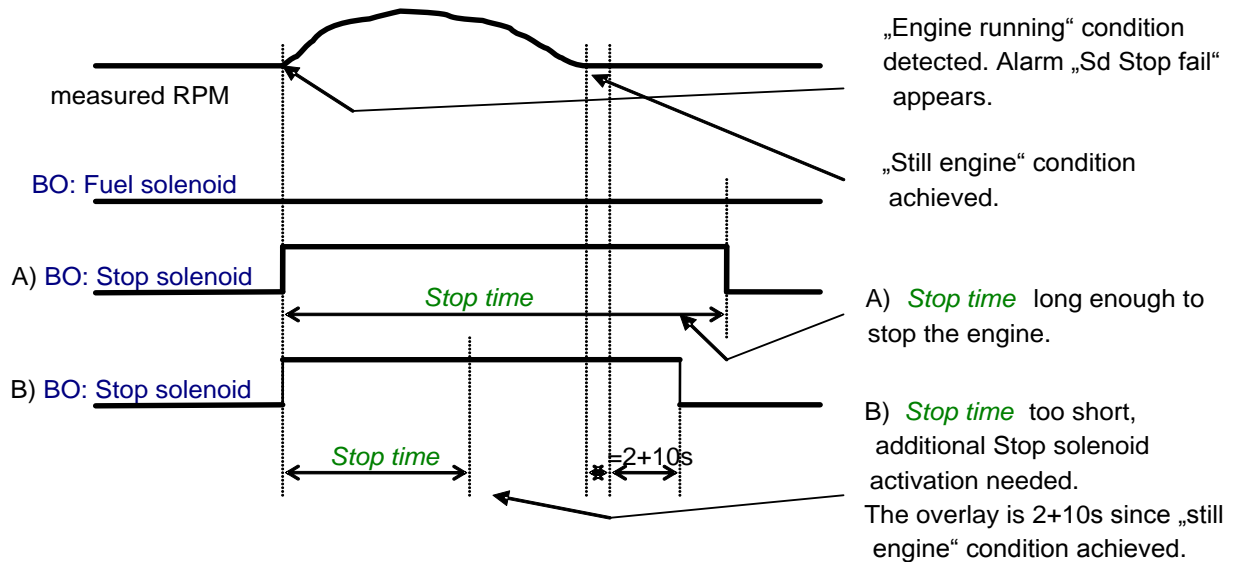
Unsuccessful engine stop:



“Forced” stop in still state:

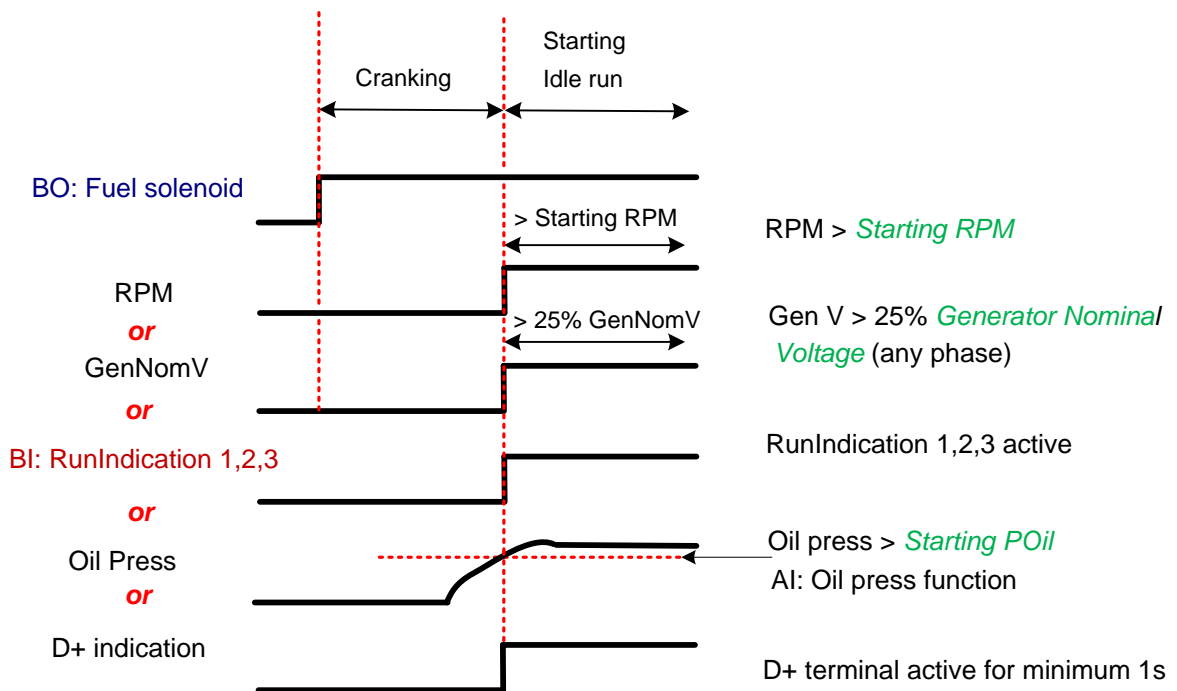


Spontaneous engine start-up:



“Engine started” conditions

- Engine speed (RPM) > *Starting RPM* or
- AI: Oil press > *Starting POil* or
- D+ terminal active for minimum 1s or
- BI: RunIndication 1 or 2 or 3 = active or
- Generator voltage > 25% of *GenNomV* (any phase)
-



“Engine running” conditions

- RPM > **Engine params:** *Starting RPM* or
- Analog input Oil pressure > **Engine params:** *Starting POil* or
- D+ terminal active and **Engine params:** *D+ function* = ENABLED or
- Active Binary input RunIndication1 or

- Active Binary input RunIndication2 or
- Active Binary input RunIndication3 or
- Vgen > 15 V (any phase).

“Still engine” conditions

- Engine speed (RPM) = 0 and
- AI: Oil press < *Starting POil* and
- D+ terminal not active and
- BI: RunIndication 1 and 2 and 3 = not active and
- Generator voltage < 15V (all phases) and
- Generator frequency = 0 Hz and
- if all above conditions are fulfilled, additional 2s delay is necessary to confirm “still engine”

NOTE:

If any of the functions not used (e.g. BI RunIndication3 not configured), it's state is omitted in the evaluation. This is not valid for RPM comparisons, this condition is always active.

Circuit breakers operation sequence, GCB/MCB fail detection

NOTE:

In the following text, “CB” abbreviation is used for MCB or GCB respectively.

Related binary inputs:

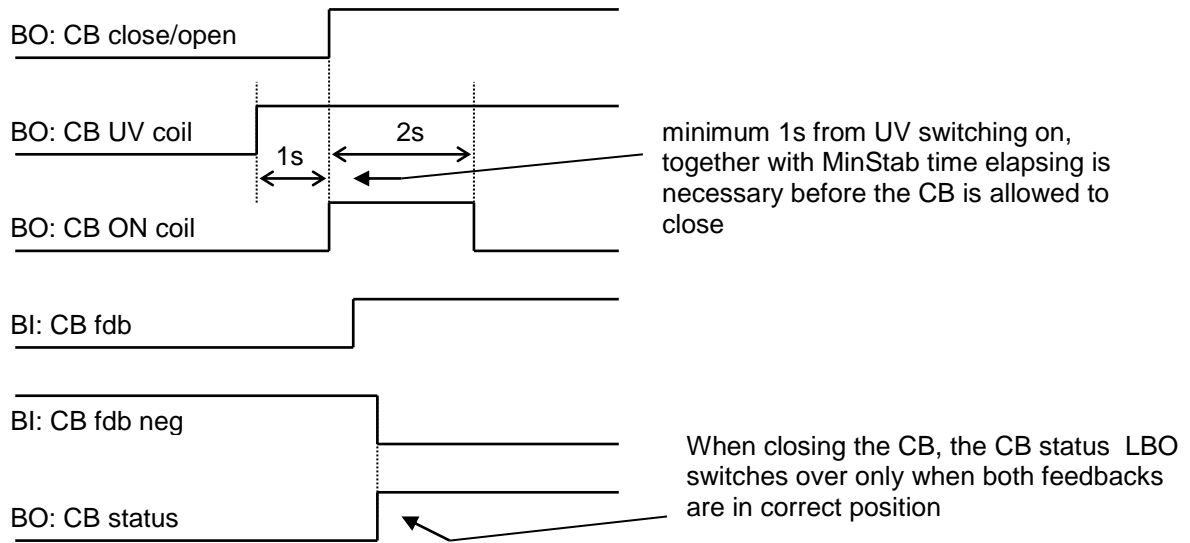
- CB fdb – CB feedback binary input
- CB fdb neg – negative CB feedback binary input. Used for increasing the reliability of CB status evaluated by the controller. In case that it is not configured, negative value of CB fdb is calculated internally within the controller.

Related binary outputs:

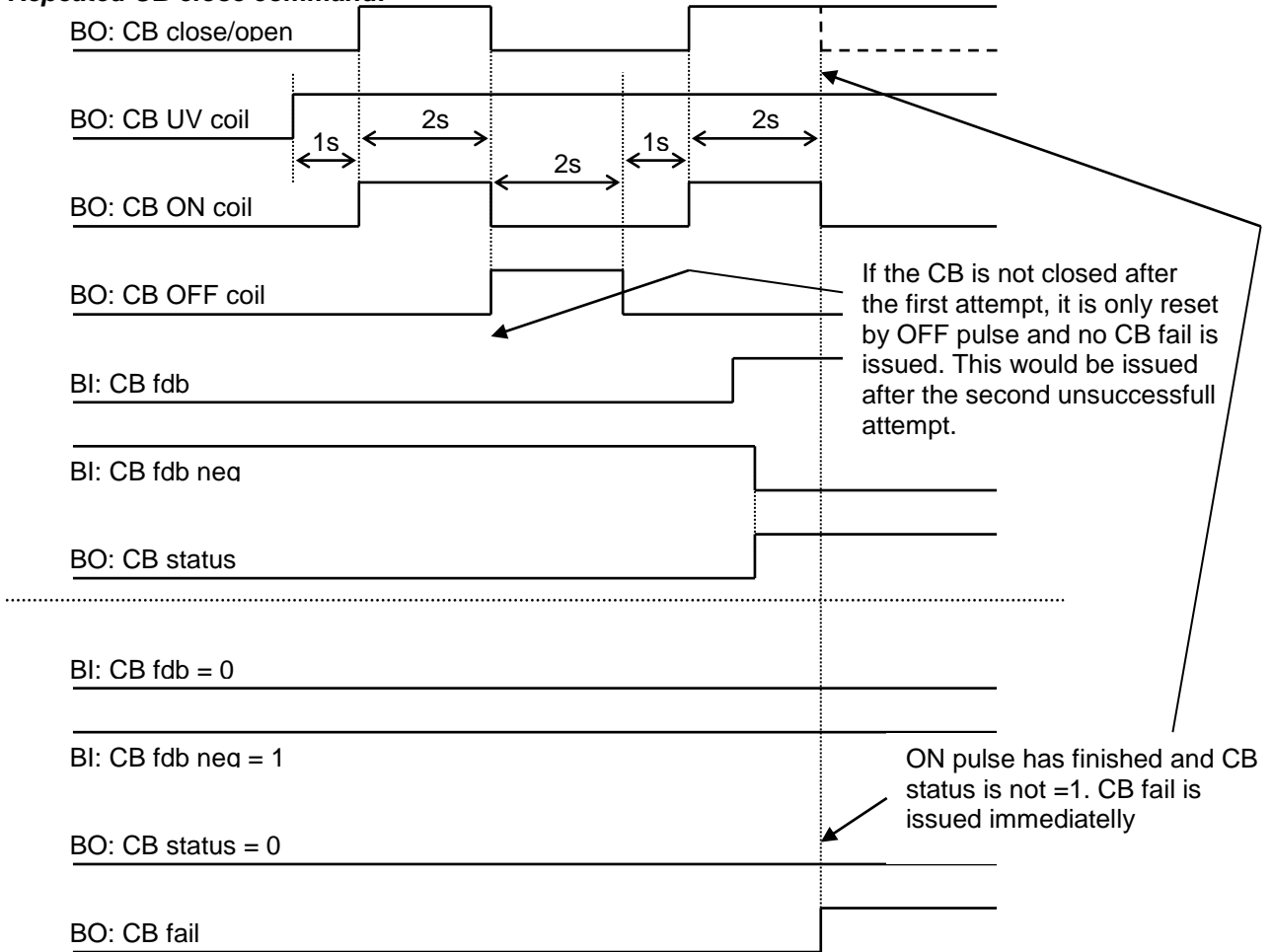
- CB close/open – output for circuit breaker. Equals to 1 during the time when CB is requested to be closed.
- CB ON coil – output for closing coil of the CB. 2s pulse (5s if synchronising is not provided by the particular CB) is used for closing the CB.
- CB OFF coil – output for opening coil of the CB. 2s pulse (5s if synchronising is not provided by the particular CB) is used for opening the CB.
- CB UV coil – output for undervoltage coil of the CB. Permanently active, 2s negative pulse (5s if synchronising is not provided by the particular CB) is used for CB opening request
- CB status – output indicating CB status as evaluated by the controller. This signal is used for lighting LEDs on the panel, switching the regulations, CB fail evaluation, etc.

Possible CB sequences:

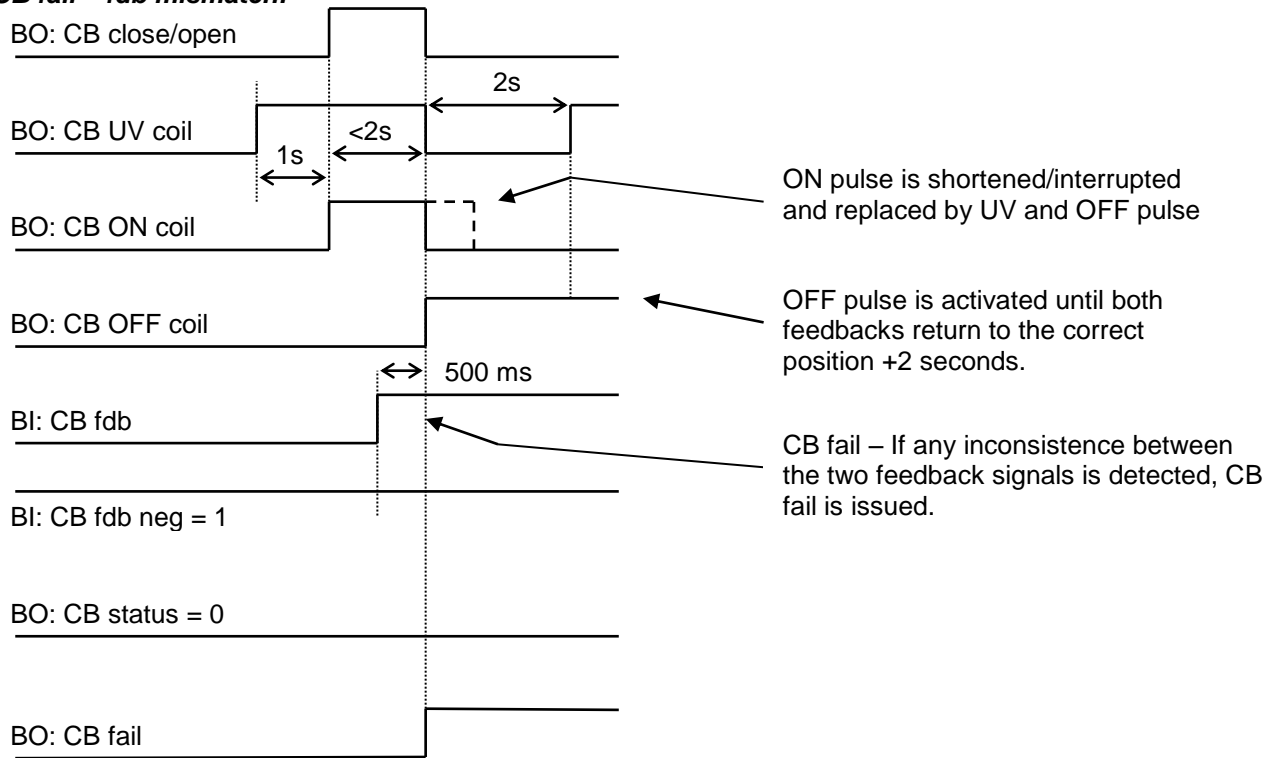
CB close command:



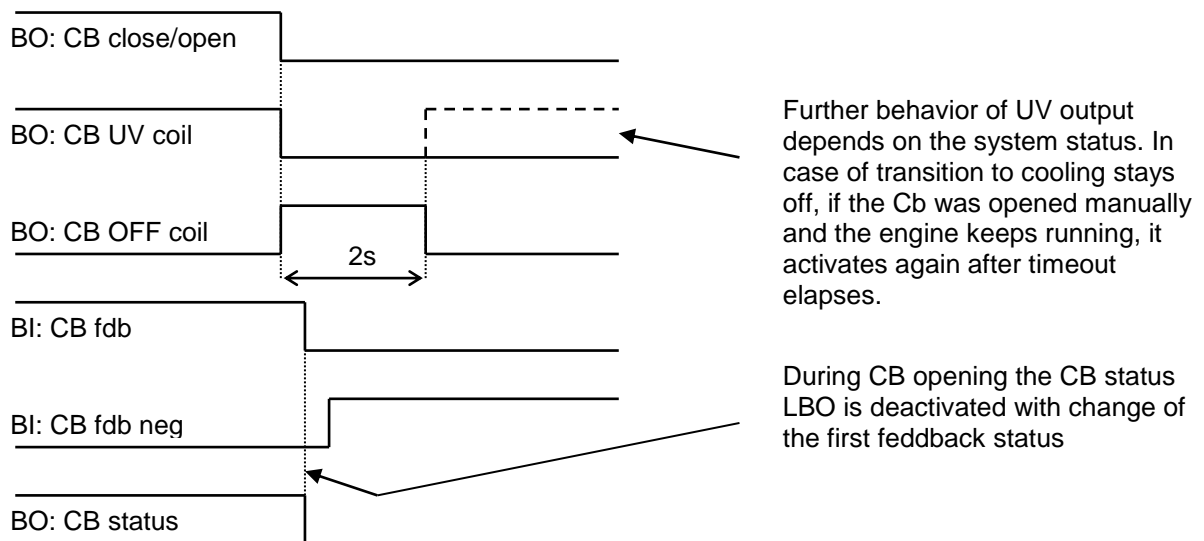
Repeated CB close command:



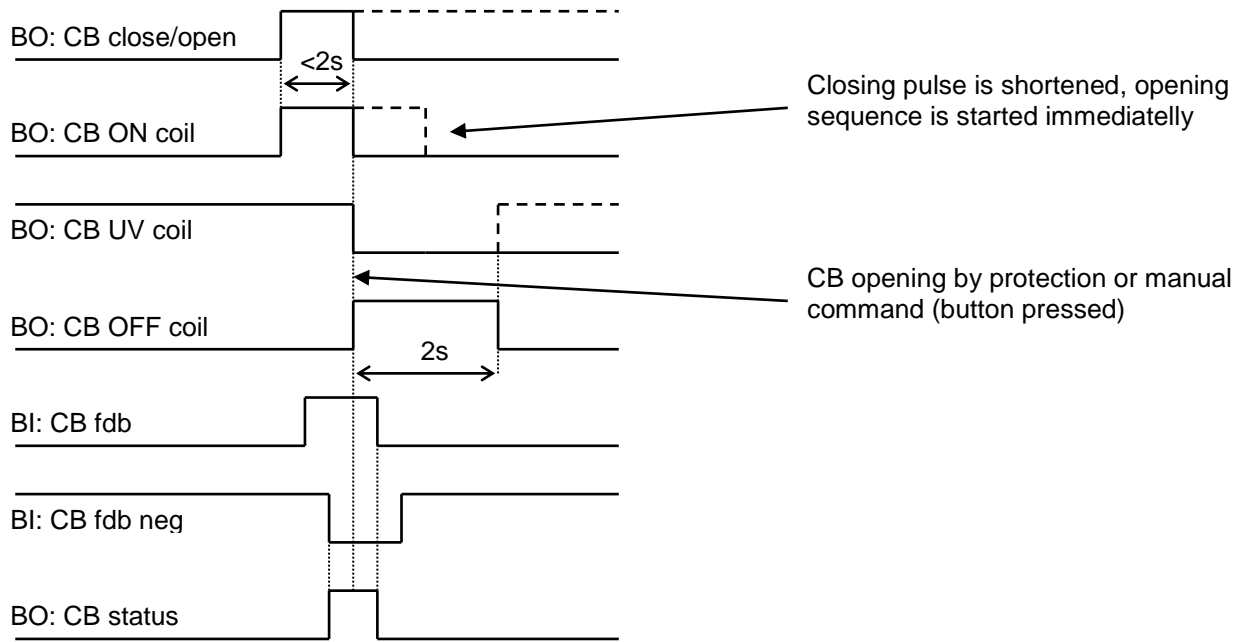
CB fail – fdb mismatch:



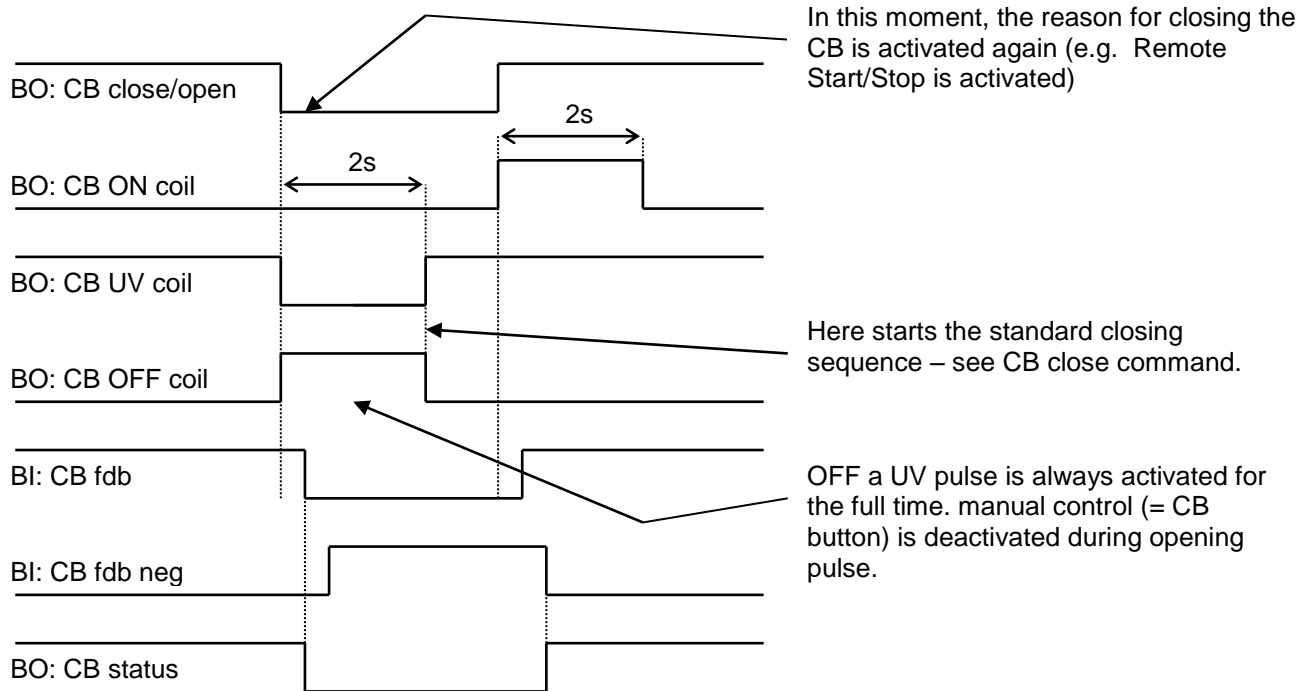
CB open command:



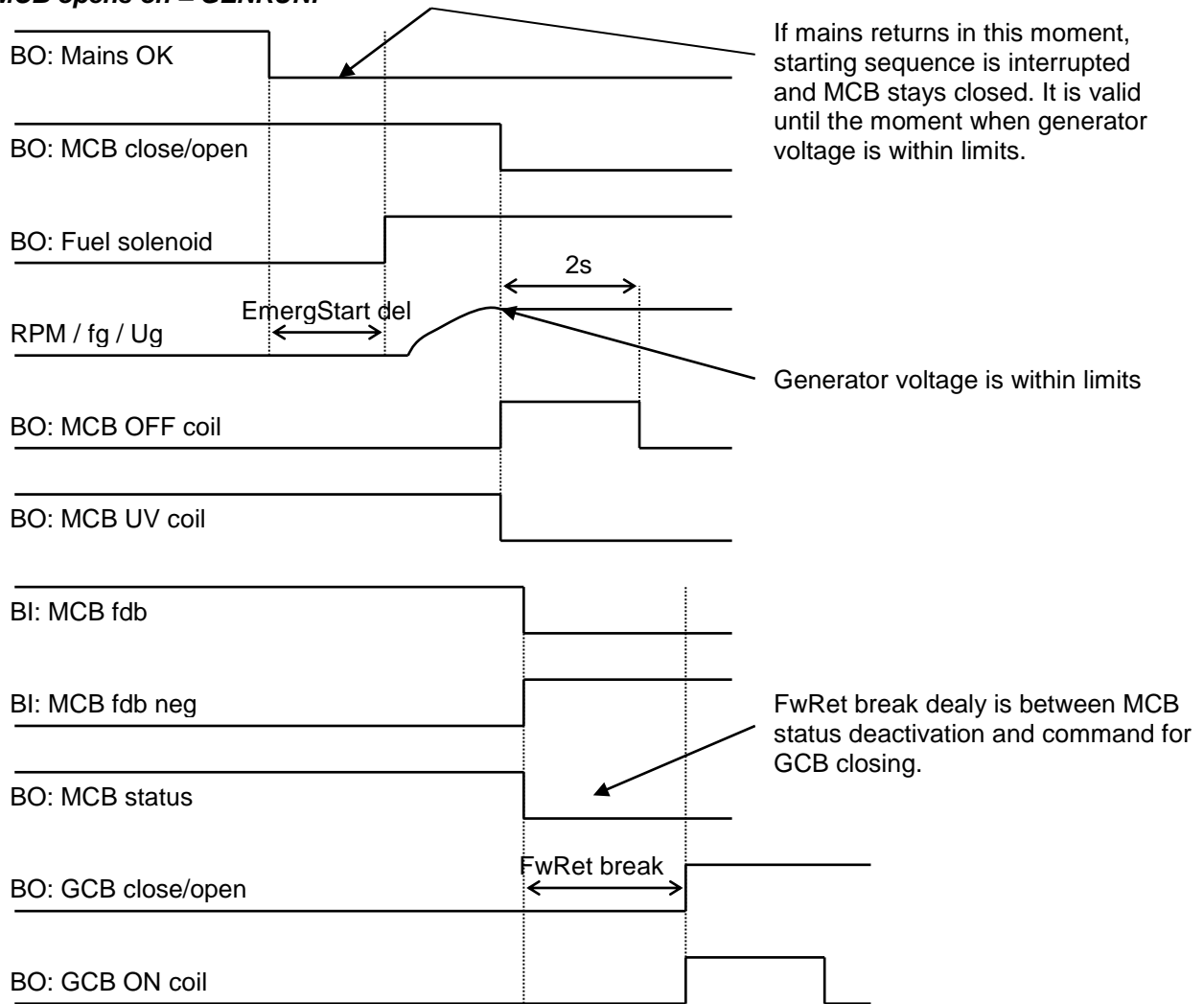
Transition closing -> opening (opening command is issued during closing pulse):



Transition opening -> closing (closing command is issued during opening pulse)

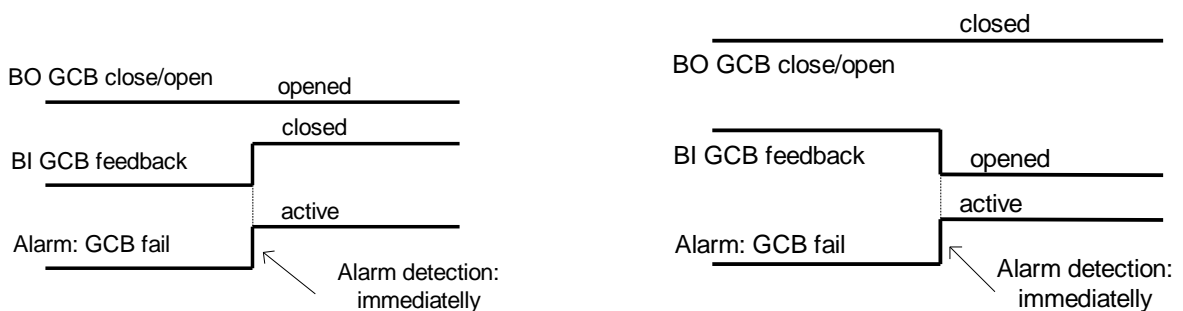


MCB opens on = GENRUN:



Other CB fail reasons:

- When the BO CB close/open is in steady state and CB feedback is changed, the CB fail is detected immediatelly (no delay).

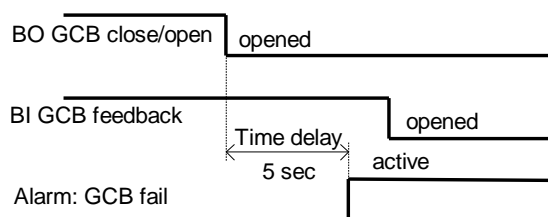


Not valid for MCB:
 MCB fail is not detected in this case.
 If BI Ext MF relay is active, controller switches to Island operation. If BI Ext MF relay is not active and Mains is OK, controller synchronizes back to the mains and tries to close MCB.

- When the BO CB close/open opens, there is 5 resp. 2 sec delay for the breaker to respond before a CB fail is detected. In such case, if CB OFF coil is used for opening the CB and CB fail occurs during

opening the CB, the signal CB OFF coil is automatically extended until the breaker opening is detected (evaluated as CB status).

- 2 sec when the CB is used for synchronizing
- 5 sec in other cases



- In case that CB fail is detected after switching the controller on (CB is closed), the CB OFF coil output is activated immediately.

Remote Alarm Messaging

It is possible to use up to five channels for Active Call, Email and SMS upon defined type of Alarm. It is possible to define protection type for all ENABLED channels to react. All the possibilities in the controller are: History record, Alarm only, Warning, Mains protect and Mains protect with Reset. Find more information about alarm types in the chapter Protections and alarm management.

Communication Types for Remote Alarm Messaging

Below there all types of communication available for each Active Call channel.

DATA-ANA: This option sends a complete archive to the recipient's PC via analog modem. An analog modem must be connected either to one of controller COM ports or to one of I-LB modules connected to the controller via CAN2 bus. The channel address must contain complete telephone number of the recipient's PC where IntelliMonitor is running in Active call receiving mode.

DATA-GSM: This option sends a complete archive to the recipient's PC via GSM modem. A GSM modem with activated CSD data transfers must be connected either to one of controller COM ports or to one of I-LB modules connected to the controller via CAN2 bus. The channel address must contain complete telephone number of the recipient's PC where IntelliMonitor is running in Active call receiving mode.

DATA-ISDN: This option sends a complete archive to the recipient's PC via ISDN modem. An ISDN modem must be connected either to one of controller COM ports or to one of I-LB modules connected to the controller via CAN2 bus. The channel address must contain complete telephone number of the recipient's PC where IntelliMonitor is running in Active call receiving mode.

DATA-CDMA: This option sends a complete archive to the recipient's PC via CDMA modem. A CDMA modem must be connected either to one of controller COM ports or to one of I-LB modules connected to the controller via CAN2 bus. The local CDMA network must allow point-to-point data transfers. The channel address must contain complete telephone number of the recipient's PC where IntelliMonitor is running in Active call receiving mode.

SMS-GSM: This option sends a short text message (SMS) containing the actual Alarmlist contents to the recipient's mobile phone via the GSM modem. The channel address must contain complete telephone number of the recipient's mobile phone.

SMS-CDMA: This option sends a short text message (SMS) containing the actual Alarmlist contents to the recipient's mobile phone via the CDMA modem. The channel address must contain complete telephone number of the recipient's mobile phone.

IB-E-MAIL: This option sends an e-mail containing the actual Alarmlist contents and latest 20 history records (only date, time, reason) to the recipient's mailbox via the IB-COM module or IG-IB module. The channel address must contain valid e-mail address of the recipient.

NOTE:

The SMTP settings (SMTP authent, SMTP user name, SMTP password, SMTP address, Contr mailbox) must be properly adjusted for sending e-mails.

Example of setting

There is an example of setting of Remote Alarm Messaging. In this case active calls we be triggered on Mains protect and Mains protect with Reset alarms. Message is sent via email to emailAddress@domain.com (Channel 1 – available for NTC controller or with any controller with connected IB-NT or I-LB+), archive is sent via ISDN modem to the number +111222333444 (Channel 2) and SMS is sent to the number +999111333555 (Channel 3).

Name	Access Group	Value
History record	0 ON 1 OFF 2 OFF 3 OFF 4 OFF 5 OFF 6 OFF 7 OFF	DISABLED ▾
Alarm only	0 ON 1 OFF 2 OFF 3 OFF 4 OFF 5 OFF 6 OFF 7 OFF	DISABLED ▾
Warning	0 ON 1 OFF 2 OFF 3 OFF 4 OFF 5 OFF 6 OFF 7 OFF	DISABLED ▾
Mains protect	0 ON 1 OFF 2 OFF 3 OFF 4 OFF 5 OFF 6 OFF 7 OFF	ENABLED ▾
MainsP w/Reset	0 ON 1 OFF 2 OFF 3 OFF 4 OFF 5 OFF 6 OFF 7 OFF	ENABLED ▾
AcallCH1-Type	0 ON 1 OFF 2 OFF 3 OFF 4 OFF 5 OFF 6 OFF 7 OFF	IB-E-MAIL ▾
AcallCH1-Addr	0 ON 1 OFF 2 OFF 3 OFF 4 OFF 5 OFF 6 OFF 7 OFF	emailAddress@domain.com
AcallCH2-Type	0 ON 1 OFF 2 OFF 3 OFF 4 OFF 5 OFF 6 OFF 7 OFF	DATA-ISDN ▾
AcallCH2-Addr	0 ON 1 OFF 2 OFF 3 OFF 4 OFF 5 OFF 6 OFF 7 OFF	+111222333444
AcallCH3-Type	0 ON 1 OFF 2 OFF 3 OFF 4 OFF 5 OFF 6 OFF 7 OFF	SMS-GSM ▾
AcallCH3-Addr	0 ON 1 OFF 2 OFF 3 OFF 4 OFF 5 OFF 6 OFF 7 OFF	+999111333555
NumberRings AA	0 ON 1 OFF 2 OFF 3 OFF 4 OFF 5 OFF 6 OFF 7 OFF	3
ActCallAttempt	0 ON 1 OFF 2 OFF 3 OFF 4 OFF 5 OFF 6 OFF 7 OFF	5
Acall+SMS lang	0 ON 1 OFF 2 OFF 3 OFF 4 OFF 5 OFF 6 OFF 7 OFF	1

It is also possible to adjust number of attempts that controller performs in case of not successful Active Call – **Comms settings:ActCallAttempt**. The language of messages can be changed – **Comms settings:Acall+SMS lang** (use Translator and Languages tabs in GenConfig to adjust languages). Up to five channels can be used.

Controller Redundancy

Redundant system is a general term for applications where there are two controllers at each gen-set. One is the main controller, which controls the gen-set in normal conditions, the other is the redundant controller, which takes over the control when the main controller fails. Both controllers have identical firmware and most of the configuration and setpoints. Only several things need to be adjusted/configured differently because of the redundancy function itself.

CAUTION!

If there are shared binary or analog outputs used on the controller (e.g. for system start/stop), it is necessary to prepare the configuration in the way so each controller uses binary or analog output set with different address. Configuration in gen-set controllers then needs to be altered so it can receive signals from both controllers (e.g. using built-in PLC functions).

Redundant systems using binary signals

It is not possible to use this redundancy system since correct function of the controller depends on CAN bus communication and thus CAN redundancy should be always used.

Redundant systems using CAN bus

This system uses the CAN bus for detection whether the main controller is operational or not. If the redundant controller has not received two consequent messages from the main one (~100ms) it will take over the system control - it activates the binary output CTRLHBEAT FD, which has to be wired in such a way, that it disconnects the dead main controller from the control, connects the redundancy controller instead and activates it by deactivation of the binary input EMERG. MANUAL.

As there can be up to 16 pairs of controllers at the CAN bus it is necessary to select which main controller (address) belongs to which redundant one. The setpoint **ProcessControl: Watched Contr** is used for this purpose. It must be adjusted to address of the respective main controller in each redundant controller and it must be adjusted to 0 in each main controller.

CAUTION!

Correct wiring of all inputs and outputs that should be used both by the main and the redundant controller needs to be done. Please refer to the corresponding chapter for wiring of binary inputs and outputs.

Do not use Shared Binary Inputs/Outputs for CTRLHEAT FD -> EMERG.MANUAL connection since the failed controller may not interpret it correctly!

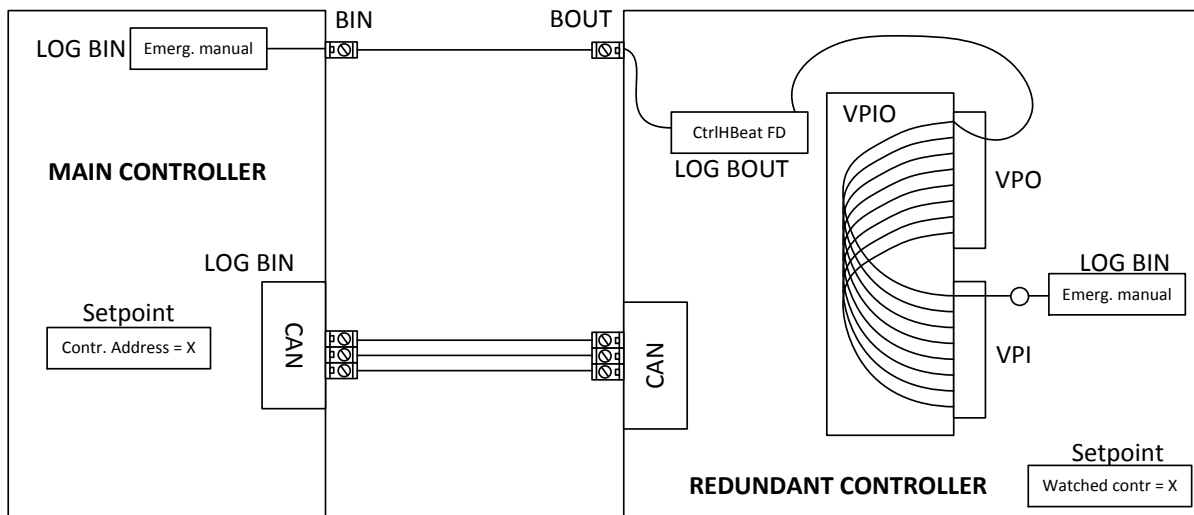


Figure: Example of redundancy function

In the figure above the signal of logical function CtrlHBeat FD is used to disable the main controller if it is lost from CAN bus or CAN bus communication from that controller becomes erratic. It is used also to disable the redundant controller when the communication on CAN bus is alright (it is negated). For more information on Virtual Binary Inputs and Outputs (VPIO) please refer to the chapter about Shared Binary Inputs and Outputs and Virtual Binary Inputs and Outputs.

NOTE:

Use pulse signals for control of circuit breakers. MCB ON COIL, MCB OFF COIL, MGCB ON COIL and MGCB OFF COIL should be used to prevent sudden opening for a short period of time when the controller fails and to ensure proper function of redundancy.

Force value – step by step guide

In this chapter there is complete step by step guide which shows how to use Force value function of the controller.

Forcing of values is used to change particular setpoint temporarily by activation of related Binary Input. This is used to change function of controller under given conditions (e.g. there are two different periods during the day when Export limit given by distribution network is required or not).

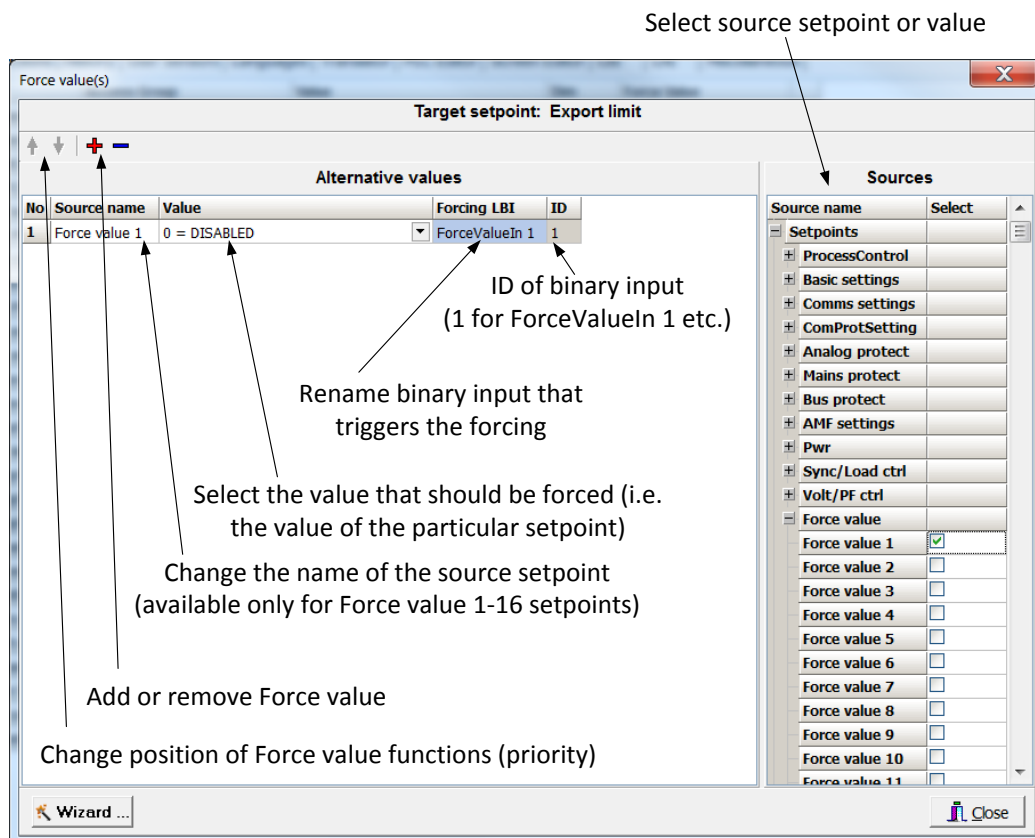
WARNING!

Setpoints must not be written **continuously** (e.g. via Modbus connection)! If continuous change of setpoints is required, combination of External values and Force value function needs to be used. The memory that holds setpoints is designed for up to 10⁵ writings. Than memory may be damaged!

Setpoints that are available for forcing may be identified by Force value button on the right side in GenConfig (see the figure below).



When the button is clicked, Force value dialog appears.



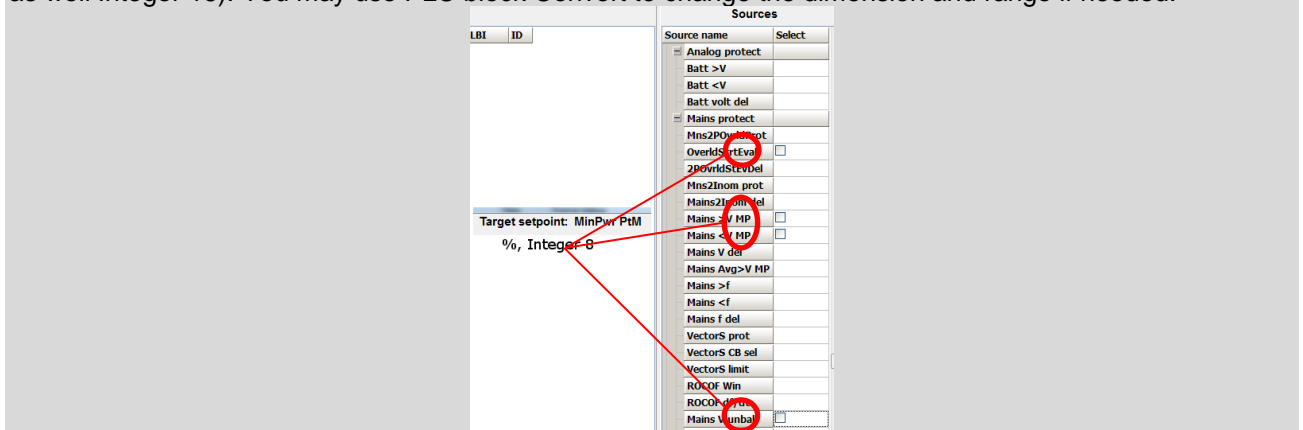
For example if we add **Force value:Force value 1** to be forced to **ProcessControl:Export limit** as value 0 (DISABLED) by Binary Input FORCEVALUEIN 1 we can change the function of Export limit from ENABLED to DISABLED by activation of FORCEVALUEIN 1. It is possible to rename the setpoint to e.g. **Force value:ExportDisabled** and Binary Input as well to e.g. DISABLEEXPLIM. The function will not change (only the corresponding names).

It is possible to use several force value functions for one setpoint. If more than one forcing Binary Input is active, the one with the highest position (lowest number in the Force value dialog) is used.

It is possible as well to use one Binary Input to force multiple setpoints (e.g. in case of complex function change).

NOTE:

It is possible only to force value or setpoint in other setpoint if their dimension and range are the same (e.g. only value with dimension in hours and which is Integer 16 to a setpoint with dimension hours and which is as well Integer 16). You may use PLC block Convert to change the dimension and range if needed.



Values for continuous writing from external sources

This function is especially designed for continuous writing of setpoints from external sources (e.g. via Modbus connection).

WARNING!

Setpoints must not be written **continuously** (e.g. via Modbus connection)! If continuous change of setpoints is required, combination of External values and Force value function needs to be used. The memory that holds setpoints is designed for up to 10^5 writings. Than memory may be damaged!

It is possible to use up to four different External values for continuous writing from external sources. The values are adjusted by setpoints in **Force value** group. Default (also initial) value may be adjusted, rate of change of *ExtValueX* (by Binary Inputs EXTVALUEX UP and EXTVALUEX DOWN) can be adjusted as well as high and low limit of the value.

There are two way, how to adjust External values. One is using Binary Inputs mentioned above. Second one is to write the value directly using e.g. Modbus. External values then may be converted using PLC block convert and force into setpoint which is then continuously forced (**note: NOT WRITTEN**) by the value of *ExtValueX*. This way internal memory is safe and no damage may occur.

External values are reverted back to their default (initial) value (given by corresponding setpoint) when Binary Input for their reset is active (and they change to the previous value after Binary Input deactivates). When the Binary Input is active the External value cannot be changed by Modbus writing or by using Binary Inputs for up and down value.

NOTE:

External values are not available for external writing when any Binary Input (up, down or reset) related to them is active.

Note also that when the controller is reset (powered down and up again), all external values are reverted back to their default (initial) values.

HINT

For information on how to write (or read) objects from controller via Modbus, please refer to the latest Communication guide for InteliGen and InteliSys.

General Purpose Timers

There is 16 general-purpose timers in the controller, each 4 of them are joined together to one output. That means there are 4 fully independent timer blocks including 4 timer channels each. The combined outputs from the timer blocks are *TIMERACT 1-4*, *TIMERACT 5-8*, *TIMERACT 9-12* AND *TIMERACT 13-16*.

The timers are intended for scheduling of any operations such as e.g. periodic tests of the gen-set, scheduled transfer of the load to the gen-set prior to an expected disconnection of the mains etc. Each timer channel can be activated only once within a single day. The activation time and duration of each channel is adjustable (both as hh:mm).

Timer modes

Available modes of each timer:

ONCE	This is a single shot mode. The timer will be activated only once at preset date/time for preset duration.
DAILY	The timer is activated every "x-th" day. The day period "x" is adjustable. Weekends can be excluded. E.g. the timer can be adjusted to every 2nd day excluding Saturdays and Sundays.
WEEKLY	The timer is activated every "x-th" week on selected weekdays. The week period "x" is adjustable. E.g. the timer can be adjusted to every 2nd week on Monday and Friday.
MONTHLY	The timer is activated every "x-th" month on the selected day. The requested day can be selected either as "y-th" day in the month or as "y-th" weekday in the month. E.g. the timer can be adjusted to every 1st month on 1st Tuesday.

SHORT PERIOD The timer is repeated with adjusted period (hh:mm). The timer duration is included in the period.

The mode of each timer channel is adjusted by an assigned setpoint. The setpoints are located in the **Timer settings** group and can be adjusted via IntelliMonitor and GenConfig.

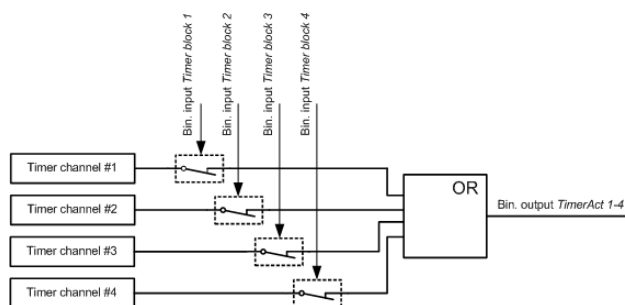
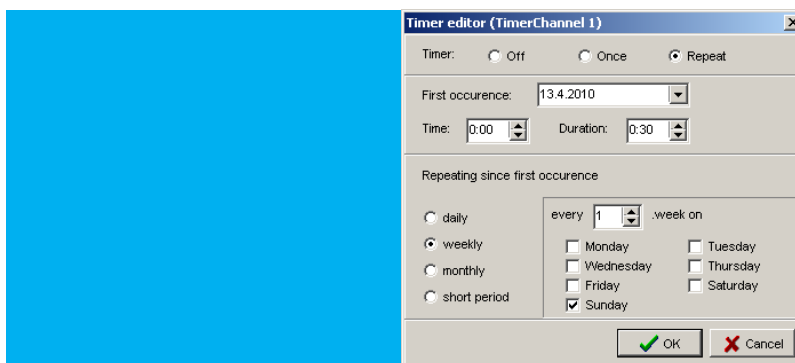


Figure: Principal scheme of one block containing 4 timers

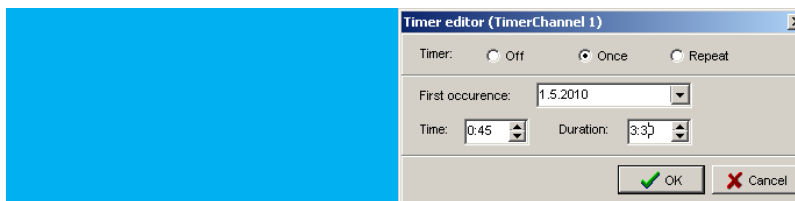
EXAMPLE:

Below is an example how to use the timers for periodic tests of the gen-set performed every sunday with duration of 30 minutes and also for scheduled transfer of the load before expected mains failure announced by the local electricity distribution company to 1.5.2010 from 01:00 to 04:00.

1. The output *TIMERACT 1-4* is configured internally in GenConfig (LBI tab) to the logical binary inputs *REMOTE TEST* and *TEST ON LOAD*.
2. The setpoint **Timer settings: TimerChannel 1** is adjusted to "repeated" mode, "weekly" period, only sundays, starting date/time next sunday at 0:00, timer duration 0:30 min.



3. The setpoint **Timer settings: TimerChannel 2** is adjusted to "once" mode, starting date/time 1.5.2010 at 01:00, timer duration 3:00 hrs.



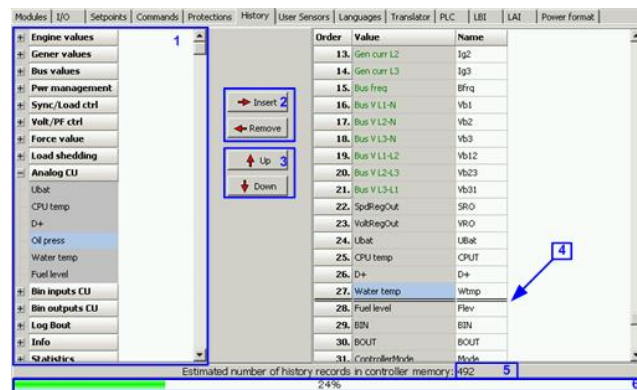
History Related functions

History Records Adjustment

It is possible to change History records content. Each record contains date, time and cause of the record as obligatory columns. The rest of columns are configurable.

The history record structure has two parts. The upper part is so-called fast and is written into the history memory immediately in the moment when the written event occurs. The rest of the record may be written

with a delay max. 100ms. The fast part is intended for fast changing values as e.g. currents, voltages or power. The parts are separated by a line in the record content list.



1. Values selection tree
2. Buttons for adding/removing values into/from the record structure
3. Buttons for ordering of the values in the record structure
4. Fast history separator. The fast part is located above the separator
5. Estimated number of records depending on record size
6. Record capacity usage indicator

NOTE:

Values that are displayed in green color are recommended to be placed in the fast part. If the checkbox 'Add modules to history automatically..' in the Modules tab is checked then all values of a module are automatically added into the history record when the module is inserted into the configuration.

Time Stamp function

The controller allows user to define when the history records are written even though there is no other reason for history record (so called Time Stamp).

It is possible to disable time stamping function (for example when time stamping is not needed and just floods the history). It may be conditioned by activation of logical Binary Input function (TIME STAMP ACT) or it may be enabled always.

Period of time stamping may be adjusted from 1 to 240 minutes.

NOTE:

Beware of History flooding by too many Time Stamps (vital information may be overwritten).

Time and Date Intercontroller Sharing

Time and Date are used mainly for History records. These values are shared between controllers that are connected to CAN. When the value is changed in one controller, it sends its new value to all other controllers that are connected to the same CAN bus and they update their time and date values and setpoints accordingly.

Summer Time Mode

Summer Time Mode function may be enabled and disabled by user. It is possible to set if the controller is located in the northern or southern hemisphere as well.

SummerTimeMode implemented in ComAp controllers is based on CET summer time which means:

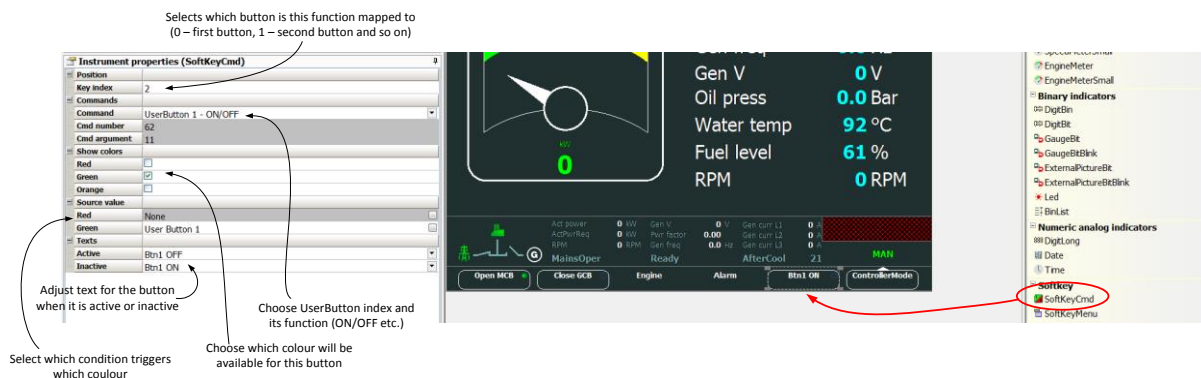
- Clock goes forward 1 hour at 2:00 a.m. on the last Sunday in March
- Clock goes backwards 1 hour at 3:00 a.m. on the last Sunday in October

NOTE:

Please be aware that in other regions summer time adjustments may be done in different time.

User Buttons

There are several User Buttons available in the controller. It is possible to set them on Soft Buttons in IntelliVision 5 or 8.



Available functions for soft buttons are listed in the following table.

ON	Pressing the button changes the state of log. Binary Output USER BUTTON X to closed. When the output is closed and the button is pressed state is not changed.
OFF	Pressing the button changes the state of log. Binary Output USER BUTTON X to opened. When the output is opened and the button is pressed state is not changed.
ON/OFF	Pressing the button changes the state of log. Binary Output USER BUTTON X to opened or closed depending on previous state (it is changed to the opposite state).
PULSE ON	Pressing the button issues log. Binary Output USER BUTTON X to close for one second.
	<p>NOTE: Repeated pressing of button during the closed period (one second) causes issuing other puls of length of one second to be generated from the moment of button pushing.</p>

HINT

It is possible to lock User Button with password (go to tab Commands in GenConfig). User Buttons 1-5, 6-8 and 9-16 can be locked separately. It is also possible to use User Buttons in SCADA diagrams.

Remote Control Function

It is possible to remotely control several Binary Outputs in the controller. You can either use Remote Switches tool in IntelliMonitor (select Remote switches in menu for corresponding controller), import Remote Switches tool to a SCADA diagram in Line Diagram Editor or use external device via Modbus (register #46361 and command #26 (1A hex), for more information on Modbus please refer to the IntelliGen/IntelliSys Communication guide).

Remote Switch will activate or deactivate depending on remote control so it can be used to manually control devices, simulate malfunctions while commissioning etc.

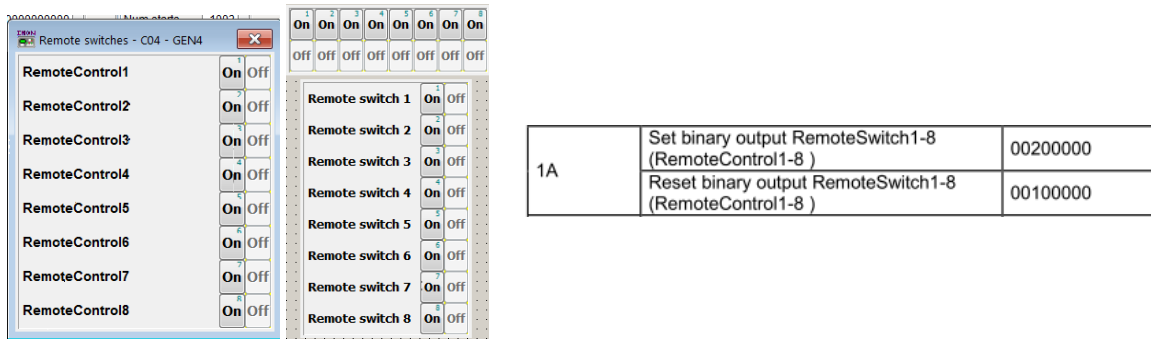


Figure: Remote Switches tool in IntelIMonitor, Remote Switches tools in Line Diagram Editor and Mobus commands

Remote Switches may be easily used to trigger logical Binary Input function and all other related functions as normal switch on Binary Input. Module VPIO (Virtual Peripheral Inputs- Outputs) can be added to configuration and it will copy the state of Remote Switch on virtual output to its counterpart virtual input. Refer to the figure below for example.

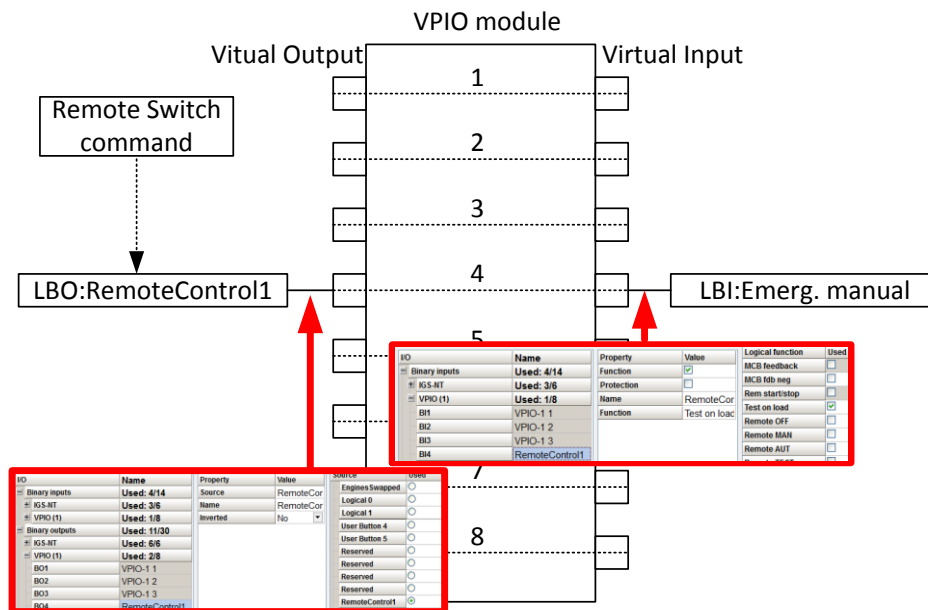


Figure: Using of Remote Switches to trigger logical binary inputs

Virtual Peripheral Inputs-Outputs (VPIO) module

For the controller there are several modules available. One of them is Virtual Peripheral Inputs-Outputs module which is particularly useful for connection of logical Binary Output functions to logical Binary Input functions. This way internal controller function may easily trigger other internal controller functions without unnecessary wiring or usage of PLC functions.

Module is functioning the same way as normal module with 8 outputs and 8 inputs, but the difference is, that each input copies its counterpart output. It is possible to select any logical Binary Output function for one of the outputs of VPIO module. Inputs on VPIO module work the same way as standard input of the controller (i.e. it can be assigned function and protection).

For example of this function please refer to the chapter Remote Control function.

Shared Inputs and Outputs

It is possible to share Binary and Analog values between all the controllers via CAN bus, thus saving physical Inputs and Outputs and excess wiring.

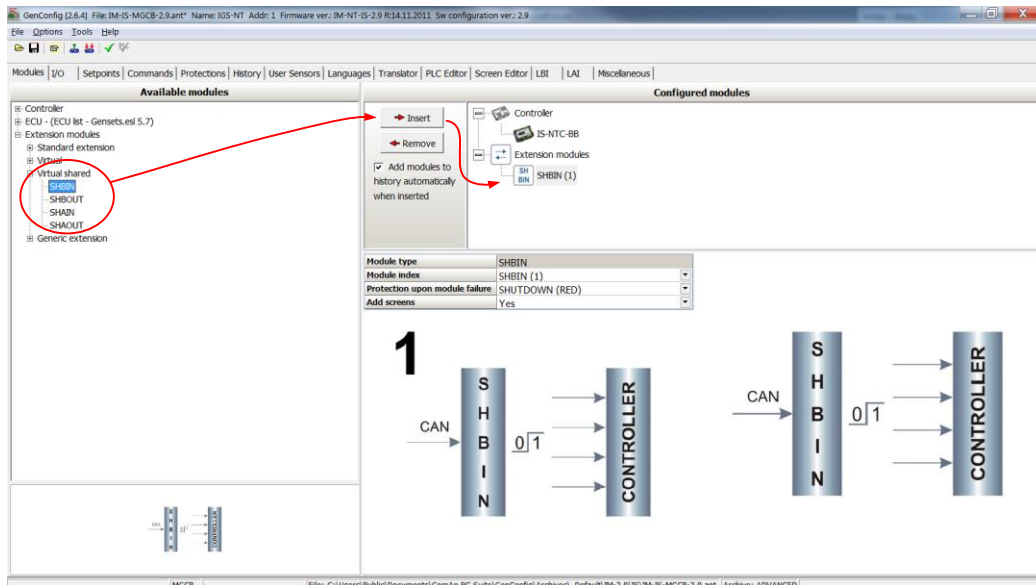


Figure: Adding of various modules

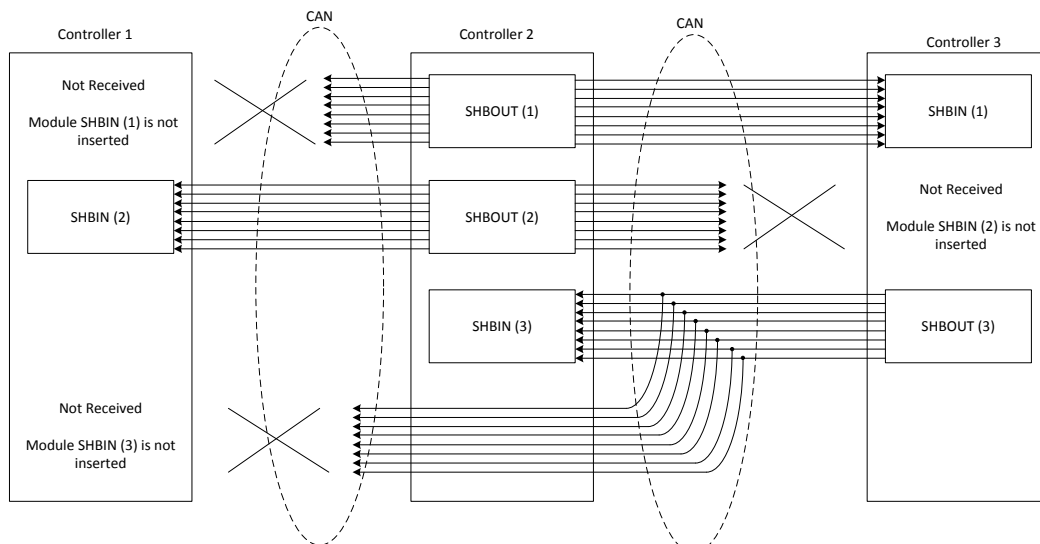


Figure: Principal Scheme (same for shared Binary I/O and shared Analogue I/O)

Shared Binary Inputs and Outputs may be used exactly in the same way as standard physical Inputs and Outputs. If SHBIN or SHAIN modules are configured, at least one corresponding module of SHBOUT or SHAOUT (respectively) is needed. If it is not configured, corresponding protection appears because SHBIN or SHAIN will be missing. See the figure below for more information.

CAUTION!

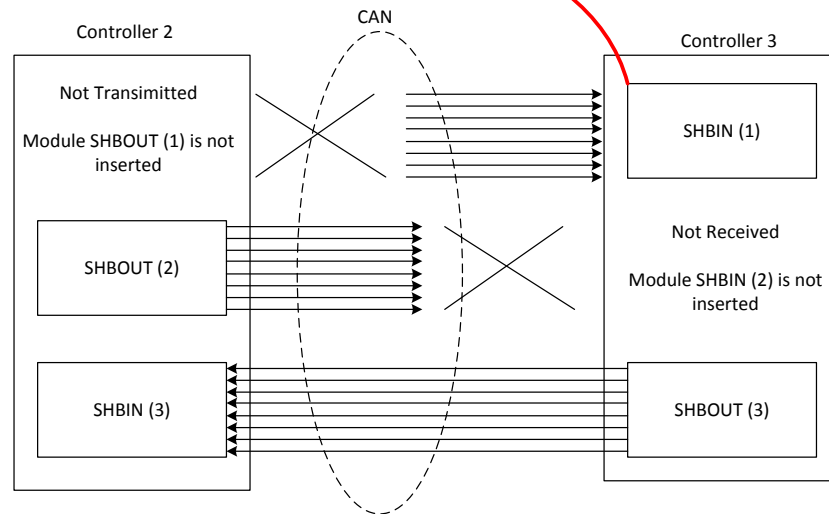
For proper function of Shared Binary and Analog Inputs and Outputs, only one source of Shared Binary or Analog Outputs must be configured (i.e. it is not possible to configure in one controller SHBOUT1 and to another one as well SHBOUT1).

HINT

Controller sends Shared Binary Outputs each 100ms if there are any changes in any bit position. If there are no changes, controller sends the information with period 1s.

Module type	SHBIN
Module index	SHBIN (1)
Protection upon module failure	SHUTDOWN (RED)
Add screens	Yes

Level 1, Level 2 or no protection is displayed



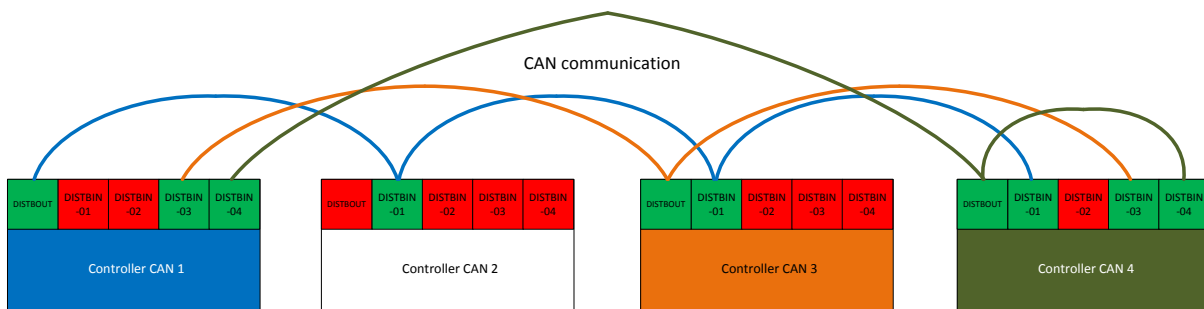
Distributed Binary Inputs and Outputs

It is possible to share Binary and Analog values between all the controllers via CAN bus, thus saving physical Inputs and Outputs and excess wiring.

DISTBIN and DISTBOUT work in a different way than SHBIN and SHBOUT. Each controller has one pack of eight DISTBOUT available (if not configured or no function is assigned to any output, it does not broadcast them). The number of DISTBOUT module is not shown in the configuration and it is always corresponding to the CAN address of the controller (e.g. the controller with address 5 will be broadcasting DISTBOUT-05 which can be received if module DISTBIN-05 is configured in another controller). Up to 32 DISTBIN modules can be configured (meaning that the controller will be receiving all DISTBOUT from all the controller, even his own).

It is not possible to change the name of DISTBIN inputs or add protections.

In the example below you can see 4 controllers with various DISTBIN and DISTBOUT configuration.



NOTE:

HINT

Controller sends Distributed Binary Outputs each 100ms if there are any changes in any bit position. If there are no changes, controller sends the information with period 1s.

NOTE:

DISTBIN and DISTBOUT function is not available for IM-NT-GC controller.

NOTE:

DISTBIN and DISTBOUT function is conditioned by IGS-NT-LSM+PMS dongle.

Modbus Reading and Writing

Controller supports Modbus Slave functions (an external device may write or read from a controller). Modbus registers corresponding to objects in the controller can be exported to text form in GenConfig.

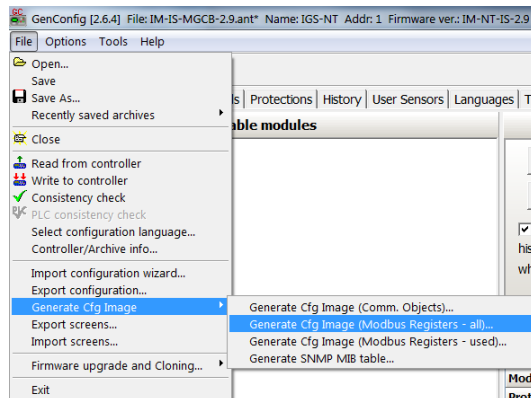
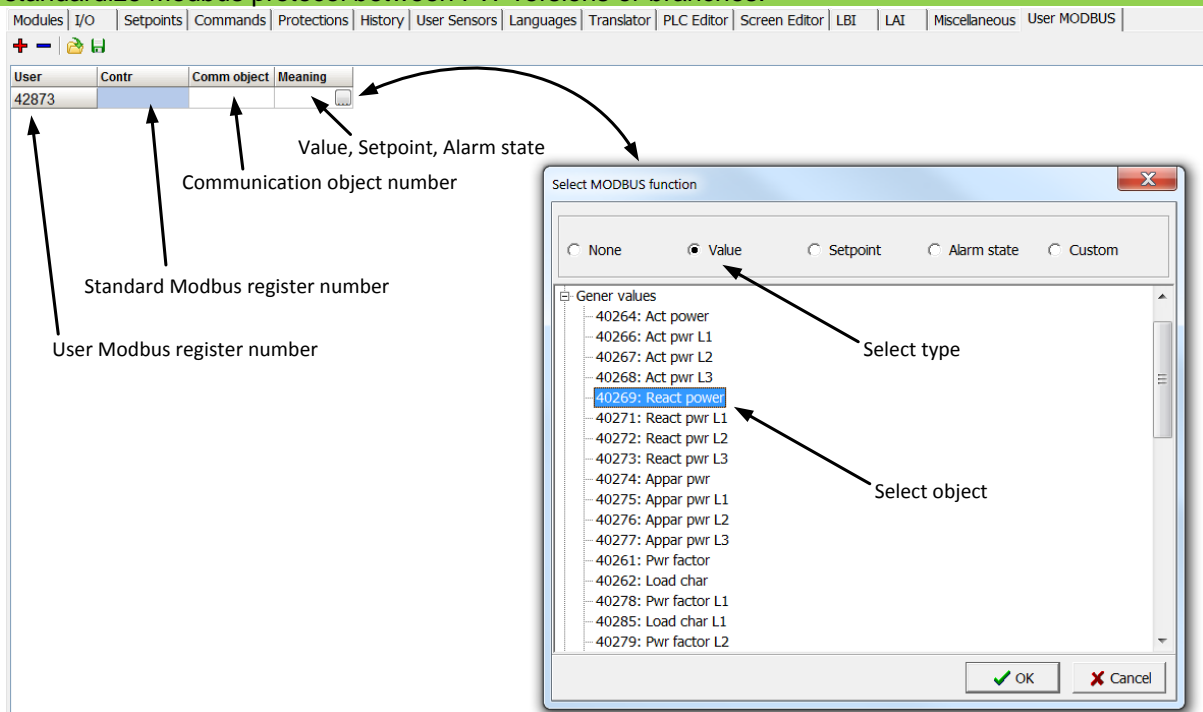


Figure: Exporting of Modbus registers

If Modbus Master function is required extension module I-CB/Modbus connected via CAN1 can be used. For more information on how to use this module please refer to IntelliGen/IntelliSys Communication Guide and to I-CBEdit manual.

User MODBUS

Users can define Modbus registers from 42873 to 43000. Values, setpoints and Alarm states can be specified for these new Modbus registers to prepare the Modbus protocol for batch reading and writing or to standardize Modbus protocol between FW versions or branches.



The screenshot shows the 'User MODBUS' configuration window. At the top, there are tabs for Modules, I/O, Setpoints, Commands, Protections, History, User Sensors, Languages, Translator, PLC Editor, Screen Editor, LBI, LAI, Miscellaneous, and User MODBUS. Below the tabs is a table with columns: User, Contr, Comm object, and Meaning. The first row contains the value '42873'. Arrows point from labels to the table: 'Standard Modbus register number' points to the 'User' column, 'User Modbus register number' points to the '42873' value, 'Communication object number' points to the 'Contr' column, and 'Value, Setpoint, Alarm state' points to the 'Meaning' column. A dialog box titled 'Select MODBUS function' is open, showing radio buttons for 'None', 'Value', 'Setpoint', 'Alarm state', and 'Custom'. The 'Value' radio button is selected. Below the radio buttons is a list of objects under the heading 'Gener values'. The object '40269: React power' is selected. Arrows point from labels to the dialog: 'Select type' points to the 'Value' radio button, and 'Select object' points to the selected object in the list. The dialog has 'OK' and 'Cancel' buttons at the bottom.

NOTE:

User MODBUS function is not available for IM-NT-GC controller.

Modbus Switches

The “Modbus Switches” contains of two groups of LBOs named “ModbusSw1” and “ModbusSw2”. Both registers are available on Modbus for simple writing (using command 6 or 16). The particular bits of these registers are available as binary status for universal use in logical binary outputs of the controller as “ModbusSw1..ModbusSw32”. No password is required for writing of those registers. There are two Values “ModbusSw1” and “ModbusSw2” in group “Log Bout” available for back-reading.

Register for writing	Modbus register number	Value for back-reading	Modbus register number
ModbusSw1	46337	ModbusSw1	40547
ModbusSw2	46338	ModbusSw2	40548

NOTE:

The LSB of ModbusSw1 (46337) corresponds with LBO “ModbusSw1”
 The LSB of ModbusSw2 (46338) corresponds with LBO “ModbusSw17”
 The Values ModbusSw1 and ModbusSw2 have the position of LSB opposite-wise.

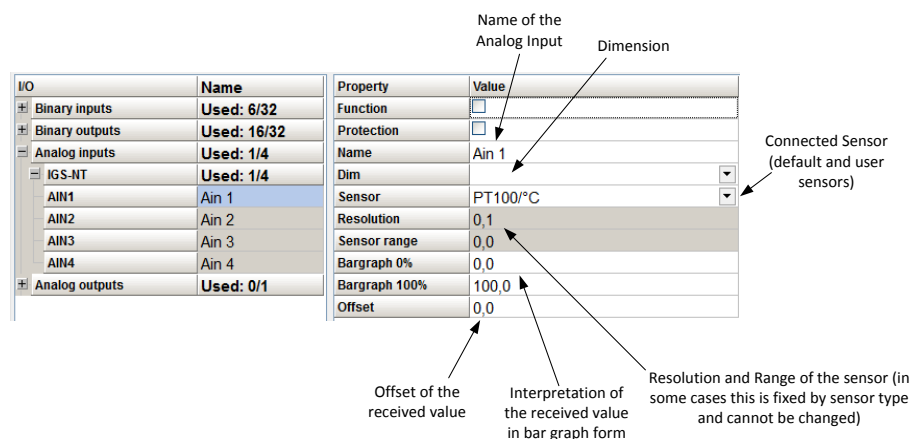
Examples:

Register port for writing	Input value	LBO ModbusSw16ModbusSw1
ModbusSw1 (46337)	000F HEX	0000 0000 0000 1111

Register port for writing	Input value	LBO ModbusSw32ModbusSw17
ModbusSw2 (46338)	F000 HEX	1111 0000 0000 0000

Analog Input Sensors and User Sensors

Controller and/or some extension modules allow connection of sensor outputs to Analog Inputs. There is whole variety of common sensor output characteristics prepared in configuration by default. Although if there is sensor that is not in the list, it is possible to prepare custom characteristics (up to 16) with up to 31 definition points.



Property	Value
Function	<input type="checkbox"/>
Protection	<input type="checkbox"/>
Name	Ain 1
Dim	PT100°C
Sensor	PT100°C
Resolution	0,1
Sensor range	0,0
Bargraph 0%	0,0
Bargraph 100%	100,0
Offset	0,0

Figure: Sensor adjustment in GenConfig

Default sensors: PT100/°C, PT1000/°C, NI1000/°C, PT100/°F, PT1000/°F, NI1000/°F, 4-20mA active, 0-2400ohm, 0-2.4V, Tristate

HINT

There is “electronic” type of sensor available for Shared Analog Inputs which can be used to interpret shared data over CAN bus.

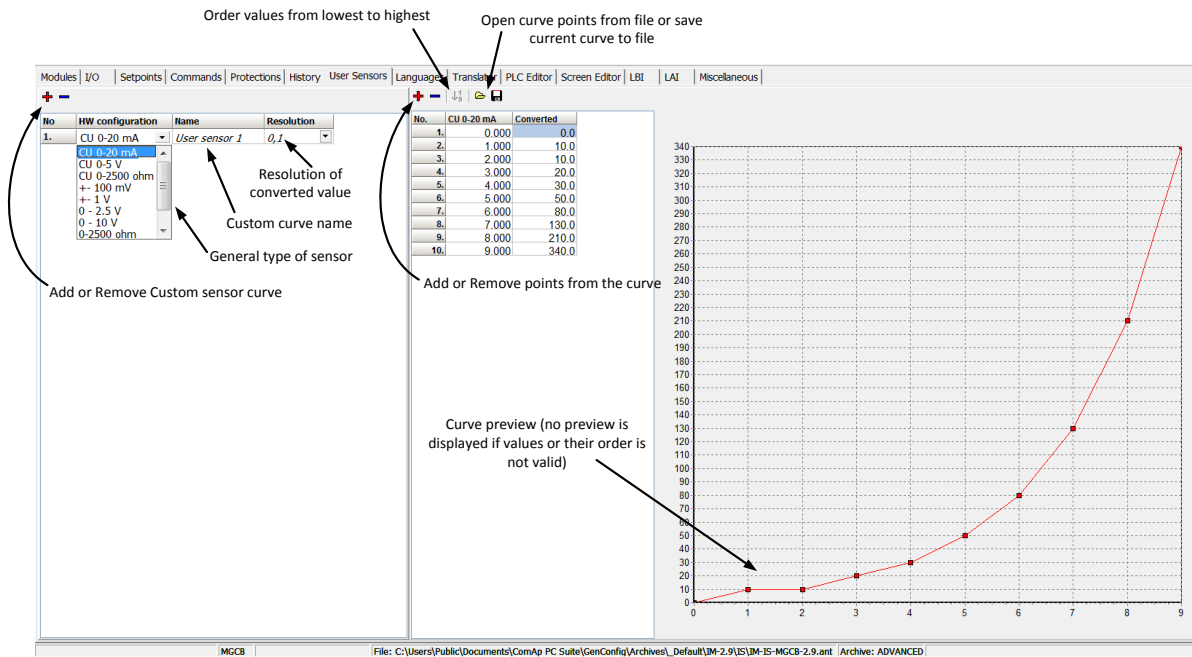


Figure: User Sensor definition

Languages and Translator tool in GenConfig

For detailed description of Languages and Translator tool please refer to GenConfig interactive help (press F1 when in corresponding tab or open Help -> GenConfig Help).

Power Formats

IGS-NT family allows user to choose from several Power Formats that affect dimensions in which values and some setpoints are interpreted or adjusted. Power formats may be changed in Miscellaneous tab in GenConfig. There are following Power Formats available:

- 1 kW kVAr kVA kX V
- 0,1 kW kVAr kVA kX V
- 0,01 MW MVAr MVA MX kV
- 0,01 MW MVAr MVA MX V

NOTE:

Range of some setpoints and values is changed significantly when different Power Formats are selected.

Last Power Format is designed to be used in combined Power/High Voltage and Low Voltage installations. High voltage is then interpreted in Volts (e.g. 33256V instead of 33kV).

Last two Power Formats can be used in combination on one CAN bus.

System Start/Stop

For proper function of the system, System start and stop signal needs to be used properly. Below there is scheme that shows how to use the Binary Output SYS START/STOP in the system using just CAN wiring (no physical wiring is needed to share the starting and stoping signal into all controllers in the system).

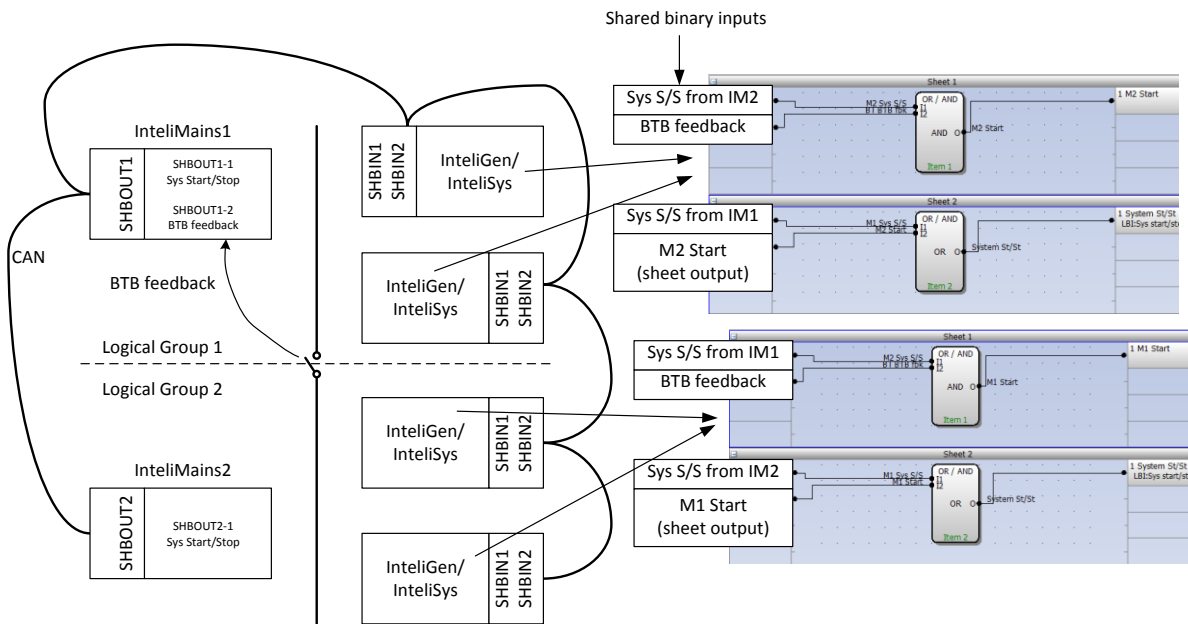
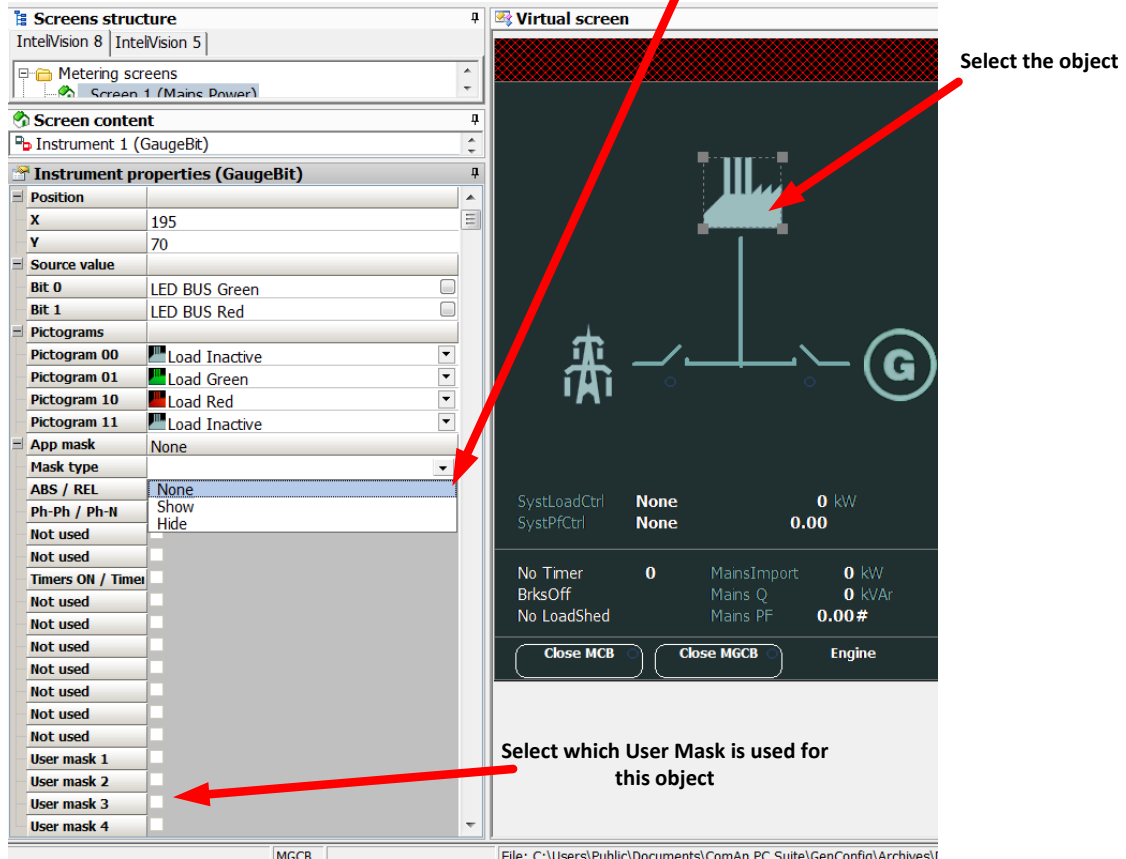


Figure: Preparation of correct system start/stop function for two logical groups

User Mask function

In GenConfig you can easily set any object in Screen Editor to show or hide based on activation of particular Logical Binary Input available for users. Below, there is diagram showing the setup of User Mask function in Screen Editor.

Select the proper function
 Show = appears when LBI gets active
 Hide = disappears when LBI gets active
 None = no function



Select the object

Select which User Mask is used for this object

NOTE:
 Masking of screens in IntelliVision 5 supports only Show function
 Use also other masking functions (masking can react on several internal states, e.g. activation of Timers).

PLC functions

See description in IGS-NT-Application Guide 05-2013.pdf.

Multi language support

NT family controllers support up to five Languages that is possible to switch during controller duty. Every terminal (i.e. Remote display or PC-InteliMonitor) can be switched to different language. Use PC-GenConfig - Translator tool to translate texts to another language.
 Default application archives contain all texts in English only.

ECU interface customizing

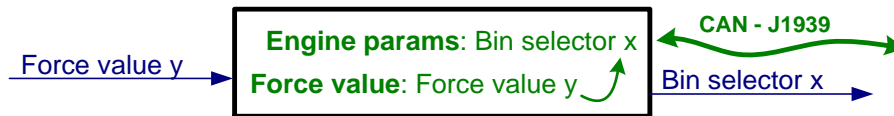
The list of available ECU interfaces can be found in GenConfig / Modules / ECU list.

Binary selector

This function enables to change the following CAN values transmitted to ECU via J1939 or binary output only. The change can be provided by setpoint or via Binary input. There are four Bin selector channels available.

J1939 value	ECU command
Governor mode	Isochronous - Droop

Idle Speed select	Idle – Nominal
Frequency select	1500 – 1800
Preheat request	Yes – No
Protection override	Yes – No



Sync/load control adjustment

HINT:

Use isochronous speed governor.

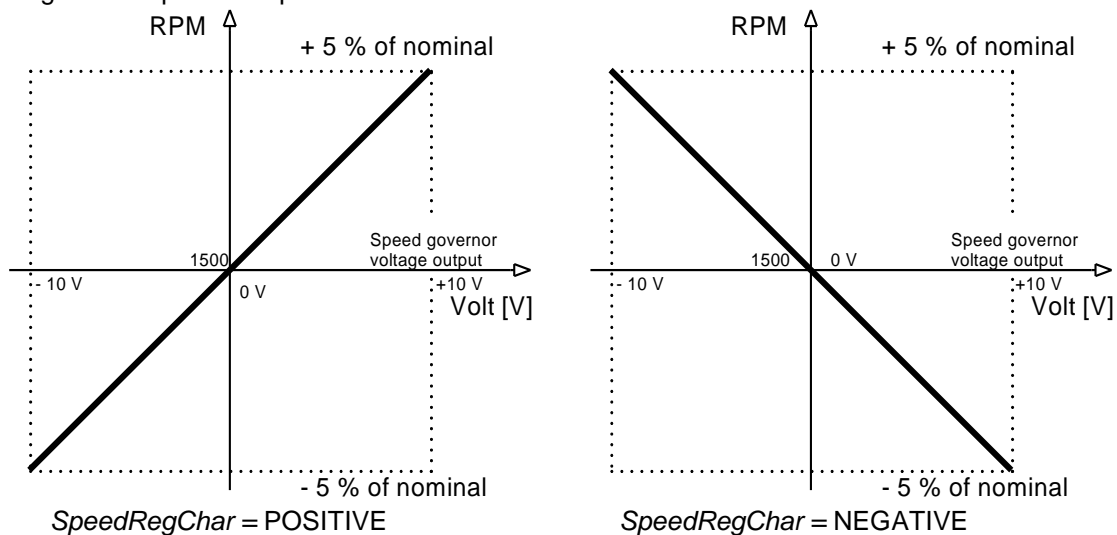
Two wire shielded connection from IGS-NT SPEED GOVERNOR output (SG OUT, SG COM) to Speed governor auxiliary input is recommended.

A full range change of the IGS-NT speed governor output (from SpeedGovLowLim to SpeedGovHiLim) should cause 5-10% change of the engine speed (SpeedGovLowLim ~ 95% RPMnom, Speed gov bias ~ 100% RPMnom, SpeedGovHiLim ~ 105% RPMnom).

IMPORTANT

Speed governor has to be adjusted for optimum performance before Sync / load control adjusting.

Check generator phase sequence before the first GCB connection.



Before optimal Sync/load setpoints adjusting disconnect GCB OPEN/CLOSE output or set *Phase window* = 0 to avoid paralleling.

Synchronizer adjustment

- 1) Start the engine in MAN Mode.
- 2) Set the engine RPM by speed trim on speed governor or by *Speed gov bias* and *SpeedGovLowLim* and *SpeedGovHiLim* to Nominal frequency.
- 3) To start synchronizing press **GCB ON/OFF** button. GCB LED starts to flash to indicate synchronization. To stop synchronization press again **GCB ON/OFF**.

Slip control adjusting:

- 4) Adjust *Freq gain* to unstable speed control and decrease value by 30 % to insure stable performance.
- 5) Adjust *Freq int* to stable (fast and smooth) slip control. Synchroscope movement on the controller measure screen should slow down and stop (in any position, because Angle control is off).

Angle control adjusting:

- 6) Set *Angle gain*. Synchroscope on the controller measure screen should move slowly and stop in “up” position. Set *Angle gain* to unstable value (synchroscope swings) and decrease value by 30 % to insure stable performance.

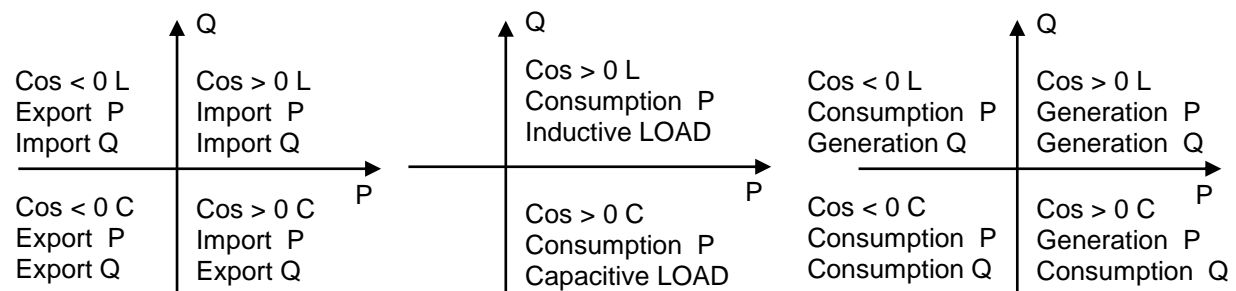
Load control adjustment

Prior to Sync/Load control adjustment, the Volt/PF control has to be adjusted! Load control loop is active in parallel to mains mode only (MCB feedback closed). Switch off other engines while adjusting.

- 1) Set *#SysLdCtrl PtM* = Baseload, set *Baseload* value to 30 % of Nominal power of one gen-set.
- 2) Set *Load gain* to the same value as *Slip freq gain*. Set *Load int* to zero.
- 3) Start the gen-set in MAN Mode, press **GCB ON/OFF** button to synchronize and close gen-set to mains.
- 4) When GCB is closed, gen-set load slowly increases to *Base load* value. Check that gen-set power is positive (CT polarity!).
- 5) Increase *Load gain* to unstable load control and decrease value by 30 % to insure stable performance. When *Load int* factor is set to zero gen-set load can differ from required Baseload.
- 6) To adjust and optimize *Load int* change several times *Base load* between 30 and 70 % of Nominal power. Usually setting *Load int* to 100% gives optimal performance.
- 7) When gen-set is running full load check if
 - a. Speed governor output voltage value is not limited (not reached *SpeedGovLowLim* or *SpeedGovHiLim*)
 - b. Speed governor actuator isn't mechanically limited or operates in small section of throttle range.

Active and reactive power terminology

MAINS		LOAD		GEN	
P > 0	Import	P > 0	Consumption	P > 0	Generation
Q > 0	Import	Q > 0	Consumption	Q > 0	Generation



Mains

Exported active power is supplied to the mains. It is displayed in negative numbers e.g. -20kW.
 Imported active power is consumed from the mains. It is displayed in positive numbers e.g. +20kW.
 When reactive power is imported (>0) IntelliMains-NT displays L (inductive) character of the load.
 When reactive power is exported (<0) IntelliMains-NT displays C (capacitive) character of the load.

Load

Active power consumed by Load is displayed in positive numbers e.g. 20kW.
 When reactive power is positive (>0) IntelliMains-NT displays L (inductive) character of the load.
 When reactive power is negative (<0) IntelliMains-NT displays C (capacitive) character of the load.

Genset

Generated active power is displayed in positive numbers e.g. 20kW.
 When reactive power is positive (>0) IGS-NT displays L (inductive) character of the load.
 When reactive power is negative (<0) IGS-NT displays C (capacitive) character of the load.

Volt/PF control adjustment

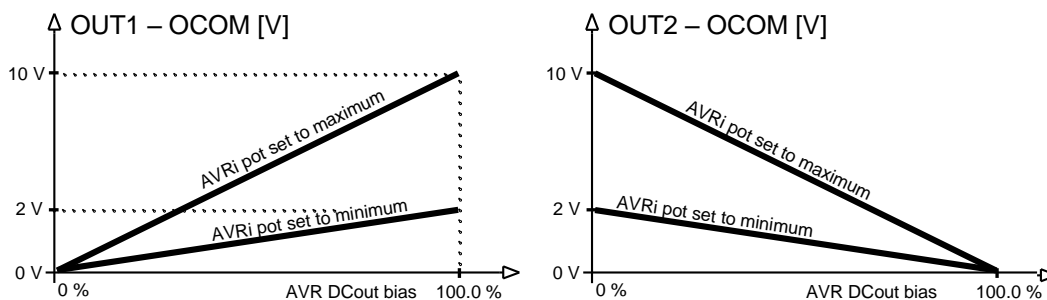
IG-AVRi output connection

Every time refer to corresponding AVR manual before interface connecting. Use no droop AVR.

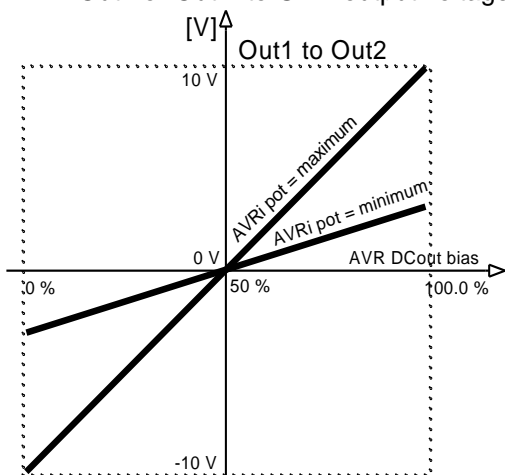
IG-AVRi-TRANS (AC power supply for AVRi) has to be supplied from gen-set voltage.

AVRi outputs can be connected as symmetrical: OUT1-OUT2 or unsymmetrical OUT1-OCOM or OUT2-OCOM.

- Potentiometer on the AVRi defines maximal OUT1, OUT2 voltage range.
- Use symmetrical (OUT1,OUT2) AVRi output to connect the AVRi to AVR auxiliary voltage input.
- Use unsymmetrical output if an external AVR potentiometer has to be replaced with AVRi.
- AVRi output voltage should change generator voltage typically in range $\pm 10\%$ of Nominal voltage.
- For more details please refer to Installation guide – chapter AVR interface examples.



AVRi Out1 or Out 2 to GND output voltage depends on AVRi trim setting



AVRi output voltage

Bias \ Pot	Out1 - OCOM		Out2 - OCOM		Out1 - Out2	
	Min	Max	Min	Max	Min	Max
0 %	0	0	2	10	- 2 V	-10 V
50 %	1	5	1	5	0 V	0 V
100 %	2	10	0	0	+ 2 V	10 V

AVRi Out1 to Out 2 output voltage

Voltage control adjustment

- 1) Set *Voltage gain*, *Voltage int* to zero and *AVR DCout bias* to 50%.
- 2) Start always with AVRi pot min adjustment (fully counterclockwise).
- 3) Start the gen-set in MAN Mode to nominal speed, without load.
- 4) Adjust generator voltage to nominal value by the potentiometer present on the AVR. If there is no potentiometer on the AVR, use *AVR DCout bias* to adjust the nominal voltage.
- 5) Change *AVR DCout bias* to 0% and 100% to check generator voltage control range (typically $\pm 10\%$ of nominal voltage). Adjust voltage control range by AVRi trim.
- 6) Set *AVR DCout bias* to be Nominal voltage on generator (50%).
- 7) When gen-set is running unloaded increase carefully *Voltage gain* to unstable point and then decrease value by 30 % to insure stable performance.
- 8) Adjust *Voltage int* (usually setting to 100% gives optimal performance).

HINT:

To judge optimal adjusting induce generator voltage jumps by AVR DCout bias change or by Nominal voltage change .

AVRi output OCOM is common output. GND was used instead of OCOM

PF control adjustment

The genset should be cca 30 % loaded in parallel to mains and baseload mode.

- 1) Set the same values *PF gain*, *PF int* as in voltage control loop.
- 2) Set **Process control**: *#SysLdCtrl PtM* = BASELOAD, *#SysBaseLoad* = 30 % of Nominal load, *#SysPFCtrl PtM* = BASEPF, *#SysPwrFactor* = 1.0.
- 3) Start and synchronize the gen-set in MAN Mode by pressing GCB ON/OFF
- 4) When running in parallel 30% loaded increase slowly *PF gain* to unstable point and then decrease value by 30 % to insure stable performance.
- 5) Adjust *PF int* (usually setting to 100% gives optimal performance).

Hint:

To judge optimal adjusting induce generator power jumps by *SysBaseLoad* change or by soft changes of *AVR DCout bias*.

Protections and Alarm management

ComAp gen-set controllers provide following range of generator protections.

For each protection adjustable limit and time delay are available.

ANSI CODE	PROTECTION	IG-NT, IG-NTC, IG-NT-BB, IG-NTC-BB	IS-NT-BB, IS-NTC-BB
25	Synchronism Check	•	•
27	Undervoltage	•	•
32	Overload	•	•
32R	Reverse Power	•	•
37	Undercurrent	•@	•@
40	Excitation Loss	•	•
46	Current Unbalance	•	•
47	Voltage Assymetry	•	•
47	Phase Rotation	•	•
50+51	Overcurrent	•	•
50N+64	Earth Fault Current	•	•
51N+64	Earth Fault Current, IDMT	•	•
55	Power Factor	•@	•@
59	Overvoltage	•	•
71	Gas (Fuel) Level	•	•
81H	Overfrequency	•	•
81L	Underfrequency	•	•

Note: -- excluded; • - included

@ - can be created using universal protections

Protection groups

There are two groups of protections in the controller: fix and universal (configurable)

PROTECTION GROUP	CONFIGURABILITY	SETTINGS
Analogu protection	Configurable	Analog protect
Generator protection	Configurable	Gener protect
Fix protections	Fix	Engine params, Gener protect, Mains protect, Analog protect

Alarm types

ALARM/EVENT KIND	LEVEL	DESCRIPTION
Warning	1	The alarm appears in the Alarmlist and is recorded into the history log. Activates the output Common Wrn as well as the standard alarm outputs.
Alarm Only	1	The alarm appears only in the Alarmlist. Activates the output Common Al as well as the standard alarm outputs.
HistRecOnly	1	The event is recorded into the history. Activates the output Common Hst for one second. Standard alarm outputs are not activated.
AL indication	1	The event is only indicated in the Alarmlist. It disappear for the alarmist automatically as soon as the cause disappears. Standard alarm outputs are not activated.
A+H indication	1	The event is only indicated in the Alarmlist and recorded into the history log. It disappear for the alarmist automatically as soon as the cause disappears. Standard alarm outputs are not activated.
Shutdown	2	The alarm appears in the Alarmlist and is recorded into the history log. It causes immediate stop of the gen-set without unloading and cooling phase. The gen-set can't be started again while there is a Shutdown alarm in the Alarmlist. Activates the output Common Sd as well as the standard alarm outputs.
Slow Stop	2	The alarm appears in the Alarmlist and is recorded into the history log. It causes stop of the gen-set by the standard stop sequence, i.e. including unloading and cooling phase. The gen-set can't be started again while there is a Slow stop alarm in the Alarmlist. Activates the output Common Stp as well as the standard alarm outputs.
Off Load	2	The event appears in the Alarmlist and is recorded into the history log. It does not require confirmation, disappears by itself. It causes immediate opening of the GCB. In AUT and SEM modes the gen-set remains running for 60 seconds and then it is stopped by the standard stop sequence. In MAN mode the gen-set remains running until the operator changes it's operational state manually. If the controller is in AUT or SEM mode and all previously active Off load alarms disappeared the gen-set is automatically started back and connected to the load if the condition for the gen-set to be running persists (e.g. Rem start/stop is active ..). This event is used to put the gen-set temporarily off the load for any reason. Activates the output Common OfL.

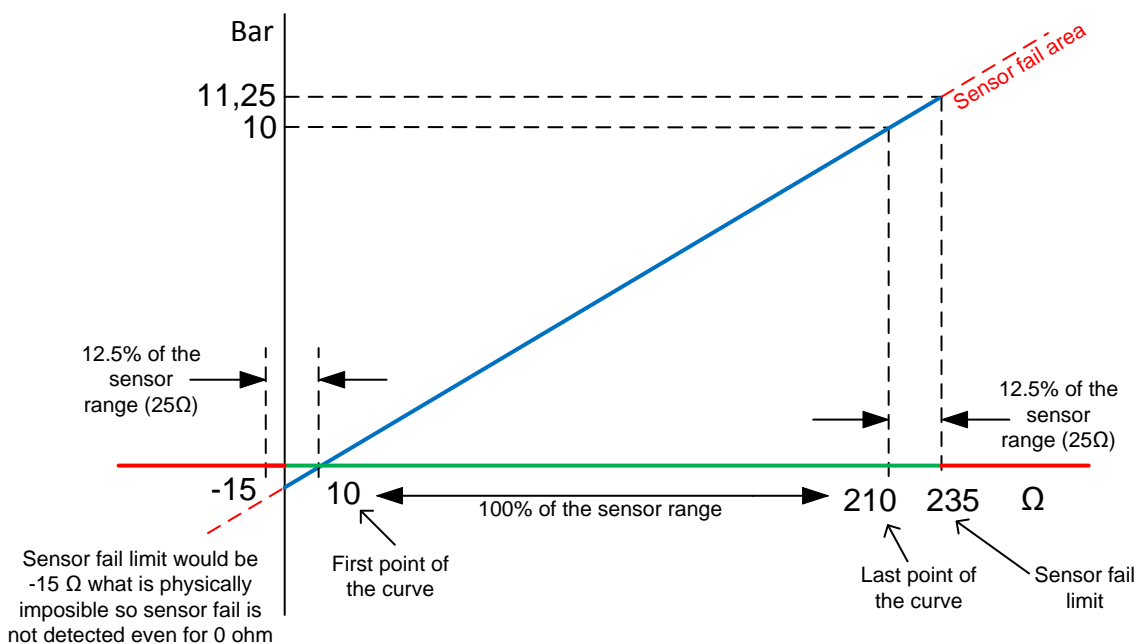
Low Power	2	<p>The event appears in the Alarmlist and is recorded into the history log. It does not require confirmation, disappears by itself.</p> <p>It causes reduction of the required gen-set load to the Min Power PtM during parallel-to-mains operation or local baseload operation.</p> <p>If all previously active Low power alarms disappeared the gen-set is automatically ramped back to the original required load, which is given according to the currently active load control mode (Load ctrl PtM) in PtM operation.</p> <p>Activates the output Common LoP.</p> <p>This alarm type is not overridden by the input Sd Override.</p> <p>Note: Available in IS-NT only.</p>
BrkOpen&CoolDn	2	<p>The event appears in the Alarmlist and is recorded into the history log. It causes immediate opening of the GCB (without unloading) and then the standard stop sequence with cooling follows.</p> <p>The gen-set can't be started again while there is a BOC alarm in the Alarmlist.</p> <p>Activates the output Common BOC as well as the standard alarm outputs.</p>
Sd Override	2	<p>The alarm appears in the Alarmlist and is recorded into the history log. It causes immediate stop of the gen-set without unloading and cooling phase.</p> <p>The gen-set can't be started again while there is a Sd override alarm in the Alarmlist.</p> <p>Activates the standard alarm outputs.</p> <p>This alarm type is not overridden by the input Sd Override.</p>

HINT

The Standard alarm outputs are Alarm and Horn.

Sensor fail detection (FLS)

If the measured resistance, voltage or current on an analog input gets out of valid range, the sensor fail will be detected and a sensor fail message will appear in the alarmlist. The valid range is defined by the most-left (R_L) and most-right (R_H) points of the sensor characteristic $\pm 12.5\%$ from $R_H - R_L$.

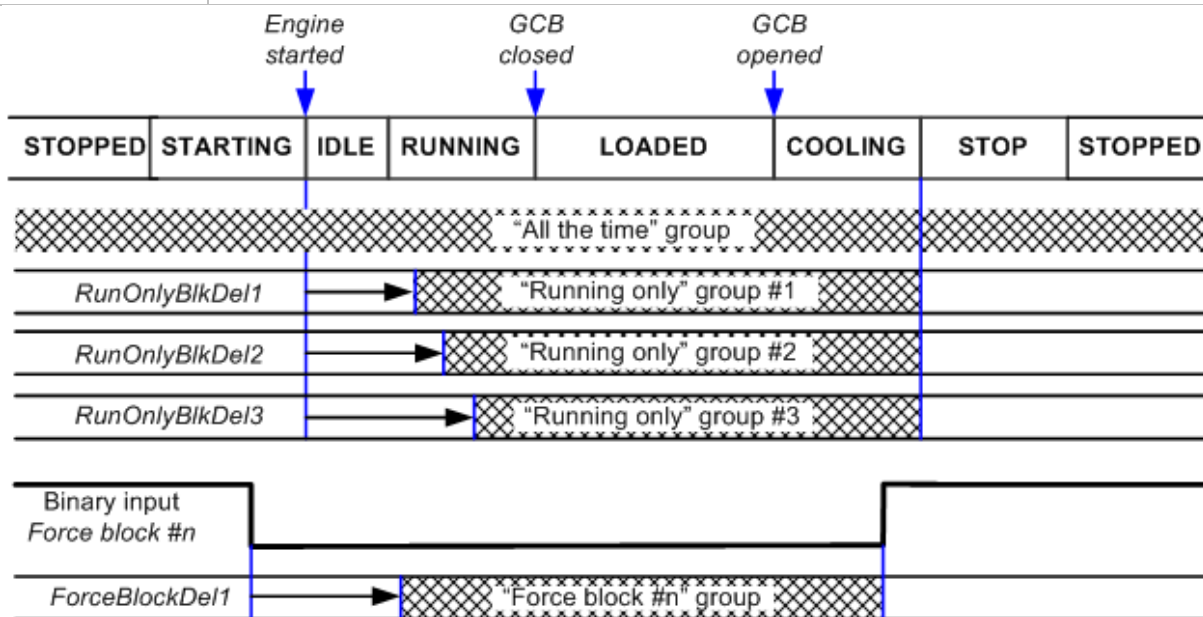



HINT

The sensor fail alarm does not influence the gen-set operation

Blocking types

BLOCKING TYPE	DESCRIPTION
All the time	The alarms are being evaluated all the time the controller is switched on.
RunOnlyBlkDel1	The alarms are being evaluated only while the gen-set is running. The evaluation begins <i>RunOnlyBlkDel1</i> seconds after the engine has been started.
RunOnlyBlkDel2	The alarms are being evaluated only while the gen-set is running. The evaluation begins <i>RunOnlyBlkDel2</i> seconds after the engine has been started.
RunOnlyBlkDel3	The alarms are being evaluated only while the gen-set is running. The evaluation begins <i>RunOnlyBlkDel3</i> seconds after the engine has been started.
Force block 1	The alarms are being evaluated while the input <i>Force block 1</i> is not active. The evaluation begins <i>ForceBlockDel1</i> seconds after the input has been deactivated.
Force block 2	The alarms are being evaluated while the input <i>Force block 2</i> is not active. The evaluation begins <i>ForceBlockDel2</i> seconds after the input has been deactivated.
Force block 3	The alarms are being evaluated while the input <i>Force block 3</i> is not active. The evaluation begins <i>ForceBlockDel3</i> seconds after the input has been deactivated.
El. prot	The alarms are being evaluated while the generator is expected to provide correct voltage and frequency. That means the alarms start to be evaluated after transition from <i>Idle</i> to <i>Running</i> phase when the period of <i>Max stab time</i> has already elapsed, remain being evaluated while the gen-set is running at nominal speed (regardless of GCB position) and stop to be evaluated by transition to the <i>Cooling</i> phase.



 Alarm group is being evaluated

Default protections in MINT

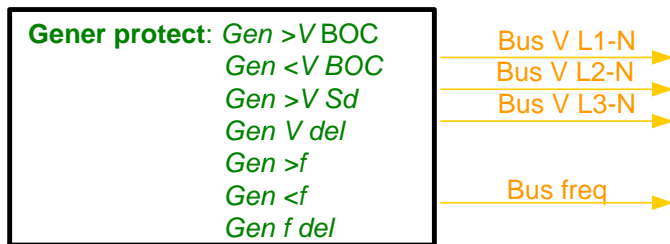
Fix – firmware based protections

ENGINE	PROTECTION TYPE	CORESPONDING SETPOINTS
Overspeed		Engine protections: <i>Overspeed</i>
Underspeed		Engine params: <i>Starting RPM</i>
GENERATOR	PROTECTION TYPE	CORESPONDING SETPOINTS
IDMT overcurrent	BOC	Basic settings: <i>Nomin current</i> ; Gener protect: <i>2Inom del</i>
IDMT Active power	BOC	Gener protect: <i>OverldStrtEval</i> ; <i>2POvrlldStrtEvDel</i>
IDMT EarthFault Current	BOC	Gener protect: <i>NomEthFltCurr</i> , <i>2EthFltCurr del</i>
Shortcurrent	BOC	Gener protect: <i>Ishort</i> ; <i>Ishort del</i>
Generator voltage: Ug1>, Ug1<, Ug2>, Ug2<, Ug3>, Ug3<	BOC	Gener protect: <i>Gen >V BOC</i> ; <i>Gen <V BOC</i> ; <i>Gen V del</i> .
Generator voltage: Ug1>>, Ug2>>, Ug3>>	Sd	Gener protect: <i>Gen >V Sd</i> ; <i>Gen V del</i> .
Generator frequency: fg<, fg>	BOC	Gener protect: <i>Gen >f</i> ; <i>Gen <f</i> ; <i>Gen V del</i>
Excitation Loss	BOC	Gener protect: <i>ExcitationLoss</i> , <i>ExctLoss del</i>
Bus	PROTECTION TYPE	CORESPONDING SETPOINTS
Bus voltage	MP	Mains protect: <i>Mains >V MP</i> ; <i>Mains <V MP</i> ; <i>Mains V del</i>
Bus frequency	MP	Mains protect: <i>Mains >f</i> ; <i>Mains <f</i> ; <i>Mains f del</i>
DEFAULT CONFIGURABLE	PROTECTION TYPE	CORESPONDING SETPOINTS
Reverse power (UnivState 1)	BOC	Gener protect: <i>Reverse power</i> ; <i>ReversePwr del</i>
Batt <V, Batt >V (UnivState 2)	Wrn	Analog protect: <i>Batt >V</i> ; <i>Batt <V</i> ; <i>Batt V del</i>
Gen Current unbalance	BOC	Gener protect: <i>Gen I unbal</i> ; <i>Gen I unb del</i>
Gen Voltage unbalance	BOC	Gener protect: <i>Gen V unbal</i> ; <i>Gen V unb del</i>
Bus Voltage unbalance	BOC	Mains protect: <i>Mains V unbal</i> ; <i>Mains V unb del</i>

Bus voltage and frequency protections - limits and indications

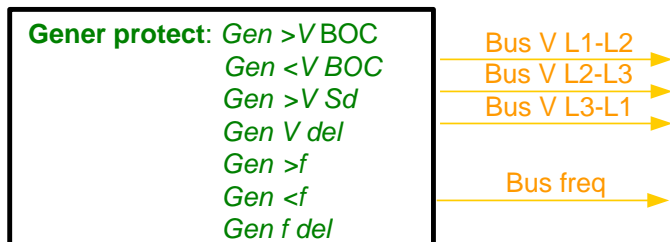
Basic settings:

VoltProtSelect = PHASE-NEUTRAL



Basic settings:

VoltProtSelect = PHASE-PHASE



Generator voltage and frequency protections - limits and indications

Basic settings:

VoltProtSelect = PHASE-NEUTRAL



Basic settings:

VoltProtSelect = PHASE-PHASE



Shutdown override

If the Binary input shutdown override (Sd override) is closed, all 2nd level protections are disabled to allow engine run in an emergency situation, e.g. sprinkler devices power supply.

All protections are shown in Alarmlist and recorded into History, but the controller doesn't stop the engine because of them. If the input is deactivated and some protections are still active or not yet reset, the controller starts to take these protections into account and consequently stops the engine.

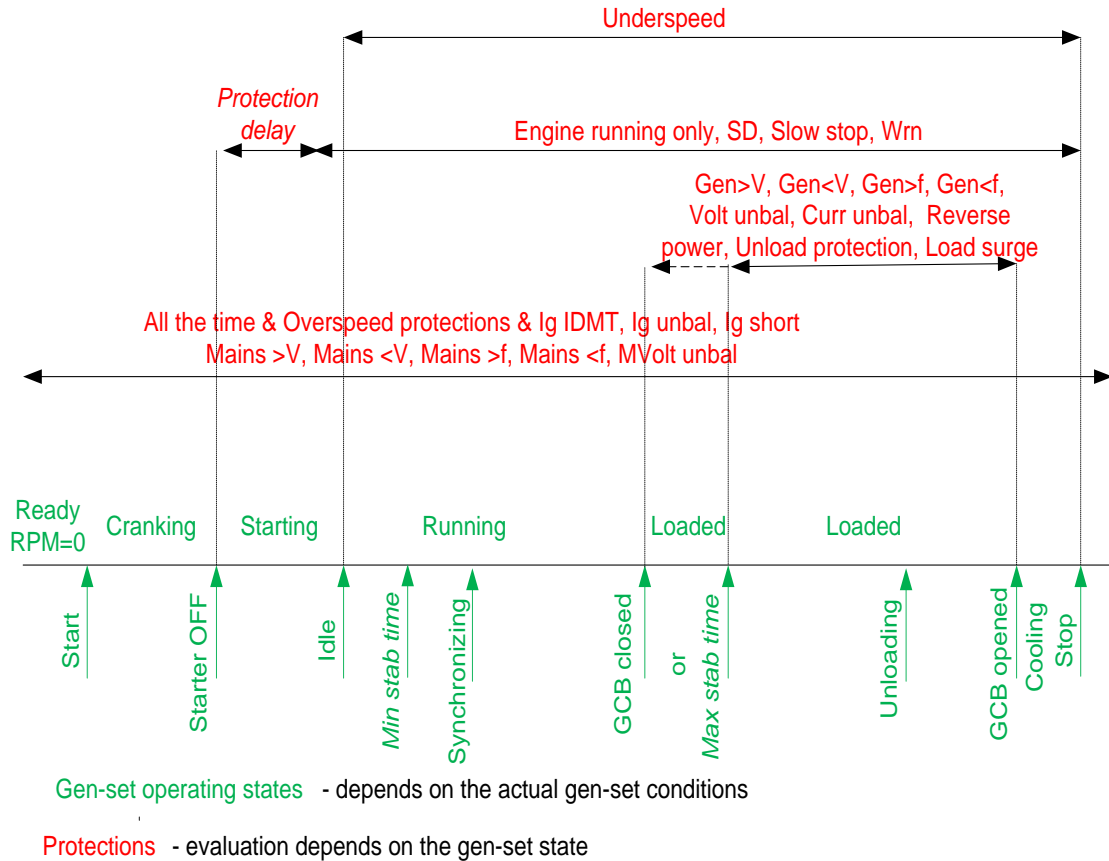
HINT

All 2nd level protections are locked out, except of these:

- Emergency stop

- Overspeed
- Underspeed (only if *Fuel solenoid* = GAS ENGINE)
- Binary and analog protections configured as *Sd override* type. In fact this protection type means "Unoverridable shutdown", i.e. it works the same way as standard shutdown protection, however it can not be overridden (blocked) by the *Sd override* input.

Alarm time chart

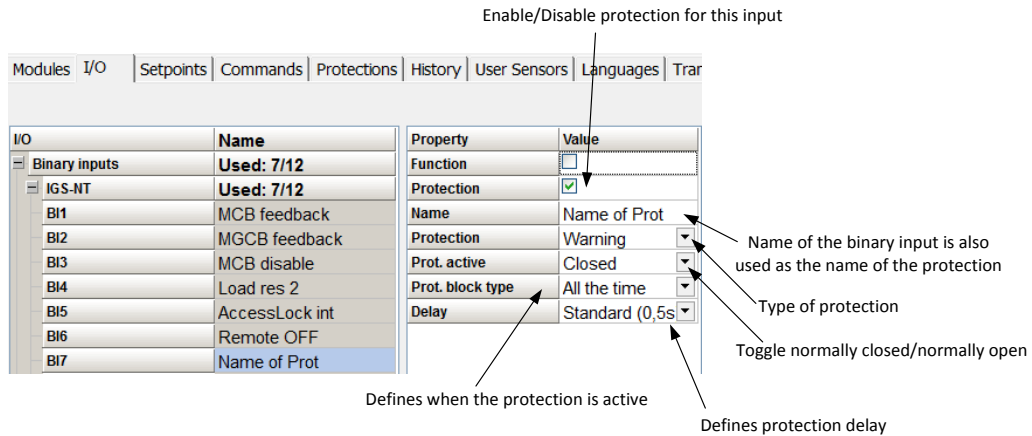


Configuration of User configurable protections in GenConfig

It is possible to configure protections on Binary Input, Analog Input or any value that is available in the controller.

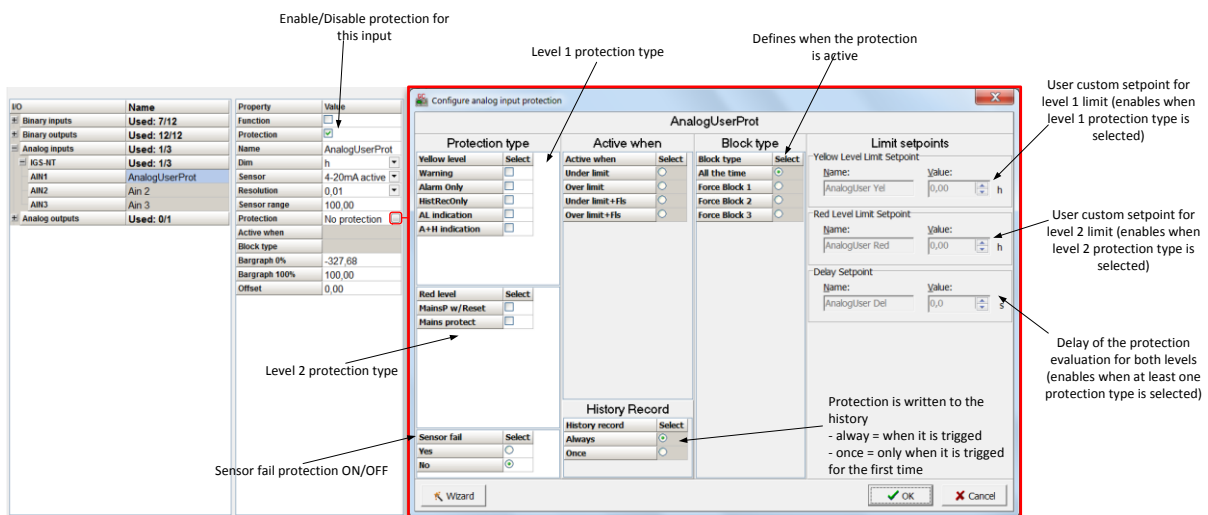
Binary Input protection configuration

Open I/O tab in GenCofig and adjust parameters that are described below.



Analog Input protection configuration

Open I/O tab in GenCofig and adjust parameters that are described below.

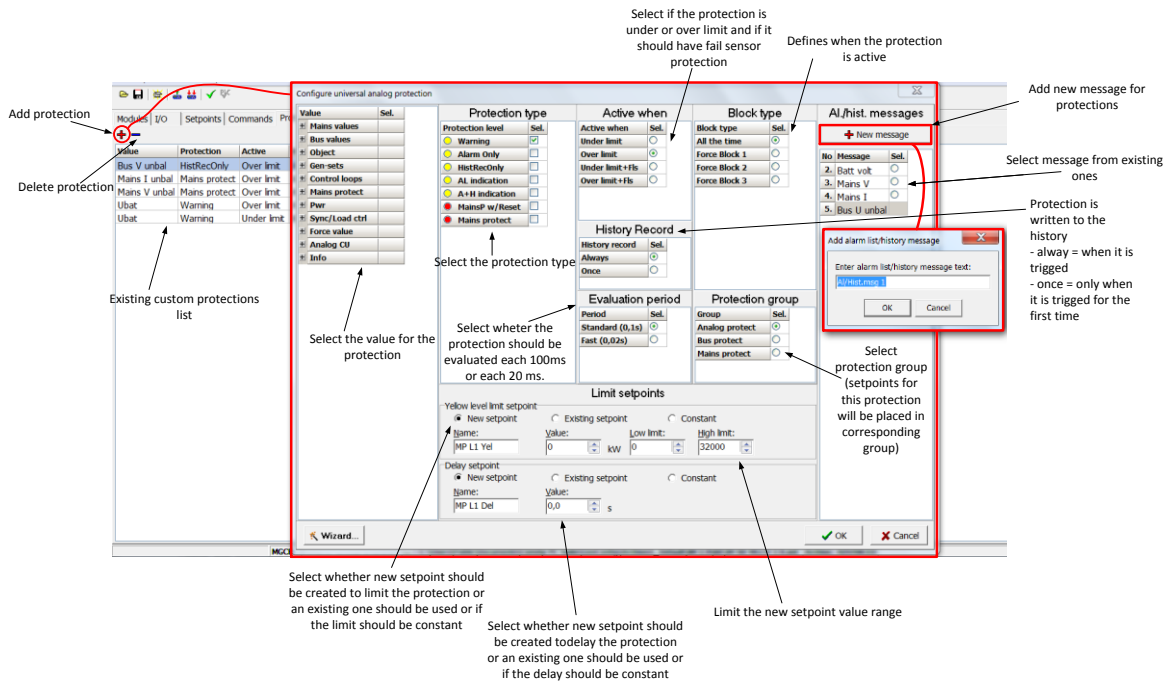


HINT

Fail Sensor protection (when activated) does not affect the function of the system itself. If you adjust "Active when" to Under limit + Fls or Over limit + Fls the protection will considered the value that is out of range (failed sensor) to be under or over limit (depending on the setting) and it will issue corresponding alarm after the delay of the protection. This can be used for example when the function of the particular sensor connected to an analog input is crucial for the operation of the system and its failure requires the system to be affected (open breakers etc.).

Custom configurable protection

Open Protections tab in GenCofig and adjust parameters that are described below.



HINT

You need to prepare two separate protections for level 1 and level 2.

Select the value for protection first and then use Wizard – it will take you through all the steps and help you adjust them correctly.

Reset Actual Alarms selection

It is possible to determine the behavior of alarms that are in alarm list when Fault Reset button is pressed. Select behavior with ComProtSetting:ResetActAlarms.

DISABLED	Pressing of the fault reset button (at any terminal or external button) resets only inactive alarms. Active alarms remain in the alarmlist unchanged and must be reset again when they become inactive.
ENABLED	Pressing of the fault reset button (at any terminal or external button) resets all alarms that are currently present in the alarm list. Inactive alarms disappear from the alarm list immediately, active alarms are changed to "confirmed" state and disappear when the alarm condition disappear or the alarm starts to be blocked.

NOTE:

ENABLED position corresponds to the method how the IG-classic and IS-classic controllers handled the alarms.

Gen-set operation states

Gen-set can operate in following states

GEN-SET STATE	DESCRIPTION
Init	Controller is powered up and configuration setting is initialized
Not ready	Gen-set is not ready to start or is not allowed to start
Ready	Gen-set is ready to run, all condition for start are fulfilled
Prestart	Prestart sequence in process. From closing of <i>Prestart</i> output to closing of <i>Starter</i> output
Cranking	Engine is cranking and the <i>starter</i> output is closed
Pause	Pause between start attempts is counting down
Starting	Starting RPM is reached
Running	Gen-set is running and waiting for GCB connection
Warming	Gen-set is running in parallel operation and gen-set load is reduced to <i>Warming load</i>
Soft load	Gen-set power is ramping up
Loaded	Gen-set is loaded
Soft unld	Gen-set power is ramping down
Cooling	State after GCB was opened and engine is not stopped
Stop	Engine is stopped
Shutdown	Shutdown alarm activated
Ventil	Gas engine – ventilation of unburned fuel when stop command comes during cranking with gas
SDVentil	Gas engine – ventilation of unburned fuel after unsuccessful start attempt
Off load	GCB is opened, gen-set keeps running on nominal RPM
Emerg man	Emergency manual state

GEN-SET OPERATION STATES

GEN-SET CONDITIONS	DESCRIPTION
IslOper	Island operation (MCB is opened, GCB is closed)
Brks Off	GCB, MCB opened
MainsOper	Mains is present (MCB is closed, GCB is opened)
Synchro	Gen-set is synchronizing (MCb is closed, GCB is opened)
ParalOper	Gen-set is in parallel with mains (MCB is closed, GCB is closed)
MainsOper/Brk Off	Engine is running idle

GEN-SET EXTERNAL CONDITIONS

Inputs and Outputs

Virtual and physical modules

Number of I/O can be extended and project wiring can be reduced using the following extension and virtual modules.

Module name	BIN	BOUT	AIN	AOUT	IMPULSE	Note
IGS-NT controller	x	x	x	x		Number of I/O depends on type.
IGS-PTM	8	8	4	1	-	Standard I/O extension module.
IS-AIN8	-	-	8	-	-	Standard I/O extension module.
IS-AIN8TC	-	-	8	-	-	8 thermocouple inputs
IS-BIN16/8	16	8	-	-	-	Standard I/O extension module.
InteliAIN8	-	-	8	-	2	
InteliAIN8TC	-	-	8	-	-	
InteliIO8/8	8	8	-	2	-	
InteliIO16/0	16	0	-	2	-	
I-CB	x	x	x	x	-	Configurable communication bridge.
IGL-RA15	-	15	-	-	-	15 Green, Red, Yellow LED panel.
I-AOUT8	-	-	-	8	-	8 Analog outputs
VPIO	8	8	-	-	-	Virtual periphery I/O module.
SHBIN	8	-	-	-	-	SHared (virtual) Binary INput module
SHBOUT	-	8	-	-	-	SHared (virtual) Binary OUTput module
SHAIN	-	-	8	-	-	SHared (virtual) Analog INput module
SHAOUT	-	-	-	8	-	SHared (virtual) Analog OUTput module
PLC	x	x	x	x	-	Programmable (internal) logic module.

HINT

For more details about Virtual peripherals (Shared and Internal virtual I/O periphery and PLC) see IGS-NT-Application guide-2.4.pdf.

CAUTION!

Usage of any 3rd-party peripheral modules in cooperation with ComAp controller is not recommended. ComAp can't guarantee the proper function of controller with none-ComAp peripheral modules.

Setpoints

Setpoints are analog, binary or special data objects, that are used for adjusting the controller to the specific environment. Setpoints are collected to groups according to their meaning. Setpoints can be adjusted from the controller front panel, PC, MODBUS etc.

Password protection

Any setpoint can be password protected - 7 levels of protection are available. There can be up to 8 users defined, each one with different access rights (levels of protection). Every user has it's own password. The password is a four-digit number. Only setpoints protected by the protection level that is covered by currently logged-in user's access rights can be modified.

If a user logs in from a particular terminal (e.g. the controller front panel), this does not unlock the other terminals for him, e.g. IntelliMonitor connected directly or via modem.

Setpoints opened from front panel are automatically closed 15 minutes (return to measurement screens) after the last setpoint change or when wrong value of password is set.

System administrator (User 0 – always present in the system) can reset the password for any other user.

The controller programming (configuration) requires the highest - password 7 level, so only User 0 is able to modify the controller configuration or firmware.

Continuous internal evaluation of setpoints validity

In case of detection of Setpoints checksum (validity) evaluation error, the Shutdown alarm "Setpoint CS error" is issued to prevent the controller to run the engine with incorrect setting. The evaluation is provided at controller startup and continuously during the standard operation. I.e. in case of detection of such error, the engine is shut down immediately.

Setpoint synchronization

Setpoints, that are marked with "#" sign at the begin of their names, are synchronized with other controllers present on the CAN bus line, i.e. the system will ensure that the respective setpoint will have identical value in each connected controller. If the setpoint is changed in one controller, the same change will occur in all other controllers. This function is necessary especially for MINT application, where the system of Power management is based on fact that the respective setpoints are identical in all controllers.

CAUTION!

Do not perform repeated writing of setpoints (e.g. power control from a PLC by repeated writing of baseload setpoint via Modbus) The setpoints are stored in EEPROM memory, which can be overwritten up to 10^5 times without risk of damage or data loss, however it may become damaged, when allowed number of writing cycles is exceeded!

List of possible events

The complete list is available in Troubleshooting guide.

Controller configuration and monitoring

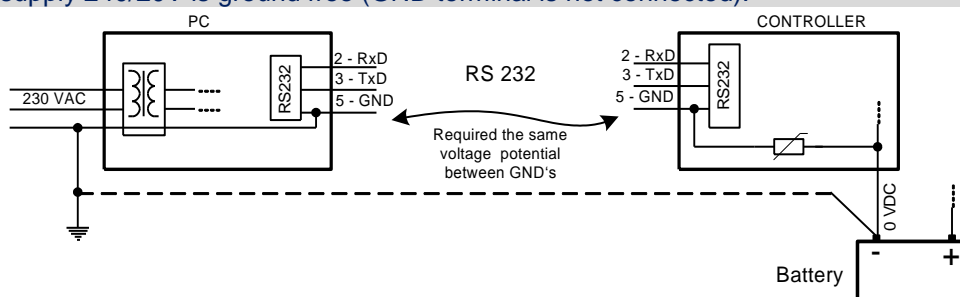
IGS-NT installation pack contains separate PC software tools: GenConfig (GC) and IntelliMonitor (IM). GC and IM are based on Windows 95/98/NT/ME/2000/XP or higher platform and require approximately 30 Mbyte of hard disc free space.

Direct connection to the PC

IGS-NT controller can be connected directly with PC via RS232 or USB interface. Use the crossed RS232 or USB cable to connect PC with controller.

HINT

Make sure the grounding system on controller and PC – COM port (negative of the PC DC supply) are identical – before the first direct connection. There must not be any voltage between these two points otherwise the internal PTC protection activates and interrupts RS232 communication. In such case disconnect RS232 line wait a minute for PTC recovery and try again. The simple solution is to assure, that the PC supply 240/20V is ground free (GND terminal is not connected).



GenConfig functions

- Extension modules addressing
- All I/O function or protection configuration
- Setpoints adjusting
- Sensor characteristics modification
- History record modification
- Password level protection modification (password value must be changed in DriveMonitor)
- Controller firmware (mhx file) upgrade
- Controller application file Up/Down load
- Language translator enables
 - Create Dictionary between two languages (Dictionary can be used repeatedly)
 - Translate current text in Controller (in any language)
 - Add new language (up to five)

Configuration steps

Following configuration steps are available in GenConfig software:

- Select Extension modules when more inputs and outputs are required
- Configure J1939 interface when Electronic engine is connected
- Configure Binary inputs as Protection or Function
- Configure Binary outputs
- Configure Analog inputs as Protection or Function
- Define user sensors
- Configure History record
- Configure password protection
- Add/Translate the language

InteliMonitor

Functions

- On-line direct, Modem or Internet single or multiple engine monitoring
- Active Modem or Internet call from the controller to PC (activated by selected Alarm)
- On-line or Off-line History record listing
- Setpoints listing and adjusting (password protected)
- Statistics value (e.g. Running hours) Set/Reset
- Password and Access code change

Modbus protocol

Standard protocol enables receive/transmit any data or command from a Master system:

- Direct connection: RS232, RS422, RS485
- Modem connection
- 9600, 19200, 38400 or 57600 bps, 8 data bits, 1 stop bit, no parity
- Transfer mode RTU
- Function 3 (Read Multiply Registers)
- Function 6 (Write Single Register)
- Function 16 (Write Multiply Registers)
- The response to an incoming message depends on the communication speed. The delay is not shorter than the time needed to send/receive 3 and ½ characters.

The complete description of Modbus communication protocol can be found in *Modbus Protocol Reference Guide PI-MBUS-300* and *Open Modbus Specification Release 1.0*. Both documents are available from web site at <http://www.modicon.com/openmbus/>.

HINT

Detail Modbus command description see in ComAp InteliCommunication guide.

Value and setpoint codes

HINT

It is possible to export actual values, setpoints and history file on-line from the controller or off-line from the archive using InteliMonitor – Monitor – Export data... function.

Technical data

HINT

Technical data of the controller and extension modules find in the IGS-NT-Installation guide-x.y.pdf.

Language support

IG-NT from display firmware version 1.4 supports following language code pages:

Code page	Language	Windows code
0	West European languages	Windows 1252
134	Chinese	GB 2312
162	Turkish	Windows 1254
129	Korean	Windows 1258
204	Russian	Windows 1251
238	East European languages	Windows 1250

IS-NT display from firmware version 1.5 supports following language code pages:

Code page	Language	Windows code
0	West European languages	Windows 1252
134	Chinese	GB 2312
162	Turkish	Windows 1254
129	Korean	Windows 1258
136	Thailand	GB 2312
204	Russian	Windows 1251
238	East European languages	Windows 1250

APPENDIX

Setpoint groups

1. [ProcessControl](#)
2. [Basic settings](#)
3. [Comms settings](#)
4. [Engine params](#)
5. [Engine protect](#)
6. [Analog protect](#)
7. [Gener protect](#)
8. [Pwr Management](#)
9. [Sync/Load ctrl](#)
10. [Volt/PF ctrl](#)
11. [Force value](#)
12. [Load shedding](#)
13. [Timer settings](#)
14. [Act. calls/SMS](#)
15. [Date/Time](#)

CAUTION!

Do not perform repeated writing of setpoints (e.g. power control from a PLC by repeated writing of baseload setpoint via Modbus) The setpoints are stored in EEPROM memory, which can be overwritten more than 10⁵ times without risk of damage or data loss, but it may become damaged, when allowed number of writing cycles is exceeded!

Setpoints - SMS/E-Mail

1. [History record](#)
2. [Alarm only](#)
3. [Warning](#)
4. [Off load](#)
5. [BrkOpen CoolDn](#)
6. [Mains protect](#)
7. [Slow stop](#)
8. [Shutdown](#)
9. [ShutdownOvr](#)
10. [AcallCH1-Type](#)
11. [AcallCH1-Addr](#)
12. [AcallCH2-Type](#)
13. [AcallCH2-Addr](#)
14. [AcallCH3-TYPE](#)
15. [AcallCH3-Addr](#)
16. [AcallCH4-TYPE](#)
17. [AcallCH4-Addr](#)
18. [AcallCH5-TYPE](#)
19. [AcallCH5-Addr](#)
20. [NumberRings AA](#)
21. [ActCallAttempt](#)
22. [Acall+SMS Lang](#)

Setpoints - Analog protect

1. [Batt >V](#)
2. [Batt <V>](#)

3. [Batt volt del](#)

Setpoints - Basic Settings

1. [Nomin Power](#)
2. [Nomin current](#)
3. [CT ratio prim](#)
4. [CT ratio sec](#)
5. [EarthFltCurCTp](#)
6. [Im3/ErFICurCTs](#)
7. [VT ratio](#)
8. [Vg InpRangeSel](#)
9. [Vb VT ratio](#)
10. [Vm InpRangeSel](#)
11. [GenNomV](#)
12. [GenNomVph-ph](#)
13. [BusNomV](#)
14. [BusNomVph-ph](#)
15. [FixVoltProtSel](#)
16. [Nominal Freq](#)
17. [Nom frq offset](#)
18. [Gear Teeth](#)
19. [Nominal RPM](#)
20. [ControllerMode](#)
21. [FltRes GoToMAN](#)
22. [Local buttons](#)
23. [DispBaklightTO](#)
24. [DispBkIStrtOff](#)
25. [FastHistPeriod](#)
26. [ConvCoefPulse1](#)
27. [ConvCoefPulse2 \(for IS-NT only\)](#)
28. [ConvCoefPulse3 \(for IS-NT only\)](#)
29. [ConvCoefPulse4 \(for IS-NT only\)](#)

Setpoints - Comms settings

1. [Gen-set name](#)
2. [Contr. address](#)
3. [RS232\(1\) mode](#)
4. [RS232\(2\) mode](#)
5. [RS232\(1\)MBCSpd](#)
6. [RS232\(2\)MBCSpd](#)
7. [RS232\(1\)Mdmlni](#)
8. [RS485\(1\) conv.](#)
9. [RS485\(2\) conv.](#)
10. [RS232\(2\)Mdmlni](#)
11. [CAN bus mode](#)
12. [CAN2emptDetect](#)
13. [LB/UART Log](#)
14. [CANAddrSwitch1](#)
15. [CANAddrSwitch2](#)
16. [IP Addr mode](#)
17. [IP address](#)
18. [Net mask](#)
19. [Gateway IP](#)
20. [ComApProtoPort](#)
21. [AirGate](#)
22. [AirGate IP](#)

23. [SMTP authent](#)
24. [SMTP user name](#)
25. [SMTP password](#)
26. [SMTP address](#)
27. [Contr mailbox](#)
28. [Time zone](#)
29. [DNS IP](#)
30. [ECU Diag](#)
31. [SHxOcol detect](#)

Setpoints - Date/Time

1. [Time stamp act](#)
2. [Time Stamp Per](#)
3. [#SummerTimeMod](#)
4. [#Time](#)
5. [#Date](#)

Setpoints - Engine Params

1. [Starting RPM](#)
2. [Starting POil](#)
3. [Prestart time](#)
4. [Prelubr time](#)
5. [Prelubr pause](#)
6. [MaxCrank time](#)
7. [CrnkFail pause](#)
8. [Crank attempts](#)
9. [Idle time](#)
10. [Min stab time](#)
11. [Max stab time](#)
12. [Warming load](#)
13. [Warming temp](#)
14. [Max warm time](#)
15. [Cooling speed](#)
16. [Cooling time](#)
17. [CoolDnAfterBOC](#)
18. [Cooldown optim](#)
19. [AfterCool time](#)
20. [Stop time](#)
21. [SDVentil time](#)
22. [Fuel solenoid](#)
23. [FuelSol offset](#)
24. [D+ Function](#)
25. [Bin selector 1](#)
26. [Bin selector 2](#)
27. [Bin selector 3](#)
28. [Bin selector 4](#)
29. [MaxLevelDrop](#)

Setpoints - Engine Protect

1. [Horn timeout](#)
2. [RunOnlyBlkDel1](#)
3. [RunOnlyBlkDel2](#)
4. [RunOnlyBlkDel3](#)

5. [BinInp delay 1](#)
6. [BinInp delay 2](#)
7. [BinInp delay 3](#)
8. [ForceBlockDel1](#)
9. [ForceBlockDel2](#)
10. [ForceBlockDel3](#)
11. [ResetActAlarms](#)
12. [Overspeed](#)
13. [Service time 1](#)
14. [Service time 2](#)
15. [Service time 3](#)
16. [Service time 4](#)
17. [Max+CylDifPmin\(for IS-NT only\)](#)
18. [Max-CylDifPmin\(for IS-NT only\)](#)
19. [Max+CylDifPnom\(for IS-NT only\)](#)
20. [Max-CylDifPnom\(for IS-NT only\)](#)
21. [PminCylDifEval\(for IS-NT only\)](#)
22. [CylDifEvalDel\(for IS-NT only\)](#)

Setpoints - Force value

1. [Force value 1](#)
2. [Force value 2](#)
3. [Force value 3](#)
4. [Force value 4](#)
5. [Force value 5](#)
6. [Force value 6](#)
7. [Force value 7](#)
8. [Force value 8](#)
9. [Force value 9](#)
10. [Force value 10](#)
11. [Force value 11](#)
12. [Force value 12](#)
13. [Force value 13](#)
14. [Force value 14](#)
15. [Force value 15](#)
16. [Force value 16](#)
17. [ExtValue1LoLim](#)
18. [ExtValue2LoLim](#)
19. [ExtValue3LoLim](#)
20. [ExtValue4LoLim](#)
21. [ExtValue1HiLim](#)
22. [ExtValue2HiLim](#)
23. [ExtValue3HiLim](#)
24. [ExtValue4HiLim](#)
25. [ExtValue1 rate](#)
26. [ExtValue2 rate](#)
27. [ExtValue3 rate](#)
28. [ExtValue4 rate](#)
29. [ExtValue1deflt](#)
30. [ExtValue2deflt](#)
31. [ExtValue3deflt](#)
32. [ExtValue4deflt](#)

Setpoints - Gener Protect

1. [OverldStrtEval](#)
2. [2PovrldStEvDel](#)

3. [Min Power PtM](#)
4. [Ishort](#)
5. [Ishort del](#)
6. [2Inom del](#)
7. [Gen >V BOC](#)
8. [Gen <V BOC](#)
9. [Gen >V Sd](#)
10. [Gen V del](#)
11. [Gen >f](#)
12. [Gen <f](#)
13. [Gen f del](#)
14. [BusMeasError](#)
15. [Reverse power](#)
16. [ReversePwr del](#)
17. [ExcitationLoss](#)
18. [ExctLoss del](#)
19. [EarthFaultCurr](#)
20. [EthFitCurr del](#)
21. [Gen V unbal](#)
22. [Gen V unb del](#)
23. [Gen I unbal](#)
24. [Gen I unb del](#)
25. [Bus V unbal](#)
26. [Bus V unb del](#)

Setpoints - Load shedding

1. [Ld shed active](#)
2. [Ld shed level](#)
3. [Ld shed delay](#)
4. [Ld recon level](#)
5. [Ld recon delay](#)
6. [AutoLd recon](#)

Setpoints - Power Management

1. [Pwr management](#)
2. [#Pwr mgmt mode](#)
3. [Priority](#)
4. [#PriorityAutoSwap](#)
5. [Priority ctrl](#)
6. [#SysAMFstrtdel](#)
7. [#SysAMFstopDel](#)
8. [#LoadResStrt 1](#)
9. [#LoadResStop 1](#)
10. [#LoadResStrt 2](#)
11. [#LoadResStop 2](#)
12. [#LoadResStrt 3](#)
13. [#LoadResStop 3](#)
14. [#LoadResStrt 4](#)
15. [#LoadResStop 4](#)
16. [##LdResStrt 1](#)
17. [##LdResStop 1](#)
18. [##LdResStrt 2](#)
19. [##LdResStop 2](#)
20. [##LdResStrt 3](#)
21. [##LdResStop 3](#)
22. [##LdResStrt 4](#)

23. [#%LdResStop 4](#)
24. [#NextStrt del](#)
25. [#OverldNextDel](#)
26. [#NextStopDel](#)
27. [#SlowStopDel](#)
28. [#MinRunPower 1](#)
29. [#MinRunPower 2](#)
30. [#MinRunPower 3](#)
31. [RunHoursBase](#)
32. [#RunHrsMaxDiff](#)
33. [#PwrBandContr1](#)
34. [#PwrBandContr2](#)
35. [#PwrBandContr3](#)
36. [#PwrBandContr4](#)
37. [#PwrBnChngDIUp](#)
38. [#PwrBnChngDIDn](#)
39. [Control group](#)
40. [GroupLinkLeft](#)
41. [GroupLinkRight](#)

Setpoints - Process Control

1. [#SysBaseLoad](#)
2. [LocalBaseload](#)
3. [#SysPwrFactor](#)
4. [#SysLdCtrl PtM](#)
5. [#SysPFctrl PtM](#)
6. [SysBaseLdMode](#)
7. [SysBasePFMode](#)
8. [Derating1 strt \(IS-NT only\)](#)
9. [Derating2 strt \(IS-NT only\)](#)
10. [Derating1 end \(IS-NT only\)](#)
11. [Derating2 end \(IS-NT only\)](#)
12. [Derated1 pwr \(IS-NT only\)](#)
13. [Derated2 pwr \(IS-NT only\)](#)
14. [#Neutral cont](#)
15. [Watched contr](#)

Setpoints - Sync/load Ctrl

1. [SpeedRegChar](#)
2. [Voltage window](#)
3. [GtoM AngleReg](#)
4. [Dwell time](#)
5. [Freq gain](#)
6. [Freq int](#)
7. [Freq reg loop](#)
8. [Angle gain](#)
9. [Speed gov bias](#)
10. [SpdGovPWM rate](#)
11. [SpeedGovLowLim](#)
12. [SpeedGovHiLim](#)
13. [TauSpeedActuat](#)
14. [Load ramp](#)
15. [Load gain](#)
16. [Load int](#)
17. [RampStartLevel](#)
18. [GCB open level](#)

19. [GCB open del](#)
20. [Sync timeout](#)
21. [LS gain](#)
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Setpoints - Timer settings

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2. [TimerChannel 2](#)
3. [TimerChannel 3](#)
4. [TimerChannel 4](#)
5. [TimerChannel 5](#)
6. [TimerChannel 6](#)
7. [TimerChannel 7](#)
8. [TimerChannel 8](#)
9. [TimerChannel 9](#)
10. [TimerChannel 10](#)
11. [TimerChannel 11](#)
12. [TimerChannel 12](#)
13. [TimerChannel 13](#)
14. [TimerChannel 14](#)
15. [TimerChannel 15](#)
16. [TimerChannel 16](#)

Setpoints - Volt/PF Control

1. [AVRRegChar](#)
2. [Voltage gain](#)
3. [Voltage int](#)
4. [PF gain](#)
5. [PF int](#)
6. [AVR DCout bias](#)
7. [VS gain](#)
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9. [TauVoltActuat](#)

Value groups

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2. [Bin inputs CU](#)
3. [Bin outputs CU](#)
4. [Engine values](#)
5. [Force value](#)
6. [Gener values](#)
7. [Info](#)
8. [Log Bout](#)
9. [Load shedding](#)
10. [Bus values](#)
11. [Power management](#)
12. [Statistics](#)
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Values group - Analog CU

1. [Ubat](#)
2. [CPU temp](#)
3. [D+](#)
4. [AIN CU-1](#)
5. [AIN CU-2](#)
6. [AIN CU-3](#)
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Values group - Bin inputs CU

1. [BIN](#)

Values group - Bin outputs CU

1. [BOUT](#)

Values group - Engine values

1. [RPM](#)
2. [T Cyl aver](#)
3. [T Cyl max](#)
4. [T Cyl min](#)

Values group - Force value

1. [ExtValue1](#)
2. [ExtValue2](#)
3. [ExtValue3](#)
4. [ExtValue4](#)

Values group - Gener values

1. [Act power](#)
2. [Act pwr L1](#)
3. [Act pwr L2](#)
4. [Act pwr L3](#)
5. [React power](#)
6. [React pwr L1](#)
7. [React pwr L2](#)
8. [React pwr L3](#)
9. [Appar pwr](#)
10. [Appar pwr L1](#)
11. [Appar pwr L2](#)
12. [Appar pwr L3](#)
13. [Pwr factor](#)
14. [Load char](#)
15. [Pwr factor L1](#)
16. [Load char L1](#)
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18. [Load char L2](#)
19. [Pwr factor L3](#)
20. [Load char L3](#)
21. [Gen freq](#)
22. [Gen V L1-N](#)
23. [Gen V L2-N](#)
24. [Gen V L3-N](#)
25. [Gen V](#)
26. [Gen curr L1](#)
27. [Gen curr L2](#)
28. [Gen curr L3](#)
29. [Gen V unbal](#)
30. [Gen I unbal](#)
31. [Slip freq](#)
32. [Angle](#)

Values group - Info

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2. [SW version](#)
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18. [AccessLock D#3 \(for IS-NT only\)](#)
19. [AccessLock ext](#)
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21. [Remote MAN](#)
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Table of setpoints

Group: ProcessControl

Setpoint: #SysBaseLoad

Group	Process Control
Range [units]	0 .. 65000 [kW]
Related FW	3.0
Description	This setpoint is used to adjust the requested load for the whole gen-set group in <i>system baseload</i> mode (i.e. #SysLdCtrl PtM = BASELOAD). Each gen-set takes proportionally equal part of this total required value. The number of running gen-sets is resolved by the power management function according to the requested total load, gen-sets nominal power and adjusted reserves.

Setpoint: LocalBaseload

Group	Process control
Range [units]	OFF, 1 .. Nomin power [kW]
Related FW	3.0
Force value possible	YES
Description	This setpoint is used to adjust local baseload level. The gen-set maintains this load instead of performing proportional load sharing whenever the total load is high enough. Load variations are then equalized by the gen-sets with lower priority (higher number) or by gen-sets with local baseload switched off. If the setpoint is adjusted to 0 (OFF) the function is off. Description of the function is available in the chapter Local baseload .

Setpoint: #SysPwrFactor

Group	Process Control
Range [units]	0.60 .. 1.20 [-]
Related FW	3.0
Description	The setpoint is used for adjusting the requested gen-set power factor during the parallel-to-mains operation if #SysPFCtrl PtM = BASEPF and also during the local baseload operation. Values 0.60 – 0.99 correspond to inductive PF (0.60L - 0.99L), 1.01 – 1.20 correspond to capacitive PF (0.99C - 0.80C).
	<p>NOTE: # sign in the name of this setpoint marks that this setpoint is shared among all controllers connected by CAN2 bus.</p>

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Setpoint: #SysLdCtrl PtM

Group	Process Control
Range [units]	BASELOAD, LDSHARING [-]
Related FW	3.0
Description	<p>This setpoint is used to adjust the power control mode in parallel-to-mains operation.</p> <ul style="list-style-type: none"> • BASELOAD: The gen-set is controlled by the load control loop (i.e. as in SPtM) to provide constant proportional part of the requested system baseload (see SysBaseLdMode). The proportional parts of all running gen-sets are equal relative to their nominal power. • LDSHARING: The gen-set load controlled by the load sharing loop as in island operation. This option is intended only for systems with IntelliMains, where the IntelliMains controls the power of the group via the load sharing line (e.g. in Import/Export mode).

Setpoint: #SysPFCtrl PtM

Group	Process Control
Range [units]	BASEPF, VSHARING [-]
Related FW	3.0
Description	<p>This setpoint is used to adjust the power factor control mode in parallel-to-mains operation.</p> <ul style="list-style-type: none"> • BASEPF: The gen-set power factor is controlled to a preadjusted level #SysPwrFactor. • VSHARING: The power factor is equalized with other gen-sets according to the actual reactive load. <p>NOTE: If the power factor control mode is switched to VSHARING the load control mode must be switched to LDSHARING.</p>

Setpoint: SysBaseLdMode

Group	Process control
Range [units]	INTERNAL, EXTERNAL [-]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint selects from where the System Base load value is taken if the load control mode in parallel-to-mains operation is switched to baseload (i.e. #SysLdCtrl PtM = BASELOAD).</p>

INTERNAL	The baseload is adjusted by the setpoint #SysBaseLoad .
EXTERNAL	The baseload is adjusted by the logical (functional) analog input MLC:AnExSysBld .
NOTE: If the external source is selected the logical analog input must be configured at each gen-set to the identical source. The <i>shared peripheral modules</i> can be used to distribute the value over the controllers via the CAN2 bus.	
<ul style="list-style-type: none"> • One controller measures the value physically on it's analog input and the function MLC:AnExSysBld is configured onto this physical input. But the value is also being transmitted from this controller to the CAN bus via one shared analog output (e.g. SHAOUT #1.1). • The other controllers reads the value from their shared analog inputs (e.g. SHAIN #1.1) and the function MLC:AnExSysBld is configured onto these shared inputs. • The transmitting controller must be always switched on! 	

Setpoint: SysBasePFMode

Group	Process control				
Range [units]	INTERNAL, EXTERNAL [-]				
Related FW	3.0				
Force value possible	YES				
Description	<p>This setpoint selects from where the System Power Factor value is taken if the PF control mode in parallel-to-mains operation is switched to BasePF (i.e. #SysPFCtrl PtM = BASEPF).</p> <table border="1"> <tr> <td style="background-color: #cccccc;">INTERNAL</td> <td>The required power factor is adjusted by the setpoint #SysPwrFactor.</td> </tr> <tr> <td style="background-color: #cccccc;">EXTERNAL</td> <td>The baseload is adjusted by the logical (functional) analog input MPF:AnExSysBPF.</td> </tr> </table> <p>NOTE: If the external source is selected the logical analog input must be configured at each gen-set to the identical source. See the note at the setpoint SysBaseLdMode.</p>	INTERNAL	The required power factor is adjusted by the setpoint #SysPwrFactor .	EXTERNAL	The baseload is adjusted by the logical (functional) analog input MPF:AnExSysBPF .
INTERNAL	The required power factor is adjusted by the setpoint #SysPwrFactor .				
EXTERNAL	The baseload is adjusted by the logical (functional) analog input MPF:AnExSysBPF .				

Setpoint: Derating1 strt

Group	Process control
Range [units]	-32000 .. +32000 [x]
Related FW	3.0

Force value possible	YES
Description	<p>This setpoint is used for adjusting the starting point of the <i>Power derating 1</i> function, where the gen-set nominal power is still 100% of the setpoint Nomin power.</p> <p>See the chapter Power derating for details.</p> <p>NOTE: The setpoint actual physical dimension depends on configuration of the physical analog input to which the logical input PowerDerating1 is assigned.</p>

Setpoint: Derating1 end

Group	Process control
Range [units]	-32000 .. +32000 [x]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used for adjusting the end point of the <i>Power derating 1</i> function, where the gen-set nominal power is reduced to the value adjusted by setpoint Derated1 pwr.</p> <p>See the chapter Power derating for details.</p> <p>NOTE: The setpoint actual physical dimension depends on configuration of the physical analog input to which the logical input PowerDerating1 is assigned.</p>

Setpoint: Derated1 pwr

Group	Process control
Range [units]	0 .. 100 [%]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used for adjusting the final power level for the <i>Power derating 1</i> function. The nominal power is not reduced below this setpoint even if the respective analog input increases further.</p> <p>See the chapter Power derating for details.</p>

Setpoint: Derating2 str

Group	Process control
Range [units]	-32000 .. +32000 [x]

Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used for adjusting the starting point of the <i>Power derating 2</i> function, where the gen-set nominal power is still 100% of the setpoint Nomin power.</p> <p>See the chapter Power derating for details.</p> <p>NOTE: The setpoint actual physical dimension depends on configuration of the physical analog input to which the logical input PowerDerating2 is assigned.</p>

Setpoint: Derating2 end

Group	Process control
Range [units]	-32000 .. +32000 [x]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used for adjusting the end point of the <i>Power derating 2</i> function, where the gen-set nominal power is reduced to the value adjusted by setpoint Derated2 pwr.</p> <p>See the chapter Power derating for details.</p> <p>NOTE: The setpoint actual physical dimension depends on configuration of the physical analog input to which the logical input PowerDerating1 is assigned.</p>

Setpoint: Derated2 pwr

Group	Process control
Range [units]	0 .. 100 [%]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used for adjusting the final power level for the <i>Power derating 2</i> function. The nominal power is not reduced below this setpoint even if the respective analog input increases further.</p> <p>See the chapter Power derating for details.</p>

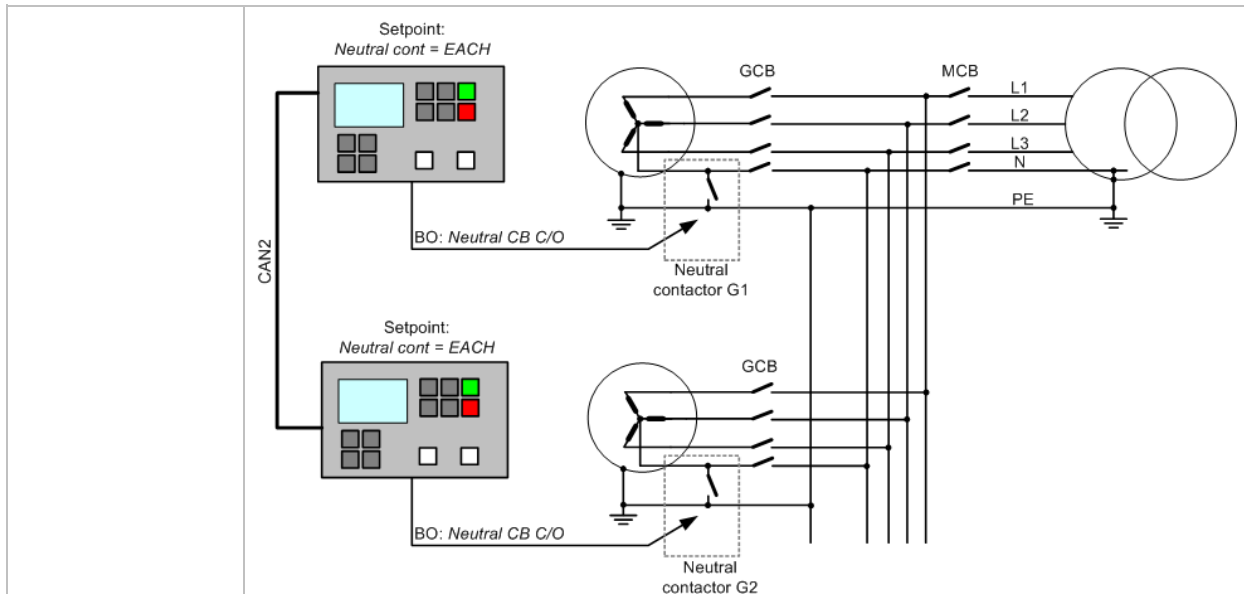
Setpoint: Synchro enable

Group	Process Control
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Range [units]	NONE, FORWARD, REVERSE, BOTH [-]
Related FW	3.0
Force value possible	YES
Description	<p>The setpoint is used for enable/disable forward and reverse synchronization.</p> <ul style="list-style-type: none"> • NONE: No synchronizing is enabled. • FORWARD: GCB synchronizing is enabled. • REVERSE: MCB synchronizing is enabled. • BOTH: GCB and MCB synchronizing are enabled. <p>NOTE: Although synchronizing of the particular breaker is disabled the breaker can be closed to a "dead" (voltage-free) bus.</p> <p>NOTE: See table with examples in the description of the setpoint MFStart enable.</p>

Setpoint: #Neutral cont

Group	Process control
Range [units]	EACH, COMMON [-]
Related FW	3.0
Description	<p>The setpoint is used for adjusting the behavior of the Neutral CB C/O output according to actual site wiring.</p> <p>The neutral contactor is used to connect the neutral wire (N) with the protective wire (PE) in a TN-S system. This connection must exist in one moment at one point of the circuit only.</p> <p>The EACH option should be used if each gen-set has it's own neutral contactor. Four-pole GCB must be used for this case.</p> <ul style="list-style-type: none"> • The output is always opened while the gen-set is not running. • The output is always opened while the MCB is closed. • While the gen-set is running and GCB is open, the output closes when generator voltage in at least one phase exceeds 85% of the nominal voltage. It opens when the generator voltage in all phases drops below 50% of the nominal voltage. • While the gen-set is running, MCB is open and GCB is closed, then the position of the output is given by an internal algorithm, which ensures, that always exactly one gen-set connected to the bus has the neutral contactor closed. <p>NOTE: Functional CAN2 communication between the controllers is required for this function.</p>



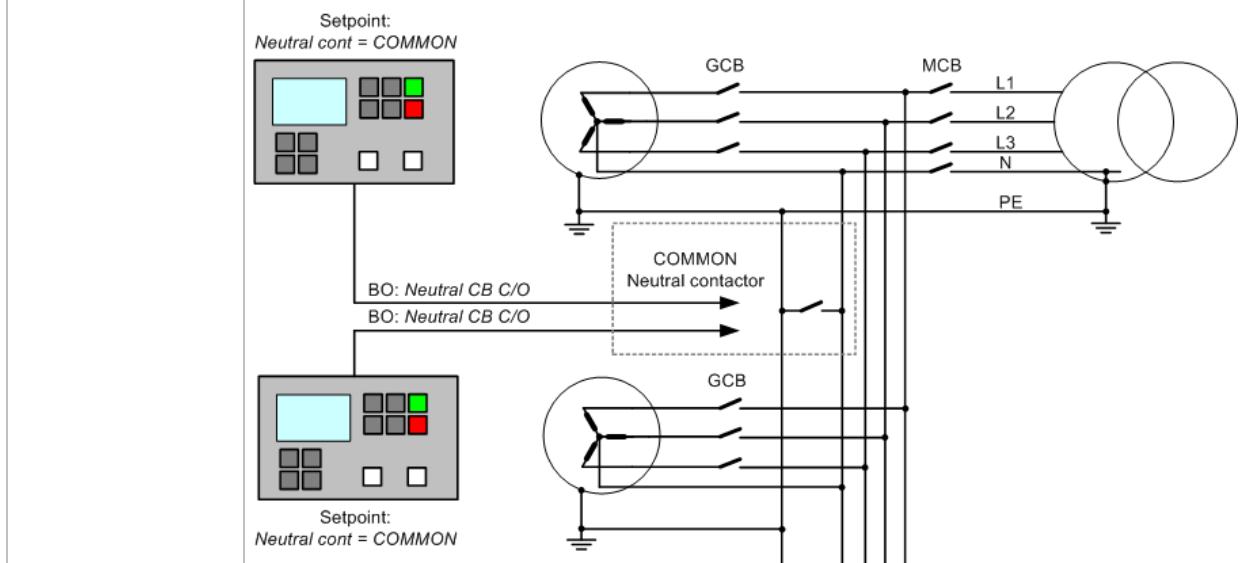
PRINCIPAL SCHEME OF A SITE IF NEUTRAL CONT = EACH

The **COMMON** option should be used if there is one common neutral contactor for the whole site. The outputs [Neutral CB C/O](#) from all controllers are combined together and the combined signal is used to control the breaker. Three-pole GCB must be used for this case.

- The output is always opened while the gen-set is not running.
- The output is always opened while the MCB is closed.
- While the gen-set is running the output closes when generator voltage in at least one phase exceeds 85% of the nominal voltage. It opens when the generator voltage in all phases drops below 50% of the nominal voltage. That means if at least one gen-set in the site is running and having proper voltage, the neutral breaker is closed.

NOTE:

If there are more logical groups the "common" option is related to the group. That means one common neutral contactor is expected for each group.



PRINCIPAL SCHEME OF A SITE IF NEUTRAL CONT = COMMON

	<p>NOTE: As there is always a connection between the N and PE wires at the mains side the generator neutral contactors are always open when the mains breaker is closed.</p>
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Setpoint: WatchedContr

Group	Process Control
Range [units]	0 .. 16 [min]
Related FW	3.0
Description	This setpoint is used at redundant controller to specify the address of the related main controller in CAN-based redundant systems . Adjust this setpoint to 0 if the controller is not used as redundant or if wired redundancy system is used.

Group: Basic settings

Setpoint: Nomin Power

Group	Basic Settings
Range [units]	1 .. 32000 [kW]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used for adjusting the gen-set nominal (rated) power, i.e. the maximum allowed gen-set power level.</p> <p>IS-NT controllers provide two independent <i>power derating</i> functions, which can be used for derating of the gen-set according to an analog value (e.g. temperature). See the setpoints Derating1 str and Derating2 str.</p> <p>The nominal power or derated nominal power is used as the basis (100%) for gen-set power protections, as the upper limit of the requested power in the parallel-to-mains operation, for power management and other functions.</p> <p>NOTE: The actual setpoint units and range depend on setting of the Power format in GenConfig.</p>

Setpoint: Nomin current

Group	Basic Settings
Range [units]	1 .. 10000 [A]
Related FW	3.0
Force value possible	YES

Description	<p>This setpoint is used for adjusting the generator nominal current.</p> <p>The nominal current is used as the basis (100%) for generator thermal-overcurrent protection (2Inom del), and for short current protection (Ishort).</p> <p>NOTE: The setpoints CT ratio prim and CT ratio sec must be adjusted properly to obtain correct generator current readings.</p> <p>CAUTION! The maximum measurable input current to the controller current terminals is 11A.</p> <p>WARNING! Do not disconnect the CT terminals from the controller while there is nonzero current in the CT primary circuit!</p>
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Setpoint: CT ratio prim

Group	Basic Settings
Range [units]	1 .. 15000 [A]
Related FW	3.0
Description	Nominal current of the primary side of the generator current transformers. The secondary side is adjusted by setpoint CT ratio sec .

Setpoint: CT ratio sec

Group	Basic settings
Range [units]	/5A, /1A [-]
Related FW	3.0
Description	<p>Nominal current of the secondary side of the generator current transformers. The primary side is adjusted by setpoint CT ratio prim.</p> <p>NOTE: The CT secondary nominal current is adjustable only in IG-NTC and IS-NT. The IG-NT has the CT secondary nominal current adjusted fixedly to 5A regardless of this setpoint.</p>

Setpoint: EarthFltCurCTp

Group	Basic settings
Range [units]	1 .. 15000 [A]
Related FW	3.0
Description	<p>Nominal current of the primary side of the current transformer connected to the controller terminals labeled <i>IN</i>. The secondary side is adjusted by setpoint EarthFltCurCTs.</p> <p>NOTE:</p>

	The <i>IN</i> terminals are used for measurement of earth fault current.
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Setpoint: *Im3/ErFICurCTs*

Group	Basic settings
Range [units]	/5, /1 [A]
Related FW	3.0
Description	<p>Nominal current of the secondary side of the current transformer connected to the controller terminals labeled <i>IN</i>. The primary side is adjusted by setpoint Im3/ErFICurCTp.</p> <p>NOTE: The <i>IN</i> terminals can be used either for measurement of earth current or mains current (mains import). See also the setpoint I/E-Pm meas.</p> <p>NOTE: The CT secondary nominal current is adjustable only in IG-NTC and IS-NT. The IG-NT has the CT secondary nominal current adjusted fixedly to 5A regardless of this setpoint.</p>

Setpoint: *VT ratio*

Group	Basic Settings
Range [units]	0.1 .. 500.0 [V/V]
Related FW	3.0
Description	<p>The setpoint is used to adjust the generator voltage transformers ratio.</p> <p>NOTE: Adjust the setpoint to the value of 1.0 if the generator voltage is connected directly to the controller terminals, i.e. without transformers.</p> <p>NOTE: Example: if you have transformers with ratio 6000/100V adjust the setpoint to the value of 60.0.</p> <p>NOTE: The range of the generator voltage inputs must be adjusted properly. See the setpoint Vg InpRangeSel.</p>

Setpoint: *Vg InpRangeSel*

Group	Basic settings
Range [units]	277V, 120V [-]
Related FW	3.0
Description	This setpoint selects the range of the generator voltage terminals. The 120V range is available only in IG-NTC and IS-NT. The IG-NT has the range adjusted

	<p>fixedly to 277V regardless of this setpoint.</p> <p>NOTE: The 277V range is suitable for both European (230V) and American (277V) measurement. The range 120V is intended for high-voltage applications where voltage transformers with 100V secondary range are used or for alternative American (120V) measurement.</p>
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Setpoint: Vb VT ratio

Group	Basic Settings
Range [units]	0.1 .. 500.0 [V/V]
Related FW	3.0
Description	<p>The setpoint is used to adjust the bus voltage transformers ratio.</p> <p>NOTE: See all notes mentioned above.</p>

Setpoint: Vm InpRangeSel

Group	Basic settings
Range [units]	277V, 120V [-]
Related FW	3.0
Description	<p>This setpoint selects the range of the mains voltage terminals. The 120V range is available only in IG-NTC and IS-NT. The IG-NT has the range adjusted fixedly to 277V regardless of this setpoint.</p> <p>NOTE: The 277V range is suitable for both European (230V) and American (277V) measurement. The range 120V is intended for high-voltage applications where voltage transformers with 100V secondary range are used or for alternative American (120V) measurement.</p>

Setpoint: Vb InpRangeSel

Group	Basic settings
Range [units]	277V, 120V [-]
Related FW	3.0
Description	<p>This setpoint selects the range of the bus voltage terminals. The 120V range is available only in IG-NTC and IS-NT. The IG-NT has the range adjusted fixedly to 277V regardless of this setpoint.</p> <p>NOTE: See all notes mentioned above.</p>

Setpoint: GenNomV

Group	Basic Settings
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Range [units]	10 .. 34641 [V]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used to adjust the nominal (rated) generator voltage (phase to neutral). If you do not know the phase-neutral nominal voltage, you can adjust the phase-phase nominal voltage GenNomVph-ph. The controller will then recalculate the phase-neutral nominal voltage automatically.</p> <p>NOTE: The actual setpoint units and range depend on setting of the Power format in GenConfig.</p> <p>NOTE: If different voltage on gen-set and on Bus/Mains is required the following procedure is required: Both setpoints (BusNomV and GenNomV) must be adjusted to the same values according to the value of actual generator nominal voltage. E.g. gen-set nominal is 231 V but Bus/Mains nominal is 240 V. In this case both setpoints need to be adjusted to 231 V and setpoints of corresponding protections for Bus/Mains need to be set assymmetrically. For 240 V on Bus/Mains it is typical to open MCB when voltage reaches 254 V or 225 V. Since the setpoint is adjusted to 231 V corresponding protection setpoints need to be adjusted to $Mains >V MP = 106\%$ and $Mains <V MP = 97\%$ (hence the desired values are reached).</p>

Setpoint: GenNomVph-ph

Group	Basic Settings
Range [units]	17 .. 60000 [V]
Related FW	3.0
Description	<p>This setpoint is used to adjust the nominal (rated) generator voltage (phase to phase). This setpoint is also recalculated automatically when the phase-neutral nominal voltage GenNomV is changed.</p> <p>This setpoint can be used if you know the phase-phase nominal voltage only. The controller will recalculate the phase-neutral nominal voltage automatically when this setpoint is changed.</p> <p>NOTE: The actual setpoint units and range depend on setting of the Power format in GenConfig.</p> <p>NOTE: If different voltage on gen-set and on Bus/Mains is required the following procedure is required: Both setpoints (GenNomVph-ph and BusNomVph-ph) must be adjusted to the same values according to the value of actual generator nominal voltage. E.g. gen-set nominal is 400 V but Bus/Mains nominal is 415 V. In this case both setpoints need to be adjusted to 400 V and setpoints of corresponding protections for Bus/Mains need to be set assymmetrically. For 415 V on Bus/Mains it is typical to open MCB when voltage reaches 440 V or 390 V. Since the setpoint is adjusted to 400 V corresponding protection setpoints</p>

	need to be adjusted to <i>Mains >V MP</i> = 106% and <i>Mains <V MP</i> = 97 % (hence the desired values are reached).
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Setpoint: BusNomV

Group	Basic Settings
Range [units]	10 .. 34641 [V]
Related FW	3.0
Description	<p>This setpoint is used to adjust the nominal bus voltage (phase to neutral). If you do not know the phase-neutral nominal voltage, you can adjust the phase-phase nominal voltage BusNomVph-ph. The controller will then recalculate the phase-neutral nominal voltage automatically.</p> <p>NOTE: The actual setpoint units and range depend on setting of the Power format in GenConfig.</p> <p>NOTE: If different voltage on gen-set and on Bus/Mains is required the following procedure is required: Both setpoints (BusNomV and GenNomV) must be adjusted to the same values according to the value of actual generator nominal voltage. E.g. gen-set nominal is 231 V but Bus/Mains nominal is 240 V. In this case both setpoints need to be adjusted to 231 V and setpoints of corresponding protections for Bus/Mains need to be set assymmetrically. For 240 V on Bus/Mains it is typical to open MCB when voltage reaches 254 V or 225 V. Since the setpoint is adjusted to 231 V corresponding protection setpoints need to be adjusted to <i>Mains >V MP</i> = 106% and <i>Mains <V MP</i> = 97 % (hence the desired values are reached).</p>

Setpoint: BusNomVph-ph

Group	Basic settings
Range [units]	17 .. 60000 [V]
Related FW	3.0
Description	<p>In application MINT and COX.</p> <p>This setpoint is used to adjust the nominal bus voltage (phase to phase). This setpoint is also recalculated automatically when the phase-neutral nominal voltage BusNomV is changed.</p> <p>This setpoint can be used if you know the phase-phase nominal voltage only. The controller will recalculate the phase-neutral nominal voltage automatically when this setpoint is changed.</p> <p>NOTE: The actual setpoint units and range depend on setting of the Power format in GenConfig.</p> <p>NOTE: If different voltage on gen-set and on Bus/Mains is required the following</p>

	<p>procedure is required: Both setpoints (GenNomVph-ph and BusNomVph-ph) must be adjusted to the same values according to the value of actual generator nominal voltage. E.g. gen-set nominal is 400 V but Bus/Mains nominal is 415 V. In this case both setpoints need to be adjusted to 400 V and setpoints of corresponding protections for Bus/Mains need to be set assymmetrically. For 415 V on Bus/Mains it is typical to open MCB when voltage reaches 440 V or 390 V. Since the setpoint is adjusted to 400 V corresponding protection setpoints need to be adjusted to $Mains >V MP = 106\%$ and $Mains <V MP = 97\%$ (hence the desired values are reached).</p>
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Setpoint: FixVoltProtSel

Group	Basic settings
Range [units]	PHASE-NEUTRAL, PHASE-PHASE [-]
Related FW	3.0
Description	<p>PHASE-NEUTRAL: The generator and mains/bus voltage protections are based on phase-neutral voltages and the phase-neutral nominal voltages are taken as 100%.</p> <p>PHASE-PHASE: The generator and mains/bus voltage protections are based on phase-phase voltages and the phase-phase nominal voltages are taken as 100%.</p> <p>NOTE: Both options require different settings of protection levels to achieve identical results.</p> <p>EXAMPLE: Phase-nominal voltage is 231V, actual voltages are L1N = 231V, L2N = 231V, L3N = 219.5V => the L3N voltage is at 95% of the nominal. The same situation evaluated from phase-phase voltages gives following results: nominal phase-phase voltage is 400V, measured voltages are L12 = 400V, L23 = 390V, L31 = 390V => the L23 and L31 are at 97.5% of the nominal. It is obvious that if the situation is evaluated from phase-neutral voltages the tripping level must be adjusted to 95%, whereas the same situation evaluated from phase-phase voltages require tripping level adjusted to 97.5%.</p>

Setpoint: Nominal Freq

Group	Basic Settings
Range [units]	50 Hz, 60 Hz [-]
Related FW	3.0
Force value possible	YES
Description	<p>The setpoint adjusts nominal system frequency (choose 50 Hz or 60 Hz).</p> <p>Setpoint Nom frq offset is used for setting offset to the chosen nominal frequency (-2 to +2 Hz with step 0.01 Hz). Controller regulates to the Nominal Freq + Nom frq offset frequency.</p> <p>The value Nominal Freq + Nom frq offset is used as 100% for generator and</p>

	mains/bus frequency protections and as requested value for frequency regulation (except synchronizing) if the setpoint Freq reg loop is set to ALL THE TIME.
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Setpoint: Nom frq offset

Group	Basic Settings
Range [units]	-2.00 .. 2.00 [Hz]
Related FW	3.0
Force value possible	YES
Description	<p>The setpoint adjusts offset of nominal system frequency (Nominal Freq) with step 0.01 Hz.</p> <p>Controller regulates to the Nominal Freq + Nom frq offset frequency.</p> <p>The value Nominal Freq + Nom frq offset is used as 100% for generator and mains/bus frequency protections and as requested value for frequency regulation (except synchronizing) if the setpoint Freq reg loop is set to ALL THE TIME.</p>

Setpoint: Gear Teeth

Group	Basic Settings
Range [units]	1 .. 500 [-]
Related FW	3.0
Description	<p>Number of teeth on the engine's flywheel for the pick-up sensor. Adjust the setpoint to Fgen->RPM (0), if the pick-up sensor is not used. Then the engine speed will be calculated from the generator frequency.</p> <p>NOTE: Generator voltage must be higher than 10V effective to measure the speed from the frequency correctly. If this condition is not fulfilled at low speeds (cranking) it is recommended using additional running indication as e.g. D+ signal to prevent overcranking of the engine. See the binary output Starter for additional information.</p> <p>CAUTION! The starting procedure of gas engine may not work without the pickup. The pickup must be always used for gas engines.</p>

Setpoint: Nominal RPM

Group	Basic Settings
Range [units]	100 .. 4000 [RPM]
Related FW	3.0
Force value possible	YES

Description	<p>The setpoint adjusts the nominal gen-set speed.</p> <p>The nominal speed is used:</p> <ul style="list-style-type: none"> • As 100% for the overspeed protection (setpoint Overspeed) • For current speed calculation if it is calculated from generator frequency. See the setpoint Gear teeth. <p>NOTE: The setpoints Nominal RPM and system frequency (Nominal Freq + Nom frq offset) must correspond to each other, i.e. if the engine speed is at nominal value then the generator frequency must be at nominal value as well.</p>
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Setpoint: ControllerMode

Group	Basic Settings								
Range [units]	OFF, MAN, SEM, AUT, TEST [-]								
Related FW	3.0								
Description	<p>This setpoint can be used to select the controller mode. It is equivalent to selecting the mode by the buttons on the front panel. Currently active mode is displayed on the controller main screen.</p> <p>NOTE: If any of the mode forcing inputs Remote OFF, Remote MAN, Remote AUT or Remote TEST is active, then the currently active mode can be different than the mode selected by the setpoint (resp. panel buttons).</p> <table border="1" style="width: 100%; margin-top: 10px;"> <tr> <td style="background-color: #cccccc;">OFF</td> <td>The GCB is opened and the engine is immediately stopped in this mode without unloading and cooling. After that the controller is in <i>Not ready</i> state and can not be started any way. The MCB is closed permanently (MCB Opens On = GENRUN) or is open or closed according to the mains is present or not (MCB Opens On = MAINSFAIL).</td> </tr> <tr> <td style="background-color: #cccccc;">MAN</td> <td>The engine can be started and stopped manually using START and STOP buttons (or external buttons wired to appropriate binary inputs) in MAN mode. When the engine is running, GCB can be closed to a dead bus or synchronizing can be started by the GCB button. Also MCB can be closed and opened manually using the MCB button, regardless the mains is present or not. No autostart is performed. No reaction to the inputs Sys Start/Stop or Rem Start/Stop.</td> </tr> <tr> <td style="background-color: #cccccc;">SEM</td> <td>(IS-NT only) - The gen-set is started and stopped only manually using START and STOP buttons (or external buttons wired to appropriate binary inputs), however the the full start sequence up to the moment when the engine is loaded is automatic as well as unloading and stop sequence. The only case when the gen-set starts automatically in SEMI is the start/stop initiated by the AMF function.</td> </tr> <tr> <td style="background-color: #cccccc;">AUT</td> <td>This is fully automatic operation. The engine is started and stopped by:</td> </tr> </table>	OFF	The GCB is opened and the engine is immediately stopped in this mode without unloading and cooling. After that the controller is in <i>Not ready</i> state and can not be started any way. The MCB is closed permanently (MCB Opens On = GENRUN) or is open or closed according to the mains is present or not (MCB Opens On = MAINSFAIL).	MAN	The engine can be started and stopped manually using START and STOP buttons (or external buttons wired to appropriate binary inputs) in MAN mode. When the engine is running, GCB can be closed to a dead bus or synchronizing can be started by the GCB button. Also MCB can be closed and opened manually using the MCB button, regardless the mains is present or not. No autostart is performed. No reaction to the inputs Sys Start/Stop or Rem Start/Stop .	SEM	(IS-NT only) - The gen-set is started and stopped only manually using START and STOP buttons (or external buttons wired to appropriate binary inputs), however the the full start sequence up to the moment when the engine is loaded is automatic as well as unloading and stop sequence. The only case when the gen-set starts automatically in SEMI is the start/stop initiated by the AMF function.	AUT	This is fully automatic operation. The engine is started and stopped by:
OFF	The GCB is opened and the engine is immediately stopped in this mode without unloading and cooling. After that the controller is in <i>Not ready</i> state and can not be started any way. The MCB is closed permanently (MCB Opens On = GENRUN) or is open or closed according to the mains is present or not (MCB Opens On = MAINSFAIL).								
MAN	The engine can be started and stopped manually using START and STOP buttons (or external buttons wired to appropriate binary inputs) in MAN mode. When the engine is running, GCB can be closed to a dead bus or synchronizing can be started by the GCB button. Also MCB can be closed and opened manually using the MCB button, regardless the mains is present or not. No autostart is performed. No reaction to the inputs Sys Start/Stop or Rem Start/Stop .								
SEM	(IS-NT only) - The gen-set is started and stopped only manually using START and STOP buttons (or external buttons wired to appropriate binary inputs), however the the full start sequence up to the moment when the engine is loaded is automatic as well as unloading and stop sequence. The only case when the gen-set starts automatically in SEMI is the start/stop initiated by the AMF function.								
AUT	This is fully automatic operation. The engine is started and stopped by:								

	<ul style="list-style-type: none"> • Binary input Rem Start/Stop (SPtM, SPI, COMBI) • Mains import dependent autostart function (peak start/stop) (SPtM, SPI, Combi) • AMF function (SPtM, Combi) • Power management (MINT, Combi) <p>Buttons MCB, GCB, START, STOP including the appropriate binary inputs for external buttons are not active. The full start sequence up to the moment when the engine is loaded is automatic as well as unloading and stop sequence.</p> <p>WARNING! If an red alarm is present and the gen-set is in AUT mode, it can start by self after all red alarms becomes inactive and are acknowledged!!! If you want to avoid this situation, adjust the setpoint FltRes GoToMAN to the ENABLED position.</p>
TEST	(SPtM, Combi) - the gen-set is started when the controller is switched to TEST mode and remains running unloaded until the mode is changed. If a mains failure occurs, the gen-set takes over the load.

Setpoint: FltRes GoToMAN

Group	Basic Settings				
Range [units]	DISABLED,ENABLED [-]				
Related FW	3.0				
Force value possible	YES				
Description	<p>This setpoint can be used to avoid possible unexpected automatic start of the gen-set in AUT mode after the gen-set was stopped by a protection and then fault reset was pressed.</p> <table border="1" style="width: 100%;"> <tr> <td style="background-color: #cccccc;">ENABLED</td> <td>The controller mode is automatically changed from any mode except OFF to MAN if any red-level protection is acknowledged by pressing of the fault reset.</td> </tr> <tr> <td style="background-color: #cccccc;">DISABLED</td> <td>The automatic change of the controller mode is disabled.</td> </tr> </table> <p>NOTE: The function will not work if the current controller mode is forced by one of the inputs Remote AUT or Remote TEST.</p>	ENABLED	The controller mode is automatically changed from any mode except OFF to MAN if any red-level protection is acknowledged by pressing of the fault reset.	DISABLED	The automatic change of the controller mode is disabled.
ENABLED	The controller mode is automatically changed from any mode except OFF to MAN if any red-level protection is acknowledged by pressing of the fault reset.				
DISABLED	The automatic change of the controller mode is disabled.				

Setpoint: Local buttons

Group	Basic settings
Range [units]	PANEL, EXTBUTTONS, BOTH [-]
Related FW	3.0

Description	<p>The setpoint selects which set of control buttons is currently active. Its function depends on which type of controller is used. Please refer to the section which suits your controller/display version.</p> <ul style="list-style-type: none"> • First section deals with the case of IGS-NT with built-in monochrome display. • Second section deals with the case of IGS-NT-BB with IV5 display. • Third section deals with the case of IGS-NT-BB with IV8. <p>NOTE: If you have IGS-NT (built-in display) and you use additional IV display all the sections may be relevant (depending on the type of additional displays).</p> <p>IGS-NT (built-in monochrome display)</p> <table border="1"> <tr> <td>PANEL</td> <td>The built-in buttons on the controller front panel (IG-NT) or terminal #1 (IS-NT) are enabled, the binary inputs for external buttons are disabled.</td> </tr> <tr> <td>EXTBUTTONS</td> <td>The built-in buttons are disabled and the binary inputs for external buttons are enabled.</td> </tr> <tr> <td>BOTH</td> <td>Both built-in buttons and binary inputs for external buttons are enabled.</td> </tr> </table> <p>NOTE: In case that additional IV display is connected to a controller it behaves in the way described below.</p> <p>NOTE: The binary inputs for external buttons may be the following: GCBButton, MCBButton, FaultResButton, HornResButton, StartButton, StopButton etc.</p> <p>IGS-NT-BB with IV-5 display</p> <p>Situation is depicted in the following figure.</p> <ul style="list-style-type: none"> • Buttons in red box are inactive when EXTBUTTONS option is selected and active when PANEL or BOTH option is selected. • Buttons in green box are active when any option is selected. • Behavior of buttons in orange box depends on functions assigned to each button individually. If any function in the list in the note below is assigned to these buttons then it behaves as buttons in the red box, if any other function is assigned to these buttons it behaves as buttons in the green box. • The binary inputs for external buttons are affected in the same way as in the case of IGS-NT (built-in monochrome display) by this setpoint. 	PANEL	The built-in buttons on the controller front panel (IG-NT) or terminal #1 (IS-NT) are enabled, the binary inputs for external buttons are disabled.	EXTBUTTONS	The built-in buttons are disabled and the binary inputs for external buttons are enabled.	BOTH	Both built-in buttons and binary inputs for external buttons are enabled.
PANEL	The built-in buttons on the controller front panel (IG-NT) or terminal #1 (IS-NT) are enabled, the binary inputs for external buttons are disabled.						
EXTBUTTONS	The built-in buttons are disabled and the binary inputs for external buttons are enabled.						
BOTH	Both built-in buttons and binary inputs for external buttons are enabled.						



NOTE:

In the case that more IV displays are connected they all behave the same (they are all clones of each other).


NOTE:

The binary inputs for external buttons may be the following (depending on used application): *GCBButton*, *MCBButton*, *MGCBButton*, *FDRButton*, *BTBButton*, *FaultResButton*, *HornResButton*, *StartButton*, *StopButton* etc.

IGS-NT-BB with IV-8 display

Situation is depicted in the following figure.

- Buttons in red box are inactive when EXTBUTTONS option is selected and active when PANEL or BOTH option is selected.
- Buttons in green box are active when any option is selected.
- Behavior of buttons in orange box depends on functions assigned to each button individually. If any function in the list in the note below is assigned to these buttons then it behaves as buttons in the red box, if any other function is assigned to these buttons it behaves as buttons in the green box.
- The binary inputs for external buttons are affected in the same way as in the case of IGS-NT (built-in monochrome display) by this setpoint.



NOTE:
In the case that more IV displays are connected they all behave the same (they are all clones of each other).

NOTE:
The binary inputs for external buttons may be the following (depending on used application): *GCBButton*, *MCBButton*, *MGCBButton*, *FDRButton*, *BTBButton*, *FaultResButton*, *HornResButton*, *StartButton*, *StopButton* etc.

Setpoint: DispBaklightTO

Group	Basic settings				
Range [units]	OFF, 1-240 min, NO TIMEOUT [min]				
Related FW	3.0				
Force value possible	YES				
Force value possible	YES				
Description	<p>This setpoint adjusts timeout after which the display (internal display or IS display #1) backlight is switched off.</p> <p>NOTE: When IntelliVision is used this setpoint does not adjust its behavior. Its backlight is adjusted by internal IntelliVision "setpoint".</p> <table border="1" data-bbox="438 1792 1364 1892"> <tr> <td>OFF</td> <td>The backlight is off all the time</td> </tr> <tr> <td>NO TIMEOUT</td> <td>The backlight is on all the time</td> </tr> </table>	OFF	The backlight is off all the time	NO TIMEOUT	The backlight is on all the time
OFF	The backlight is off all the time				
NO TIMEOUT	The backlight is on all the time				

Setpoint: DispBklStrtOff

Group	Basic settings
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0
Force value possible	YES
Description	If this setpoint is in ENABLED position the display backlight is temporarily switched off during gen-set start.

Setpoint: FastHistPeriod

Group	Basic settings
Range [units]	100 ms, 300 ms, 500 ms, 1 s, 3 s [-]
Related FW	3.0
Description	This setpoint adjusts the period with which fast history records are written. Fast history is triggered if level 2 alarm (for more information on alarm levels please refer to this section) is issued and the engine is running (at least one condition from this list is fulfilled). For any setting of this setpoint Fast History contains 50 records.

Setpoint: ConvCoefPulse1

Group	Engine Params
Range [units]	1 .. 6500 [-]
Related FW	3.0
Description	This setpoint adjusts the rate of increasing of the PulseCounter #1 module. The module counts pulses at the input PulseCounter 1 and if the input pulses counter reaches value given by this setpoint, the counter value <i>PulseCounter 1</i> (in the group Statistic) is increased by 1 and input pulses counter is reset to 0. Both counter value and input pulses counter are stored in the nonvolatile memory.

Setpoint: ConvCoefPulse2

Group	Basic settings
Range [units]	1 .. 6500 [-]
Related FW	3.0
Description	This setpoint adjusts the rate of increasing of the PulseCounter #2 module. The module counts pulses at the input PulseCounter 2 and if the input pulses counter reaches value given by this setpoint, the counter value <i>PulseCounter 2</i> (in the group Statistic) is increased by 1 and input pulses counter is reset to 0. Both counter value and input pulses counter are stored in the nonvolatile memory.

Setpoint: ConvCoefPulse3

Group	Basic settings
Range [units]	1 .. 6500 [-]
Related FW	3.0
Description	This setpoint adjusts the rate of increasing of the PulseCounter #3 module. The module counts pulses at the input PulseCounter 3 and if the input pulses counter reaches value given by this setpoint, the counter value <i>PulseCounter 3</i> (in the group Statistic) is increased by 1 and input pulses counter is reset to 0. Both counter value and input pulses counter are stored in the nonvolatile memory.

Setpoint: ConvCoefPulse4

Group	Basic settings
Range [units]	1 .. 6500 [-]
Related FW	3.0
Description	This setpoint adjusts the rate of increasing of the PulseCounter #4 module. The module counts pulses at the input PulseCounter 4 and if the input pulses counter reaches value given by this setpoint, the counter value <i>PulseCounter 4</i> (in the group Statistic) is increased by 1 and input pulses counter is reset to 0. Both counter value and input pulses counter are stored in the nonvolatile memory.

Group: Comms settings

Setpoint: Gen-set name

Group	Comms settings
Range [units]	[-]
Related FW	3.0
Description	This setpoint is intended for a custom name of the gen-set, which is used for identification of the gen-set in saved archives or remote connections. Maximal length of the name is 15 characters. The setpoint can't be modified via the IG-NT built-in terminal.

Setpoint: Contr. address

Group	Comms settings
Range [units]	1 .. 32 [-]
Related FW	3.0
Description	This setpoint adjusts the address of the particular controller at the CAN2 and/or RS485 bus. Each gen-set connected to the same bus must have unique address . If the setpoint <i>CANnegotiation</i> (COMBI application only) is in AUT position, the address is assigned automatically. The setpoint Contr. addr is preferred then, however if it is in conflict with other controller present on the CAN2 bus other

	<p>address will be assigned to avoid address collision.</p> <p>NOTE: Address 1 is recommended for standalone gen-sets.</p> <p>NOTE: If you are connecting to the gen-set remotely you have to adjust the proper controller address in connection settings of the remote client (InteliMonitor, GenConfig, Modbus client etc.)</p> <p>NOTE: Address of the controller is also used for Modbus communication via RS485 etc. Address adjusted by this setpoint is therefore universal address of the controller.</p>
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Setpoint: RS232(1) mode

Group	Comms settings										
Range [units]	DIRECT, MODEM (HW), MODEM (SW), MODBUS-DIRECT, MODBUS-MDM(HW), ECU LINK [-]										
Related FW	3.0										
Description	<p>This setpoint selects the connection type for the serial port COM1.</p> <ul style="list-style-type: none"> • Available as RS232 in all controller types. • Available also as RS485 in the IG-NT if the external display bus is not used. Selectable by the setpoint RS485(1) conv. (not available in IG-NT-BB, IG-NTC-BB, IS-NTC-BB and IS-NT - see RS485(1) conv.). <p>See the diagram of all related terminals in the chapter Communication.</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="background-color: #cccccc;">DIRECT</td> <td>Connection to a local PC via RS232 or RS485 (with internal or external converter) interface. Use this option also for IG-IB connected via RS232 cable. The internal RS485 converter is enabled/disabled by the setpoint RS485(1) conv.</td> </tr> <tr> <td style="background-color: #cccccc;">MODEM (HW)</td> <td>Modem point-to-point connection to a remote PC with hardware data flow control using signals RTS/CTS. Full modem cable is required for this option.</td> </tr> <tr> <td style="background-color: #cccccc;">MODEM (SW)</td> <td>Modem point-to-point connection to a remote PC with software data flow control. 3-wire cable (RX, TX, GND) is sufficient for this option. Use this option only if your modem does not provide RTS/CTS signals.</td> </tr> <tr> <td style="background-color: #cccccc;">MODBUS</td> <td>Modbus RTU connection in slave mode via RS232 or RS485 (with internal or external converter) interface. The internal RS485 converter is enabled/disabled by the setpoint RS485(1) conv., the communication speed is adjustable by the setpoint RS232(1)MBCSpd. See the latest communication guide for more information about MODBUS protocol.</td> </tr> <tr> <td style="background-color: #cccccc;">MODBUS-MDM(HW)</td> <td>Modbus RTU connection in slave mode via modem</td> </tr> </table>	DIRECT	Connection to a local PC via RS232 or RS485 (with internal or external converter) interface. Use this option also for IG-IB connected via RS232 cable. The internal RS485 converter is enabled/disabled by the setpoint RS485(1) conv.	MODEM (HW)	Modem point-to-point connection to a remote PC with hardware data flow control using signals RTS/CTS. Full modem cable is required for this option.	MODEM (SW)	Modem point-to-point connection to a remote PC with software data flow control. 3-wire cable (RX, TX, GND) is sufficient for this option. Use this option only if your modem does not provide RTS/CTS signals.	MODBUS	Modbus RTU connection in slave mode via RS232 or RS485 (with internal or external converter) interface. The internal RS485 converter is enabled/disabled by the setpoint RS485(1) conv. , the communication speed is adjustable by the setpoint RS232(1)MBCSpd . See the latest communication guide for more information about MODBUS protocol.	MODBUS-MDM(HW)	Modbus RTU connection in slave mode via modem
DIRECT	Connection to a local PC via RS232 or RS485 (with internal or external converter) interface. Use this option also for IG-IB connected via RS232 cable. The internal RS485 converter is enabled/disabled by the setpoint RS485(1) conv.										
MODEM (HW)	Modem point-to-point connection to a remote PC with hardware data flow control using signals RTS/CTS. Full modem cable is required for this option.										
MODEM (SW)	Modem point-to-point connection to a remote PC with software data flow control. 3-wire cable (RX, TX, GND) is sufficient for this option. Use this option only if your modem does not provide RTS/CTS signals.										
MODBUS	Modbus RTU connection in slave mode via RS232 or RS485 (with internal or external converter) interface. The internal RS485 converter is enabled/disabled by the setpoint RS485(1) conv. , the communication speed is adjustable by the setpoint RS232(1)MBCSpd . See the latest communication guide for more information about MODBUS protocol.										
MODBUS-MDM(HW)	Modbus RTU connection in slave mode via modem										

	with hardware data flow control. The communication speed is adjustable by the setpoint RS232(1)MBCSpd . See the latest communication guide for more information about MODBUS protocol.
ECU-LINK	Connection to an electronic-controlled engine which uses non-J1939 ECU. The proper ECU type must be also configured with GenConfig.

Setpoint: RS232(2) mode

Group	Comms settings												
Range [units]	DIRECT, MODEM (HW), MODEM (SW), MODBUS-DIRECT, MODBUS-MDM(HW), ECU LINK [-]												
Related FW	3.0												
Description	<p>This setpoint selects the connection type for the serial port COM2.</p> <ul style="list-style-type: none"> • Available as RS232 or RS485 in the IG-NTC and IS-NT controllers. Selectable by the setpoint RS485(2) conv. • Available only as RS485 in the IG-NTC-BB and IS-NTC-BB controllers. • Not available in IG-NT. <p>See the diagram of all related terminals in the chapter Communication.</p> <table border="1" data-bbox="438 1077 1366 1998"> <tr> <td>DIRECT</td> <td>Connection to a local PC via RS232 or RS485 (with internal or external converter) interface. Use this option also for IG-IB connected via RS232 cable. The internal RS485 converter is enabled/disabled by the setpoint RS485(2) conv.</td> </tr> <tr> <td>MODEM (HW)</td> <td>Modem point-to-point connection to a remote PC with hardware data flow control using signals RTS/CTS. Full modem cable is required for this option.</td> </tr> <tr> <td>MODEM (SW)</td> <td>Modem point-to-point connection to a remote PC with software data flow control. 3-wire cable (RX, TX, GND) is sufficient for this option. Use this option only if your modem does not provide RTS/CTS signals.</td> </tr> <tr> <td>MODBUS</td> <td>Modbus RTU connection in slave mode via RS232 or RS485 (with internal or external converter) interface. The internal RS485 converter is enabled/disabled by the setpoint RS485(2) conv., the communication speed is adjustable by the setpoint RS232(2)MBCSpd. See the latest communication guide for more information about MODBUS protocol.</td> </tr> <tr> <td>MODBUS-MDM(HW)</td> <td>Modbus RTU connection in slave mode via modem with hardware data flow control. The communication speed is adjustable by the setpoint RS232(2)MBCSpd. See the latest communication guide for more information about MODBUS protocol.</td> </tr> <tr> <td>ECU LINK</td> <td>Connection to an electronic-controlled engine which</td> </tr> </table>	DIRECT	Connection to a local PC via RS232 or RS485 (with internal or external converter) interface. Use this option also for IG-IB connected via RS232 cable. The internal RS485 converter is enabled/disabled by the setpoint RS485(2) conv.	MODEM (HW)	Modem point-to-point connection to a remote PC with hardware data flow control using signals RTS/CTS. Full modem cable is required for this option.	MODEM (SW)	Modem point-to-point connection to a remote PC with software data flow control. 3-wire cable (RX, TX, GND) is sufficient for this option. Use this option only if your modem does not provide RTS/CTS signals.	MODBUS	Modbus RTU connection in slave mode via RS232 or RS485 (with internal or external converter) interface. The internal RS485 converter is enabled/disabled by the setpoint RS485(2) conv. , the communication speed is adjustable by the setpoint RS232(2)MBCSpd . See the latest communication guide for more information about MODBUS protocol.	MODBUS-MDM(HW)	Modbus RTU connection in slave mode via modem with hardware data flow control. The communication speed is adjustable by the setpoint RS232(2)MBCSpd . See the latest communication guide for more information about MODBUS protocol.	ECU LINK	Connection to an electronic-controlled engine which
DIRECT	Connection to a local PC via RS232 or RS485 (with internal or external converter) interface. Use this option also for IG-IB connected via RS232 cable. The internal RS485 converter is enabled/disabled by the setpoint RS485(2) conv.												
MODEM (HW)	Modem point-to-point connection to a remote PC with hardware data flow control using signals RTS/CTS. Full modem cable is required for this option.												
MODEM (SW)	Modem point-to-point connection to a remote PC with software data flow control. 3-wire cable (RX, TX, GND) is sufficient for this option. Use this option only if your modem does not provide RTS/CTS signals.												
MODBUS	Modbus RTU connection in slave mode via RS232 or RS485 (with internal or external converter) interface. The internal RS485 converter is enabled/disabled by the setpoint RS485(2) conv. , the communication speed is adjustable by the setpoint RS232(2)MBCSpd . See the latest communication guide for more information about MODBUS protocol.												
MODBUS-MDM(HW)	Modbus RTU connection in slave mode via modem with hardware data flow control. The communication speed is adjustable by the setpoint RS232(2)MBCSpd . See the latest communication guide for more information about MODBUS protocol.												
ECU LINK	Connection to an electronic-controlled engine which												

	uses non-J1939 ECU. The proper ECU type must be also configured with GenConfig.
NOTE: The COM2 prot is not available in the basic IG-NT version.	
NOTE: The RS232 connector is no more available in hardware version 2.0 and above. The COM2 port is redirected to the RS485(2) terminals all the time. That means modem is not supported at COM2 in these hardware versions. For modem use the COM1 port instead.	

Setpoint: RS232(1)MBCSpd

Group	Comms settings
Range [units]	9600, 19200, 38400, 57600 [bps]
Related FW	3.0
Description	The setpoint adjusts the communication speed on the COM1 connector when it is switched to MODBUS or MODBUS-MDM(HW) mode. See also the setpoint RS232(1) mode .

Setpoint: RS232(2)MBCSpd

Group	Comms settings
Range [units]	9600, 19200, 38400, 57600 [bps]
Related FW	3.0
Description	The setpoint adjusts the communication speed on the COM2 connector when it is switched to MODBUS or MODBUS-MDM(HW) mode. See also the setpoint RS232(2) mode .

Setpoint: RS232(1)MdmIni

Group	Comms settings
Range [units]	[-]
Related FW	3.0
Description	This setpoint can be used to add extra AT commands at the end of the initialization sequence of the modem connected to the COM1 port. The command can be entered with as well as without the "AT" prefix, are separated with semicolon and maximal length is 31 characters. The setpoint can't be modified via the IG-NT built-in terminal.

Setpoint: RS485(1) conv.

Group	Comms settings
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Range [units]	DISABLED, ENABLED [-]				
Related FW	3.0				
Description	<p>This setpoint selects function of the built-in RS485(1) converter.</p> <table border="1" data-bbox="438 385 1366 613"> <tr> <td>ENABLED</td> <td>The communication port COM1 is redirected to the integrated RS485(1) converter. The RS232(1) connector has no function and the external display interface is not available.</td> </tr> <tr> <td>DISABLED</td> <td>The communication port COM1 is present at the RS232(1) connector and the RS485(1) connector is used for the external display interface.</td> </tr> </table> <p>NOTE: The redirection is applied only for DIRECT, MODBUS and ECU-LINK modes. See the setpoint RS232(1) mode.</p> <p>NOTE: This setpoint must be set to DISABLED at controllers that do not have internal display. i.e. InteliVision-5 or InteliVision-8 is connected to the RS485(1) terminals.</p>	ENABLED	The communication port COM1 is redirected to the integrated RS485(1) converter. The RS232(1) connector has no function and the external display interface is not available.	DISABLED	The communication port COM1 is present at the RS232(1) connector and the RS485(1) connector is used for the external display interface.
ENABLED	The communication port COM1 is redirected to the integrated RS485(1) converter. The RS232(1) connector has no function and the external display interface is not available.				
DISABLED	The communication port COM1 is present at the RS232(1) connector and the RS485(1) connector is used for the external display interface.				

Setpoint: RS232(2)MdmIni

Group	Comms settings
Range [units]	[-]
Related FW	3.0
Description	<p>This setpoint can be used to add extra AT commands at the end of the initialization sequence of the modem connected to the COM2 port. The command can be entered with as well as without the "AT" prefix, are separated with semicolon and maximal length is 31 characters.</p> <p>The setpoint can't be modified via the IG-NT built-in terminal.</p> <p>Using a modem at the COM2 port is not supported since the hardware version 2.0. For modem use the COM1 port instead.</p>

Setpoint: RS485(2) conv.

Group	Comms settings				
Range [units]	DISABLED, ENABLED [-]				
Related FW	3.0				
Description	<p>This setpoint selects function of the built-in RS485(2) converter.</p> <table border="1" data-bbox="438 1841 1366 2007"> <tr> <td>ENABLED</td> <td>The communication port COM2 is redirected to the integrated RS485(2) converter. The RS232(2) connector has no function.</td> </tr> <tr> <td>DISABLED</td> <td>The communication port COM2 is present at the RS232(2) connector.</td> </tr> </table>	ENABLED	The communication port COM2 is redirected to the integrated RS485(2) converter. The RS232(2) connector has no function.	DISABLED	The communication port COM2 is present at the RS232(2) connector.
ENABLED	The communication port COM2 is redirected to the integrated RS485(2) converter. The RS232(2) connector has no function.				
DISABLED	The communication port COM2 is present at the RS232(2) connector.				

	<p>NOTE: The redirection is applied only for DIRECT, MODBUS and ECU-LINK modes. See the setpoint RS232(2) mode.</p> <p>NOTE: This setpoint has no function for IG-NT(C)-BB and IS-NTC-BB as this controller modifications do not provide the RS232 connector at the COM2 port. The port is redirected to the RS485 interface all the time regardless of this setpoint.</p>
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Setpoint: CAN bus mode

Group	Comms settings
Range [units]	32C,8C [-]
Related FW	3.0
Description	<p>CAN bus speed selection.</p> <ul style="list-style-type: none"> • 32C: High speed CAN (250 kbps) applicable up to 32 controllers, CAN bus length limited up to 200 meters. • 8C: Low speed CAN (50 kbps) applicable up to 8 controllers, CAN bus length limited up to 900 meters. <p>Change of this setpoint is applied after the controller is switched off and on again.</p> <p>NOTE: Use low speed for long distance connection only. Set all connected controllers to the same speed.</p>

Setpoint: CAN2emptDetect

Group	Comms settings
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0
Force value possible	YES
Force value possible	YES
Description	<p>Enables the detection of missing other controllers on the CAN2 bus. If the setpoint is in ENABLED position and there aren't any other controllers detected on the CAN2 bus (the complete bus, not only within the logical group) the alarm <i>CAN2Empty</i> is issued.</p>

Setpoint: LB/UART Log

Group	Comms settings
Range [units]	DISABLED, ENABLED

Related FW	3.0
Force value possible	YES
Force value possible	YES
Description	<p>The setpoint enables/disables logging of remote communication activity. If logging is enabled connection and disconnection of each remote terminal as well as entering access code are recorded into the history.</p> <p>NOTE: The terminal is disconnected automatically after 5 min of inactivity and next communication request from the same terminal is considered as a new connection. When logging is enabled in certain conditions the history may be filled up with large number of records related to the communication and important records may be overwritten quite fast.</p>

Setpoint: CANAddrSwitch1

Group	Comms settings				
Range [units]	[-]				
Related FW	3.0				
Description	<p>The setpoint selects function of the terminal address 122 at the CAN2 line. See the latest communication guide for details about this topic.</p> <table border="1" data-bbox="438 1137 1366 1279"> <tr> <td>MODEM</td> <td>The address is used for modem connection via I-LB</td> </tr> <tr> <td>OTHER</td> <td>The address is used for direct connection to any other device as e.g. IV8 or I-RD.</td> </tr> </table>	MODEM	The address is used for modem connection via I-LB	OTHER	The address is used for direct connection to any other device as e.g. IV8 or I-RD.
MODEM	The address is used for modem connection via I-LB				
OTHER	The address is used for direct connection to any other device as e.g. IV8 or I-RD.				

Setpoint: CANAddrSwitch2

Group	Comms settings				
Range [units]	[-]				
Related FW	3.0				
Description	<p>The setpoint selects function of the terminal address 125 at the CAN2 line. See the latest communication guide for details about this topic.</p> <table border="1" data-bbox="438 1675 1366 1816"> <tr> <td>MODEM</td> <td>The address is used for modem connection via I-LB</td> </tr> <tr> <td>OTHER</td> <td>The address is used for direct connection to any other device as e.g. IV8 or I-RD</td> </tr> </table>	MODEM	The address is used for modem connection via I-LB	OTHER	The address is used for direct connection to any other device as e.g. IV8 or I-RD
MODEM	The address is used for modem connection via I-LB				
OTHER	The address is used for direct connection to any other device as e.g. IV8 or I-RD				

Setpoint: IP address

Group	Comms settings
Range [units]	[-]

Related FW	3.0
Description	<ul style="list-style-type: none"> In fixed settings mode this setpoint is used to adjust the IP address of the ethernet interface of the controller. Ask your IT specialist for help with this setting. In Automatic settings mode this setpoint is used to display the IP address, which has been assigned by the DHCP server. It is not possible to change the setpoint value manually in this setting (the value is immediately reverted back by controller communication module IB-COM).

Setpoint: IP Addr mode

Group	Comms settings				
Range [units]	[-]				
Related FW	3.0				
Description	<p>The setpoint is used to select the method how the ethernet connection is adjusted.</p> <table border="1" data-bbox="438 891 1366 1563"> <tr> <td style="background-color: #cccccc;">FIXED</td> <td> <p>The ethernet connection is adjusted fixedly according to the setpoints IP address, Net mask, Gateway IP, DNS IP. .</p> <p>This method should be used for classic ethernet or Internet connection. When this type of connection is opening the controller is specified by it's IP address. That means it would be inconvenient if the IP address were not fixed (static).</p> </td> </tr> <tr> <td style="background-color: #cccccc;">AUTOMATIC</td> <td> <p>The ethernet connection settings is obtained automatically from the DHCP server. The obtained settings is then copied to the related setpoints (it is not possible to set those setpoints manually in this setting, for more information please see the following setpoints: IP address, Net mask, Gateway IP and DNS IP). If the process of obtaining the settings from DHCP server is not successful the value <i>000.000.000.000</i> is copied to the setpoint IP address and the module continues trying to obtain the settings.</p> <p>This method is beneficial for AirGate connection as it makes the connection very easy, in fact "plug and play". When this type of connection is opening the controller is specified by it's AirGate ID and the IP address does not play any role.</p> </td> </tr> </table> <p style="background-color: #cccccc; margin-top: 10px;">CAUTION! If you need to use fixed ethernet settings you should consult the proper setting with your IT specialist.</p>	FIXED	<p>The ethernet connection is adjusted fixedly according to the setpoints IP address, Net mask, Gateway IP, DNS IP. .</p> <p>This method should be used for classic ethernet or Internet connection. When this type of connection is opening the controller is specified by it's IP address. That means it would be inconvenient if the IP address were not fixed (static).</p>	AUTOMATIC	<p>The ethernet connection settings is obtained automatically from the DHCP server. The obtained settings is then copied to the related setpoints (it is not possible to set those setpoints manually in this setting, for more information please see the following setpoints: IP address, Net mask, Gateway IP and DNS IP). If the process of obtaining the settings from DHCP server is not successful the value <i>000.000.000.000</i> is copied to the setpoint IP address and the module continues trying to obtain the settings.</p> <p>This method is beneficial for AirGate connection as it makes the connection very easy, in fact "plug and play". When this type of connection is opening the controller is specified by it's AirGate ID and the IP address does not play any role.</p>
FIXED	<p>The ethernet connection is adjusted fixedly according to the setpoints IP address, Net mask, Gateway IP, DNS IP. .</p> <p>This method should be used for classic ethernet or Internet connection. When this type of connection is opening the controller is specified by it's IP address. That means it would be inconvenient if the IP address were not fixed (static).</p>				
AUTOMATIC	<p>The ethernet connection settings is obtained automatically from the DHCP server. The obtained settings is then copied to the related setpoints (it is not possible to set those setpoints manually in this setting, for more information please see the following setpoints: IP address, Net mask, Gateway IP and DNS IP). If the process of obtaining the settings from DHCP server is not successful the value <i>000.000.000.000</i> is copied to the setpoint IP address and the module continues trying to obtain the settings.</p> <p>This method is beneficial for AirGate connection as it makes the connection very easy, in fact "plug and play". When this type of connection is opening the controller is specified by it's AirGate ID and the IP address does not play any role.</p>				

Setpoint: Net mask

Group	Comms settings
Range [units]	[-]

Related FW	3.0
Description	<ul style="list-style-type: none"> In fixed settings mode this setpoint is used to adjust the network mask of the network segment where the controller is connected. In Automatic settings mode this setpoint is used to display the network mask which has been assigned by the DHCP server. It is not possible to change the setpoint value manually in this setting (the value is immediately reverted back by controller communication module IB-COM).

Setpoint: Gateway IP

Group	Comms settings
Range [units]	[-]
Related FW	3.0
Description	<ul style="list-style-type: none"> In fixed settings mode this setpoint is used to adjust the IP address of the gateway of the network segment where the controller is connected. In Automatic settings mode this setpoint is used to display the gateway IP address which has been assigned by the DHCP server. It is not possible to change the setpoint value manually in this setting (the value is immediately reverted back by controller communication module IB-COM). <p>A gateway is a device which connects the respective segment with the other segments and/or Internet.</p>

Setpoint: ComApProtoPort

Group	Comms settings
Range [units]	1 .. 255 [-]
Related FW	3.0
Description	<p>This setpoint is used to adjust the port, which is used for ethernet connection to a PC with any of ComAp PC program (i.e. IntelliMonitor, GenConfig). This setpoint should be adjusted to 23, which is the default port used by all ComAp PC programs. A different value should be used only in special situations as e.g. sharing one public IP address among many controllers or to overcome a firewall restrictions.</p>

Setpoint: AirGate

Group	Comms settings
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0
Description	<p>This setpoint selects the ethernet connection mode.</p>

DISABLED	This is a standard mode, in which the controller listens to the incoming traffic and answers the TCP/IP queries addressed to him. This mode requires the controller to be accessible from the remote device (PC), i.e. it must be accessible at a public and static IP address if you want to connect to it from the Internet.
ENABLED	This mode uses the "AirGate" service, which hides all the issues with static/public address into a black box and you do not need to take care about it. You just need only a connection to the Internet. The AirGate server address is adjusted by the setpoint AirGate addr.

Setpoint: AirGate IP

Group	Comms settings
Range [units]	max. 32 characters [-]
Related FW	3.0
Description	This setpoint is used for entering the domain name or IP address of the AirGate server. Use the free AirGate server provided by ComAp at address airgate.comap.cz if your company does not operate it's own AirGate server.

Setpoint: SMTP authent

Group	Comms settings
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0
Description	Switch this setpoint to ENABLED position if your SMTP server requires authenticated access. You have also adjust SMTP user name and SMTP password . Ask your internet provider or IT manager for this information. NOTE: Most of public free SMTP servers require authentication. You will get instructions when you register to the freemail service.

Setpoint: SMTP user name

Group	Comms settings
Range [units]	max. 32 characters [-]
Related FW	3.0
Description	Use this setpoint to enter the user name for the SMTP server if SMTP authentication is enabled.

Setpoint: SMTP password

Group	Comms settings
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Range [units]	max. 32 characters [-]
Related FW	3.0
Description	Use this setpoint to enter the password for the SMTP server if SMTP authentication is enabled.

Setpoint: SMTP address

Group	Comms settings
Range [units]	max. 32 characters
Related FW	3.0
Description	<p>CAUTION! Proper setting of SMTP-related setpoints as well as controller mailbox are essential for sending alerts via e-mails.</p> <p>This setpoint is used for entering the domain name (e.g. <i>smtp.yourprovider.com</i>) or IP address (e.g. 74.125.39.109) of the SMTP server. Please ask your internet provider or IT manager for this information.</p> <p>NOTE: You may also use one of free SMTP servers, e.g. <i>smtp.gmail.com</i>. However, please note that some free SMTP servers may cause delays (in hours..) when sending e-mails.</p> <p>NOTE: If you do not want to send active e-mails, you may leave this setpoint blank, as well as other setpoints related to SMTP server and e-mail settings.</p>

Setpoint: Contr mailbox

Group	Comms settings
Range [units]	max. 32 characters [-]
Related FW	3.0
Description	<p>Enter an existing e-mail address into this setpoint. This address will be used as sender address in active e-mails that will be sent from the controller. Do not enter your or other recipient's e-mail address. Recipient's addresses are to be entered into the setpoints AcallCH1-Addr, AcallCH2-Addr and AcallCH3-Addr.</p> <p>NOTE: Most of SMTP server will reject sending e-mails that contain nonexisting address in the sender address field.</p>

Setpoint: Time zone

Group	Comms settings
Range [units]	- [-]
Related FW	3.0

Description	<p>This setpoint is used to select the time zone where the controller is located. See your computer time zone setting (click on the time indicator located in the rightmost position of the the windows task bar) if you are not sure about your time zone.</p> <p>NOTE: If the time zone is not selected properly the active e-mails may contain incorrect information about sending time, which may result in confusion when the respective problem actually occurred.</p>
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Setpoint: DNS IP

Group	Comms settings
Range [units]	[-]
Related FW	3.0
Description	<ul style="list-style-type: none"> • In fixed settings mode this setpoint is used to adjust the domain name server (DNS), which is needed to traslate domain names in e-mail addresses and server names into correct IP addresses. • In Automatic settings mode this setpoint is used to display DNS server, which has been assigned by the DHCP server. It is not possible to change the setpoint value manually in this setting (the value is immediately reverted back by controller communication module IB-COM).

Setpoint: ECU Diag

Group	Comms settings
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used to disable reading of diagnostic codes from the ECU if an external diagnostic tool is connected to the engine.</p> <p>A message <i>ECU Diag disabled</i> is displayed in the alarm list while ECU diagnostics is disabled.</p>

Setpoint: SHxOcol detect

Group	Comms settings
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0
Description	<p>This setpoint is used to enable/disable evaluation of collisions of virtual shared peripheral modules. A collision means that there is more than one source (shared</p>

	outputs module) active on the CAN2 bus. NOTE: In certain situations multiple sites with bus tie breakers may need to have more shared outputs sources as the CAN bus line is in some points interrupted according to bus tie breakers position. Normally a collision would be indicated if there were more sources on the bus and this setpoint can be used to disable the evaluation of collisions in this special case.
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Group: Engine params

Setpoint: Starting RPM

Group	Engine Params
Range [units]	0 .. 1000 [RPM]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint adjusts "firing" speed level. When this level is reached during cranking, the engine is considered as started and the starter motor is disengaged, i.e. the output Starter is deactivated.</p> <p>NOTE: There are also other symptoms that causes disengagement of the starter. See the separate chapter Starting sequence.</p> <p>This setpoint is also used as the speed limit for the <i>Underspeed</i> protection, which is activated 5s after the starter was disengaged and the controller continued from <i>Starting to Idle</i> or <i>Running</i> phase.</p>

Setpoint: Starting POil

Group	Engine Params
Range [units]	0.0 .. 10.00 [bar]
Related FW	3.0
Force value possible	YES
Description	<p>Oil pressure can be used as one of the symptoms that are used for detection that the engine is running. This setpoint adjusts oil pressure limit above which the engine is considered as started.</p> <p>NOTE: Learn more in the separate chapter Starting sequence.</p> <p>NOTE: The logical analog input <i>Oil pressure</i> must be configured onto the appropriate analog input where the oil pressure sensor is connected.</p>

Setpoint: Prestart time

Group	Engine Params
Range [units]	0 .. 3600 [s]
Related FW	3.0
Force value possible	YES
Description	This setpoint adjust length of the prestart period before starter is engaged. The output Prestart is active during the prestart period. Adjust the setpoint to zero if you want to disable the prestart function.

Setpoint: Prelubr time

Group	Engine params
Range [units]	0 .. 3600 [s]
Related FW	3.0
Force value possible	YES
Description	This setpoint is used for adjusting duration of the prelubrication cycle. See the output Prelubr pump for details about prelubrication.

Setpoint: Prelubr pause

Group	Engine params
Range [units]	1 .. 3000 [min]
Related FW	3.0
Force value possible	YES
Description	YES This setpoint is used for adjusting the pause between two consequent prelubrication cycles. See the output Prelubr pump for details about prelubrication.

Setpoint: MaxCrank Time

Group	Engine Params
Range [units]	1 .. 240 [s]
Related FW	3.0
Force value possible	YES
Description	The setpoint adjusts the maximum duration the starter motor is energized within one cranking cycle. If there is none of <i>running engine symptoms</i> activated within this period the particular cranking attempt is finished and either a cranking pause

	<p>follows or <i>start fail</i> alarm is issued.</p> <p>NOTE: At gas engines the last cranking cycle is extended about 25% and the engine is cranked with closed gas valve during this additional time to ventilate the remaining gas.</p> <p>NOTE: If magnetic pickup is used and the controller does not detect non-zero RPM within 2s (gas engine) or 5s (diesel engine) after energizing the starter motor then cranking pause follows immediately (as the pinion is probably not properly engaged).</p> <p>NOTE: Learn more in the separate chapter Starting sequence.</p>
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Setpoint: CrnkFail pause

Group	Engine Params
Range [units]	5 .. 60 [s]
Related FW	3.0
Force value possible	YES
Description	<p>The setpoint adjusts the pause between two subsequent cranking cycles.</p> <p>NOTE: Learn more in the separate chapter Starting sequence.</p>

Setpoint: Crank attempts

Group	Engine Params
Range [units]	1 .. 10 [-]
Related FW	3.0
Force value possible	YES
Description	<p>The setpoint adjusts the maximum number of cranking cycles. The alarm <i>Start fail</i> is issued when the engine does not start within this number of cranking cycles.</p> <p>NOTE: An gas engines the last cranking cycle is extended about 25% and the engine is cranked with closed gas valve during this additional time to ventilate the remaining gas.</p> <p>NOTE: Learn more in the separate chapter Starting sequence.</p>

Setpoint: Idle time

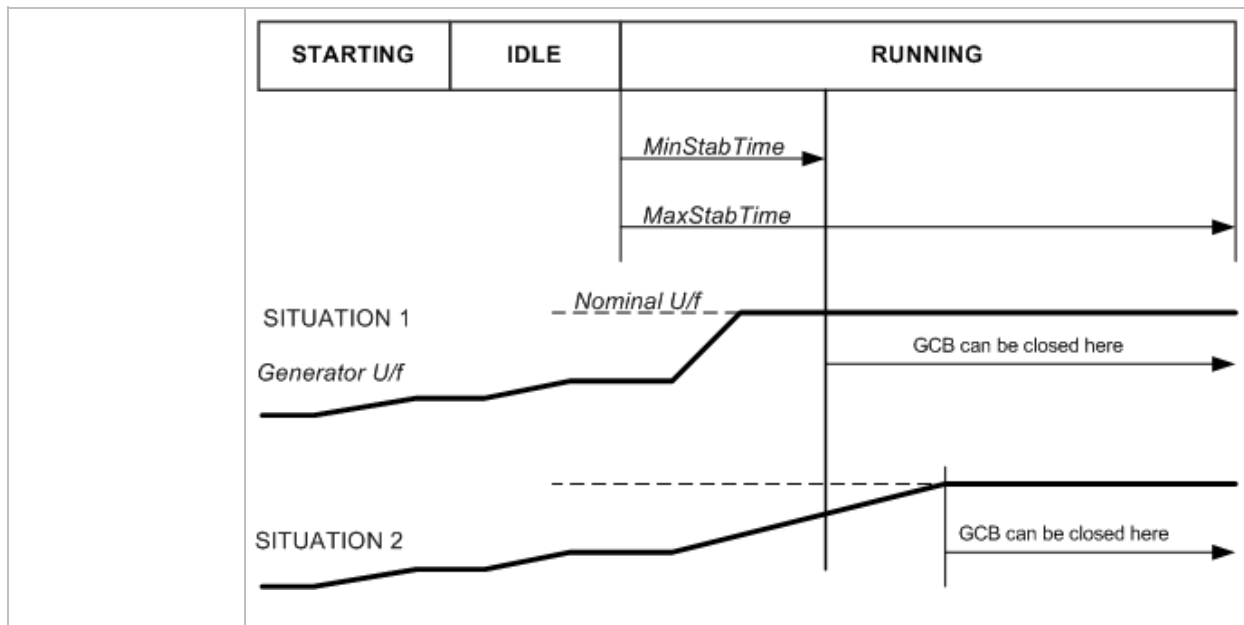
Group	Engine Params
Range [units]	1 .. 3600 [s]
Related FW	3.0
Force value possible	YES
Description	This setpoint adjusts duration of the idle period, which begins in the moment when the engine is started (e.g. the starter motor is disengaged). The output Idle/Nominal is not active to keep the engine at idle speed (if the governor supports idling) during idle period.

Setpoint: Min stab time

Group	Engine Params
Range [units]	1 .. Max Stab Time [s]
Related FW	3.0
Force value possible	YES
Description	This setpoint adjusts the minimum time between the end of the idle period and closing of the GCB. Closing of the GCB is blocked during this period even if generator voltage and frequency are in limits.

Setpoint: Max Stab Time

Group	Engine Params
Range [units]	Min Stab Time .. 3600 [s]
Related FW	3.0
Force value possible	YES
Description	This setpoint adjusts the maximum time between the end of the idle period and reaching proper generator voltage and frequency. If the proper generator voltage and frequency is not reached within this period generator voltage and/or frequency alarm is issued and the gen-set is stopped.



Setpoint: Warming load

Group	Engine params
Range [units]	0 .. 100 [%]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used to adjust the requested load level during <i>warming</i> period in % of the Nomin power.</p> <p>The warming period takes place after the gen-set has been synchronized to the mains if the temperature measured at the logical analog input <i>Warming Temp</i> is below the value of Warming temp. The gen-set load is maintained at Warming load, which should be adjusted to cca 20-30% of the nominal load to allow the engine reaching of it's operational temperature smoothly. The warming period is finished either when the temperature reaches the warming level or if duration of the warming period reaches Max warm time.</p>

Setpoint: Warming temp

Group	Engine params
Range [units]	-32000 .. 32000 [°C]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint adjusts the warming temperature. The warming phase is finished when either the water temperature at the logical analog input Warming temp reaches this level or the Max warm time elapses.</p> <p>NOTE:</p>

	See also the setpoint Warming load .
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Setpoint: Max warm time

Group	Gener Protect
Range [units]	0 .. 3600 [s]
Related FW	3.0
Force value possible	YES
Description	This setpoint adjusts the maximum duration of the warming phase after the genset was synchronized to the mains. The warming phase is finished when either the water temperature at the logical analog input <i>Warming Temp</i> reaches this level or the Max warm time elapses.

Setpoint: Cooling speed

Group	Engine Params				
Range [units]	IDLE, NOMINAL				
Related FW	3.0				
Force value possible	YES				
Description	<p>This setpoint is used to select whether the cooling phase is performed at idle or nominal speed, i.e. whether the output Idle/Nominal is open or closed during the idle phase.</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="background-color: #cccccc; width: 15%;">NOMINAL</td> <td>Gen-set performs cooling at nominal speed, generator voltage and frequency protections remain active during cooling phase.</td> </tr> <tr> <td style="background-color: #cccccc;">IDLE</td> <td>Gen-set performs cooling at idle speed, generator protections are not active in the cooling phase (except of <i>Gen >V Sd</i>).</td> </tr> </table>	NOMINAL	Gen-set performs cooling at nominal speed, generator voltage and frequency protections remain active during cooling phase.	IDLE	Gen-set performs cooling at idle speed, generator protections are not active in the cooling phase (except of <i>Gen >V Sd</i>).
NOMINAL	Gen-set performs cooling at nominal speed, generator voltage and frequency protections remain active during cooling phase.				
IDLE	Gen-set performs cooling at idle speed, generator protections are not active in the cooling phase (except of <i>Gen >V Sd</i>).				

Setpoint: Cooling time

Group	Engine Params
Range [units]	0 .. 3600 [s]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used to adjust the length of the <i>Cooling</i> phase, which takes place after the gen-set has been unloaded (GCB opened) and before it is stopped. The cooling phase can be performed either at nominal or at idle speed. See the setpoint Cooling speed.</p> <p>If the cooling phase length optimization is enabled, the actual length depend on the actual genset load in the moment the stop sequence was started. See the</p>

	setpoint Cooldown optim.
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Setpoint: CoolDnAfterBOC

Group	Engine Params				
Range [units]	STOP, INFIN COOLING [-]				
Related FW	3.0				
Force value possible	YES				
Description	<p>The setpoint selects the controller behavior in cooling phase after a BOC alarm:</p> <table border="1" data-bbox="438 698 1366 1016"> <tr> <td>STOP</td> <td>The controller behaves as usually, e.g. the cooling phase lasts for period adjusted by the setpoint Cooling time and then the gen-set is stopped.</td> </tr> <tr> <td>INFIN COOLING</td> <td>The cooling phase is not finished automatically when the Cooling time elapses. The gen-set remains in cooling until another event changes the it's state, e.g. it is manually stopped. If the gen-set is in AUT mode and the alarm is not active and has been reset the gen-set returns to loaded state automatically.</td> </tr> </table>	STOP	The controller behaves as usually, e.g. the cooling phase lasts for period adjusted by the setpoint Cooling time and then the gen-set is stopped.	INFIN COOLING	The cooling phase is not finished automatically when the Cooling time elapses. The gen-set remains in cooling until another event changes the it's state, e.g. it is manually stopped. If the gen-set is in AUT mode and the alarm is not active and has been reset the gen-set returns to loaded state automatically.
STOP	The controller behaves as usually, e.g. the cooling phase lasts for period adjusted by the setpoint Cooling time and then the gen-set is stopped.				
INFIN COOLING	The cooling phase is not finished automatically when the Cooling time elapses. The gen-set remains in cooling until another event changes the it's state, e.g. it is manually stopped. If the gen-set is in AUT mode and the alarm is not active and has been reset the gen-set returns to loaded state automatically.				

Setpoint: Cooldown optim

Group	Engine params				
Range [units]	DISABLED, ENABLED [-]				
Related FW	3.0				
Description	<p>This setpoint enables optimization of the cooling phase length based on the previous gen-set load.</p> <table border="1" data-bbox="438 1420 1366 1704"> <tr> <td>DISABLED</td> <td>The length of the cooling phase is given by the setpoint Cooling time regardless of the previous gen-set load.</td> </tr> <tr> <td>ENABLED</td> <td>The length of the cooling phase is linearly reduced according to the gen-set load in the moment the stop sequence started (i.e. prior to the gen-set begun to ramp down or opened the GCB). If the load was 100% of the nominal power the length will be 100% of the setpoint Cooling time, if the load was 50% the length will be reduced to 50% etc...</td> </tr> </table>	DISABLED	The length of the cooling phase is given by the setpoint Cooling time regardless of the previous gen-set load.	ENABLED	The length of the cooling phase is linearly reduced according to the gen-set load in the moment the stop sequence started (i.e. prior to the gen-set begun to ramp down or opened the GCB). If the load was 100% of the nominal power the length will be 100% of the setpoint Cooling time , if the load was 50% the length will be reduced to 50% etc...
DISABLED	The length of the cooling phase is given by the setpoint Cooling time regardless of the previous gen-set load.				
ENABLED	The length of the cooling phase is linearly reduced according to the gen-set load in the moment the stop sequence started (i.e. prior to the gen-set begun to ramp down or opened the GCB). If the load was 100% of the nominal power the length will be 100% of the setpoint Cooling time , if the load was 50% the length will be reduced to 50% etc...				

Setpoint: AfterCool time

Group	Engine params
Range [units]	0 .. 3600 [s]
Related FW	3.0
Force value	YES

possible	
Description	The setpoint is used to adjust the length of the <i>aftercooling</i> period, i.e. how long the cooling pump remains running after the gen-set has been stopped.

Setpoint: Stop time

Group	Engine Params
Range [units]	0 .. 240 [s]
Related FW	3.0
Force value possible	YES
Description	This setpoint is used to adjust the time period the gen-set needs to stop completely. If the gen-set does not stop within this period the alarm <i>Stop fail</i> is issued. The setpoint also adjusts the minimal length of stop solenoid activation. See the output Stop Solenoid for more information.

Setpoint: SDVentil time

Group	Engine Params
Range [units]	0 .. 60 [s]
Related FW	3.0
Description	<p>This setpoint is used to adjust the length of the preventilation phase at gas engines, i.e. if the setpoint Fuel solenoid is switched to GAS ENGINE. The preventilation phase is a period of cranking without opened gas valve which takes place prior to the first start attempt after a shutdown or after switching on the controller.</p> <p>The purpose of the preventilation phase is to clean the engine and exhaust system from possible unburned gas.</p>

Setpoint: Fuel Solenoid

Group	Engine Params
Range [units]	DIESEL ENGINE, GAS ENGINE [-]
Related FW	3.0
Description	<p>This setpoint is used to select the type of starting sequence. The diagrams of both sequences are indicated in the separate chapter Starting sequence.</p> <p>The main difference in the behavior of the fuel Solenoid at diesel and gas engine is that at diesel engines the fuel solenoid is activated prior to the starter motor, whereas at gas engines it is not activated until the gen-set reaches 30RPM.</p> <p>CAUTION! It is strongly recommended to use pickup sensor for gas engines.</p>

Setpoint: FuelSol offset

Group	Engine Params
Range [units]	-5.0 .. 5.0 [s]
Related FW	3.0
Description	<p>This setpoint is used for fine adjustment of the moment when the Fuel Solenoid output is activated. The time is related to the activation of the Starter output, where negative values mean the fuel solenoid is activated in advance to the starter motor and positive values mean the fuel solenoid is delayed after the starter motor.</p> <p>NOTE: This setpoint is taken into account at diesel engines only, i.e. if the setpoint Fuel solenoid is set to DIESEL ENGINE.</p>

Setpoint: D+ Function

Group	Engine Params						
Range [units]	ENABLED,CHRGFAIL,DISABLED [-]						
Related FW	3.0						
Description	<p>This setpoint adjusts the function of the D+ terminal.</p> <table border="1" data-bbox="438 1048 1366 1267"> <tr> <td>ENABLED</td> <td>The D+ terminal is used for running engine detection as well as for charger failure alarm detection.</td> </tr> <tr> <td>CHRGFAIL</td> <td>The D+ terminal is used for charger failure alarm detection only.</td> </tr> <tr> <td>DISABLED</td> <td>The D+ terminal is not used.</td> </tr> </table> <p>NOTE: Some alternators provide a terminal labelled as "L" instead of "D+". It is not possible to connect this "L" terminal to the "D+" terminal of the controller.</p>	ENABLED	The D+ terminal is used for running engine detection as well as for charger failure alarm detection.	CHRGFAIL	The D+ terminal is used for charger failure alarm detection only.	DISABLED	The D+ terminal is not used.
ENABLED	The D+ terminal is used for running engine detection as well as for charger failure alarm detection.						
CHRGFAIL	The D+ terminal is used for charger failure alarm detection only.						
DISABLED	The D+ terminal is not used.						

Setpoint: Bin selector 1

Group	Engine params
Range [units]	OFF, ON [-]
Related FW	3.0
Force value possible	YES
Description	The setpoint is used to switch on and off the output Bin selector 1 .

Setpoint: Bin selector 2

Group	Engine params
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Range [units]	OFF, ON [-]
Related FW	3.0
Force value possible	YES
Description	The setpoint is used to switch on and off the output Bin selector 2 .

Setpoint: Bin selector 3

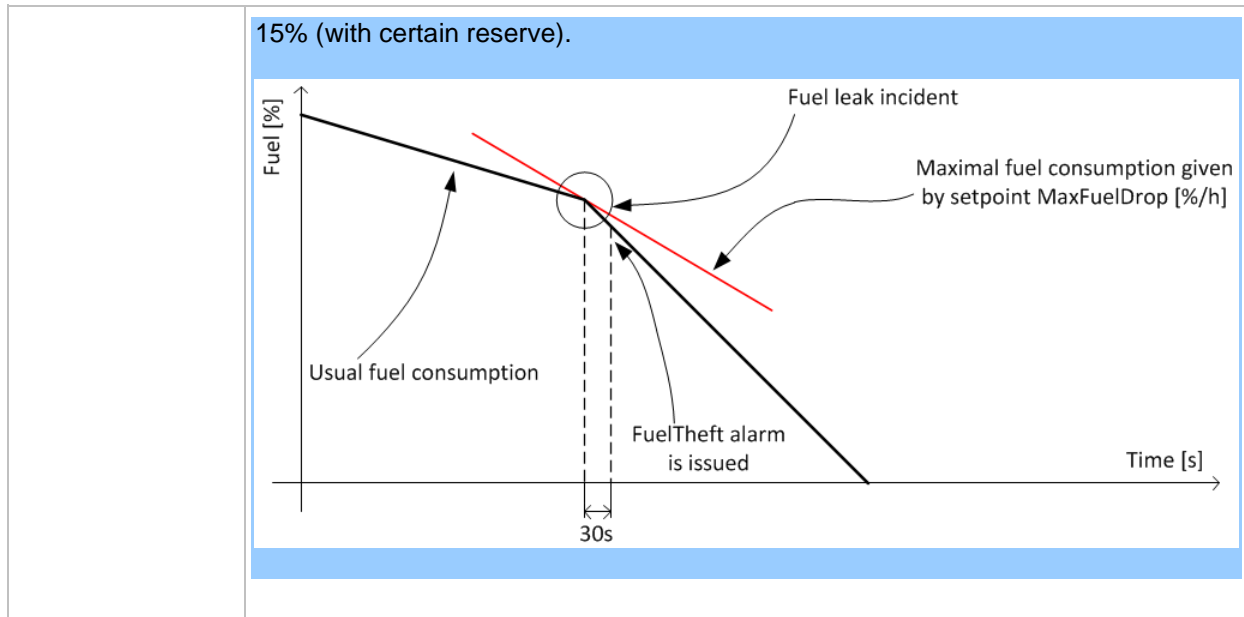
Group	Engine params
Range [units]	OFF, ON [-]
Related FW	3.0
Force value possible	YES
Description	The setpoint is used to switch on and off the output Bin selector 3 .

Setpoint: Bin selector 4

Group	Engine params
Range [units]	OFF, ON [-]
Related FW	3.0
Force value possible	YES
Description	The setpoint is used to switch on and off the output Bin selector 4 .

Setpoint: MaxFuelDrop

Group	Engine params
Range [units]	3 .. 50 [%/h]
Related FW	3.0
Description	<p>This setpoint adjusts the maximal allowed drop of the fuel level within one hour. If measured drop is higher then <i>Fuel theft</i> alarm is issued. The setpoint should be adjusted according to the maximal hour fuel rate of the engine and capacity of the tank.</p> <p>NOTE: The logical analog input Fuel level must be configured onto the physical analog input where fuel level sensor is connected.</p> <p>EXAMPLE: A 100kW engine has specific fuel rate of 180g/kWh. Fuel tank capacity is 200l.</p> <p>The hour fuel rate at nominal power is then $100 * 180 = 18000\text{g}$ per hour, what is about 21 litres (density cca 830g/l => $18000/830 = 21$). The maximal hour rate is then about 10% of the tank capacity, so optimal adjustment for this case will be</p>



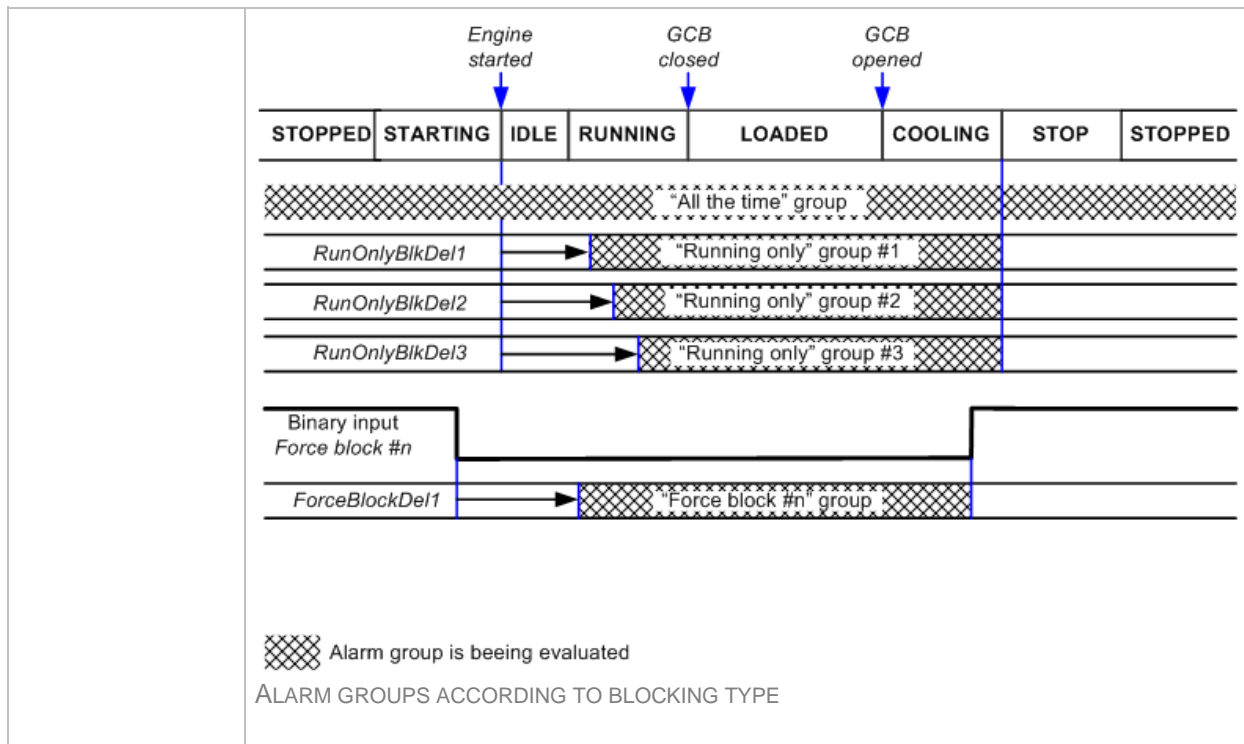
Group: Engine protect

Setpoint: Horn Timeout

Group	Engine Protect
Range [units]	OFF, 1s - 3600s, NO TIMEOUT [-]
Related FW	3.0
Force value possible	YES
Force value possible	YES
Description	This setpoint adjusts time after which the Horn output is automatically deactivated although the alarms still haven't been reset. If the setpoint is adjusted to OFF the horn output is not activated at all, the NO TIMEOUT position means the horn output is not deactivated until the alarms are reset.

Setpoint: RunOnlyBlkDel1

Group	Engine protect
Range [units]	0.0 .. 3000.0 [s]
Related FW	3.0
Description	This setpoint adjusts the delay after engine start when the alarms configured as <i>RunOnlyBlkDel1</i> (i.e. "running only", group #1) are started to be evaluated. The "running only" alarms are not being evaluated while the engine is not running or then, after start, while the adjusted delay is running.



Setpoint: RunOnlyBlkDel2

Group	Engine protect
Range [units]	0.0 .. 3000.0 [s]
Related FW	3.0
Description	<p>This setpoint adjusts the delay after engine start when the alarms configured as <i>RunOnlyBlkDel2</i> (i.e. "running only", group #2) are started to be evaluated. The "running only" alarms are not being evaluated while the engine is not running or then, after start, while the adjusted delay is running.</p> <p>See the setpoint RunOnlyBlkDel1 for diagram of alarm groups and their blocking periods.</p>

Setpoint: RunOnlyBlkDel3

Group	Engine protect
Range [units]	0.0 .. 3000.0 [s]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint adjusts the delay after engine start when the alarms configured as <i>RunOnlyBlkDel3</i> (i.e. "running only", group #3) are started to be evaluated. The "running only" alarms are not being evaluated while the engine is not running or then, after start, while the adjusted delay is running.</p> <p>See the setpoint RunOnlyBlkDel1 for diagram of alarm groups and their blocking</p>

	periods.
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Setpoint: BinInp delay 1

Group	Engine protect
Range [units]	0.0 .. 600.0 [s]
Related FW	3.0
Description	<p>This setpoint adjusts the delay #1 which can be assigned to an input configured as alarm input (protection).</p> <p>NOTE: Protections configured at a binary inputs can have either fixed 0.5s evaluation delay or there are three independent delay setpoints and one of them can be assigned to each particular binary input protection.</p>

Setpoint: BinInp delay 2

Group	Engine protect
Range [units]	0.0 .. 600.0 [s]
Related FW	3.0
Description	<p>This setpoint adjusts the delay #2 which can be assigned to an input configured as alarm input (protection).</p> <p>NOTE: Protections configured at a binary inputs can have either fixed 0.5s evaluation delay or there are three independent delay setpoints and one of them can be assigned to each particular binary input protection.</p>

Setpoint: BinInp delay 3

Group	Engine protect
Range [units]	0.0 .. 600.0 [s]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint adjusts the delay #3 which can be assigned to an input configured as alarm input (protection).</p> <p>NOTE: Protections configured at a binary inputs can have either fixed 0.5s evaluation delay or there are three independent delay setpoints and one of them can be assigned to each particular binary input protection.</p>

Setpoint: ForceBlockDel1

Group	Engine protect
Range [units]	0.0 .. 60.0 [s]
Related FW	3.0
Description	This setpoint adjusts the delay after the binary input Force block 1 has been deactivated, when the alarms configured as <i>Force block #1</i> are started to be evaluated.

Setpoint: ForceBlockDel2

Group	Engine protect
Range [units]	0.0 .. 60.0 [s]
Related FW	3.0
Description	This setpoint adjusts the delay after the binary input Force block 2 has been deactivated, when the alarms configured as <i>Force block #2</i> are started to be evaluated.

Setpoint: ForceBlockDel3

Group	Engine protect
Range [units]	0.0 .. 60.0 [s]
Related FW	3.0
Force value possible	YES
Description	This setpoint adjusts the delay after the binary input Force block 3 has been deactivated, when the alarms configured as <i>Force block #3</i> are started to be evaluated.

Setpoint: ResetActAlarms

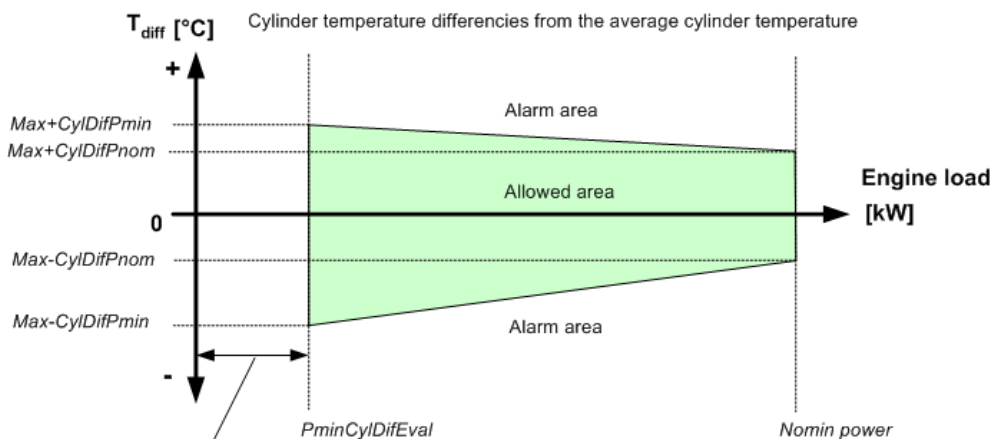
Group	Engine protect				
Range [units]	[-]				
Related FW	3.0				
Description	<table border="1"> <tr> <td>DISABLED</td> <td>Pressing of the fault reset button (at any terminal or external button) resets only inactive alarms. Active alarms remain in the alarmlist unchanged and must be reset again when they become inactive.</td> </tr> <tr> <td>ENABLED</td> <td>Pressing of the fault reset button (at any terminal or external button) resets all alarms that are currently present in the alarm list. Inactive alarms disappear from the alarm list immediately, active alarms are changed to "confirmed" state and disappear when the alarm condition disappear or the alarm starts to be</td> </tr> </table>	DISABLED	Pressing of the fault reset button (at any terminal or external button) resets only inactive alarms. Active alarms remain in the alarmlist unchanged and must be reset again when they become inactive.	ENABLED	Pressing of the fault reset button (at any terminal or external button) resets all alarms that are currently present in the alarm list. Inactive alarms disappear from the alarm list immediately, active alarms are changed to "confirmed" state and disappear when the alarm condition disappear or the alarm starts to be
DISABLED	Pressing of the fault reset button (at any terminal or external button) resets only inactive alarms. Active alarms remain in the alarmlist unchanged and must be reset again when they become inactive.				
ENABLED	Pressing of the fault reset button (at any terminal or external button) resets all alarms that are currently present in the alarm list. Inactive alarms disappear from the alarm list immediately, active alarms are changed to "confirmed" state and disappear when the alarm condition disappear or the alarm starts to be				

	<div style="background-color: #cccccc; padding: 5px;"> blocked. </div> <p>NOTE: ENABLED position corresponds to the method how the IG-classic and IS-classic controllers handled the alarms.</p>
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Setpoint: Overspeed

Group	Engine Protect
Range [units]	0 .. 200 [%]
Related FW	3.0
Description	<p>This setpoint adjusts the threshold level for overspeed protection.</p> <p>NOTE: The overspeed protection is evaluated all the time and without any delay.</p>

Setpoint: Max+CylDifPmin

Group	Engine protect
Range [units]	-32000 .. +32000 [°C]
Related FW	3.0
Description	<p>This setpoint adjusts the maximum allowed positive difference between a particular cylinder temperature and average cylinder temperature at minimum power level adjusted by setpoint PminCylDifEval. This setpoint is one of four setpoints that define the allowed area of cylinder temperature differences depending on gen-set power. See the picture below.</p> <div style="text-align: center;">  <p style="font-size: small;">Cylinder temperature differences from the average cylinder temperature</p> <p style="font-size: small;">Cylinder temperature differences alarm is not being evaluated</p> <p style="font-size: small;">ALLOWED AREA OF CYLINDER TEMPERATURE DIFFERENCIES DEPENDING ON GENSET POWER</p> </div> <p>If the difference of actual cylinder temperature from the average temperature is out of the allowed range at one or more cylinders the alarm <i>Wrn CylTemp</i> is issued after the delay CylDifEvalDel elapses. The alarm is intended for detection that</p>

	<p>there is a problem with combustion at the particular cylinders.</p> <p>NOTE: Logical analog inputs <i>Cyl temp "n"</i> must be configured onto the appropriate physical analog inputs where the cylinder temperature sensors are connected. Use the "Cylinder temperature configuration wizard" in GenConfig - Analog inputs tab for easy configuration of cylinder temperature sensors.</p> <p>NOTE: The cylinder temperature difference protection is available in IS-NT only.</p>
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Setpoint: Max-CylDifPmin

Group	Engine protect
Range [units]	-32000 .. +32000 [°C]
Related FW	3.0
Description	This setpoint adjusts the maximum allowed negative difference between a particular cylinder temperature and average cylinder temperature at minimum power level adjusted by setpoint PminCylDifEval . This setpoint is one of four setpoints that define the allowed area of cylinder temperature differences depending on gen-set power. See the setpoint Max+CylDifPmin for more details.

Setpoint: Max+CylDifPnom

Group	Engine protect
Range [units]	-32000 .. +32000 [°C]
Related FW	3.0
Description	This setpoint adjusts the maximum allowed positive difference between a particular cylinder temperature and average cylinder temperature at nominal power . This setpoint is one of four setpoints that define the allowed area of cylinder temperature differences depending on gen-set power. See the setpoint Max+CylDifPmin for more details.

Setpoint: Max-CylDifPnom

Group	Engine protect
Range [units]	-32000 .. +32000 [°C]
Related FW	3.0
Description	This setpoint adjusts the maximum allowed negative difference between a particular cylinder temperature and average cylinder temperature at nominal power . This setpoint is one of four setpoints that define the allowed area of cylinder temperature differences depending on gen-set power. See the setpoint Max+CylDifPmin for more details.

Setpoint: PminCylDifEval

Group	Engine protect
Range [units]	0.0 .. Nomin power [kW]
Related FW	3.0
Description	This setpoint adjusts the gen-set power level below which the cylinder temperature difference protection is not evaluated. Learn more about this protection in the description of the setpoint Max+CylDifPmin .

Setpoint: CylDifEvalDel

Group	Engine protect
Range [units]	0 .. 600 [s]
Related FW	3.0
Description	This setpoint adjusts the evaluation delay of the cylinder temperature difference protection. Learn more about this protection in the description of the setpoint Max+CylDifPmin .

Setpoint: Service time 1

Group	Engine protect
Range [units]	0 .. 65535 [h]
Related FW	3.0
Description	<p>This setpoint is used as maintenance interval counter #1. There are four independent maintenance interval counters, all of them work the same way - their values are decremented every hour while the gen-set is running and when the zero value is reached the related alarm is issued (i.e. <i>WrnServiceT1+2</i> or <i>WrnServiceT3+4</i>). The alarm remains active until the respective counter is readjusted back to nonzero value.</p> <p>Each of the maintenance intervals can be used for different type of regular maintenance works such as oil change, spark plug change etc.</p> <p>When the particular maintenance works have been performed, readjust the appropriate counter again to the period of next regular maintenance cycle. The counter will then count down again.</p> <p>The unused maintenance timers should be adjusted to maximal value, i.e. 65535.</p>

Setpoint: Service time 2

Group	Engine protect
Range [units]	0 .. 65535 [h]
Related FW	3.0
Description	This setpoint is used as maintenance interval counter #2. There are four independent maintenance interval counters, all of them work the same way - their

	<p>values are decremented every hour while the gen-set is running and when the zero value is reached the related alarm is issued (i.e. <i>WrnServiceT1+2</i> or <i>WrnServiceT3+4</i>). The alarm remains active until the respective counter is readjusted back to nonzero value.</p> <p>Each of the maintenance intervals can be used for different type of regular maintenance works such as oil change, spark plug change etc.</p> <p>When the particular maintenance works have been performed, readjust the appropriate counter again to the period of next regular maintenance cycle. The counter will then count down again.</p> <p>The unused maintenance timers should be adjusted to maximal value, i.e. 65535.</p>
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Setpoint: Service time 3

Group	Engine protect
Range [units]	0 .. 65535 [h]
Related FW	3.0
Description	<p>This setpoint is used as maintenance interval counter #3. There are four independent maintenance interval counters, all of them work the same way - their values are decremented every hour while the gen-set is running and when the zero value is reached the related alarm is issued (i.e. <i>WrnServiceT1+2</i> or <i>WrnServiceT3+4</i>). The alarm remains active until the respective counter is readjusted back to nonzero value.</p> <p>Each of the maintenance intervals can be used for different type of regular maintenance works such as oil change, spark plug change etc.</p> <p>When the particular maintenance works have been performed, readjust the appropriate counter again to the period of next regular maintenance cycle. The counter will then count down again.</p> <p>The unused maintenance timers should be adjusted to maximal value, i.e. 65535.</p>

Setpoint: Service time 4

Group	Engine protect
Range [units]	0 .. 65535 [h]
Related FW	3.0
Description	<p>This setpoint is used as maintenance interval counter #4. There are four independent maintenance interval counters, all of them work the same way - their values are decremented every hour while the gen-set is running and when the zero value is reached the related alarm is issued (i.e. <i>WrnServiceT1+2</i> or <i>WrnServiceT3+4</i>). The alarm remains active until the respective counter is readjusted back to nonzero value.</p> <p>Each of the maintenance intervals can be used for different type of regular maintenance works such as oil change, spark plug change etc.</p> <p>When the particular maintenance works have been performed, readjust the</p>

	<p>appropriate counter again to the period of next regular maintenance cycle. The counter will then count down again.</p> <p>The unused maintenance timers should be adjusted to maximal value, i.e. 65535.</p>
--	---

Group: Analog protect

Setpoint: Batt >V

Group	Analog protect
Range [units]	8.0 .. 40.0 [V]
Related FW	3.0
Description	This setpoint adjusts the warning level for battery overvoltage alarm.

Setpoint: Batt <V

Group	Analog protect
Range [units]	8.0 .. 40.0 [V]
Related FW	3.0
Description	This setpoint adjusts the warning level for battery undervoltage alarm.

Setpoint: Batt volt del

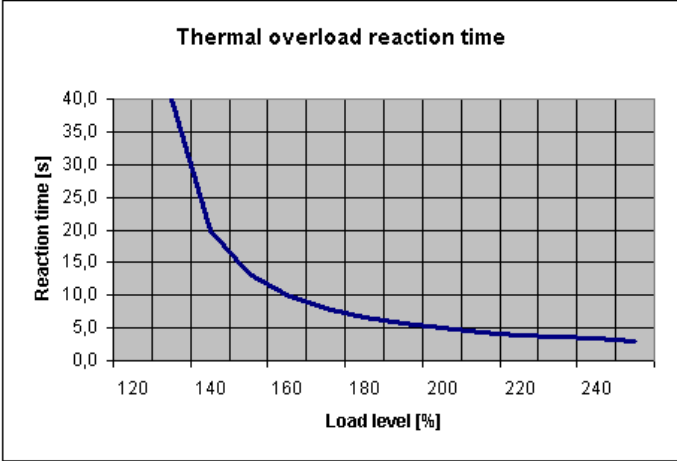
Group	Analog protect
Range [units]	0 .. 600 [s]
Related FW	3.0
Description	This setpoint adjusts the delay for battery overvoltage and undervoltage alarms.

Group: Gener protect

Setpoint: OverldStrtEval

Group	Gener Protect
Range [units]	100 .. 200 [%]
Related FW	3.0
Force value possible	YES
Description	This setpoint specifies the power level relative to the nominal power , where the thermal overload protection starts to be evaluated. See the setpoint 2PovrldStEvDel for more information about the thermal overload protection.

Setpoint: 2POvrdStEvDel

Group	Gener Protect																																		
Range [units]	0.0 .. 600.0 [s]																																		
Related FW	3.0																																		
Description	<p>This setpoint adjusts the reaction time of the thermal overload protection if the load level is 200% of the base level given by the setpoint OverldStrtEval.</p> <p>The reaction time of the thermal overload protection is not fixed; it depends on how much is the load above the limit (base level). The higher is the load the shorter the reaction time will be.</p> <div style="border: 1px solid black; padding: 5px;"> <table style="width: 100%; border-collapse: collapse;"> <thead> <tr style="background-color: #333; color: white;"> <th style="text-align: left; padding: 2px;">Load level [% of P_{nom}]</th> <th style="text-align: left; padding: 2px;">Reaction time [s]</th> </tr> </thead> <tbody> <tr> <td style="padding: 2px;">100</td> <td style="padding: 2px;">no alarm</td> </tr> <tr> <td style="padding: 2px;">110</td> <td style="padding: 2px;">no alarm</td> </tr> <tr> <td style="padding: 2px;">120</td> <td style="padding: 2px;">3600,0</td> </tr> <tr> <td style="padding: 2px;">130</td> <td style="padding: 2px;">40,0</td> </tr> <tr> <td style="padding: 2px;">140</td> <td style="padding: 2px;">20,0</td> </tr> <tr> <td style="padding: 2px;">150</td> <td style="padding: 2px;">13,3</td> </tr> <tr> <td style="padding: 2px;">160</td> <td style="padding: 2px;">10,0</td> </tr> <tr> <td style="padding: 2px;">170</td> <td style="padding: 2px;">8,0</td> </tr> <tr> <td style="padding: 2px;">180</td> <td style="padding: 2px;">6,7</td> </tr> <tr> <td style="padding: 2px;">190</td> <td style="padding: 2px;">5,7</td> </tr> <tr> <td style="padding: 2px;">200</td> <td style="padding: 2px;">5,0</td> </tr> <tr> <td style="padding: 2px;">210</td> <td style="padding: 2px;">4,4</td> </tr> <tr> <td style="padding: 2px;">220</td> <td style="padding: 2px;">4,0</td> </tr> <tr> <td style="padding: 2px;">230</td> <td style="padding: 2px;">3,6</td> </tr> <tr> <td style="padding: 2px;">240</td> <td style="padding: 2px;">3,3</td> </tr> <tr> <td style="padding: 2px;">250</td> <td style="padding: 2px;">3,1</td> </tr> </tbody> </table> </div> <div style="margin-top: 10px;"> <p>Example: 2POvrdStEvDel = 5 s OverldStrtEval = 120 %</p> $\text{REACTION TIME [s]} = \frac{2POvrdStEvDel [s] * (200 - OverldStrtEval [\%])}{\text{Engine load [\%]} - OverldStrtEval [\%]}$ </div> <div style="margin-top: 10px;">  </div>	Load level [% of P _{nom}]	Reaction time [s]	100	no alarm	110	no alarm	120	3600,0	130	40,0	140	20,0	150	13,3	160	10,0	170	8,0	180	6,7	190	5,7	200	5,0	210	4,4	220	4,0	230	3,6	240	3,3	250	3,1
Load level [% of P _{nom}]	Reaction time [s]																																		
100	no alarm																																		
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160	10,0																																		
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190	5,7																																		
200	5,0																																		
210	4,4																																		
220	4,0																																		
230	3,6																																		
240	3,3																																		
250	3,1																																		

NOTE:
The thermal overload protection is *Breaker open and cool down (BOC)* type.

Setpoint: Min Power PtM

Group	Gener protect
Range [units]	1 .. 100 [%]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used for adjusting of the lower limit of the requested gen-set power in parallel to the mains operation. If the requested load (given by the active load control mode, e.g. Baseload, Import/Export etc.) is below this limit the requested load is limited to the level adjusted by this setpoint.</p>

	<p>The only situation, where the <i>Min Power PtM</i> is ignored, is the warming procedure after the gen-set is synchronized to the mains, i.e. the Warming load can be adjusted also below the setpoint <i>Min Power PtM</i>.</p> <p>This setpoint is also used as the requested load level if a protection of <i>Low power</i> type is active.</p> <p>NOTE: Note that if IntelliMains is used and it is in active control mode (i.e. the SysLdCtrl PtM is set to LDSHARING) this setpoint is not considered and minimal power in parallel to Mains operation is given by ProcessControlMinPwr PtM is used to determine minimal power of each gen-set in the group in percentage of its nominal power.</p>
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Setpoint: *Ishort*

Group	Gener Protect
Range [units]	100 .. 500 [%]
Related FW	3.0
Description	<p>This setpoint adjusts the threshold level (in % of the nominal current) for the generator fast overcurrent protection. The protection is activated (alarm <i>Ishort</i> is issued) when the generator current in at least one phase exceeds the threshold limit for time longer than Ishort del.</p> <p>NOTE: The protection type is <i>Breaker open and cool down</i> (BOC).</p>

Setpoint: *Ishort del*

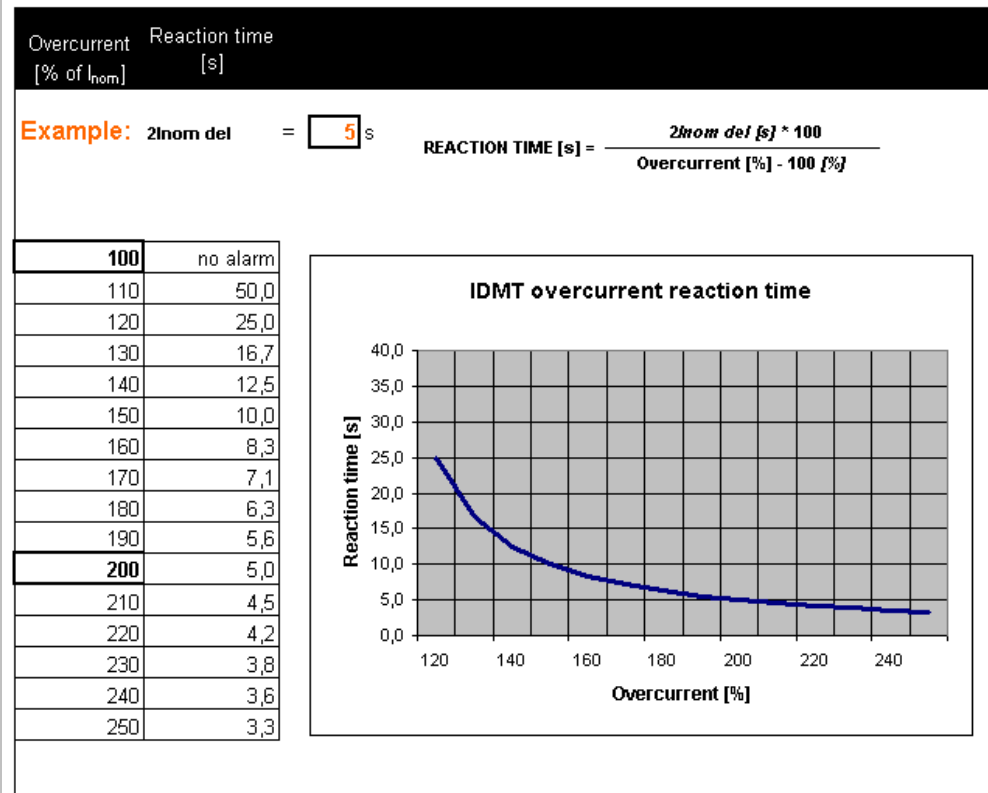
Group	Gener Protect
Range [units]	0.00 .. 10.00 [s]
Related FW	3.0
Description	<p>This setpoint adjust the delay for generator fast overcurrent protection. The limit for the protection is adjusted by the setpoint Ishort.</p> <p>NOTE: Although the resolution of this setpoint is 0.01s, in fact the adjusted delay is rounded to the next higher multiple of the period of the generator voltage. The period is either 0.02s for 50Hz systems or 0.0166s for 60Hz systems. E.g. if the delay is set to 0.03s at 50Hz system the real delay will be 0.04s.</p>

Setpoint: *2Inom del*

Group	Gener Protect
Range [units]	1 .. 600.0 [s]
Related FW	3.0
Description	This setpoint adjusts the reaction time of the IDMT overcurrent protection if the

overcurrent level is 200% of the [nominal current](#).

The reaction time of the IDMT overcurrent protection is not fixed; it depends on how much is the actual current above the limit (nominal). The higher is the overcurrent the shorter the reaction time will be.



EXAMPLE OF IDMT OVERCURRENT PROTECTION CURVE

NOTE:

The IDMT overcurrent protection is *Breaker open and cool down (BOC)* type.

Setpoint: Gen >V BOC

Group	Gener Protect
Range [units]	Gen <V BOC .. 150 [%]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint adjusts the threshold level for the generator overvoltage protection. The threshold is adjusted in % of the nominal generator voltage, which is either GenNomV or GenNomVph-ph, depending on the position of the setpoint FixVoltProtSel.</p> <p>The protection activates if the voltage in at least one phase gets over the threshold for time longer than Gen V del.</p> <p>NOTE: The associated protection to this setpoint is <i>Breaker open and cool down (BOC)</i> type. There is also <i>Shutdown</i> overvoltage protection, which is adjusted by setpoint</p>

Gen >V Sd.
<p>NOTE: The BOC protections are active after the Max stab time elapsed or after the GCB was closed, then while the GCB is closed and then also during cooling (if Cooling speed = NOMINAL).</p>

Setpoint: Gen <V BOC

Group	Gener Protect
Range [units]	20 .. Gen >V BOC [%]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint adjusts the threshold level for the generator undervoltage protection. The threshold is adjusted in % of the nominal generator voltage, which is either GenNomV or GenNomVph-ph, depending on the position of the setpoint FixVoltProtSel.</p> <p>The protection activates if the voltage in at least one phase drops below the threshold for time longer than Gen V del.</p> <p>NOTE: The generator undervoltage protection is <i>Breaker open and cool down (BOC)</i> type.</p> <p>NOTE: The BOC protections are active after the Max stab time elapsed or after the GCB was closed, then while the GCB is closed and then also during cooling (if Cooling speed = NOMINAL).</p>

Setpoint: Gen >V Sd

Group	Gener protect
Range [units]	50 .. 150 [%]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint adjusts the threshold level for the generator overvoltage shutdown protection. The threshold is adjusted in % of the nominal generator voltage, which is either GenNomV or GenNomVph-ph, depending on the position of the setpoint FixVoltProtSel.</p> <p>The protection activates if the voltage in at least one phase gets over the threshold for time longer than Gen V del.</p> <p>NOTE: The associated protection to this setpoint is <i>Shutdown</i> type. There is also <i>Breaker open and cool down (BOC)</i> overvoltage protection, which is adjusted by setpoint Gen >BOC. The BOC overvoltage protection is intended to be used as first</p>

	level protection with lower threshold, whereas the shutdown one is intended as second level with higher threshold.
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Setpoint: Gen V del

Group	Gener protect
Range [units]	0.00 .. 600.00 [s]
Related FW	3.0
Description	<p>The setpoint adjusts the delay for generator under- and overvoltage protections. The thresholds for these protections are adjusted by setpoints Gen >V BOC, Gen <V BOC and Gen >V Sd.</p> <p>NOTE: Although the resolution of this setpoint is 0.01s, in fact the adjusted delay is rounded to the next higher multiple of the period of the generator voltage. The period is either 0.02s for 50Hz systems or 0.0166s for 60Hz systems. E.g. if the delay is set to 0.03s at 50Hz system the real delay will be 0.04s.</p>

Setpoint: Gen >f

Group	Gener Protect
Range [units]	Gen <f .. 150 [%]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint adjusts the threshold level for the generator overfrequency protection. The threshold is adjusted in % of the system frequency (Nominal Freq + Nom frq offset).</p> <p>The protection activates if the frequency in phase L3 gets over the threshold for time longer than Gen f del.</p> <p>NOTE: The generator overfrequency protection is <i>Breaker open and cool down (BOC)</i> type.</p> <p>NOTE: The BOC protections are active after the Max stab time elapsed or after the GCB was closed, then while the GCB is closed and then also during cooling (if Cooling speed = NOMINAL).</p>

Setpoint: Gen <f

Group	Gener Protect
Range [units]	50 .. Gen >f [%]
Related FW	3.0
Force value	YES

possible	
Description	<p>This setpoint adjusts the threshold level for the generator underfrequency protection. The threshold is adjusted in % of the system frequency (Nominal Freq + Nom frq offset).</p> <p>The protection activates if the frequency in phase L3 drops below the threshold for time longer than Gen f del.</p> <p>NOTE: The generator underfrequency protection is <i>Breaker open and cool down (BOC)</i> type.</p> <p>NOTE: The BOC protections are active after the Max stab time elapsed or after the GCB was closed, then while the GCB is closed and then also during cooling (if Cooling speed = NOMINAL).</p>

Setpoint: Gen f del

Group	Gener Protect
Range [units]	0.00 .. 600.00 [s]
Related FW	3.0
Description	<p>The setpoint adjusts the delay for generator under and overfrequency protections. The thresholds for these protections are adjusted by setpoints Gen >f and Gen <f.</p> <p>NOTE: Although the resolution of this setpoint is 0.01s, in fact the adjusted delay is rounded to the next higher multiple of the period of the generator voltage. The period is either 0.02s for 50Hz systems or 0.0166s for 60Hz systems. E.g. if the delay is set to 0.03s at 50Hz system the real delay will be 0.04s.</p>

Setpoint: BusMeasError

Group	Gener protect
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used to enable and disable the <i>Bus meas error</i> alarm. If enabled, it is issued when the controller detects a mismatch between the expected and current voltage on the busbar. The mismatch means the measured voltage is out of limits, although the controller receives information that there is a breaker closed, through which the bus should be supplied. The alarm is issued when the mismatch lasts more than 20s.</p> <p>The breaker mentioned above may be MCB, GCB of the respective controller or GCB of any other controller in the group.</p> <p>If there is a mismatch of bus voltage then closing of the GCB is blocked even if</p>

	the 20s delay hasn't elapsed yet.
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Setpoint: Reverse power

Group	Gener Protect
Range [units]	0 .. 50 [%]
Related FW	3.0
Description	<p>This setpoint adjusts the threshold level for the generator reverse (negative) power protection. The threshold is adjusted in % of the generator nominal power.</p> <p>The protection activates if the generator power drops below the threshold for time longer than ReversePwr del.</p> <p>NOTE: The generator reverse power protection is <i>Breaker open and cool down (BOC)</i> type.</p>

Setpoint: ReversePwr del

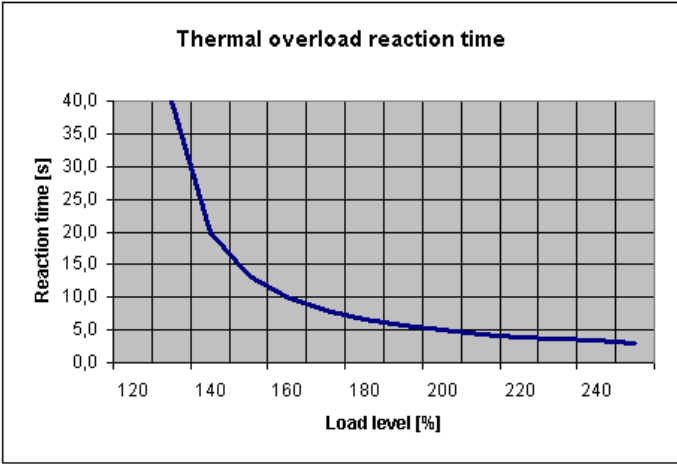
Group	Gener Protect
Range [units]	0 .. 600.0 [s]
Related FW	3.0
Description	The setpoint adjusts the delay for generator reverse power protection. The threshold for the protection is adjusted by setpoint Reverse power .

Setpoint: Nom EthFltCurr

Group	Gener protect
Range [units]	0 .. 10000 [A]
Related FW	3.0
Force value possible	YES
Description	This setpoint adjust the level of EarthFault Current when IDMT protection starts to get evaluated. Time of evaluation of this protection is given by the setpoint 2EthFltCur del . When the EarthFault Current goes below the level given by Nom EthFltCurr , protection starts decreasing its thermal counter. For more information about this protection, refer to the setpoint 2EthFltCur del .

Setpoint: 2EthFltCur del

Group	Gener protect
Range [units]	OFF, 0.1 .. 600.0 [s]
Related FW	3.0

Force value possible	YES																																		
Description	<p>This setpoint adjusts the reaction time of the IDMT EarthFault Current protection if the current is 200% of the base level given by the setpoint Nom EthFltCurr.</p> <p>The reaction time of the IDMT EarthFault Current protection is not fixed; it depends on how much is the current above the limit (base level). The higher is the current the shorter the reaction time will be.</p> <div style="border: 1px solid black; padding: 5px;"> <p>Load level [% of P_{nom}] Reaction time [s]</p> <p>Example: 2POvridStEvDel = <input type="text" value="5"/> s OverIdStrtEval = <input type="text" value="120"/> % REACTION TIME [s] = $\frac{2POvridStEvDel [s] * (200 - OverIdStrtEval [\%])}{Engine\ load [\%] - OverIdStrtEval [\%]}$</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th>Load level [% of P_{nom}]</th> <th>Reaction time [s]</th> </tr> </thead> <tbody> <tr><td>100</td><td>no alarm</td></tr> <tr><td>110</td><td>no alarm</td></tr> <tr><td>120</td><td>3600,0</td></tr> <tr><td>130</td><td>40,0</td></tr> <tr><td>140</td><td>20,0</td></tr> <tr><td>150</td><td>13,3</td></tr> <tr><td>160</td><td>10,0</td></tr> <tr><td>170</td><td>8,0</td></tr> <tr><td>180</td><td>6,7</td></tr> <tr><td>190</td><td>5,7</td></tr> <tr><td>200</td><td>5,0</td></tr> <tr><td>210</td><td>4,4</td></tr> <tr><td>220</td><td>4,0</td></tr> <tr><td>230</td><td>3,6</td></tr> <tr><td>240</td><td>3,3</td></tr> <tr><td>250</td><td>3,1</td></tr> </tbody> </table>  </div> <p>EXAMPLE OF IDMT CURRENT PROTECTION CURVE</p> <p>NOTE: The IDMT EarthFault Current protection is <i>Breaker open and cool down (BOC)</i> type.</p> <p>NOTE: This protection's internal counter accumulates and it starts continuously decreasing when the EarthFault Current goes below Nom EthFltCurr. This function prevents the protection from completely resetting when the EarthFault Current goes below Nom EthFltCurr for only a short period of time. This behavior emulates circuit-breaker with thermal current protection.</p>	Load level [% of P _{nom}]	Reaction time [s]	100	no alarm	110	no alarm	120	3600,0	130	40,0	140	20,0	150	13,3	160	10,0	170	8,0	180	6,7	190	5,7	200	5,0	210	4,4	220	4,0	230	3,6	240	3,3	250	3,1
Load level [% of P _{nom}]	Reaction time [s]																																		
100	no alarm																																		
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220	4,0																																		
230	3,6																																		
240	3,3																																		
250	3,1																																		

Setpoint: ExcitationLoss

Group	Gener protect
Range [units]	0 .. 150 [%]
Related FW	3.0
Force value possible	YES

Description	<p>This setpoint adjusts excitation loss protection level. Corresponding level in kVA is calculated from nominal power of gen-set as a negative percentage given by this setpoint (e.g. this setpoint is adjusted to 50% and nominal power of gen-set is 200 kW, therefore excitation loss protection level is set to -100 kVA)</p> <p>Delay for this protection is given by the setpoint ExctLoss del.</p> <p>This protection is breaker off and cooldown type. For more information on protection types please refer to the section Alarm types.</p>
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Setpoint: ExctLoss del

Group	Gener protect
Range [units]	OFF, 0.1 .. 600.0 [s]
Related FW	3.0
Force value possible	YES
Description	This setpoint adjusts the delay for loss of excitation protection. Threshold of this protection is given by the setpoint ExcitationLoss .

Setpoint: Gen V unbal

Group	Gener protect
Range [units]	0 .. 200 [%]
Related FW	3.0
Description	<p>This setpoint adjusts the threshold level for the generator voltage unbalance protection. The threshold is adjusted in % of the nominal generator voltage, which is either GenNomV or GenNomVph-ph, depending on the position of the setpoint FixVoltProtSel. The protection is <i>Breaker open and cool down</i> type and is created in the default archive as universal analog protection at the value Gen V unbal, which is calculated as maximum difference between two phase voltages.</p> <p>The protection activates if the voltage unbalance gets over the threshold for time longer than Gen V unb del.</p> <p>NOTE: The voltage unbalance protection is created in the default archive using the mechanism of <i>universal analog protections</i>. That means this setpoint is one of general-purpose setpoints, which may be used for different purpose if the protection is deleted from the configuration.</p>

Setpoint: Gen V unb del

Group	Gener protect
Range [units]	0.0 .. 600.0 [s]
Related FW	3.0
Description	This setpoint adjusts the delay for the generator voltage unbalance protection.

	<p>The threshold for the protection is adjusted by setpoint Gen V unbal.</p> <p>NOTE: The generator voltage unbalance protection is created in the default archive using the mechanism of <i>universal analog protections</i>. That means this setpoint is one of general-purpose setpoints, which may be used for different purpose if the protection is deleted from the configuration.</p>
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Setpoint: Gen I unbal

Group	Gener protect
Range [units]	0 .. 200 [%]
Related FW	3.0
Description	<p>This setpoint adjusts the threshold level for the generator current unbalance protection. The threshold is adjusted in % of the generator nominal current. The protection is <i>Breaker open and cool down</i> type and is created in the default archive as universal analog protection at the value Gen I unbal, which is calculated as maximum difference between two phase currents.</p> <p>The protection activates if the current unbalance gets over the threshold for time longer than Gen I unb del.</p> <p>NOTE: The current unbalance protection is created in the default archive using the mechanism of <i>universal analog protections</i>. That means this setpoint is one of general-purpose setpoints, which may be used for different purpose if the protection is deleted from the configuration.</p>

Setpoint: Gen I unb del

Group	Gener protect
Range [units]	0.0 .. 600.0 [s]
Related FW	3.0
Description	<p>This setpoint adjusts the delay for the generator current unbalance protection. The threshold for the protection is adjusted by setpoint Gen I unbal.</p> <p>NOTE: The generator current unbalance protection is created in the default archive using the mechanism of <i>universal analog protections</i>. That means this setpoint is one of general-purpose setpoints, which may be used for different purpose if the protection is deleted from the configuration.</p>

Setpoint: Bus V unbal

Group	Gener protect
Range [units]	0 .. 200 [%]
Related FW	3.0

Description	<p>This setpoint adjusts the threshold level for the bus voltage unbalance protection. The threshold is adjusted in % of the nominal generator voltage, which is either BusNomV or BusNomVph-ph, depending on the position of the setpoint FixVoltProtSel. The protection is created in the default archive as universal analog protection at the value <i>Bus V unbal</i>, which is calculated as maximum difference between two bus phase voltages.</p> <p>The protection activates if the voltage unbalance gets over the threshold for time longer than Bus V unbal del.</p> <p>NOTE: Activation of the protection is only recorded into the history file, no other actions are performed.</p> <p>NOTE: The voltage unbalance protection is created in the default archive using the mechanism of <i>universal analog protections</i>. That means this setpoint is one of general-purpose setpoints, which may be used for different purpose if the protection is deleted from the configuration.</p>
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Setpoint: Bus V unbal del

Group	Gener protect
Range [units]	0.0 .. 600.0 [s]
Related FW	3.0
Description	<p>This setpoint adjusts the delay for the bus voltage unbalance protection. The threshold for the protection is adjusted by setpoint Bus V unbal.</p> <p>NOTE: The bus voltage unbalance protection is created in the default archive using the mechanism of <i>universal analog protections</i>. That means this setpoint is one of general-purpose setpoints, which may be used for different purpose if the protection is deleted from the configuration.</p>

Group: Power management

Setpoint: Pwr Management

Group	Pwr Management
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used to enable/disable the power management function in the particular controller.</p> <p>If the function is disabled the start and stop of the gen-set is performed only according to the position of the binary input Sys start/stop, i.e. if the input is active the gen-set is running and vice versa.</p>

Setpoint: #Pwr mgmt mode

Group	Pwr management						
Range [units]	ABS(kW), ABS(kVA), REL(%LOAD) [-]						
Related FW	3.0						
Description	<p>This setpoint is used to select the power management mode:</p> <table border="1"> <tr> <td>ABS (kW)</td> <td>The power management is based on actual active power and gen-set nominal power. The reserves are calculated and adjusted in kW.</td> </tr> <tr> <td>ABS (kVA)</td> <td>The power management is based on actual apparent power and gen-set "nominal apparent power" is calculated as $3 * \text{Nomin current} * \text{GenNomV}$. The reserves are calculated and adjusted in kVA. NOTE: This mode is intended for systems supplying loads with low power factor. It prevents the gen-sets from operating at high currents.</td> </tr> <tr> <td>REL (%)</td> <td>The power management is based on the relative load, i.e. ratio active power to nominal power. The reserves are calculated and adjusted in %.</td> </tr> </table>	ABS (kW)	The power management is based on actual active power and gen-set nominal power . The reserves are calculated and adjusted in kW.	ABS (kVA)	The power management is based on actual apparent power and gen-set "nominal apparent power" is calculated as $3 * \text{Nomin current} * \text{GenNomV}$. The reserves are calculated and adjusted in kVA. NOTE: This mode is intended for systems supplying loads with low power factor. It prevents the gen-sets from operating at high currents.	REL (%)	The power management is based on the relative load, i.e. ratio active power to nominal power. The reserves are calculated and adjusted in %.
ABS (kW)	The power management is based on actual active power and gen-set nominal power . The reserves are calculated and adjusted in kW.						
ABS (kVA)	The power management is based on actual apparent power and gen-set "nominal apparent power" is calculated as $3 * \text{Nomin current} * \text{GenNomV}$. The reserves are calculated and adjusted in kVA. NOTE: This mode is intended for systems supplying loads with low power factor. It prevents the gen-sets from operating at high currents.						
REL (%)	The power management is based on the relative load, i.e. ratio active power to nominal power. The reserves are calculated and adjusted in %.						

Setpoint: Priority

Group	Pwr Management
Range [units]	1 .. 32 [-]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used for adjusting of the gen-set priority. Value of 1 represents the the highest priority (lowest starting order), value of 32 is the lowest priority (highest starting order).</p> <p>To "push" the particular genset temporarily into the highest priority, value of 0 can be forced (see Force value 1) into this setpoint.</p>

Setpoint: #PriorAutoSwap

Group	Pwr management		
Range [units]	DISABLED, RUN HOURS EQU, LD DEMAND SWAP [-]		
Related FW	3.0		
Description	<p>This setpoint selects the method of optimization of priorities:</p> <table border="1"> <tr> <td>DISABLED</td> <td>Optimalization is disabled. Priorities are given directly by the values adjusted into the setpoints Priority.</td> </tr> </table>	DISABLED	Optimalization is disabled. Priorities are given directly by the values adjusted into the setpoints Priority .
DISABLED	Optimalization is disabled. Priorities are given directly by the values adjusted into the setpoints Priority .		

RUN HOURS EQU	The priority setpoints are automatically updated (swapped) to equalize running hours of the gen-sets or to keep constant difference of running hours.
LD DEMAND SWAP	This method changes the priorities (not the setpoints itself) of up to 3 gen-sets of different capacity to optimize which gen-sets are running according to their capacities and actual load demand (if more gen-sets are needed, please use IGS-NT-PSC firmware in additional controller - more information about this FW can be found on our webpages www.comap.cz). Note that this priority swapping function may be used only if Pwr mgmt mode is set to ABS (kW).
NOTE: See the chapter Optimization of priorities for more details.	
NOTE: Setpoint Priority in gen-set controllers is not actually changed by AutoSwap functions - the priority is changed only locally during AutoSwap function is enabled. Note that after RHE is activated any changes in the actual priority setpoints need to be confirmed by disabling and enabling RHE again to take effect.	
NOTE: If the optimization is enabled at least one gen-set in the group must be set as the master for the optimization (Priority ctrl = MASTER). It is possible to have more than one master, the one with lowest CAN address will play the role of the master and if it is switched off the next one will take the master role.	
CAUTION! If the controller which is set to MASTER in PriorAutoSwap function is in Emerg. manual , priority autoswapping will not work and no other controller will assume MASTER role.	

Setpoint: Priority ctrl

Group	Pwr management				
Range [units]	SLAVE, MASTER [-]				
Related FW	3.0				
Force value possible	YES				
Description	<p>This setpoint is used to select the role of this particular controller in the optimization of priorities.</p> <table border="1" style="width: 100%;"> <tr> <td style="background-color: #cccccc;">SLAVE</td> <td>The controller plays only passive role. Priority can be changed from other controller (active master).</td> </tr> <tr> <td style="background-color: #cccccc;">MASTER</td> <td>The controller can play both active or passive role. It plays active master role, i.e. changes priorities in slave controllers, if it has the lowest address from all the controllers being switched to MASTER position. Otherwise it plays the passive role as if switched to SLAVE position.</td> </tr> </table>	SLAVE	The controller plays only passive role. Priority can be changed from other controller (active master).	MASTER	The controller can play both active or passive role. It plays active master role, i.e. changes priorities in slave controllers, if it has the lowest address from all the controllers being switched to MASTER position. Otherwise it plays the passive role as if switched to SLAVE position.
SLAVE	The controller plays only passive role. Priority can be changed from other controller (active master).				
MASTER	The controller can play both active or passive role. It plays active master role, i.e. changes priorities in slave controllers, if it has the lowest address from all the controllers being switched to MASTER position. Otherwise it plays the passive role as if switched to SLAVE position.				

	<p>NOTE: It is possible to have more than one master; always only the one with lowest CAN address will play the master role.</p>
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Setpoint: #SysAMFstrDel

Group	Pwr management
Range [units]	0 .. 600 [s]
Related FW	3.0
Description	<p>This setpoint adjusts the delay between closing of the input Sys start/stop and activation of the gen-set group into island operation (i.e. the MCB feedback is open). The delay of activation of the group into parallel-to-mains operation is fixed 1s.</p> <p>The setpoint is primarily intended for adjusting the "Mains failure autostart" delay in sites, where the input Sys start/stop is controlled directly by a mains decoupling relay.</p>

Setpoint: ##SysAMFstopDel

Group	Pwr Management
Range [units]	0 .. 600 [s]
Related FW	3.0
Description	<p>This setpoint adjusts the delay between opening of the input Sys start/stop and deactivation of the gen-set group if MCB feedback is open. If the MCB feedback is closed, the the delay is fixed 1s.</p> <p>The setpoint is primarily intended for adjusting the "Mains return" delay in sites, where the input Sys start/stop is controlled directly by a mains decoupling relay.</p>

Setpoint: #LoadResStrt 1

Group	Pwr Management
Range [units]	-32000 .. LoadResStop 1 [kX]
Related FW	3.0
Description	<p>This setpoint is used to adjust the load reserve for start in absolute mode. i.e. Pwr mgmt mode = ABS (kW) or ABS (kVA) if the reserve set #1 is active. Learn more about reserves in the chapter Reserves, minimal running power.</p> <p>The currently active reserve set is selected by binary inputs Load res 2, Load res 3 and Load res 4. If none of these inputs is active the set #1 is selected.</p> <p>NOTE: If the absolute power management is selected, this setpoint (or the setpoints LoadResStrt 2, LoadResStrt 3 or LoadResStrt 4 depending on which load reserve set is selected) determines also the number of gensets (that are part of the power</p>

	management) which will start (according to their priority and nominal power).
	<p>NOTE: There is a possibility to assign this setpoint negative number. This can be used in some situations to allow genset start after Sys Start/Stop gets active. It is not destined for normal operation. Please refer to the Troubleshooting guide for more information (chapter "MGCB is not closed although gensets are running").</p>
	<p>NOTE: # sign in the name of this setpoint marks that this setpoint is shared among all controllers connected by CAN2 bus.</p>

Setpoint: #LoadResStop 1

Group	Pwr Management
Range [units]	LoadResStrt 1 .. 32000 [kX]
Related FW	3.0
Description	<p>This setpoint is used to adjust the load reserve for stop in absolute mode. i.e. Pwr mgmt mode = ABS (kW) or ABS (kVA) if the reserve set #1 is active. Learn more about reserves in the chapter Reserves, minimal running power.</p> <p>The currently active reserve set is selected by binary inputs Load res 2, Load res 3 and Load res 4. If none of these inputs is active the set #1 is selected.</p> <p>NOTE: The reserve for stop must be always adjusted higher than the reserve for start.</p>

Setpoint: #LoadResStrt 2

Group	Pwr Management
Range [units]	-32000 .. LoadResStop 2 [kX]
Related FW	3.0
Description	<p>This setpoint is used to adjust the load reserve for start in absolute mode. i.e. Pwr mgmt mode = ABS (kW) or ABS (kVA) if the reserve set #2 is active. Learn more about reserves in the chapter Reserves, minimal running power.</p> <p>The currently active reserve set is selected by binary inputs Load res 2, Load res 3 and Load res 4. If none of these inputs is active the set #1 is selected.</p> <p>NOTE: If the absolute power management is selected, this setpoint (or the setpoints LoadResStrt 1, LoadResStrt 3 or LoadResStrt 4 depending on which load reserve set is selected) determines also the number of gensets (that are part of the power management) which will start (according to their priority and nominal power).</p> <p>NOTE: There is a possibility to assign this setpoint negative number. This can be used in some situations to allow genset start after Sys Start/Stop gets active. It is not destined for normal operation. Please refer to the Troubleshooting guide for more information (chapter "MGCB is not closed although gensets are running").</p>

NOTE: # sign in the name of this setpoint marks that this setpoint is shared among all controllers connected by CAN2 bus.

Setpoint: #LoadResStop 2

Group	Pwr Management
Range [units]	LoadResStrt 2 .. 32000 [kX]
Related FW	3.0
Description	<p>This setpoint is used to adjust the load reserve for stop in absolute mode. i.e. Pwr mgmt mode = ABS (kW) or ABS (kVA) if the reserve set #2 is active. Learn more about reserves in the chapter Reserves, minimal running power.</p> <p>The currently active reserve set is selected by binary inputs Load res 2, Load res 3 and Load res 4. If none of these inputs is active the set #1 is selected.</p> <p style="background-color: #e0e0e0;">NOTE: The reserve for stop must be always adjusted higher than the reserve for start.</p>

Setpoint: #LoadResStrt 3

Group	Pwr Management
Range [units]	-32000 .. LoadResStop 3 [kX]
Related FW	3.0
Description	<p>This setpoint is used to adjust the load reserve for start in absolute mode. i.e. Pwr mgmt mode = ABS (kW) or ABS (kVA) if the reserve set #3 is active. Learn more about reserves in the chapter Reserves, minimal running power.</p> <p>The currently active reserve set is selected by binary inputs Load res 2, Load res 3 and Load res 4. If none of these inputs is active the set #1 is selected.</p> <p style="background-color: #e0e0e0;">NOTE: If the absolute power management is selected, this setpoint (or the setpoints LoadResStrt 1, LoadResStrt 2 or LoadResStrt 4 depending on which load reserve set is selected) determines also the number of gensets (that are part of the power management) which will start (according to their priority and nominal power).</p> <p style="background-color: #e0e0e0;">NOTE: There is a possibility to assign this setpoint negative number. This can be used in some situations to allow genset start after Sys Start/Stop gets active. It is not destined for normal operation. Please refer to the Troubleshooting guide for more information (chapter "MGCB is not closed although gensets are running").</p> <p style="background-color: #e0e0e0;">NOTE: # sign in the name of this setpoint marks that this setpoint is shared among all controllers connected by CAN2 bus.</p>

Setpoint: #LoadResStop 3

Group	Pwr Management
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Range [units]	LoadResStrt 3 .. 32000 [kX]
Related FW	3.0
Description	<p>This setpoint is used to adjust the load reserve for stop in absolute mode. i.e. Pwr mgmt mode = ABS (kW) or ABS (kVA) if the reserve set #3 is active. Learn more about reserves in the chapter Reserves, minimal running power.</p> <p>The currently active reserve set is selected by binary inputs Load res 2, Load res 3 and Load res 4. If none of these inputs is active the set #1 is selected.</p> <p>NOTE: The reserve for stop must be always adjusted higher than the reserve for start.</p>

Setpoint: #LoadResStrt 4

Group	Pwr Management
Range [units]	-32000 .. LoadResStop 4 [kX]
Related FW	3.0
Description	<p>This setpoint is used to adjust the load reserve for start in absolute mode. i.e. Pwr mgmt mode = ABS (kW) or ABS (kVA) if the reserve set #4 is active. Learn more about reserves in the chapter Reserves, minimal running power.</p> <p>The currently active reserve set is selected by binary inputs Load res 2, Load res 3 and Load res 4. If none of these inputs is active the set #1 is selected.</p> <p>NOTE: If the absolute power management is selected, this setpoint (or the setpoints LoadResStrt 1, LoadResStrt 2 or LoadResStrt 3 depending on which load reserve set is selected) determines also the number of gensets (that are part of the power management) which will start (according to their priority and nominal power).</p> <p>NOTE: There is a possibility to assign this setpoint negative number. This can be used in some situations to allow genset start after Sys Start/Stop gets active. It is not destined for normal operation. Please refer to the Troubleshooting guide for more information (chapter "MGCB is not closed although gensets are running").</p> <p>NOTE: # sign in the name of this setpoint marks that this setpoint is shared among all controllers connected by CAN2 bus.</p>

Setpoint: #LoadResStop 4

Group	Pwr Management
Range [units]	LoadResStrt 4 .. 32000 [kX]
Related FW	3.0
Description	<p>This setpoint is used to adjust the load reserve for stop in absolute mode. i.e. Pwr mgmt mode = ABS (kW) or ABS (kVA) if the reserve set #4 is active. Learn more about reserves in the chapter Reserves, minimal running power.</p> <p>The currently active reserve set is selected by binary inputs Load res 2, Load res</p>

	<p>3 and Load res 4. If none of these inputs is active the set #1 is selected.</p> <p>NOTE: The reserve for stop must be always adjusted higher than the reserve for start.</p>
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Setpoint: $\# \%LdResStrt 1$

Group	Pwr Management
Range [units]	0 .. $\# \%LdResStop 1$ [%]
Related FW	3.0
Description	<p>This setpoint is used to adjust the load reserve for start in relative mode. i.e. Pwr mgmt mode = REL (%) if the reserve set #1 is active. Learn more about reserves in the chapter Reserves, minimal running power.</p> <p>The currently active reserve set is selected by binary inputs Load res 2, Load res 3 and Load res 4. If none of these inputs is active the set #1 is selected.</p>

Setpoint: $\# \%LdResStop 1$

Group	Pwr Management
Range [units]	$\# \%LdResStrt 1$.. 110 [%]
Related FW	3.0
Description	<p>This setpoint is used to adjust the load reserve for stop in relative mode. i.e. Pwr mgmt mode = REL (%) if the reserve set #1 is active. Learn more about reserves in the chapter Reserves, minimal running power.</p> <p>The currently active reserve set is selected by binary inputs Load res 2, Load res 3 and Load res 4. If none of these inputs is active the set #1 is selected.</p> <p>NOTE: The reserve for stop must be always adjusted higher than the reserve for start.</p>

Setpoint: $\# \%LdResStrt 2$

Group	Pwr Management
Range [units]	0 .. $\# \%LdResStop 2$ [%]
Related FW	3.0
Description	<p>This setpoint is used to adjust the load reserve for start in relative mode. i.e. Pwr mgmt mode = REL (%) if the reserve set #2 is active. Learn more about reserves in the chapter Reserves, minimal running power.</p> <p>The currently active reserve set is selected by binary inputs Load res 2, Load res 3 and Load res 4. If none of these inputs is active the set #1 is selected.</p>

Setpoint: #LdResStop 2

Group	Pwr Management
Range [units]	#LdResStrt 2 .. 110 [%]
Related FW	3.0
Description	<p>This setpoint is used to adjust the load reserve for stop in relative mode. i.e. Pwr mgmt mode = REL (%) if the reserve set #2 is active. Learn more about reserves in the chapter Reserves, minimal running power.</p> <p>The currently active reserve set is selected by binary inputs Load res 2, Load res 3 and Load res 4. If none of these inputs is active the set #1 is selected.</p> <p>NOTE: The reserve for stop must be always adjusted higher than the reserve for start.</p>

Setpoint: #LdResStrt 3

Group	Pwr Management
Range [units]	0 .. %LdResStop 3 [%]
Related FW	3.0
Description	<p>This setpoint is used to adjust the load reserve for start in relative mode. i.e. Pwr mgmt mode = REL (%) if the reserve set #3 is active. Learn more about reserves in the chapter Reserves, minimal running power.</p> <p>The currently active reserve set is selected by binary inputs Load res 2, Load res 3 and Load res 4. If none of these inputs is active the set #1 is selected.</p>

Setpoint: #LdResStop 3

Group	Pwr Management
Range [units]	#LdResStrt 3 .. 110 [%]
Related FW	3.0
Description	<p>This setpoint is used to adjust the load reserve for stop in relative mode. i.e. Pwr mgmt mode = REL (%) if the reserve set #3 is active. Learn more about reserves in the chapter Reserves, minimal running power.</p> <p>The currently active reserve set is selected by binary inputs Load res 2, Load res 3 and Load res 4. If none of these inputs is active the set #1 is selected.</p> <p>NOTE: The reserve for stop must be always adjusted higher than the reserve for start.</p>

Setpoint: #LdResStrt 4

Group	Pwr Management
Range [units]	0 .. %LdResStop 4 [%]
Related FW	3.0

Description	<p>This setpoint is used to adjust the load reserve for start in relative mode. i.e. Pwr mgmt mode = REL (%) if the reserve set #4 is active. Learn more about reserves in the chapter Reserves, minimal running power.</p> <p>The currently active reserve set is selected by binary inputs Load res 2, Load res 3 and Load res 4. If none of these inputs is active the set #1 is selected.</p>
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Setpoint: #LdResStop 4

Group	Pwr Management
Range [units]	#LdResStrt 4 .. 110 [%]
Related FW	3.0
Description	<p>This setpoint is used to adjust the load reserve for stop in relative mode. i.e. Pwr mgmt mode = REL (%) if the reserve set #4 is active. Learn more about reserves in the chapter Reserves, minimal running power.</p> <p>The currently active reserve set is selected by binary inputs Load res 2, Load res 3 and Load res 4. If none of these inputs is active the set #1 is selected.</p> <p>NOTE: The reserve for stop must be always adjusted higher than the reserve for start.</p>

Setpoint: #NextStrt Del

Group	Pwr Management
Range [units]	0 .. 3600 [s]
Related FW	3.0
Description	<p>This setpoint is used to adjust the delay of starting the next gen-set when the actual load reserve drops below the adjusted reserve for start, but the group is still not overloaded.</p>

Setpoint: ##OverldNextDel

Group	Pwr Management
Range [units]	0 .. 3600 [s]
Related FW	3.0
Description	<p>If the system reserve drops below the start limit for next gen-set the delay #NextStrt del will begin to count down. But if the load raises too quickly it might happen that the system gets overloaded already before the delay #NextStrt del reaches zero.</p> <p>This setpoint is used to prevent this situation. If the #NextStrt del timer is already counting down (i.e. the condition for starting of next gen-set based on reserves is fulfilled), the total load of running gen-sets reaches 90% of their nominal capacity and the remaining time of the running timer is higher than #OverldNextDel, the running timer is shortened to the value of #OverldNextDel to speed up the start-up</p>

	of the next gen-set.
	NOTE: The setpoint takes place only in island operation.

Setpoint: #NextStopDel

Group	Pwr Management
Range [units]	0 .. 3600 [s]
Related FW	3.0
Description	This setpoint is used to adjust the delay of stopping the next gen-set when the actual load reserve rises above the adjusted load reserve for stop.

Setpoint: #SlowStopDel

Group	Pwr Management
Range [units]	0 .. 600 [s]
Related FW	3.0
Description	This setpoint is used to adjust how long the particular gen-set will suppress it's own <i>Slow stop</i> alarm to give chance to another gen-set to start and replace the defective one. If there isn't any available gen-set to start, the alarm is not suppressed.

Setpoint: #MinRunPower 1

Group	Power Management
Range [units]	0 .. 65000 [kW]
Related FW	3.0
Description	This setpoint is used to adjust certain minimum value of the sum of nominal power of all running gen-sets. If the function is active, then the gen-sets would not be stopped, although the reserve for stop is fulfilled, if the total remaining nominal power dropped below this minimal value. There are 3 different <i>MinRunPower</i> setpoints, this particular one is activated by the input MinRun power 1 . NOTE: If more than one binary input for MinRunPower activation is closed MinRunPower with higher number is used (i.e. binary inputs with higher number have higher priority). When no binary input is closed, then minimal running power is 0.

Setpoint: #MinRunPower 2

Group	Power Management
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Range [units]	0 .. 65000 [kW]
Related FW	3.0
Description	<p>This setpoint is used to adjust certain minimum value of the sum of nominal power of all running gen-sets. If the function is active, then the gen-sets would not be stopped, although the reserve for stop is fulfilled, if the total remaining nominal power dropped below this minimal value.</p> <p>There are 3 different <i>MinRunPower</i> setpoints, this particular one is activated by the input MinRun power 2.</p> <p>NOTE: If more than one binary input for MinRunPower activation is closed MinRunPower with higher number is used (i.e. binary inputs with higher number have higher priority). When no binary input is closed, then minimal running power is 0.</p>

Setpoint: #MinRunPower 3

Group	Power Management
Range [units]	0 .. 65000 [kW]
Related FW	3.0
Description	<p>This setpoint is used to adjust certain minimum value of the sum of nominal power of all running gen-sets. If the function is active, then the gen-sets would not be stopped, although the reserve for stop is fulfilled, if the total remaining nominal power dropped below this minimal value.</p> <p>There are 3 different <i>MinRunPower</i> setpoints, this particular one is activated by the input MinRun power 3.</p> <p>NOTE: If more than one binary input for MinRunPower activation is closed MinRunPower with higher number is used (i.e. binary inputs with higher number have higher priority). When no binary input is closed, then minimal running power is 0.</p>

Setpoint: RunHoursBase

Group	Pwr management
Range [units]	0 .. 200000 [h]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used for adjustment of the "initial point" of the running hours equalization function. It is used either for reflecting the difference of engine hours in the moment when the RHE function was activated or for keeping certain constant difference in the engine hours.</p> <p>See the examples in the chapter Running hours equalization.</p>

Setpoint: #RunHrsMaxDiff

Group	Pwr management
Range [units]	0 .. 65000 [h]
Related FW	3.0
Description	This setpoint adjusts the "deadband" for the running hours equalization function. The priorities are swapped not until the relative engine hours (RHE) difference is higher than this deadband.

Setpoint: #PwrBandContr 1

Group	Pwr management
Range [units]	1, 2, 1+2, 3, 1+3, 2+3, 1+2+3 [-]
Related FW	3.0
Description	This setpoint is used to select the gen-sets which will run within the power band #1 if the optimization according to gen-set size is active. Learn more about this topic in the chapter Gen-set size optimization . NOTE: The combinations of gensets must be created so, that the total nominal power of the Power band #1 < #2 < #3 < #4.

Setpoint: #PwrBandContr 2

Group	Pwr management
Range [units]	1, 2, 1+2, 3, 1+3, 2+3, 1+2+3 [-]
Related FW	3.0
Description	This setpoint is used to select the gen-sets which will run within the power band #2 if the optimization according to gen-set size is active. Learn more about this topic in the chapter Gen-set size optimization . NOTE: The combinations of gensets must be created so, that the total nominal power of the Power band #1 < #2 < #3 < #4.

Setpoint: #PwrBandContr 3

Group	Pwr management
Range [units]	1, 2, 1+2, 3, 1+3, 2+3, 1+2+3 [-]
Related FW	3.0
Description	This setpoint is used to select the gen-sets which will run within the power band #3 if the optimization according to gen-set size is active. Learn more about this topic in the chapter Gen-set size optimization .

	<p>NOTE: The combinations of gensets must be created so, that the total nominal power of the Power band #1 < #2 < #3 < #4.</p>
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Setpoint: #PwrBandContr 4

Group	Pwr management
Range [units]	1, 2, 1+2, 3, 1+3, 2+3, 1+2+3 [-]
Related FW	3.0
Description	<p>This setpoint is used to select the gen-sets which will run within the power band #4 if the optimization according to gen-set size is active. Learn more about this topic in the chapter Gen-set size optimization.</p> <p>NOTE: The combinations of gensets must be created so, that the total nominal power of the Power band #1 < #2 < #3 < #4.</p>

Setpoint: #PwrBnChngDIUp

Group	Pwr management
Range [units]	0 .. 3600 [s]
Related FW	3.0
Description	<p>This setpoint is used for adjusting the delay of changing the power band if the load demand rose above the upper limit of the current power band. Learn more about this topic in the chapter Gen-set size optimization.</p>

Setpoint: #PwrBnChngDIDn

Group	Pwr management
Range [units]	0 .. 3600 [s]
Related FW	3.0
Description	<p>This setpoint is used for adjusting the delay of changing the power band if the load demand dropped below the lower limit of the current power band. Learn more about this topic in the chapter Gen-set size optimization.</p>

Setpoint: Control group

Group	Pwr management
Range [units]	COMMON (=1), 2 .. 32 [-]
Related FW	3.0
Description	<p>This setpoint selects the logical group to which the particular gen-set belongs. If there aren't logical groups at the site, adjust the setpoint to 1 (COMMON).</p>

Setpoint: GroupLinkLeft

Group	Pwr management
Range [units]	COMMON (=1), 2 .. 32 [-]
Related FW	3.0
Description	If the input GroupLink of this particular controller is used to provide the "group link" information for two logical groups , then this setpoint is used to select which group is located at the left side of the group link breaker (bus tie breaker). If this particular controller is not used for the group link function adjust this setpoint to 1 (COMMON).

Setpoint: GroupLinkRight

Group	Pwr management
Range [units]	COMMON (=1), 2 .. 32 [-]
Related FW	3.0
Description	If the input GroupLink of this particular controller is used to provide the "group link" information for two logical groups , then this setpoint is used to select which group is located at the right side of the group link breaker (bus tie breaker). If this particular controller is not used for the group link function adjust this setpoint to 1 (COMMON).

Group: Sync/Load ctrl

Setpoint: SpeedRegChar

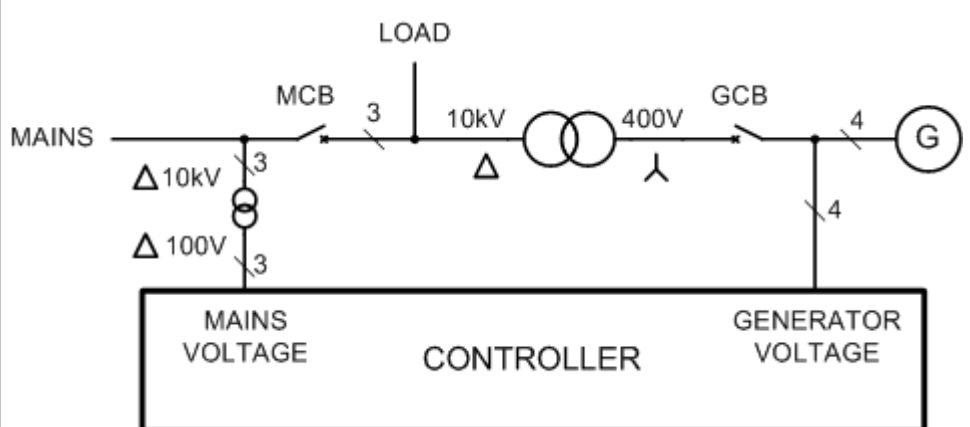
Group	Sync/Load Ctrl				
Range [units]	POSITIVE, NEGATIVE [-]				
Related FW	3.0				
Description	<p>This setpoint selects the characteristic of the speed governor output of the controller. Adjust it according to the behavior of the remote speed input of your speed governor:</p> <table border="1" data-bbox="438 1556 1364 1724"> <tr> <td>POSITIVE</td> <td>Select this option if raising of the voltage on the governor remote speed input causes engine speed to raise.</td> </tr> <tr> <td>NEGATIVE</td> <td>Select this option if raising of the voltage on the governor remote speed input causes engine speed to lower.</td> </tr> </table>	POSITIVE	Select this option if raising of the voltage on the governor remote speed input causes engine speed to raise .	NEGATIVE	Select this option if raising of the voltage on the governor remote speed input causes engine speed to lower .
POSITIVE	Select this option if raising of the voltage on the governor remote speed input causes engine speed to raise .				
NEGATIVE	Select this option if raising of the voltage on the governor remote speed input causes engine speed to lower .				

Setpoint: Voltage window

Group	Sync/Load Ctrl
Range [units]	0.0 .. 100.0 [%]
Related FW	3.0

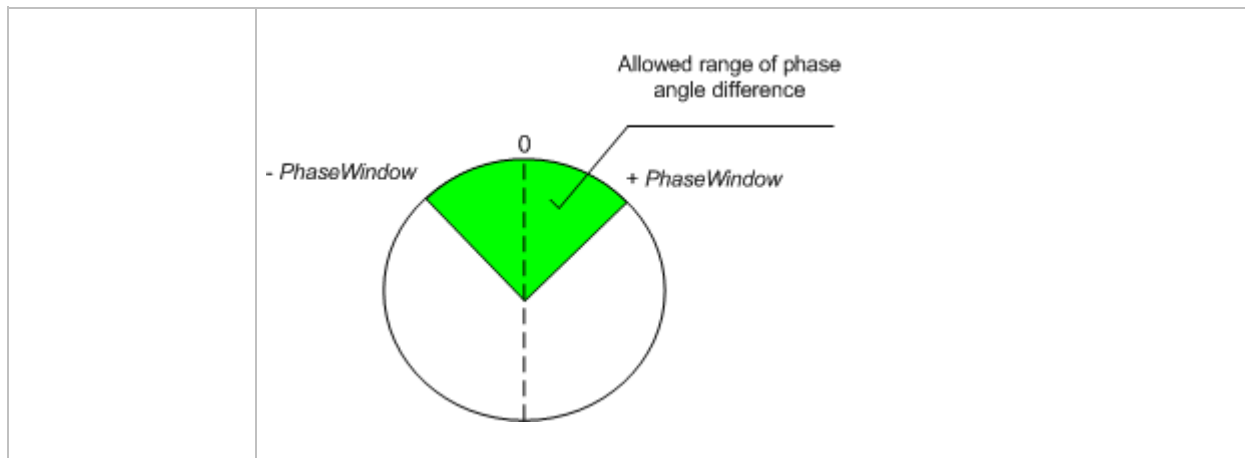
Force value possible	YES
Description	This setpoint adjusts maximum difference between generator and mains/bus voltage in respective phases for voltage matching during synchronizing.

Setpoint: GtoM AngleReq

Group	Sync/Load ctrl
Range [units]	-45 .. 45 [°]
Related FW	3.0
Description	<p>Requested angle between the phasors of the generator and mains voltage for synchronizing. This setpoint is intended for correction of the phase shift caused by a delta-triangle transformer located between the generator and mains voltage measuring points. In other situations the setpoint should be adjusted to 0.</p> <p>The diagram below shows a situation where the 230V/10kV triangle-delta transformer causes 30° phase shift between the primary and secondary side. That means when there is 0° phase difference at the both sides of the GCB the phase difference measured by the controller is 30°. Correct setting for this kind of wiring is then <i>GtoM AngleReq</i> = 30.</p> 

Setpoint: Phase window

Group	Sync/Load Ctrl
Range [units]	0 .. 90 [°]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint adjusts maximum absolute value of difference between actual phase angle between the generator and mains/bus voltages for synchronizing.</p> <p>NOTE: To disable issuing the breaker close command (i.e. for test purpose) adjust this setpoint to 0. Synchronizing will continue until timeout occurs or the breaker is closed externally.</p>



Setpoint: Dwell time

Group	Sync/Load Ctrl
Range [units]	0.0 .. 25.0 [s]
Related FW	3.0
Force value possible	YES
Force value possible	YES
Description	This setpoint adjusts the period of time that the phase angle difference must stay within +/- Phase Window and voltage difference within Voltage Window before the respective breaker, which is actually being synchronized, is closed.

Setpoint: Freq gain

Group	Sync/Load Ctrl
Range [units]	0.0 .. 200.0 [%]
Related FW	3.0
Description	This setpoint adjusts the gain factor (P-factor) of the frequency control PI loop. The integration factor (I-factor) for the frequency loop is adjusted by the setpoint Freq int .
	NOTE: See the chapter Regulation loops overview for general information about regulation loops and their adjustment.

Setpoint: Freq int

Group	Sync/Load Ctrl
Range [units]	0 .. 100 [%]
Related FW	3.0
Description	This setpoint adjusts the relative integration factor (I-factor) of the frequency

	control PI loop. The gain factor (P-factor) for the frequency loop is adjusted by the setpoint Freq gain .
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Setpoint: Freq reg loop

Group	Sync/Load ctrl						
Range [units]	ALL THE TIME, SYNC ONLY, GCB OPEN [-]						
Related FW	3.0						
Force value possible	YES						
Description	<p>This setpoint selects when is the frequency regulation loop active.</p> <table border="1" data-bbox="438 728 1364 1467"> <tr> <td style="background-color: #cccccc;">SYNC ONLY</td> <td> <p>The frequency regulation loop is active only during synchronizing to match the generator and mains frequencies together. It is assumed that in all other situations where the frequency is to be regulated the engine governor maintains it self.</p> <p>NOTE: This option is suitable for most governors.</p> </td> </tr> <tr> <td style="background-color: #cccccc;">ALL THE TIME</td> <td> <p>SPTM, SPI, Combi: This option activates the frequency regulation loop also while the gen-set is running without load and during the island operation. The controller maintains frequency at it's nominal value adjusted by setpoint system frequency (Nominal Freq + Nom frq offset).</p> <p>NOTE: This option can be used e.g. for elimination of the droop at governors that do not support isochronous mode.</p> </td> </tr> <tr> <td style="background-color: #cccccc;">GCB OPEN</td> <td> <p>MINT, COX: This option activates the frequency regulation loop also while the gen-set is running without load The controller maintains frequency at it's nominal value adjusted by the system frequency (Nominal Freq + Nom frq offset).</p> </td> </tr> </table> <p>The P and I factors of the frequency regulation loop are adjusted by setpoints Freq gain and Freq int.</p>	SYNC ONLY	<p>The frequency regulation loop is active only during synchronizing to match the generator and mains frequencies together. It is assumed that in all other situations where the frequency is to be regulated the engine governor maintains it self.</p> <p>NOTE: This option is suitable for most governors.</p>	ALL THE TIME	<p>SPTM, SPI, Combi: This option activates the frequency regulation loop also while the gen-set is running without load and during the island operation. The controller maintains frequency at it's nominal value adjusted by setpoint system frequency (Nominal Freq + Nom frq offset).</p> <p>NOTE: This option can be used e.g. for elimination of the droop at governors that do not support isochronous mode.</p>	GCB OPEN	<p>MINT, COX: This option activates the frequency regulation loop also while the gen-set is running without load The controller maintains frequency at it's nominal value adjusted by the system frequency (Nominal Freq + Nom frq offset).</p>
SYNC ONLY	<p>The frequency regulation loop is active only during synchronizing to match the generator and mains frequencies together. It is assumed that in all other situations where the frequency is to be regulated the engine governor maintains it self.</p> <p>NOTE: This option is suitable for most governors.</p>						
ALL THE TIME	<p>SPTM, SPI, Combi: This option activates the frequency regulation loop also while the gen-set is running without load and during the island operation. The controller maintains frequency at it's nominal value adjusted by setpoint system frequency (Nominal Freq + Nom frq offset).</p> <p>NOTE: This option can be used e.g. for elimination of the droop at governors that do not support isochronous mode.</p>						
GCB OPEN	<p>MINT, COX: This option activates the frequency regulation loop also while the gen-set is running without load The controller maintains frequency at it's nominal value adjusted by the system frequency (Nominal Freq + Nom frq offset).</p>						

Setpoint: Angle Gain

Group	Sync/Load Ctrl
Range [units]	0.0 .. 200.0 [%]
Related FW	3.0
Description	<p>This setpoint is used for adjusting of the gain factor (P-factor) of the phase angle P-control loop.</p> <p>The synchronizing process contains two following steps:</p>

	<ol style="list-style-type: none"> 1. The first step is to match the generator frequency to the mains frequency. In this step the frequency regulation loop (Freq reg loop) is active. 2. The following step is to match the phase angle difference of the mains and generator voltages to the setpoint GtoM AngleReq. The angle regulation loop is active in this step. <p>As soon as the phase angle difference stays within the window adjusted by Phase window and the voltage difference stays in the Voltage window, both for period Dwell time, the circuit breaker closing command is issued.</p> <p>NOTE: See the chapter Regulation loops overview for general information about regulation loops and their adjustment.</p>
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Setpoint: Speed gov bias

Group	Sync/Load Cont
Range [units]	SpeedGovLowLim .. SpeedGovHiLim [V]
Related FW	3.0
Force value possible	YES
Description	This setpoint adjusts the initial voltage level for the speed governor output, which is present on the output, if no speed or power regulation loop is active.

Setpoint: SpdGovPWM rate

Group	Sync/Load ctrl
Range [units]	500 .. 3000 [Hz]
Related FW	3.0
Description	<p>This setpoint adjusts the frequency of the speed governor output in PWM mode. The PWM mode of the speed governor output is activated by the jumper located next to the speed governor output terminals.</p> <p>The PWM interface is used for several governor types as e.g. CAT or Cummins. Adjust the PWM frequency according to the governor specification. Adjust the setpoint to 1200Hz if the PWM interface is not used.</p>

Setpoint: SpeedGovLowLim

Group	Sync/Load Ctrl
Range [units]	-10.00 .. SpeedGovHiLim [V]
Related FW	3.0
Description	Lower limit of the speed governor output. Use this setpoint to adapt the governor output range to the input range of your governor.

Setpoint: SpeedGovHiLim

Group	Sync/Load Ctrl
Range [units]	SpeedGovLowLim .. 10.00 [V]
Related FW	3.0
Description	Upper limit of the speed governor output. Use this setpoint to adapt the governor output range to the input range of your governor.

Setpoint: TauSpeedActuat

Group	Sync/Load Ctrl
Range [units]	1.0 .. 300.0 [s]
Related FW	3.0
Description	This setpoint is used to adjust the transformation ratio of the speed governor output to the pulses at the binary outputs Speed up and Speed dn . Adjust the setpoint to the pulse duration which is needed for the speed control device to travel from minimal position to the maximal position.

Setpoint: Load Ramp

Group	Sync/Load Ctrl
Range [units]	0 .. GCB open del [s]
Related FW	3.0
Force value possible	YES
Description	<p>All changes of requested gen-set load (except in loadsharing mode) are not made as one step, but are ramped - i.e. the requested load is changing slowly with the rate adjusted by this setpoint.</p> <p>The rate is adjusted in seconds for 100% load change (from 0 to 100% of nominal power).</p> <p>The ramp takes place in following situations:</p> <ul style="list-style-type: none"> • The gen-set has been just synchronized and is ramping up to the target load level (e.g. baseload in parallel to mains operation or average gen-set load in multiple loadsharing operation). The starting point of the ramp for this case is adjustable by the setpoint RampStartLevel. • The gen-set is running parallel to the mains and baseload is changed. • The gen-set is being unloaded before opening the GCB and stop. In this case the end load level is adjusted by setpoint GCB Open Level and the timeout for unloading is adjusted by setpoint GCB Open Del.

Setpoint: Load gain

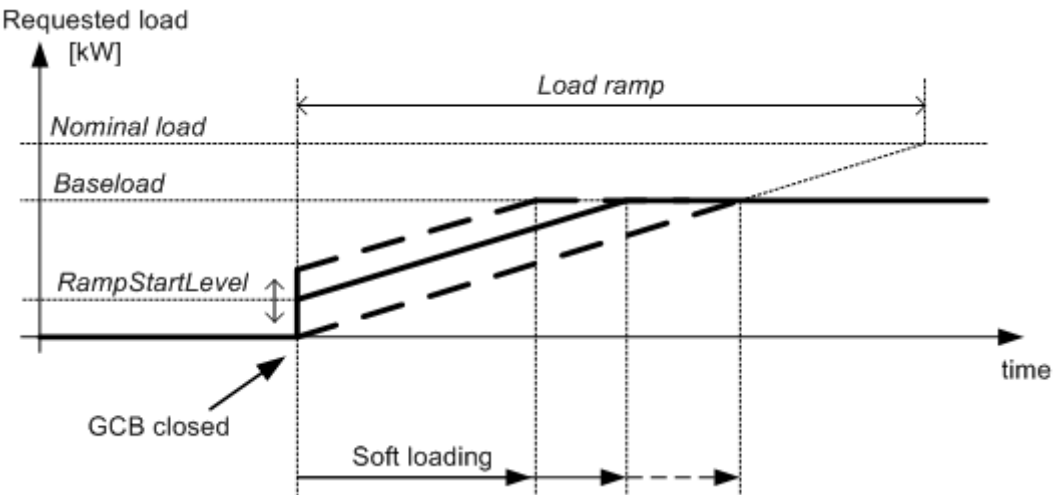
Group	Sync/Load Ctrl
Range [units]	0.0 .. 200.0 [%]
Related FW	3.0
Description	<p>This setpoint adjusts the gain factor (P-factor) of the load control PI loop. The integration factor (I-factor) for the load control loop is adjusted by the setpoint Load int.</p> <p>NOTE: See the chapter Regulation loops overview for general information about regulation loops and their adjustment.</p>

Setpoint: Load int

Group	Sync/Load Ctrl
Range [units]	0 .. 100 [%]
Related FW	3.0
Description	<p>This setpoint adjusts the relative integration factor (I-factor) of the load control PI loop. The gain factor (P-factor) for the load control loop is adjusted by the setpoint Load gain.</p>

Setpoint: RampStartLevel

Group	Sync/Load ctrl
Range [units]	0 .. 100 [%]
Related FW	3.0
Description	<p>This setpoint adjusts the load level at which the Load ramp starts after the GCB has been closed. The intention of this setpoint is to give the gen-set certain "loading impulse" right after closing the GCB to avoid possible oscillations around 0kW or even reverse power if the ramp begun at 0kW.</p>



The graph illustrates the requested load in kW over time. Key features include:

- Nominal load:** The target load level, indicated by a horizontal dashed line.
- Baseload:** The steady-state load level, indicated by a horizontal solid line.
- RampStartLevel:** The load level at which the ramp begins after GCB closure, indicated by a horizontal dashed line.
- GCB closed:** The event triggering the load ramp, marked by a vertical dashed line.
- Load ramp:** The period during which the load increases from RampStartLevel to Nominal load, shown as a solid line.
- Soft loading:** A dashed line representing a gradual load increase starting from 0kW.
- time:** The horizontal axis representing the duration of the process.

Setpoint: GCB open level

Group	Sync/Load Cont
Range [units]	0 .. 100 [%]
Related FW	3.0
Description	<p>This setpoint adjusts the end point of the gen-set unloading ramp, i.e. power level at which the GCB is opened. If this level is not reached within time period adjusted by setpoint GCB open del the GCB is then opened regardless of the gen-set power.</p> <p>NOTE: The speed of the ramp is adjusted by the setpoint Load ramp.</p>

Setpoint: GCB open del

Group	Sync/Load Ctrl
Range [units]	Load ramp .. 1800 [s]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint adjusts the maximum duration of the gen-set unloading ramp. If the end point of the ramp (GCB open level) is not reached within time period adjusted by this setpoint the GCB is then opened regardless of the gen-set power.</p> <p>NOTE: The speed of the ramp is adjusted by the setpoint Load ramp.</p>

Setpoint: Sync timeout

Group	Sync/Load Ctrl
Range [units]	1 .. 1800, NO TIMEOUT [s]
Related FW	3.0
Description	<p>This setpoint adjusts the maximum duration of forward or reverse synchronization. If the synchronizing is not successful within this period of time, the <i>Sync Timeout</i> or <i>RevSyncTimeout</i> alarm will be issued.</p> <p>NOTE: If the synchronizing is not successful within 1/10 of the <i>Sync timeout</i> or 60s (if <i>Sync timeout</i> <600s) the synchronization process is automatically restarted again, i.e. the speed governor output is reset to bias value and then frequency regulation loop is started again. If NO TIMEOUT is selected the automatic restart occurs every 180s. This method helps to synchronize successfully even in difficult conditions.</p>

Setpoint: LS gain

Group	Sync/Load ctrl
Range [units]	0.0 .. 200.0 [%]
Related FW	3.0
Description	<p>This setpoint adjusts the gain factor (P-factor) of the load-sharing PI loop. The integration factor (I-factor) for the load-sharing loop is adjusted by the setpoint LS int.</p> <p>NOTE: See the chapter Regulation loops overview for general information about regulation loops and their adjustment.</p>

Setpoint: LS int

Group	Sync/Load ctrl
Range [units]	0 .. 100 [%]
Related FW	3.0
Description	<p>This setpoint adjusts the relative integration factor (I-factor) of the load-sharing PI loop. The gain factor (P-factor) for the load-sharing loop is adjusted by the setpoint LS gain.</p>

Group: Volt/PF ctrl

Setpoint: AVRRegChar

Group	Volt/PF Ctrl				
Range [units]	POSITIVE, NEGATIVE [-]				
Related FW	3.0				
Description	<p>This setpoint selects the characteristic of the AVRi output of the controller. Adjust it according to the behavior of the remote voltage adjustment input of your AVR:</p> <table border="1" data-bbox="438 1467 1364 1630"> <tr> <td>POSITIVE</td> <td>Select this option if raising of the voltage on the remote voltage adjustment input causes the generator voltage to raise.</td> </tr> <tr> <td>NEGATIVE</td> <td>Select this option if raising of the voltage on the remote voltage adjustment input causes the generator voltage to lower.</td> </tr> </table> <p>NOTE: The characteristic can be also inverted by swapping the AVRi outputs that are connected to the AVR. However, it is recommended to use the <i>AVRRegChar</i> setpoint for selection of the characteristic instead of swapping the wires.</p>	POSITIVE	Select this option if raising of the voltage on the remote voltage adjustment input causes the generator voltage to raise .	NEGATIVE	Select this option if raising of the voltage on the remote voltage adjustment input causes the generator voltage to lower .
POSITIVE	Select this option if raising of the voltage on the remote voltage adjustment input causes the generator voltage to raise .				
NEGATIVE	Select this option if raising of the voltage on the remote voltage adjustment input causes the generator voltage to lower .				

Setpoint: Voltage gain

Group	Volt/PF Ctrl
Range [units]	0.0 .. 200.0 [%]

Related FW	3.0
Description	<p>This setpoint adjusts the gain factor (P-factor) of the voltage control PI loop. The integration factor (I-factor) for the voltage control loop is adjusted by the setpoint Voltage int.</p> <p>NOTE: See the chapter Regulation loops overview for general information about regulation loops and their adjustment.</p>

Setpoint: Voltage Int

Group	Volt/PF Ctrl
Range [units]	0 .. 100 [%]
Related FW	3.0
Description	<p>This setpoint adjusts the relative integration factor (I-factor) of the voltage control PI loop. The gain factor (P-factor) for the voltage control loop is adjusted by the setpoint Voltage gain.</p>

Setpoint: PF gain

Group	Volt/PF Ctrl
Range [units]	0.0 .. 200.0 [%]
Related FW	3.0
Description	<p>This setpoint adjusts the gain factor (P-factor) of the cos-phi control PI loop. The integration factor (I-factor) for the cos-phi control loop is adjusted by the setpoint PF int.</p> <p>NOTE: See the chapter Regulation loops overview for general information about regulation loops and their adjustment.</p>

Setpoint: PF int

Group	Volt/PF Ctrl
Range [units]	0 .. 100 [%]
Related FW	3.0
Description	<p>This setpoint adjusts the relative integration factor (I-factor) of the cos-phi control PI loop. The gain factor (P-factor) for the cos-phi control loop is adjusted by the setpoint PF gain.</p>

Setpoint: AVR DCout bias

Group	Volt/PF Ctrl
Range [units]	0.0 .. 100.0 [%]

Related FW	3.0
Force value possible	YES
Description	<p>This setpoint adjusts the initial level for the AVRi output. This level is present on the output if no regulation loop is active.</p> <p>NOTE: The resulting voltage at the input of the AVR also depends on position of the trimmer at the AVRi module.</p>

Setpoint: VS gain

Group	Volt/PF ctrl
Range [units]	0.0 .. 200.0 [%]
Related FW	3.0
Description	<p>This setpoint adjusts the gain factor (P-factor) of the VAR-sharing PI loop. The integration factor (I-factor) for the VAR-sharing loop is adjusted by the setpoint VS int.</p> <p>NOTE: See the chapter Regulation loops overview for general information about regulation loops and their adjustment.</p>

Setpoint: VS int

Group	Volt/PF ctrl
Range [units]	0 .. 100 [%]
Related FW	3.0
Description	<p>This setpoint adjusts the relative integration factor (I-factor) of the VAR-sharing PI loop. The gain factor (P-factor) for the VAR-sharing loop is adjusted by the setpoint VS gain.</p>

Setpoint: TauVoltActuat

Group	Volt/PF ctrl
Range [units]	1.0 .. 300.0 [s]
Related FW	3.0
Description	<p>This setpoint is used to adjust the transformation ratio of the AVRi output to the pulses at the binary outputs AVR up and AVR dn. Adjust the setpoint to the pulse duration which is needed for the AVR to change the requested voltage from minimum to maximum.</p>

Group: Force value

Setpoint: Force value 1

Group	Force value
Range [units]	[-]
Related FW	3.0
Description	<p>This is one of the 16 setpoints reserved for using as alternative setpoints for the force value functions. The alternative setpoint is to be assigned to a particular force value function and renamed in GenConfig.</p> <p>See also the input Force value 1.</p> <p>NOTE: It is not obligatory to use one of these reserved setpoints for a force value function. It is possible to use also any other setpoint or value with matching dimension and decimal resolution.</p> <p>NOTE: There isn't any relation between the default names of the force value function blocks, associated binary inputs and the default names of the reserved setpoints. In other words, the setpoint with default name <i>Force value 3</i> is not related to the <i>Force value 3</i> function block.</p>

Setpoint: Force value 2

Group	Force value
Range [units]	[-]
Related FW	3.0
Description	<p>This is one of the 16 setpoints reserved for using as alternative setpoints for the force value functions. The alternative setpoint is to be assigned to a particular force value function and renamed in GenConfig.</p> <p>NOTE: It is not obligatory to use one of these reserved setpoints for a force value function. It is possible to use also any other setpoint or value with matching dimension and decimal resolution.</p> <p>NOTE: There isn't any relation between the default names of the force value function blocks, associated binary inputs and the default names of the reserved setpoints. In other words, the setpoint with default name <i>Force value 3</i> is not related to the <i>Force value 3</i> function block.</p>

Setpoint: Force value 3

Group	Force value
Range [units]	[-]
Related FW	3.0
Description	<p>This is one of the 16 setpoints reserved for using as alternative setpoints for the force value functions. The alternative setpoint is to be assigned to a particular</p>

	<p>force value function and renamed in GenConfig.</p> <p>See also the input Force value 1.</p> <p>NOTE: It is not obligatory to use one of these reserved setpoints for a force value function. It is possible to use also any other setpoint or value with matching dimension and decimal resolution.</p> <p>NOTE: There isn't any relation between the default names of the force value function blocks, associated binary inputs and the default names of the reserved setpoints. In other words, the setpoint with default name <i>Force value 3</i> is not related to the <i>Force value 3</i> function block.</p>
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Setpoint: Force value 4

Group	Force value
Range [units]	[-]
Related FW	3.0
Description	<p>This is one of the 16 setpoints reserved for using as alternative setpoints for the force value functions. The alternative setpoint is to be assigned to a particular force value function and renamed in GenConfig.</p> <p>See also the input Force value 1.</p> <p>NOTE: It is not obligatory to use one of these reserved setpoints for a force value function. It is possible to use also any other setpoint or value with matching dimension and decimal resolution.</p> <p>NOTE: There isn't any relation between the default names of the force value function blocks, associated binary inputs and the default names of the reserved setpoints. In other words, the setpoint with default name <i>Force value 3</i> is not related to the <i>Force value 3</i> function block.</p>

Setpoint: Force value 5

Group	Force value
Range [units]	[-]
Related FW	3.0
Description	<p>This is one of the 16 setpoints reserved for using as alternative setpoints for the force value functions. The alternative setpoint is to be assigned to a particular force value function and renamed in GenConfig.</p> <p>See also the input Force value 1.</p> <p>NOTE: It is not obligatory to use one of these reserved setpoints for a force value function. It is possible to use also any other setpoint or value with matching</p>

	dimension and decimal resolution.
	<p>NOTE: There isn't any relation between the default names of the force value function blocks, associated binary inputs and the default names of the reserved setpoints. In other words, the setpoint with default name <i>Force value 3</i> is not related to the <i>Force value 3</i> function block.</p>

Setpoint: Force value 6

Group	Force value
Range [units]	[-]
Related FW	3.0
Description	<p>This is one of the 16 setpoints reserved for using as alternative setpoints for the force value functions. The alternative setpoint is to be assigned to a particular force value function and renamed in GenConfig.</p> <p>See also the input Force value 1.</p> <p>NOTE: It is not obligatory to use one of these reserved setpoints for a force value function. It is possible to use also any other setpoint or value with matching dimension and decimal resolution.</p> <p>NOTE: There isn't any relation between the default names of the force value function blocks, associated binary inputs and the default names of the reserved setpoints. In other words, the setpoint with default name <i>Force value 3</i> is not related to the <i>Force value 3</i> function block.</p>

Setpoint: Force value 7

Group	Force value
Range [units]	[-]
Related FW	3.0
Description	<p>This is one of the 16 setpoints reserved for using as alternative setpoints for the force value functions. The alternative setpoint is to be assigned to a particular force value function and renamed in GenConfig.</p> <p>See also the input Force value 1.</p> <p>NOTE: It is not obligatory to use one of these reserved setpoints for a force value function. It is possible to use also any other setpoint or value with matching dimension and decimal resolution.</p> <p>NOTE: There isn't any relation between the default names of the force value function blocks, associated binary inputs and the default names of the reserved setpoints. In other words, the setpoint with default name <i>Force value 3</i> is not related to the <i>Force value 3</i> function block.</p>

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Setpoint: Force value 8

Group	Force value
Range [units]	[-]
Related FW	3.0
Description	<p>This is one of the 16 setpoints reserved for using as alternative setpoints for the force value functions. The alternative setpoint is to be assigned to a particular force value function and renamed in GenConfig.</p> <p>See also the input Force value 1.</p> <p>NOTE: It is not obligatory to use one of these reserved setpoints for a force value function. It is possible to use also any other setpoint or value with matching dimension and decimal resolution.</p> <p>NOTE: There isn't any relation between the default names of the force value function blocks, associated binary inputs and the default names of the reserved setpoints. In other words, the setpoint with default name <i>Force value 3</i> is not related to the <i>Force value 3</i> function block.</p>

Setpoint: Force value 9

Group	Force value
Range [units]	[-]
Related FW	3.0
Description	<p>This is one of the 16 setpoints reserved for using as alternative setpoints for the force value functions. The alternative setpoint is to be assigned to a particular force value function and renamed in GenConfig.</p> <p>See also the input Force value 1.</p> <p>NOTE: It is not obligatory to use one of these reserved setpoints for a force value function. It is possible to use also any other setpoint or value with matching dimension and decimal resolution.</p> <p>NOTE: There isn't any relation between the default names of the force value function blocks, associated binary inputs and the default names of the reserved setpoints. In other words, the setpoint with default name <i>Force value 3</i> is not related to the <i>Force value 3</i> function block.</p>

Setpoint: Force value 10

Group	Force value
Range [units]	[-]

Related FW	3.0
Description	<p>This is one of the 16 setpoints reserved for using as alternative setpoints for the force value functions. The alternative setpoint is to be assigned to a particular force value function and renamed in GenConfig.</p> <p>See also the input Force value 1.</p> <p>NOTE: It is not obligatory to use one of these reserved setpoints for a force value function. It is possible to use also any other setpoint or value with matching dimension and decimal resolution.</p> <p>NOTE: There isn't any relation between the default names of the force value function blocks, associated binary inputs and the default names of the reserved setpoints. In other words, the setpoint with default name <i>Force value 3</i> is not related to the <i>Force value 3</i> function block.</p>

Setpoint: Force value 11

Group	Force value
Range [units]	[-]
Related FW	3.0
Description	<p>This is one of the 16 setpoints reserved for using as alternative setpoints for the force value functions. The alternative setpoint is to be assigned to a particular force value function and renamed in GenConfig.</p> <p>See also the input Force value 1.</p> <p>NOTE: It is not obligatory to use one of these reserved setpoints for a force value function. It is possible to use also any other setpoint or value with matching dimension and decimal resolution.</p> <p>NOTE: There isn't any relation between the default names of the force value function blocks, associated binary inputs and the default names of the reserved setpoints. In other words, the setpoint with default name <i>Force value 3</i> is not related to the <i>Force value 3</i> function block.</p>

Setpoint: Force value 12

Group	Force value
Range [units]	[-]
Related FW	3.0
Description	<p>This is one of the 16 setpoints reserved for using as alternative setpoints for the force value functions. The alternative setpoint is to be assigned to a particular force value function and renamed in GenConfig.</p> <p>See also the input Force value 1.</p>

	<p>NOTE: It is not obligatory to use one of these reserved setpoints for a force value function. It is possible to use also any other setpoint or value with matching dimension and decimal resolution.</p> <p>NOTE: There isn't any relation between the default names of the force value function blocks, associated binary inputs and the default names of the reserved setpoints. In other words, the setpoint with default name <i>Force value 3</i> is not related to the <i>Force value 3</i> function block.</p>
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Setpoint: Force value 13

Group	Force value
Range [units]	[-]
Related FW	3.0
Description	<p>This is one of the 16 setpoints reserved for using as alternative setpoints for the force value functions. The alternative setpoint is to be assigned to a particular force value function and renamed in GenConfig.</p> <p>See also the input Force value 1.</p> <p>NOTE: It is not obligatory to use one of these reserved setpoints for a force value function. It is possible to use also any other setpoint or value with matching dimension and decimal resolution.</p> <p>NOTE: There isn't any relation between the default names of the force value function blocks, associated binary inputs and the default names of the reserved setpoints. In other words, the setpoint with default name <i>Force value 3</i> is not related to the <i>Force value 3</i> function block.</p>

Setpoint: Force value 14

Group	Force value
Range [units]	[-]
Related FW	3.0
Description	<p>This is one of the 16 setpoints reserved for using as alternative setpoints for the force value functions. The alternative setpoint is to be assigned to a particular force value function and renamed in GenConfig.</p> <p>See also the input Force value 1.</p> <p>NOTE: It is not obligatory to use one of these reserved setpoints for a force value function. It is possible to use also any other setpoint or value with matching dimension and decimal resolution.</p> <p>NOTE: There isn't any relation between the default names of the force value function</p>

	blocks, associated binary inputs and the default names of the reserved setpoints. In other words, the setpoint with default name <i>Force value 3</i> is not related to the <i>Force value 3</i> function block.
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Setpoint: Force value 15

Group	Force value
Range [units]	[-]
Related FW	3.0
Description	<p>This is one of the 16 setpoints reserved for using as alternative setpoints for the force value functions. The alternative setpoint is to be assigned to a particular force value function and renamed in GenConfig.</p> <p>See also the input Force value 1.</p> <p>NOTE: It is not obligatory to use one of these reserved setpoints for a force value function. It is possible to use also any other setpoint or value with matching dimension and decimal resolution.</p> <p>NOTE: There isn't any relation between the default names of the force value function blocks, associated binary inputs and the default names of the reserved setpoints. In other words, the setpoint with default name <i>Force value 3</i> is not related to the <i>Force value 3</i> function block.</p>

Setpoint: Force value 16

Group	Force value
Range [units]	[-]
Related FW	3.0
Description	<p>This is one of the 16 setpoints reserved for using as alternative setpoints for the force value functions. The alternative setpoint is to be assigned to a particular force value function and renamed in GenConfig.</p> <p>See also the input Force value 1.</p> <p>NOTE: It is not obligatory to use one of these reserved setpoints for a force value function. It is possible to use also any other setpoint or value with matching dimension and decimal resolution.</p> <p>NOTE: There isn't any relation between the default names of the force value function blocks, associated binary inputs and the default names of the reserved setpoints. In other words, the setpoint with default name <i>Force value 3</i> is not related to the <i>Force value 3</i> function block.</p>

Setpoint: ExtValue1deflt

Group	Force value
Range [units]	-32000 .. 32000 [x]
Related FW	3.0
Force value possible	YES
Force value possible	YES
Description	This setpoint adjusts the reset (initial) value of the <i>ExtValue 1</i> . This initial value is applied either when the controller is powered-on or when the <i>ExtValue 1</i> is reset by the binary input ExtValue1reset .

Setpoint: ExtValue1LoLim

Group	Force value
Range [units]	-32000 .. ExtValue1HiLim [X]
Related FW	3.0
Description	This setpoint adjusts the low limit of the value of <i>ExtValue 1</i> if the value is lowered/raised by the binary inputs ExtValue1 up and ExtValue1 down . The <i>ExtValue 1</i> is never lowered below this limit. NOTE: This limit is not taken into account if the value <i>ExtValue 1</i> is written remotely from a terminal using the appropriate command <i>ExtValue #n</i> . NOTE: For IS-NT only.

Setpoint: ExtValue1HiLim

Group	Force value
Range [units]	ExtValue1LoLim .. 32000 [X]
Related FW	3.0
Description	This setpoint adjusts the high limit of the value of <i>ExtValue 1</i> if the value is lowered/raised by the binary inputs ExtValue1 up and ExtValue1 down . The <i>ExtValue 1</i> is never raised over this limit. NOTE: This limit is not taken into account if the value <i>ExtValue 1</i> is written remotely from a terminal using the appropriate command <i>ExtValue #n</i> . NOTE: For IS-NT only.

Setpoint: ExtValue1 rate

Group	Force value
Range [units]	1 .. 10000 [X/s]
Related FW	3.0
Force value possible	YES
Force value possible	YES
Description	This setpoint adjusts the rate per second at which the <i>ExtValue 1</i> is being changed while the input ExtValue1 up or ExtValue1 down is active.

Setpoint: ExtValue2deflt

Group	Force value
Range [units]	-32000 .. 32000 [x]
Related FW	3.0
Force value possible	YES
Force value possible	YES
Description	This setpoint adjusts the reset (initial) value of the <i>ExtValue 2</i> . This initial value is applied either when the controller is powered-on or when the <i>ExtValue 2</i> is reset by the binary input ExtValue2reset .

Setpoint: ExtValue2LoLim

Group	Force value
Range [units]	-32000 .. ExtValue2HiLim [X]
Related FW	3.0
Description	<p>This setpoint adjusts the low limit of the value of <i>ExtValue 2</i> if the value is lowered/raised by the binary inputs ExtValue2 up and ExtValue2 down. The <i>ExtValue 2</i> is never lowered below this limit.</p> <p>NOTE: This limit is not taken into account if the value <i>ExtValue 2</i> is written remotely from a terminal using the appropriate command <i>ExtValue #n</i>.</p> <p>NOTE: For IS-NT only.</p>

Setpoint: ExtValue2HiLim

Group	Force value
Range [units]	ExtValue2LoLim .. 32000 [X]

Related FW	3.0
Description	<p>This setpoint adjusts the high limit of the value of <i>ExtValue 2</i> if the value is lowered/raised by the binary inputs ExtValue2 up and ExtValue2 down. The <i>ExtValue 2</i> is never raised over this limit.</p> <p>NOTE: This limit is not taken into account if the value <i>ExtValue 2</i> is written remotely from a terminal using the appropriate command <i>ExtValue #n</i>.</p> <p>NOTE: For IS-NT only.</p>

Setpoint: ExtValue2 rate

Group	Force value
Range [units]	1 .. 10000 [X/s]
Related FW	3.0
Force value possible	YES
Force value possible	YES
Description	<p>This setpoint adjusts the rate per second at which the <i>ExtValue 2</i> is being changed while the input ExtValue2 up or ExtValue2 down is active.</p>

Setpoint: ExtValue3deflt

Group	Force value
Range [units]	-32000 .. 32000 [x]
Related FW	3.0
Force value possible	YES
Force value possible	YES
Description	<p>This setpoint adjusts the reset (initial) value of the <i>ExtValue 3</i>. This initial value is applied either when the controller is powered-on or when the <i>ExtValue 3</i> is reset by the binary input ExtValue3reset.</p>

Setpoint: ExtValue3LoLim

Group	Force value
Range [units]	-32000 .. ExtValue3HiLim [X]
Related FW	3.0
Description	<p>This setpoint adjusts the low limit of the value of <i>ExtValue 3</i> if the value is lowered/raised by the binary inputs ExtValue3 up and ExtValue3 down. The</p>

	<p><i>ExtValue 3</i> is never lowered below this limit.</p> <p>NOTE: This limit is not taken into account if the value <i>ExtValue 3</i> is written remotely from a terminal using the appropriate command <i>ExtValue #n</i>.</p> <p>NOTE: For IS-NT only.</p>
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Setpoint: *ExtValue3HiLim*

Group	Force value
Range [units]	ExtValue3LoLim .. 32000 [X]
Related FW	3.0
Description	<p>This setpoint adjusts the high limit of the value of <i>ExtValue 3</i> if the value is lowered/raised by the binary inputs ExtValue3 up and ExtValue3 down. The <i>ExtValue 3</i> is never raised over this limit.</p> <p>NOTE: This limit is not taken into account if the value <i>ExtValue 3</i> is written remotely from a terminal using the appropriate command <i>ExtValue #n</i>.</p> <p>NOTE: For IS-NT only.</p>

Setpoint: *ExtValue3 rate*

Group	Force value
Range [units]	1 .. 10000 [X/s]
Related FW	3.0
Force value possible	YES
Force value possible	YES
Description	<p>This setpoint adjusts the rate per second at which the <i>ExtValue 3</i> is being changed while the input ExtValue3 up or ExtValue3 down is active.</p>

Setpoint: *ExtValue4deflt*

Group	Force value
Range [units]	-32000 .. 32000 [x]
Related FW	3.0
Force value possible	YES
Force value	YES

possible	
Description	This setpoint adjusts the reset (initial) value of the <i>ExtValue 4</i> . This initial value is applied either when the controller is powered-on or when the <i>ExtValue 4</i> is reset by the binary input ExtValue4reset .

Setpoint: ExtValue4LoLim

Group	Force value
Range [units]	-32000 .. ExtValue4HiLim [X]
Related FW	3.0
Description	<p>This setpoint adjusts the low limit of the value of <i>ExtValue 4</i> if the value is lowered/raised by the binary inputs ExtValue4 up and ExtValue4 down. The <i>ExtValue 4</i> is never lowered below this limit.</p> <p>NOTE: This limit is not taken into account if the value <i>ExtValue 4</i> is written remotely from a terminal using the appropriate command <i>ExtValue #n</i>.</p> <p>NOTE: For IS-NT only.</p>

Setpoint: ExtValue4HiLim

Group	Force value
Range [units]	ExtValue4LoLim .. 32000 [X]
Related FW	3.0
Description	<p>This setpoint adjusts the high limit of the value of <i>ExtValue 4</i> if the value is lowered/raised by the binary inputs ExtValue4 up and ExtValue4 down. The <i>ExtValue 4</i> is never raised over this limit.</p> <p>NOTE: This limit is not taken into account if the value <i>ExtValue 4</i> is written remotely from a terminal using the appropriate command <i>ExtValue #n</i>.</p> <p>NOTE: For IS-NT only.</p>

Setpoint: ExtValue4 rate

Group	Force value
Range [units]	1 .. 10000 [X/s]
Related FW	3.0
Force value possible	YES
Force value possible	YES

Description	This setpoint adjusts the rate per second at which the <i>ExtValue 4</i> is being changed while the input ExtValue4 up or ExtValue4 down is active.
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Group: Load shedding

Setpoint: Ld shed active

Group	Load shedding								
Range [units]	DISABLED, ISLAND ONLY, ISL+TRIP PARAL, ALL THE TIME [-]								
Related FW	3.0								
Force value possible	YES								
Description	<p>This setpoint is used for adjustment when the load shedding function will be active (see also IM-NT-MCB/MGCB help for more information on MCB/MGCB).</p> <table border="1" data-bbox="438 806 1364 1232"> <tr> <td>DISABLED</td> <td>The Load shedding function is disabled. All the outputs are open.</td> </tr> <tr> <td>ISLAND ONLY</td> <td>In Island operation (e.g. MCB is open and MGCB is closed) Load shedding outputs (e.g. LdShed stage 1) are controlled by load shedding function.</td> </tr> <tr> <td>ISL+TRIP PARAL</td> <td>This setting adjusts the same behavior as ISLAND ONLY but in addition to it all load shedding outputs are closed when gen-set group goes to island operation. For more information see the chapter Load shedding.</td> </tr> <tr> <td>ALL THE TIME</td> <td>Outputs are controlled by the load shedding function regardless of breaker positions.</td> </tr> </table> <p>NOTE: Learn more about load shedding in the separate chapter Load shedding.</p>	DISABLED	The Load shedding function is disabled. All the outputs are open.	ISLAND ONLY	In Island operation (e.g. MCB is open and MGCB is closed) Load shedding outputs (e.g. LdShed stage 1) are controlled by load shedding function.	ISL+TRIP PARAL	This setting adjusts the same behavior as ISLAND ONLY but in addition to it all load shedding outputs are closed when gen-set group goes to island operation. For more information see the chapter Load shedding .	ALL THE TIME	Outputs are controlled by the load shedding function regardless of breaker positions.
DISABLED	The Load shedding function is disabled. All the outputs are open.								
ISLAND ONLY	In Island operation (e.g. MCB is open and MGCB is closed) Load shedding outputs (e.g. LdShed stage 1) are controlled by load shedding function.								
ISL+TRIP PARAL	This setting adjusts the same behavior as ISLAND ONLY but in addition to it all load shedding outputs are closed when gen-set group goes to island operation. For more information see the chapter Load shedding .								
ALL THE TIME	Outputs are controlled by the load shedding function regardless of breaker positions.								

Setpoint: Ld shed level

Group	Load shedding
Range [units]	Ld recon level .. 200 [%]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used to adjust the relative load level (in % of nominal power of gen-set) for load shedding. When the relative load level exceeds this level for more than Ld shed delay time the next load shedding output is closed.</p> <p>NOTE: Learn more about load shedding in the separate chapter Load shedding.</p>

Setpoint: Ld shed delay

Group	Load shedding
Range [units]	0.0 .. 600.0 [s]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used to adjust time period the relative load level must be above the Ld shed level limit to close the next load shedding output.</p> <p>NOTE: Learn more about load shedding in the separate chapter Load shedding.</p>

Setpoint: Ld recon level

Group	Load shedding
Range [units]	0 .. Ld shed level [%]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used to adjust the relative load level (in % of nominal power of gen-set) for load reconnection. When the relative load level drops below this level for more than Ld recon delay time the next load can be reconnected back.</p> <p>The appropriate load shedding output is either opened automatically when the condition above is fulfilled (AutoLd recon = ENABLED) or manually by activation of the input ManualLdRecon.</p> <p>NOTE: Learn more about load shedding in the separate chapter Load shedding.</p>

Setpoint: Ld recon del

Group	Load shedding
Range [units]	0 .. 600 [s]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used to adjust time period the relative load level must be below the Ld recon level limit to allow reconnection of next load group.</p> <p>NOTE: Learn more about load shedding in the separate chapter Load shedding.</p>

Setpoint: AutoLd recon

Group	Engine Protect
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint selects whether the reconnection of the load occurs automatically when the relative load level stays below the reconnection limit for a period of the reconnection delay or the reconnection must be initiated manually by the input ManualLdRecon.</p> <p>NOTE: Learn more about load shedding in the separate chapter Load shedding.</p>

Group: Timer settings

Setpoint: Timer channel 1

Group	Timer settings
Range [units]	[-]
Related FW	3.0
Description	<p>This setpoint adjusts the mode of the <i>Timer channel #1</i>. Output from this channel is available in the combined output TimerAct 1-4.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Setpoint: Timer channel 2

Group	Timer settings
Range [units]	[-]
Related FW	3.0
Description	<p>This setpoint adjusts the mode of the <i>Timer channel #2</i>. Output from this channel is available in the combined output TimerAct 1-4.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Setpoint: Timer channel 3

Group	Timer settings
Range [units]	[-]
Related FW	3.0
Description	<p>This setpoint adjusts the mode of the <i>Timer channel #3</i>. Output from this channel</p>

	is available in the combined output TimerAct 1-4 .
	NOTE: See the chapter Timers for more details about timers.

Setpoint: Timer channel 4

Group	Timer settings
Range [units]	[-]
Related FW	3.0
Description	This setpoint adjusts the mode of the <i>Timer channel #4</i> . Output from this channel is available in the combined output TimerAct 1-4 .
	NOTE: See the chapter Timers for more details about timers.

Setpoint: Timer channel 5

Group	Timer settings
Range [units]	[-]
Related FW	3.0
Description	This setpoint adjusts the mode of the <i>Timer channel #5</i> . Output from this channel is available in the combined output TimerAct 5-8 .
	NOTE: See the chapter Timers for more details about timers.

Setpoint: Timer channel 6

Group	Timer settings
Range [units]	[-]
Related FW	3.0
Description	This setpoint adjusts the mode of the <i>Timer channel #6</i> . Output from this channel is available in the combined output TimerAct 5-8 .
	NOTE: See the chapter Timers for more details about timers.

Setpoint: Timer channel 7

Group	Timer settings
Range [units]	[-]
Related FW	3.0

Description	<p>This setpoint adjusts the mode of the <i>Timer channel #7</i>. Output from this channel is available in the combined output TimerAct 5-8.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>
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Setpoint: Timer channel 8

Group	Timer settings
Range [units]	[-]
Related FW	3.0
Description	<p>This setpoint adjusts the mode of the <i>Timer channel #8</i>. Output from this channel is available in the combined output TimerAct 5-8.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Setpoint: Timer channel 9

Group	Timer settings
Range [units]	[-]
Related FW	3.0
Description	<p>This setpoint adjusts the mode of the <i>Timer channel #9</i>. Output from this channel is available in the combined output TimerAct 9-12.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Setpoint: Timer channel 10

Group	Timer settings
Range [units]	[-]
Related FW	3.0
Description	<p>This setpoint adjusts the mode of the <i>Timer channel #10</i>. Output from this channel is available in the combined output TimerAct 9-12.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Setpoint: Timer channel 11

Group	Timer settings
Range [units]	[-]
Related FW	3.0

Description	<p>This setpoint adjusts the mode of the <i>Timer channel #11</i>. Output from this channel is available in the combined output TimerAct 9-12.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>
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Setpoint: Timer channel 12

Group	Timer settings
Range [units]	[-]
Related FW	3.0
Description	<p>This setpoint adjusts the mode of the <i>Timer channel #12</i>. Output from this channel is available in the combined output TimerAct 9-12.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Setpoint: Timer channel 13

Group	Timer settings
Range [units]	[-]
Related FW	3.0
Description	<p>This setpoint adjusts the mode of the <i>Timer channel #13</i>. Output from this channel is available in the combined output TimerAct 13-16.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Setpoint: Timer channel 14

Group	Timer settings
Range [units]	[-]
Related FW	3.0
Description	<p>This setpoint adjusts the mode of the <i>Timer channel #14</i>. Output from this channel is available in the combined output TimerAct 13-16.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Setpoint: Timer channel 15

Group	Timer settings
Range [units]	[-]
Related FW	3.0

Description	<p>This setpoint adjusts the mode of the <i>Timer channel #15</i>. Output from this channel is available in the combined output TimerAct 13-16.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>
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Setpoint: Timer channel 16

Group	Timer settings
Range [units]	[-]
Related FW	3.0
Description	<p>This setpoint adjusts the mode of the <i>Timer channel #16</i>. Output from this channel is available in the combined output TimerAct 13-16.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Group: Act. calls/SMS

Setpoint: History record

Group	Act. calls/SMS
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0
Force value possible	YES
Force value possible	YES
Description	<p>This setpoint is used to enable sending SMS and/or e-mail alerts when a "protection" configured as <i>History record</i> occurs. See the chapter Alarm management for more information about protection types.</p> <p>NOTE: As the <i>History record</i> protection does not appear in the alarmlist, the SMS or e-mail may contain empty alarmlist.</p>

Setpoint: Alarm only

Group	Act. calls/SMS
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0
Force value possible	YES
Force value possible	YES

Description	This setpoint is used to enable sending SMS and/or e-mail alerts when a "protection" configured as <i>Alarm only</i> occurs. See the chapter Alarm management for more information about protection types.
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Setpoint: Warning

Group	Act. calls/SMS
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0
Force value possible	YES
Force value possible	YES
Description	This setpoint is used to enable sending SMS and/or e-mail alerts when a <i>warning</i> -type protection occurs. See the chapter Alarm management for more information about protection types.

Setpoint: Off load

Group	Act. calls/SMS
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used to enable sending SMS and/or e-mail alerts when a "protection" configured as <i>Off load</i> occurs. See the chapter Alarm management for more information about protection types.</p> <p>NOTE: As the <i>Off load</i> protection does not appear in the alarmlist, the SMS or e-mail may contain empty alarmlist.</p>

Setpoint: BrkOpen&CoolDn

Group	Act. calls/SMS
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0
Force value possible	YES
Description	This setpoint is used to enable sending SMS and/or e-mail alerts when a <i>BrkOpen&CoolDn</i> -type alarm occurs. See the chapter Alarm management for more information about protection types.

Setpoint: Mains protect

Group	Act. calls/SMS
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0
Force value possible	YES
Force value possible	YES
Description	<p>This setpoint is used to enable sending SMS and/or e-mail alerts when a "protection" configured as <i>Mains protect</i> occurs. See the chapter Alarm management for more information about protection types.</p> <p>NOTE: As the <i>Mains protect</i> protection does not appear in the alarmlist, the SMS or e-mail may contain empty alarmlist.</p>

Setpoint: Slow stop

Group	Act. calls/SMS
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used to enable sending SMS and/or e-mail alerts when a <i>Slow stop</i>-type alarm occurs. See the chapter Alarm management for more information about protection types.</p>

Setpoint: Shutdown

Group	Act. calls/SMS
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0
Force value possible	YES
Description	<p>This setpoint is used to enable sending SMS and/or e-mail alerts when a <i>Shutdown</i>-type alarm occurs. See the chapter Alarm management for more information about protection types.</p>

Setpoint: ShutdownOvr

Group	Act. calls/SMS
Range [units]	DISABLED, ENABLED [-]
Related FW	3.0

Force value possible	YES
Description	This setpoint is used to enable sending SMS and/or e-mail alerts when a <i>Sd Override</i> -type alarm occurs. See the chapter Alarm management for more information about protection types.

Setpoint: AcallCH1-Type

Group	Act. calls/SMS
Range [units]	[-]
Related FW	3.0
Description	The setpoint is used to specify the alert type of the active calls - channel 1. See the chapter Alarm messaging for more details.

Setpoint: AcallCH1-Addr

Group	Act. calls/SMS
Range [units]	[-]
Related FW	3.0
Description	The setpoint is used to specify the recipient address for the active calls - channel 1. The content of the address must correspond to the selected alert type (e.g. it must contain e-mail address if the alert type is e-mail). See the chapter Alarm messaging for more details.

Setpoint: AcallCH2-Type

Group	Act. calls/SMS
Range [units]	[-]
Related FW	3.0
Description	The setpoint is used to specify the alert type of the active calls - channel 2. See the chapter Alarm messaging for more details.

Setpoint: AcallCH2-Addr

Group	Act. calls/SMS
Range [units]	[-]
Related FW	3.0
Description	The setpoint is used to specify the recipient address for the active calls - channel 2. The content of the address must correspond to the selected alert type (e.g. it must contain e-mail address if the alert type is e-mail). See the chapter Alarm messaging for more details.

Setpoint: AcallCH3-Type

Group	Act. calls/SMS
Range [units]	[-]
Related FW	3.0
Description	The setpoint is used to specify the alert type of the active calls - channel 3. See the chapter Alarm messaging for more details.

Setpoint: AcallCH3-Addr

Group	Act. calls/SMS
Range [units]	[-]
Related FW	3.0
Description	The setpoint is used to specify the recipient address for the active calls - channel 2. The content of the address must correspond to the selected alert type (e.g. it must contain e-mail address if the alert type is e-mail). See the chapter Alarm messaging for more details.

Setpoint: AcallCH4-Type

Group	Act. calls/SMS
Range [units]	[-]
Related FW	3.0
Description	The setpoint is used to specify the alert type of the active calls - channel 4. See the chapter Alarm messaging for more details.

Setpoint: AcallCH4-Addr

Group	Act. calls/SMS
Range [units]	[-]
Related FW	3.0
Description	The setpoint is used to specify the recipient address for the active calls - channel 4. The content of the address must correspond to the selected alert type (e.g. it must contain e-mail address if the alert type is e-mail). See the chapter Alarm messaging for more details.

Setpoint: AcallCH5-Type

Group	Act. calls/SMS
Range [units]	[-]
Related FW	3.0
Description	The setpoint is used to specify the alert type of the active calls - channel 5. See

	the chapter Alarm messaging for more details.
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Setpoint: AcallCH5-Addr

Group	Act. calls/SMS
Range [units]	[-]
Related FW	3.0
Description	The setpoint is used to specify the recipient address for the active calls - channel 5. The content of the address must correspond to the selected alert type (e.g. it must contain e-mail address if the alert type is e-mail). See the chapter Alarm messaging for more details.

Setpoint: NumberRings AA

Group	Act. calls/SMS
Range [units]	1 .. 30 [-]
Related FW	3.0
Description	<p>This setpoint is used to adjust the number of rings after which the modem, which is attached to the controller, answers the incoming call.</p> <p>Number of rings prior to answering the modem connection from PC to controller.</p> <p>NOTE: Any change of this setpoint is applied first after next switching the controller or modem off and on or after disconnecting the modem from the controller and connecting it back.</p>

Setpoint: ActCallAttempt

Group	Act. calls/SMS
Range [units]	1 .. 250 [-]
Related FW	3.0
Description	This setpoint is used to adjust the maximum number of consequent attempts to perform an active data call. The next attempt is performed 120s after the previous unsuccessful attempt.

Setpoint: Acall+SMS lang

Group	Act. calls/SMS
Range [units]	1 .. 7 [-]
Related FW	3.0
Description	The setpoint specifies in which language the active SMS and e-mail messages are issued. Adjust the setpoint to the index of the required language. The index

	can be obtained from the tab Languages in GenConfig. Index 1 is always english.
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Group: Date/Time

Setpoint: Time stamp act

Group	Date/Time						
Range [units]	DISABLED, ENGINE RUNNING, ALWAYS [-]						
Related FW	3.0						
Description	<p>The setpoint selects the <i>Time stamp</i> function mode.</p> <table border="1" data-bbox="438 667 1366 947"> <tr> <td>DISABLED</td> <td>The function is disabled.</td> </tr> <tr> <td>ENGINE RUNNING</td> <td>While the engine is running the <i>Time stamps</i> records are recorded into the history log with period adjusted by setpoint Time Stamp Per.</td> </tr> <tr> <td>ALWAYS</td> <td>The <i>Time stamps</i> records are recorded into the history log with period adjusted by setpoint Time Stamp Per all the time while the controller is switched on.</td> </tr> </table>	DISABLED	The function is disabled.	ENGINE RUNNING	While the engine is running the <i>Time stamps</i> records are recorded into the history log with period adjusted by setpoint Time Stamp Per .	ALWAYS	The <i>Time stamps</i> records are recorded into the history log with period adjusted by setpoint Time Stamp Per all the time while the controller is switched on.
DISABLED	The function is disabled.						
ENGINE RUNNING	While the engine is running the <i>Time stamps</i> records are recorded into the history log with period adjusted by setpoint Time Stamp Per .						
ALWAYS	The <i>Time stamps</i> records are recorded into the history log with period adjusted by setpoint Time Stamp Per all the time while the controller is switched on.						

Setpoint: Time Stamp Per

Group	Date/Time
Range [units]	1 .. 240 [min]
Related FW	3.0
Description	The setpoint adjusts the time interval for <i>Time stamp</i> records. See also the setpoint Time stamp act .

Setpoint: #SummerTimeMod

Group	Date/Time								
Range [units]	DISABLED, WINTER, SUMMER, WINTER-S, SUMMER-S [-]								
Related FW	3.0								
Description	<p>The setpoint is used to select the mode of automatic daylight saving time change.</p> <table border="1" data-bbox="438 1684 1366 2009"> <tr> <td>DISABLED</td> <td>The automatic change to daylight saving time and back is disabled.</td> </tr> <tr> <td>WINTER</td> <td>The automatic change is enabled, the current season is winter and the controller is located in the northern hemisphere.</td> </tr> <tr> <td>SUMMER</td> <td>The automatic change is enabled, the current season is summer and the controller is located in the northern hemisphere.</td> </tr> <tr> <td>WINTER-S</td> <td>The automatic change is enabled, the current season is winter</td> </tr> </table>	DISABLED	The automatic change to daylight saving time and back is disabled.	WINTER	The automatic change is enabled, the current season is winter and the controller is located in the northern hemisphere.	SUMMER	The automatic change is enabled, the current season is summer and the controller is located in the northern hemisphere.	WINTER-S	The automatic change is enabled, the current season is winter
DISABLED	The automatic change to daylight saving time and back is disabled.								
WINTER	The automatic change is enabled, the current season is winter and the controller is located in the northern hemisphere.								
SUMMER	The automatic change is enabled, the current season is summer and the controller is located in the northern hemisphere.								
WINTER-S	The automatic change is enabled, the current season is winter								

		and the controller is located in the southern hemisphere.
	SUMMER-S	The automatic change is enabled, the current season is summer and the controller is located in the southern hemisphere.

Setpoint: #Time

Group	Date/Time
Range [units]	[HH:MM:SS]
Related FW	3.0
Description	<p>The setpoint shows the current time from the internal RTC clock of the controller and can be also used to readjust it.</p> <p>NOTE: If the controller is connected to other controllers via the CAN2 bus, the setpoints #Time and #Date are automatically synchronized each hour with the controller that has lowest address. If date/time is changed at one controller it is automatically updated also in all other controllers in the group.</p> <p>NOTE: Setpoint with the symbol # are synchronized between controllers.</p>

Setpoint: #Date

Group	Date/Time
Range [units]	[dd.mm.yyyy]
Related FW	3.0
Description	<p>The setpoint shows the date from the internal RTC clock of the controller and can be also used to readjust it.</p> <p>NOTE: If the controller is connected to other controllers via the CAN2 bus, the setpoints #Time and #Date are automatically synchronized each hour with the controller that has lowest address. If date/time is changed at one controller it is automatically updated also in all other controllers in the group.</p> <p>NOTE: Setpoint with the symbol # are synchronized between controllers.</p>

Table of values

Group: Engine values

Value: RPM

Group	Engine values
Units	1/min

Related FW	3.0
Description	Current engine speed.

Value: T Cyl aver

Group	Engine values
Units	°C
Related FW	3.0
Description	<p>The value contains average cylinder temperature, i.e. average of all configured logical analog inputs Cyl temp 1 ... Cyl temp 32</p> <p>NOTE: Available in IS-NT only.</p>

Value: T Cyl max

Group	Engine values
Units	°C
Related FW	3.0
Description	<p>The value contains the maximum of all cylinder temperatures, i.e. maximum of all configured logical analog inputs Cyl temp 1 ... Cyl temp 32</p> <p>NOTE: The value is intended for creating the "high cylinder temperature" alarm using an universal analog protection. There is a special wizard at the I/O tab in GenConfig which makes the configuration of cylinder temperatures easy.</p> <p>NOTE: Available in IS-NT only.</p>

Value: T Cyl min

Group	Engine values
Units	°C
Related FW	3.0
Description	<p>The value contains the minimus of all cylinder temperatures, i.e. maximum of all configured logical analog inputs Cyl temp 1 ... Cyl temp 32</p> <p>NOTE: The value is intended for creating the "misfiring cylinder" alarm using an universal analog protection.</p> <p>NOTE: Available in IS-NT only.</p>

Group: Gener values

Value: Act power

Group	Generator
Units	kW
Related FW	3.0
Description	Generator total active power.

Value: Act pwr L1

Group	Gener values
Units	kW
Related FW	3.0
Description	Generator active power in phase L1.

Value: Act pwr L2

Group	Gener values
Units	kW
Related FW	3.0
Description	Generator active power in phase L2.

Value: Act pwr L3

Group	Gener values
Units	kW
Related FW	3.0
Description	Generator active power in phase L3.

Value: React power

Group	Gener values
Units	kVAr
Related FW	3.0
Description	Generator total reactive power.

Value: React pwr L1

Group	Gener values
Units	kVAr
Related FW	3.0
Description	Generator reactive power in phase L1.

Value: React pwr L2

Group	Gener values
Units	kVAr
Related FW	3.0
Description	Generator reactive power in phase L2.

Value: React pwr L3

Group	Gener values
Units	kVAr
Related FW	3.0
Description	Generator reactive power in phase L3.

Value: Appar pwr

Group	Gener values
Units	kVA
Related FW	3.0
Description	Generator total apparent power.

Value: Appar pwr L1

Group	Gener values
Units	kVA
Related FW	3.0
Description	Generator apparent power in phase L1.

Value: Appar pwr L2

Group	Gener values
Units	kVA
Related FW	3.0
Description	Generator apparent power in phase L2.

Value: Appar pwr L3

Group	Gener values
Units	kVA
Related FW	3.0
Description	Generator apparent power in phase L3.

Value: Pwr factor

Group	Gener values
Units	-
Related FW	3.0
Description	<p>Generator cos-phi factor.</p> <p>NOTE: The "cos-phi" factor is widely used instead of power factor for pure harmonic waveforms, because a simplified method can be used for calculation of it's value. However, if this simplified method is used for significantly distorted waveforms, it may provide inaccurate results. This fact causes the controller "power factor" value may be different from a value measured by another true-rms measurement device if the waveform contains significant portion of higher harmonic frequencies.</p>

Value: Load char

Group	Gener values
Units	-
Related FW	3.0
Description	Character of the generator load. "L" means inductive load, "C" is capacitive and "R" is resistive load (power factor = 1).

Value: Pwr factor L1

Group	Gener values
Units	-
Related FW	3.0
Description	Generator power factor in phase L1.

Value: Load char L1

Group	Gener values
Units	-
Related FW	3.0
Description	Character of the generator load in the L1 phase. "L" means inductive load, "C" is capacitive and "R" is resistive load (power factor = 1).

Value: Pwr factor L2

Group	Gener values
Units	-
Related FW	3.0
Description	Generator power factor in phase L2.

Value: Load char L2

Group	Gener values
Units	-
Related FW	3.0
Description	Character of the generator load in the L2 phase. "L" means inductive load, "C" is capacitive and "R" is resistive load (power factor = 1).

Value: Pwr factor L3

Group	Gener values
Units	-
Related FW	3.0
Description	Generator power factor in phase L3.

Value: Load char L3

Group	Gener values
Units	-
Related FW	3.0
Description	Character of the generator load in the L3 phase. "L" means inductive load, "C" is capacitive and "R" is resistive load (power factor = 1).

Value: Gen freq

Group	Gener values
Units	Hz
Related FW	3.0
Description	Generator frequency. The frequency is measured in the phase L3.

Value: Gen V L1-N

Group	Gener values
Units	V
Related FW	3.0
Description	Generator voltage in phase L1. NOTE: The ratio between the voltage measured at the input terminals and the displayed voltage is adjusted by the setpoint VT ratio .

Value: Gen V L2-N

Group	Gener values
Units	V

Related FW	3.0
Description	Generator voltage in phase L2. NOTE: The ratio between the voltage measured at the input terminals and the displayed voltage is adjusted by the setpoint VT ratio .

Value: Gen V L3-N

Group	Gener values
Units	V
Related FW	3.0
Description	Generator voltage in phase L3. NOTE: The ratio between the voltage measured at the input terminals and the displayed voltage is adjusted by the setpoint VT ratio .

Value: Gen V

Group	Gener values
Units	V
Related FW	3.0
Description	Generator voltage. Average from all three phases. NOTE: The ratio between the voltage measured at the input terminals and the displayed voltage is adjusted by the setpoint VT ratio .

Value: Gen V L1-L2

Group	Gener values
Units	V
Related FW	3.0
Description	Generator voltage between phases L1 and L2. NOTE: The ratio between the voltage measured at the input terminals and the displayed voltage is adjusted by the setpoint VT ratio .

Value: Gen V L2-L3

Group	Gener values
Units	V
Related FW	3.0
Description	Generator voltage between phases L2 and L3. NOTE:

	The ratio between the voltage measured at the input terminals and the displayed voltage is adjusted by the setpoint VT ratio .
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Value: Gen V L3-L1

Group	Gener values
Units	V
Related FW	3.0
Description	Generator voltage between phases L3 and L1. NOTE: The ratio between the voltage measured at the input terminals and the displayed voltage is adjusted by the setpoint VT ratio .

Value: Gen curr L1

Group	Gener values
Units	A
Related FW	3.0
Description	Generator current in phase L1. NOTE: The ratio between the current measured at the input terminals and the displayed current is adjusted by the setpoints CT ratio prim and CT ratio sec .

Value: Gen curr L2

Group	Gener values
Units	A
Related FW	3.0
Description	Generator current in phase L2. NOTE: The ratio between the current measured at the input terminals and the displayed current is adjusted by the setpoints CT ratio prim and CT ratio sec .

Value: Gen curr L3

Group	Gener values
Units	A
Related FW	3.0
Description	Generator current in phase L3. NOTE: The ratio between the current measured at the input terminals and the displayed current is adjusted by the setpoints CT ratio prim and CT ratio sec .

Value: Gen V unbal

Group	Gener values
Units	%
Related FW	3.0
Description	<p>Generator voltage unbalance. The value is calculated as maximal difference of two phase voltages at one moment and expressed in % of the nominal voltage.</p> <p>NOTE: This value can be used for creating the generator voltage unbalance protection using the "universal analog protections".</p>

Value: Gen I unbal

Group	Gener values
Units	V
Related FW	3.0
Description	<p>Generator current unbalance. The value is calculated as maximal difference of two phase currents at one moment and expressed in % of the nominal current.</p> <p>NOTE: This value can be used for creating the generator current unbalance protection using the "universal analog protections".</p>

Value: Slip freq

Group	Gener values
Units	Hz
Related FW	3.0
Description	Differential frequency between the generator and the mains/bus.

Value: Angle

Group	Gener values
Units	°
Related FW	3.0
Description	The angle between the phasors of the generator and mains/bus voltage.

Group: Bus values

Value: Mains freq

Group	Mains values
Units	Hz
Related FW	3.0
Description	Mains frequency. The frequency is measured in the phase L3.

Value: Bus freq

Group	Bus values
Units	Hz
Related FW	3.0
Description	Bus frequency. The frequency is measured in the phase L3.

Value: Mains V L1-N

Group	Mains values
Units	V
Related FW	3.0
Description	<p>Mains voltage in phase L1.</p> <p>NOTE: The ratio between the voltage measured at the input terminals and the displayed voltage is adjusted by the setpoint Vm VT ratio.</p>

Value: Bus V L1-N

Group	Bus values
Units	V
Related FW	3.0
Description	<p>Bus voltage in phase L1.</p> <p>NOTE: The ratio between the voltage measured at the input terminals and the displayed voltage is adjusted by the setpoint Vb VT ratio.</p>

Value: Mains V L2-N

Group	Mains values
Units	V
Related FW	3.0
Description	<p>Mains voltage in phase L2.</p> <p>NOTE: The ratio between the voltage measured at the input terminals and the displayed voltage is adjusted by the setpoint Vm VT ratio.</p>

Value: Bus V L2-N

Group	Bus values
Units	V
Related FW	3.0
Description	<p>Bus voltage in phase L2.</p> <p>NOTE: The ratio between the voltage measured at the input terminals and the displayed voltage is adjusted by the setpoint Vb VT ratio.</p>

Value: Mains V L3-N

Group	Mains values
Units	V
Related FW	3.0
Description	<p>Mains voltage in phase L3.</p> <p>NOTE: The ratio between the voltage measured at the input terminals and the displayed voltage is adjusted by the setpoint Vm VT ratio.</p>

Value: Bus V L3-N

Group	Bus values
Units	V
Related FW	3.0
Description	<p>Bus voltage in phase L3.</p> <p>NOTE: The ratio between the voltage measured at the input terminals and the displayed voltage is adjusted by the setpoint Vb VT ratio.</p>

Value: Mains V

Group	Mains values
Units	V
Related FW	3.0
Description	<p>Mains voltage. Average from all three phases.</p> <p>NOTE: The ratio between the voltage measured at the input terminals and the displayed voltage is adjusted by the setpoint Vm VT ratio.</p>

Value: Bus V

Group	Bus values
Units	V
Related FW	3.0
Description	<p>Bus voltage. Average from all three phases.</p> <p>NOTE: The ratio between the voltage measured at the input terminals and the displayed voltage is adjusted by the setpoint Vb VT ratio.</p>

Value: Mains V L1-L2

Group	Mains values
Units	V
Related FW	3.0
Description	Mains voltage phase L1 to L2.

Value: Bus V L1-L2

Group	Bus values
Units	V
Related FW	3.0
Description	Bus voltage phase L1 to L2.

Value: Mains V L2-L3

Group	Mains values
Units	V
Related FW	3.0
Description	Mains voltage phase L2 to L3.

Value: Bus V L2-L3

Group	Bus values
Units	V
Related FW	3.0
Description	Bus voltage phase L2 to L3.

Value: Mains V L3-L1

Group	Mains values
Units	V
Related FW	3.0
Description	Mains voltage phase L3 to L1.

Value: Bus V L3-L1

Group	Bus values
Units	V
Related FW	3.0
Description	Bus voltage phase L3 to L1.

Value: Bus V unbal

Group	Bus values
Units	V
Related FW	3.0
Description	Bus voltage unbalance. The value is calculated as maximal difference of two phase voltages at one moment and expressed in % of the Bus nominal voltage.

Value: Im3/EarthFC

Group	Mains values
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Units	A
Related FW	3.0
Description	<p>This value contains the current measured at the current input labeled "IN". This input is used either for measurement of the mains current in phase L3 or for earth fault current. The function depends on the setpoint I/E-Pm meas.</p> <p>NOTE: The ratio between the current measured at the input terminals and the displayed current is adjusted by the setpoints EarthFltCurCTp and Im3/ErFICurCTS.</p>

Value: EarthFC

Group	Bus values
Units	A
Related FW	3.0
Description	<p>This value contains the current measured at the current input labeled "IN". This input is used for measurement of the earth fault current.</p> <p>NOTE: The ratio between the current measured at the input terminals and the displayed current is adjusted by the setpoints EarthFltCurCTp and Im3/ErFICurCTS.</p>

Group: Power management

Value: EnginePriority

Group	Pwr management
Units	-
Related FW	3.0
Description	<p>This value shows current priority number. It corresponds to the setpoint Priority except following situations:</p> <ul style="list-style-type: none"> • If at least one of binary inputs <i>Priority SW "X"</i> is configured on some source and is active then the actual gen-set priority is given by the combination of these inputs. • If a force value function is configured at the Priority setpoint and the forcing binary input is active, the actual gen-set priority is given by the alternative setting from the force value function. • If the Gen-set size optimization is active then the actual priority is given by the optimization function.

Value: Act Reserve

Group	Pwr management
Units	-
Related FW	3.0
Description	Actual absolute reserve .

Value: Reserve

Group	Pwr management
Units	-
Related FW	3.0
Description	Actual absolute reserve for start. This value contains a copy of the setpoint <i>#LoadResStrt</i> from the currently selected reserve set .

Value: Reserve Stp

Group	Pwr management
Units	kX
Related FW	3.0
Description	Actual absolute reserve - when the reserve is higher than this value the last started gen-set (the gen-set with the highest priority) is stopped. This value contains the following: <i>#LoadResStop</i> plus <i>Nominal power</i> of the genset which is first to stop. <i>#LoadResStop</i> is used from the currently selected reserve set .

Value: ActRes rel

Group	Power management
Units	%
Related FW	3.0
Description	Actual relative reserve .

Value: Res rel

Group	Power management
Units	%
Related FW	3.0
Description	Actual relative reserve for start. This value contains a copy of the setpoint <i>##LdResStrt</i> from the currently selected reserve set .

Value: ResStp rel

Group	Power management
Units	%
Related FW	3.0
Description	Actual relative reserve - when the relative reserve is higher than this value the last started gen-set (the gen-set with the highest priority) is stopped. This value contains the following:

	<p><i>[Nominal power of gen-set which is next to be stopped + ((%LdResStp/100) * Sum of nominal powers of gen-sets loaded in power management except the one which is next to be stopped)]/(Sum of nominal powers of gen-sets loaded in power management).</i></p> <p>#%LdResStp is used from the currently selected reserve set.</p>
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Value: MinR PWR

Group	Power management
Units	kW
Related FW	3.0
Description	Currently active Minimal Running Power level. If the value contains 0 the minimal running power function is disabled.

Group: Sync/Load ctrl

Value: ActPwrReq

Group	Sync/Load ctrl
Units	kW
Related FW	3.0
Description	This value contains actual required load level, which is used as the input into the load regulation loop in the parallel to mains operation.

Value: SpdRegOut

Group	Sync/Load ctrl
Units	V
Related FW	3.0
Description	This is the actual voltage on the speed governor output of the controller. In case the output is switched to PWM mode, the relation is 10V ~ 100% PWM.

Value: Speed request

Group	Sync/Load ctrl
Units	%
Related FW	3.0
Description	<p>This value contains the speed control signal expressed in %. This value is used for digital interfacing (via a communication bus) with ECUs that require the requested speed in %. The relation between Speed request and SpdRegOut is following:</p> <ul style="list-style-type: none"> 0% is sent for SpeedRegOut = -10V

	<ul style="list-style-type: none"> 100% is sent for SpeedRegOut = 10V <p>NOTE: Most of ECU units use the J1939 TSC1 frame for speed control, where the requested speed is expressed directly in RPM. Use the value SpeedReq RPM for this purpose.</p>
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Value: SpeedReq RPM

Group	Sync/Load ctrl
Units	RPM
Related FW	3.0
Description	<p>This value contains the speed which is currently requested by the controller from the attached ECU. This value is used for digital interfacing (via a communication bus) with ECUs that require the requested speed directly in RPM. The relation between SpeedReq RPM and Speed request is following:</p> <ul style="list-style-type: none"> 0.9 * Nominal RPM is sent for 0% 1.1 * Nominal RPM is sent for 100%

Value: ReqEngineSpeed

Group	Sync/Load ctrl
Units	RPM
Related FW	3.0
Description	<p>This value contains an exact copy of the required speed which is being sent to the ECU (e.g. in the TSC1 frame). It is intended for checking if the speed regulation chain is configured properly.</p>

Value: SystLoadCtrl

Group	Sync/Load ctrl
Units	-
Related FW	3.0
Description	<p>Code of the current load control mode. The description how to obtain the text representation of each code can be found at the value Engine state.</p>

Value: TotRunPact Q

Group	Pwr management
Units	kVAr
Related FW	3.0
Description	<p>Sum of reactive power of all gen-sets within the group that are connected to the bus.</p>

Value: TotRunPact P

Group	Pwr management
Units	kW
Related FW	3.0
Description	Sum of active power of all gen-sets within the group that are connected to the bus.

Value: netPgnomPh

Group	Pwr management
Units	kW
Related FW	3.0
Description	Sum of nominal power of all gen-sets within the group that are connected to the bus.

Group: Volt/PF ctrl

Value: VoltRegOut

Group	Volt/PF ctrl
Units	%
Related FW	3.0
Description	This is the actual PWM percentage on the AVRi output of the controller.

Value: SystPfCtrl

Group	Volt/PF ctrl
Units	-
Related FW	3.0
Description	Code of the current power factor control mode. The description how to obtain the text representation of each code can be found at the value Engine state .

Group: Force value

Value: ExtValue1

Group	Force value
Units	-
Related FW	3.0
Description	<p>This data object is intended for remote control of the gen-set via the communication if some kind of data is to be passed into the controller.</p> <p>This object can be written via the communication (e.g. Modbus) without any limitation. Use GenConfig function Generate Cfg Image to get the communication</p>

	<p>object number or register number of this particular value object. Below is a typical example of using this object.</p> <p>EXAMPLE: The gen-set is required to be running in parallel-to-mains mode at constant load level (baseload), however the baseload level is adjusted from a supervisory PLC system via Modbus.</p> <p>CAUTION! It is not allowed to solve this task by cyclic writing of the baseload setpoint from the supervisory device. The EEPROM memory may become damaged when any setpoint is written repeatedly with a short period.</p> <p>The proper solution is following:</p> <ol style="list-style-type: none"> 1. Go to GenConfig, download the configuration from the controller, select the LAI tab and configure the logical analog input <i>LdCtrl:AnExBlid</i> onto the <i>ExtValue1</i>, which is located in the Force value group. If you do not see the LAI tab you have to switch the GenConfig to "advanced" mode. Then upload the configuration into the controller. 2. Go to IntelliMonitor and change the setpoint <i>Load ctrl PtM</i> to ANEXT BASELOAD. 3. Now you have to program your PLC to write requested gen-set baseload into the Modbus register <i>ExtValue1</i> (register number 40392 for IG/IS-NT-2.4).
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Value: ExtValue2

Group	Force value
Units	-
Related FW	3.0
Description	<p>This data object is intended for remote control of the gen-set via the communication if some kind of data is to be passed into the controller.</p> <p>This object can be written via the communication (e.g. Modbus) without any limitation. Use GenConfig function Generate Cfg Image to get the communication object number or register number of this particular value object. See an example at the object ExtValue1.</p>

Value: ExtValue3

Group	Force value
Units	-
Related FW	3.0
Description	<p>This data object is intended for remote control of the gen-set via the communication if some kind of data is to be passed into the controller.</p> <p>This object can be written via the communication (e.g. Modbus) without any limitation. Use GenConfig function Generate Cfg Image to get the communication</p>

	object number or register number of this particular value object. See an example at the object ExtValue1 .
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Value: ExtValue4

Group	Force value
Units	X
Related FW	3.0
Description	<p>This data object is intended for remote control of the gen-set via the communication if some kind of data is to be passed into the controller.</p> <p>This object can be written via the communication (e.g. Modbus) without any limitation. Use GenConfig function Generate Cfg Image to get the communication object number or register number of this particular value object. See an example at the object ExtValue1.</p>

Group: Load shedding

Value: StatLdShed

Group	Load shedding
Units	-
Related FW	3.0
Description	The value indicates the current load shedding stage. 0 indicates that the load shedding is not active. See the chapter Load shedding for more details.

Group: Analog CU

Value: UBat

Group	Analog CU
Units	V
Related FW	3.0
Description	Voltage at the controller power supply terminals.

Value: CPU Temp

Group	Analog CU
Units	°C
Related FW	3.0
Description	Temperature inside the controller (on the CPU).

Value: D+

Group	Analog CU
Units	V
Related FW	3.0
Description	Voltage measured at the D+ terminal. If this voltage is > 80% of the Ubat the D+ terminal is evaluated as active and the engine is evaluated as running. See also the chapter Start sequence .

Value: AIN CU-1

Group	Analog CU
Units	configurable
Related FW	3.0
Description	This is the value of the analog input 1 of the controller. Analog inputs are fully configurable so the name and units depend on configuration. In the default configuration the input is used for oil pressure measurement.

Value: AIN CU-2

Group	Analog CU
Units	configurable
Related FW	3.0
Description	This is the value of the analog input 2 of the controller. Analog inputs are fully configurable so the name and units depend on configuration. In the default configuration the input is used for water temperature measurement.

Value: AIN CU-3

Group	Analog CU
Units	configurable
Related FW	3.0
Description	This is the value of the analog input 3 of the controller. Analog inputs are fully configurable so the name and units depend on configuration. In the default configuration the input is used for fuel level measurement.

Value: AIN CU-4

Group	Analog CU
Units	configurable
Related FW	3.0
Description	This is the value of the analog input 4 of the controller. Analog inputs are fully configurable so the name and units depend on configuration. In the default configuration the input is used for fuel level measurement.

Group: Bin inputs CU

Value: BIN

Group	Bin inputs CU
Units	-
Related FW	3.0
Description	<p>This is a bit array containing status of physical binary inputs of the controller. Bit0 represents BI1, bit1 represents BI2 etc..</p> <p>NOTE: All terminals display binary values in "human-readable" form - from left to right. That means the bit 0 is displayed in the most left position. This is different from common use in computer science, where binary values are displayed from right to left.</p> <p>NOTE: Click on button with "... " to get a clear list of BI names with their corresponding values.</p>

Group: Bin outputs CU

Value: BOUT

Group	Bin outputs CU
Units	-
Related FW	3.0
Description	<p>This is a bit array containing status of physical binary outputs of the controller. Bit0 represents BO1, bit1 represents BO2 etc..</p> <p>NOTE: All terminals display binary values in "human-readable" form - from left to right. That means the bit 0 is displayed in the most left position. This is different from common use in computer science, where binary values are displayed from right to left.</p> <p>NOTE: Click on button with "... " to get a clear list of BI names with their corresponding values.</p>

Group: Log Bout

Value: LogBout 1

Group	Log bout
Units	-
Related FW	3.0
Description	<p>This is a bit array containing status of logical binary outputs 1-16 of the controller. Bit0 represents LBO1, bit1 represents LBO2 etc..</p> <p>NOTE: All terminals display binary values in "human-readable" form - from left to right. That means the bit 0 is displayed in the most left position. This is different from common use in computer science, where binary values are displayed from right to left.</p>

	<p>NOTE: Click on button with "... " to get a clear list of BI names with their corresponding values.</p>
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Value: LogBout 2

Group	Log bout
Units	-
Related FW	3.0
Description	<p>This is a bit array containing status of logical binary outputs 17-32 of the controller. Bit0 represents LBO17, bit1 represents LBO18 etc..</p> <p>NOTE: All terminals display binary values in "human-readable" form - from left to right. That means the bit 0 is displayed in the most left position. This is different from common use in computer science, where binary values are displayed from right to left.</p> <p>NOTE: Click on button with "... " to get a clear list of BI names with their corresponding values.</p>

Value: LogBout 3

Group	Log bout
Units	-
Related FW	3.0
Description	<p>This is a bit array containing status of logical binary outputs 33-48 of the controller. Bit0 represents LBO33, bit1 represents LBO34 etc..</p> <p>NOTE: All terminals display binary values in "human-readable" form - from left to right. That means the bit 0 is displayed in the most left position. This is different from common use in computer science, where binary values are displayed from right to left.</p> <p>NOTE: Click on button with "... " to get a clear list of BI names with their corresponding values.</p>

Value: LogBout 4

Group	Log bout
Units	-
Related FW	3.0
Description	<p>This is a bit array containing status of logical binary outputs 49-64 of the controller. Bit0 represents LBO49, bit1 represents LBO50 etc..</p> <p>NOTE: All terminals display binary values in "human-readable" form - from left to right.</p>

	<p>That means the bit 0 is displayed in the most left position. This is different from common use in computer science, where binary values are displayed from right to left.</p> <p>NOTE: Click on button with "... " to get a clear list of BI names with their corresponding values.</p>
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Value: LogBout 5

Group	Log bout
Units	-
Related FW	3.0
Description	<p>This is a bit array containing status of logical binary outputs 65-80 of the controller. Bit0 represents LBO65, bit1 represents LBO66 etc..</p> <p>NOTE: All terminals display binary values in "human-readable" form - from left to right. That means the bit 0 is displayed in the most left position. This is different from common use in computer science, where binary values are displayed from right to left.</p> <p>NOTE: Click on button with "... " to get a clear list of BI names with their corresponding values.</p>

Value: LogBout 6

Group	Log bout
Units	-
Related FW	3.0
Description	<p>This is a bit array containing status of logical binary outputs 81-96 of the controller. Bit0 represents LBO81, bit1 represents LBO82 etc..</p> <p>NOTE: All terminals display binary values in "human-readable" form - from left to right. That means the bit 0 is displayed in the most left position. This is different from common use in computer science, where binary values are displayed from right to left.</p> <p>NOTE: Click on button with "... " to get a clear list of BI names with their corresponding values.</p>

Value: LogBout 7

Group	Log bout
Units	-
Related FW	3.0
Description	This is a bit array containing status of logical binary outputs 97-112 of the

	<p>controller. Bit0 represents LBO97, bit1 represents LBO98 etc..</p> <p>NOTE: All terminals display binary values in "human-readable" form - from left to right. That means the bit 0 is displayed in the most left position. This is different from common use in computer science, where binary values are displayed from right to left.</p>
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Value: LogBout 8

Group	Log bout
Units	-
Related FW	3.0
Description	<p>This is a bit array containing status of logical binary outputs 113-128 of the controller. Bit0 represents LBO113, bit1 represents LBO114 etc..</p> <p>NOTE: All terminals display binary values in "human-readable" form - from left to right. That means the bit 0 is displayed in the most left position. This is different from common use in computer science, where binary values are displayed from right to left.</p>

Value: LogBout 9

Group	Log bout
Units	-
Related FW	3.0
Description	<p>This is a bit array containing status of logical binary outputs 128-143 of the controller. Bit0 represents LBO128, bit1 represents LBO129 etc..</p> <p>NOTE: All terminals display binary values in "human-readable" form - from left to right. That means the bit 0 is displayed in the most left position. This is different from common use in computer science, where binary values are displayed from right to left.</p>

Value: RemoteControl

Group	Log bout
Units	-
Related FW	3.0
Description	<p>This is a bit array containing status of the binary outputs Remote control1 ... Remote control8.</p>

Group: Info

Value: Controller mode

Group	Info
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Units	-
Related FW	3.0
Description	This value contains actual controller mode. The controller mode is selected by the setpoint Controller mode but the setpoint position can be overridden by binary inputs Remote OFF , Remote MAN , Remote AUT or Remote TEST .

Value: SW Version

Group	Info
Units	-
Related FW	3.0
Description	Major and minor firmware version number. E.g. value "2,4" means version 2.4. Release version number is not included.

Value: Application

Group	Info
Units	-
Related FW	3.0
Description	Code of the application type. E.g. 1 for SPtM, 2 for SPI, 3 for MINT etc. The value is intended for diagnostic purposes.

Value: SW Branch

Group	Info
Units	-
Related FW	3.0
Description	Firmware branch code. Contains 1 in case of standard branches.

Value: PasswordDecode

Group	Info
Units	-
Related FW	3.0
Description	This value contains encrypted serial number of the controller and administrator password and is intended for retrieving of the lost password. Send this number together with controller serial number to your distributor if you need to retrieve your password.

Value: CAN16

Group	Info
Units	-

Related FW	3.0
Description	<p>Bits of this value show "1" if the controller receives messages from the controller which has address corresponding with the bit position. Bit 0 represents address 1 etc. This value contains information about controllers with addresses 1-16.</p> <p>NOTE: The bit which corresponds to the own controller is always set to "1".</p>

Value: CAN32

Group	Info
Units	-
Related FW	3.0
Description	<p>Bits of this value show "1" if the controller receives messages from the controller which has address corresponding with the bit position. Bit 0 represents address 17 etc. This value contains information about controllers with addresses 17-32.</p> <p>NOTE: The bit which corresponds to the own controller is always set to "1".</p>

Value: Reg16

Group	Info
Units	-
Related FW	3.0
Description	<p>Bits of this value show "1" if the controller which has address corresponding with the bit position plays active role in the power management. Bit 0 represents address 1 etc. This value contains information about controllers with addresses 1-16.</p>

Value: Reg32

Group	Info
Units	-
Related FW	3.0
Description	<p>Bits of this value show "1" if the controller which has address corresponding with the bit position plays active role in the power management. Bit 0 represents address 17 etc. This value contains information about controllers with addresses 17-32.</p>

Value: GL16

Group	Info
Units	-
Related FW	3.0
Description	<p>Bits of this value show "1" if the controller which has address corresponding with the bit position has GCB closed. Bit 0 represents address 1 etc. This value</p>

	contains information about controllers with addresses 1-16.
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Value: GL32

Group	Info
Units	-
Related FW	3.0
Description	Bits of this value show "1" if the controller which has address corresponding with the bit position has GCB closed. Bit 0 represents address 1 etc. This value contains information about controllers with addresses 17-32.

Value: Engine state

Group	Info
Units	-
Related FW	3.0
Description	<p>Code of the current state of the engine control. The text representation of each code can be obtained following way:</p> <ol style="list-style-type: none"> 1. Open the archive in GenConfig and use the function File -> Generate Cfg Image -> Comm. objects to create a list of all communication objects. 2. Open the file, find the row containing this value and look for the column "Type". The column "Type" contains reference to a list of codes and their representations located in the bottom part of the file.

Value: Breaker state

Group	Info
Units	-
Related FW	3.0
Description	Code of the current state of the breaker control. The text representation of each code can be obtained by the procedure described at the value Engine state .

Value: Timer text

Group	Info
Units	-
Related FW	3.0
Description	Code of the currently running system process timer. The text representation of each code can be obtained by the procedure described at the value Engine state . Remaining time of the timer is available in the value Timer val .

Value: Timer val

Group	Info
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Units	-
Related FW	3.0
Description	The value contains remaining time of the currently running system process timer. The name of the timer is available in the value Timer text .

Value: ECU DiagSource

Group	Info
Units	-
Related FW	3.0
Description	This value indicates from which source the ECU diagnostic messages are being received. The source depends on ECU type.

Value: NextTime1-4

Group	Info
Units	-
Related FW	3.0
Description	This value contains time of next activation of the timer block 1-4 (i.e. of the output TimerAct 1-4). The related date is available in the value NextDate1-4 . NOTE: More information about timers is available in the chapter General purpose timers .

Value: NextDate1-4

Group	Info
Units	-
Related FW	3.0
Description	This value contains date of next activation of the timer block 1-4 (i.e. of the output TimerAct 1-4). The related time is available in the value NextTime1-4 . NOTE: More information about timers is available in the chapter General purpose timers .

Value: NextTime5-8

Group	Info
Units	-
Related FW	3.0
Description	This value contains time of next activation of the timer block 5-8 (i.e. of the output TimerAct 5-8). The related date is available in the value NextDate5-8 .

	<p>NOTE: More information about timers is available in the chapter General purpose timers.</p>
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Value: NextDate5-8

Group	Info
Units	-
Related FW	3.0
Description	<p>This value contains date of next activation of the timer block 5-8 (i.e. of the output TimerAct 5-8). The related time is available in the value NextTime5-8.</p> <p>NOTE: More information about timers is available in the chapter General purpose timers.</p>

Value: NextTime9-12

Group	Info
Units	-
Related FW	3.0
Description	<p>This value contains time of next activation of the timer block 9-12 (i.e. of the output TimerAct 9-12). The related date is available in the value NextDate9-12.</p> <p>NOTE: More information about timers is available in the chapter General purpose timers.</p>

Value: NextDate9-12

Group	Info
Units	-
Related FW	3.0
Description	<p>This value contains date of next activation of the timer block 9-12 (i.e. of the output TimerAct 9-12). The related time is available in the value NextTime9-12.</p> <p>NOTE: More information about timers is available in the chapter General purpose timers.</p>

Value: NextTime13-16

Group	Info
Units	-
Related FW	3.0
Description	<p>This value contains time of next activation of the timer block 13-16 (i.e. of the</p>

	<p>output TimerAct 13-16). The related date is available in the value NextDate13-16.</p> <p>NOTE: More information about timers is available in the chapter General purpose timers.</p>
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Value: NextDate13-16

Group	Info
Units	-
Related FW	3.0
Description	<p>This value contains date of next activation of the timer block 13-16 (i.e. of the output TimerAct 13-16). The related time is available in the value NextTime13-16.</p> <p>NOTE: More information about timers is available in the chapter General purpose timers.</p>

Value: AirGate ID

Group	Info
Units	-
Related FW	3.0
Description	<p>If the controller is connected to an AirGate server this value displays the ID string assigned by the server. This ID string is to be used in ComAp PC tools (e.g. IntelliMonitor) to specify the respective controller when the connection is opened.</p>

Value: AirGate status

Group	Info												
Units	-												
Related FW	3.0												
Description	<p>This value displays actual status of the connection to the AirGate server.</p> <table border="1" data-bbox="438 1563 1366 1881"> <tr> <td>0</td> <td>Not connected to AirGate.</td> </tr> <tr> <td>1</td> <td>Connected, registered, waiting for authorization.</td> </tr> <tr> <td>2</td> <td>Registration denied.</td> </tr> <tr> <td>3</td> <td>Can not register, no free capacity in the server.</td> </tr> <tr> <td>4</td> <td>Can not register, other reason.</td> </tr> <tr> <td>5</td> <td>Connected, registered, authorized.</td> </tr> </table>	0	Not connected to AirGate.	1	Connected, registered, waiting for authorization.	2	Registration denied.	3	Can not register, no free capacity in the server.	4	Can not register, other reason.	5	Connected, registered, authorized.
0	Not connected to AirGate.												
1	Connected, registered, waiting for authorization.												
2	Registration denied.												
3	Can not register, no free capacity in the server.												
4	Can not register, other reason.												
5	Connected, registered, authorized.												

Value: Latitude

Group	Info
Units	-
Related FW	3.0
Description	This value contains latitude of the controller. This value is obtained from connected IB-NT with active GPS. Time is automatically synchronized as well when succesfull GPS fix is established. If no valid value is available from InternetBridge-NT, value ##### is displayed.

Value: Longitude

Group	Info
Units	-
Related FW	3.0
Description	This value contains longitude of the controller. This value is obtained from connected IB-NT with active GPS. Time is automatically synchronized as well when succesfull GPS fix is established. If no valid value is available from InternetBridge-NT, value ##### is displayed.

Group: Statistics

Value: kWhours

Group	Statistics
Units	kWh
Related FW	3.0
Description	Active energy counter. NOTE: The counter can be readjusted/reset from IntelliMonitor menu Monitor -> Set statistics .

Value: kVAhours

Group	Statistics
Units	kVAh
Related FW	3.0
Description	Reactive energy counter. NOTE: The counter can be readjusted/reset from IntelliMonitor menu Monitor -> Set statistics .

Value: Run Hours

Group	Statistics
Units	h
Related FW	3.0
Description	<p>Engine operation hours counter. If an ECU is configured and it provides engine hours value, the value is taken from ECU. If the value is not available from the ECU or ECU is not configured, the engine hours are incremented in the controller while the engine is running.</p> <p>NOTE: The counter can be readjusted/reset from IntelliMonitor menu Monitor -> Set statistics.</p>

Value: Num starts

Group	Statistics
Units	-
Related FW	3.0
Description	<p>Engine start commands counter. The counter is increased by 1 even if the particular start command will take more than one attempt.</p> <p>NOTE: The counter can be readjusted/reset from IntelliMonitor menu Monitor -> Set statistics.</p>

Value: NumUnsc start

Group	Statistics
Units	-
Related FW	3.0
Description	<p>Unsuccessful starts counter. The counter is incremented always when <i>Start fail</i> alarm is issued.</p> <p>NOTE: The counter can be readjusted/reset from IntelliMonitor menu Monitor -> Set statistics.</p>

Value: Service time 1

Group	Statistics
Units	h
Related FW	3.0
Description	<p>This is maintenance countdown timer #1. The timer is located in setpoints (group Engine protect) as well as in values (group Statistics). Adjust the timer to the requested maintenance interval. It will be then decremented while the gen-set is running. The alarm <i>WrnServiceTime</i> is issued as soon as the timer counts down to zero.</p>

Value: Service time 2

Group	Statistics
Units	h
Related FW	3.0
Description	This is maintenance countdown timer #2. The timer is located in setpoints (group Engine protect) as well as in values (group Statistics). Adjust the timer to the requested maintenance interval. It will be then decremented while the gen-set is running. The alarm <i>WrnServiceTime</i> is issued as soon as the timer counts down to zero.

Value: Service time 3

Group	Statistics
Units	h
Related FW	3.0
Description	This is maintenance countdown timer #3. The timer is located in setpoints (group Engine protect) as well as in values (group Statistics). Adjust the timer to the requested maintenance interval. It will be then decremented while the gen-set is running. The alarm <i>WrnServiceTime</i> is issued as soon as the timer counts down to zero.

Value: Service time 4

Group	Statistics
Units	h
Related FW	3.0
Description	This is maintenance countdown timer #4. The timer is located in setpoints (group Engine protect) as well as in values (group Statistics). Adjust the timer to the requested maintenance interval. It will be then decremented while the gen-set is running. The alarm <i>WrnServiceTime</i> is issued as soon as the timer counts down to zero.

Value: TotalDownTime

Group	Statistics
Units	h
Related FW	3.0
Description	This counter counts while the controller is in "not ready" state, i.e. it can not be started. The reason of the "not ready" state may be either some 2 nd level alarm or the controller switched in OFF mode. NOTE: The counter can be readjusted/reset from IntelliMonitor menu Monitor -> Set

	statistics.
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Value: DnTimeReqToRun

Group	Statistics
Units	h
Related FW	3.0
Description	<p>This counter counts while the controller is in "not ready" state (see the value Total downtime) and there is a request for the gen-set to run.</p> <p>NOTE: The counter can be readjusted/reset from IntelliMonitor menu Monitor -> Set statistics.</p>

Value: PulseCounter 1

Group	Statistics
Units	-
Related FW	3.0
Description	<p>This is the value of <i>PulseCounter #1</i> module. See the binary input PulseCounter 1.</p>

Value: PulseCounter 2

Group	Statistics
Units	-
Related FW	3.0
Description	<p>This is the value of <i>PulseCounter #2</i> module. See the binary input PulseCounter 2.</p> <p>NOTE: Available in IS-NT only.</p>

Value: PulseCounter 3

Group	Statistics
Units	-
Related FW	3.0
Description	<p>This is the value of <i>PulseCounter #3</i> module. See the binary input PulseCounter 3.</p> <p>NOTE: Available in IS-NT only.</p>

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Value: PulseCounter 4

Group	Statistics
Units	-
Related FW	3.0
Description	<p>This is the value of <i>PulseCounter #4</i> module. See the binary input PulseCounter 4.</p> <p>NOTE: Available in IS-NT only.</p>

Table of binary input functions

Binary input: GCB feedback

Related FW	3.0
Description	<p>This input is used for connection of the normally open feedback contact from the generator circuit breaker or contactor. If the input is active, the controller will consider the GCB as closed and vice versa.</p> <ul style="list-style-type: none"> • If the feedback does not respond to a change of the control output GCB close/open within 2s, the alarm <i>GCB Fail</i> will be issued. • If the feedback changes it's position unexpectedly without any command given by the control output, the alarm <i>GCB Fail</i> will be issued immediately. <p>NOTE: This input is obligatory.</p>

Binary input: MCB feedback

Related FW	3.0
Description	<p>This is the input for the mains circuit breaker or contactor auxiliary contact. If the input is active, the controller will consider the MCB as closed and vice versa.</p>

Binary input: Sys start/stop

Related FW	3.0
Description	<p>This input is used to activate and deactivate the particular gen-set within the group. Reaction of the controller to a change of this input is delayed by setpoints #SysAMFstrDel and #SysAMFstopDel.</p> <ul style="list-style-type: none"> • If the input is active, the gen-set in AUT mode takes active part in the power management of the group, i.e. starts and stops automatically

	<p>according to the load.</p> <p>NOTE:</p> <p>If the power management is disabled by the Pwr Management setpoint, the gen-set excluded from the power management and starts and stops only according to position of this input.</p> <ul style="list-style-type: none"> • If the input is not active, the gen-set is always stopped in AUT mode. <p>NOTE:</p> <p>This input is usually wired parallel into all controllers within the group to activate and deactivate all the gen-sets in the group by one switch (signal). If you want to deactivate one particular genset, switch it out from AUT mode.</p>
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Binary input: Emergency Stop

Related FW	3.0
Description	<p>If the input is activated, engine shutdown is immediately performed. However, the controller behavior is slightly different compared to other shutdown alarms:</p> <ul style="list-style-type: none"> • Outputs Ignition, Ventilation, Cooling pump and Prelubr pump are deactivated as well. • This input cannot be overridden with the input Sd override. <p>NOTE:</p> <p>Because of safety reasons it is recommended to configure this input as <i>Normally closed</i> and use a NC switch.</p> <p>CAUTION!</p> <p>This is a software function only. It can be extended by a "hard-wired" emergency stop function, which means disconnecting power supply from the controller outputs.</p>

Binary input: REMOTE: Remote off

Related FW	3.0
Description	<p>The controller is forced into OFF mode while this input is active and the genset is not running. The controller will return into the previous mode after the input is deactivated. If the genset is running, the mode does not change until it is stopped.</p> <p>Use this input if you need to disable the genset temporarily from any reason (maintenance, control from a higher-level automation system etc..).</p>

Binary input: REMOTE: Remote MAN

Related FW	3.0
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Description	<p>The controller is forced into MAN mode while this input is active.</p> <p>NOTE: Programming of firmware and/or configuration is disabled while this input is active, as the programming is allowed in OFF mode only and GenConfig is not able to switch the controller to OFF mode while MAN mode is forced by this input.</p>
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Binary input: REMOTE: Remote AUT/Remote SEM

Related FW	3.0
Description	<p>SEM mode is available in IS-NT only!</p> <p>The controller is forced into AUT or SEM mode while this input is active.</p> <p>NOTE: Programming of firmware and/or configuration is disabled while this input is active, as the programming is allowed in OFF mode only and GenConfig is not able to switch the controller to OFF mode while AUT mode is forced by this input.</p>

Binary input: REMOTE: Remote TEST

Related FW	3.0
Description	<p>The controller is forced into TEST mode while this input is active. This input can be used, among others, for following purposes:</p> <ul style="list-style-type: none"> • In combination with a timer module for periodic testing of the engine. • In combination with the input Test on load for forcing the genset to start and take over the load by one binary signal (manual switch, higher-level automation system etc.)

Binary input: REMOTE: Remote off

Related FW	3.0
Description	<p>The controller is forced into OFF mode while this input is active and the genset is not running. The controller will return into the previous mode after the input is deactivated. If the genset is running, the mode does not change until it is stopped.</p> <p>Use this input if you need to disable the genset temporarily from any reason (maintenance, control from a higher-level automation system etc..).</p>

Binary input: REMOTE: Remote MAN

Related FW	3.0
Description	<p>The controller is forced into MAN mode while this input is active.</p> <p>NOTE: Programming of firmware and/or configuration is disabled while this input is active, as the programming is allowed in OFF mode only and GenConfig is not able to switch the controller to OFF mode while MAN mode is forced by this input.</p>

Binary input: REMOTE: Remote AUT/Remote SEM

Related FW	3.0
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Description	<p>SEM mode is available in IS-NT only!</p> <p>The controller is forced into AUT or SEM mode while this input is active.</p> <p>NOTE: Programming of firmware and/or configuration is disabled while this input is active, as the programming is allowed in OFF mode only and GenConfig is not able to switch the controller to OFF mode while AUT mode is forced by this input.</p>
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Binary input: REMOTE: Remote TEST

Related FW	3.0
Description	<p>The controller is forced into TEST mode while this input is active. This input can be used, among others, for following purposes:</p> <ul style="list-style-type: none"> • In combination with a timer module for periodic testing of the engine. • In combination with the input Test on load for forcing the genset to start and take over the load by one binary signal (manual switch, higher-level automation system etc.)

Binary input: REMOTE: Remote off

Related FW	3.0
Description	<p>The controller is forced into OFF mode while this input is active and the genset is not running. The controller will return into the previous mode after the input is deactivated. If the genset is running, the mode does not change until it is stopped.</p> <p>Use this input if you need to disable the genset temporarily from any reason (maintenance, control from a higher-level automation system etc..).</p>

Binary input: REMOTE: Remote MAN

Related FW	3.0
Description	<p>The controller is forced into MAN mode while this input is active.</p> <p>NOTE: Programming of firmware and/or configuration is disabled while this input is active, as the programming is allowed in OFF mode only and GenConfig is not able to switch the controller to OFF mode while MAN mode is forced by this input.</p>

Binary input: REMOTE: Remote AUT/Remote SEM

Related FW	3.0
Description	<p>SEM mode is available in IS-NT only!</p> <p>The controller is forced into AUT or SEM mode while this input is active.</p> <p>NOTE: Programming of firmware and/or configuration is disabled while this input is active, as the programming is allowed in OFF mode only and GenConfig is not able to switch the controller to OFF mode while AUT mode is forced by this input.</p>

Binary input: REMOTE: Remote TEST

Related FW	3.0
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Description	<p>The controller is forced into TEST mode while this input is active. This input can be used, among others, for following purposes:</p> <ul style="list-style-type: none"> • In combination with a timer module for periodic testing of the engine. • In combination with the input Test on load for forcing the genset to start and take over the load by one binary signal (manual switch, higher-level automation system etc.)
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Binary input: REMOTE: Remote off

Related FW	3.0
Description	<p>The controller is forced into OFF mode while this input is active and the genset is not running. The controller will return into the previous mode after the input is deactivated. If the genset is running, the mode does not change until it is stopped.</p> <p>Use this input if you need to disable the genset temporarily from any reason (maintenance, control from a higher-level automation system etc..).</p>

Binary input: REMOTE: Remote MAN

Related FW	3.0
Description	<p>The controller is forced into MAN mode while this input is active.</p> <p>NOTE: Programming of firmware and/or configuration is disabled while this input is active, as the programming is allowed in OFF mode only and GenConfig is not able to switch the controller to OFF mode while MAN mode is forced by this input.</p>

Binary input: REMOTE: Remote AUT/Remote SEM

Related FW	3.0
Description	<p>SEM mode is available in IS-NT only!</p> <p>The controller is forced into AUT or SEM mode while this input is active.</p> <p>NOTE: Programming of firmware and/or configuration is disabled while this input is active, as the programming is allowed in OFF mode only and GenConfig is not able to switch the controller to OFF mode while AUT mode is forced by this input.</p>

Binary input: REMOTE: Remote TEST

Related FW	3.0
Description	<p>The controller is forced into TEST mode while this input is active. This input can be used, among others, for following purposes:</p> <ul style="list-style-type: none"> • In combination with a timer module for periodic testing of the engine. • In combination with the input Test on load for forcing the genset to start and take over the load by one binary signal (manual switch, higher-level automation system etc.)

Binary input: Oil press

Related FW	3.0
Description	<p>This input is to be configured to the physical binary input where engine oil pressure binary sensor is connected. It provides following alarms:</p> <ul style="list-style-type: none"> • The input must not be active at stopped engine. If it is active, the controller issues <i>Sd Oil press B</i> alarm. • The input must be active at running engine at latest in the moment when the alarm blocking delay RunOnlyBlkDel1 has elapsed. If it is not active, the controller issues <i>Sd Oil press B</i> alarm. <p>NOTE: If you use this logical binary input you do not need to configure any other protection onto the respective physical binary input.</p>

Binary input: AccessLock int

Related FW	3.0
Description	<p>This input forces the controller built-in terminal into monitoring mode.</p> <ul style="list-style-type: none"> • Setpoints changes are disabled. • Using control buttons on the panel is disabled even if the controller is in MAN mode. • Change of controller mode is disabled. <p>NOTE: As the IS-NT and IGS-NT-BB do not have built-in terminal, this input is assigned to the terminal or IntelliVision (display) #1, which is supposed to be directly attached to the controller or mounted close to it.</p>

Binary input: AccessLock ext

Related FW	3.0
Description	<p>This input forces all external remote terminals into monitoring mode.</p> <ul style="list-style-type: none"> • Setpoints changes are disabled. • Executing commands is disabled. • Change of controller mode is disabled. <p>An external remote terminal is any device, which reads and/or writes data from/into the controller and is connected to the controller via any other communication bus than the dedicated terminal RS485 bus.</p> <p>NOTE: An example of such terminal is a PC with IntelliMonitor, any kind of remote display connected via CAN2 or a PLC connected to the RS485 and communicating via MODBUS.</p>

Binary input: PrestartBypass

Related FW	3.0
Description	<p>Use this input to bypass the prestart phase of the start-up procedure and activate the Starter output immediately after start command has been issued.</p> <p>This input is typically used to skip preglowing of the engine when the engine is already warm. A built-in PLC module <i>Comparator with hysteresis</i> attached to the engine temperature value can be used to provide the "engine warm" binary signal, which is then internally configured onto this logical binary input.</p>

Binary input: Startblocking

Related FW	3.0
Description	<p>Engine start is disabled while this input is active. <i>NotReady</i> state is displayed on the controller main screen and the message <i>Start blocking</i> is displayed in the Alarmlist.</p> <p>Use this input to disable temporarily the genset to be started e.g. from an higher-level automation device such as PLC.</p> <p>NOTE: The genset will not be stopped if the input is activated while the genset is running.</p>

Binary input: Sd override

Related FW	3.0
Description	<p>If the input is closed, all 2nd level protections are overridden to allow engine run in an emergency situation, e.g. when the gen-set works as a power supply for fire extinguishing equipment.</p> <p>All protections are displayed in Alarmlist and recorded into history, however the controller leaves the gen-set in operation. If there are any protections still active or not reset in the moment when the input is deactivated, the controller will react to them in a standard way.</p> <p>Following protections are not overridden by this input:</p> <ul style="list-style-type: none"> • Emergency stop • Overspeed • Underspeed (only if Fuel solenoid = GAS ENGINE) • Binary and analog protections configured as <i>Sd override</i> type. In fact this protection type means "Unoverridable shutdown", i.e. it works the same way as standard shutdown protection, however it can not be overridden (blocked) by the Sd override input.

Binary input: GCB disable

Related FW	3.0
Description	The input is used to disable issuing the GCB closing command.

	<ul style="list-style-type: none"> • If the input is active during synchronizing, the controller will keep the genset synchronized without issuing the GCB closing command until the input is deactivated or Sync timeout is elapsed. • If the input is active and the GCB button is pressed in MAN mode to close the GCB to dead bus, the GCB will not be closed until the input is deactivated and the GCB button pressed again. • If the input is active and the GCB is to be closed to dead bus automatically, the GCB will not be closed until the input is deactivated.
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Binary input: GCB fdb neg

Related FW	3.0
Description	This input is used for connection of the normally closed feedback contact from the generator circuit breaker or contactor. This input is optional and if it is configured, it must be always in inverse position to the normally open input GCB feedback . Maximal allowed time the both inputs are in the same position is 500ms, after this time the alarm <i>GCB Fail</i> is issued.

Binary input: MCB fdb neg

Related FW	3.0
Description	This input is used for connection of the normally closed feedback contact from the mains circuit breaker or contactor. This input is optional and if it is configured, it must be always in inverse position to the normally open input MCB feedback . Maximal allowed time the both inputs are in the same position is 500ms, after this time the alarm <i>MCB Fail</i> is issued.

Binary input: Emerg. manual

Related FW	3.0
Description	<p>This input is designed to allow the gen-set to be controlled externally, not by the controller.</p> <p>This feature is especially designed for marine gen-sets, which are supposed to be started manually as the controller has no power supply before the gen-set is started. It may be also useful in case of testing the gen-set or in case of a failure, which does not allow the gen-set to be controlled by the controller, but the gen-set itself is stays operational. This function is also used in case of redundancy to disable redundant controller.</p> <p>The controller behaves following way:</p> <ul style="list-style-type: none"> • Shows the text <i>EmergMan</i> in the engine status on the main screen. • Stops all functions regarding the gen-set control, deactivates all outputs related to it. The complete list of effected logical binary outputs is at the bottom. • <i>Stop Fail</i> alarm is not being evaluated and stop solenoid is not activated if nonzero speed is detected. • Voltage, current, power and other electric measurements are active. • When the input is deactivated, the controller takes control over the gen-set according to the situation in which the gen-set was in the moment of

	<p>deactivation. I.e. the gen-set remains running loaded if it was running and GCB was closed in the moment the input was deactivated.</p> <p>NOTE: For successful recovery from a running state when the input is deactivated it is recommended to use pulse-type control outputs instead of continuous-type. E.g. Stop Solenoid for fuel supply control and GCB ON coil, GCB OFF coil for breaker control.</p> <p>Logical Binary Outputs that are deactivated (directly or indirectly) when <i>Emerg. manual</i> is active:</p> <ul style="list-style-type: none"> Starter Fuel solenoid Prestart Cooling pump CB close/open (GCB and MCB) CB ON coil (GCB and MCB) CB OFF coil (GCB and MCB) CB UV coil (GCB and MCB) Stop solenoid Stop pulse Speed up Speed dn AVR up AVR dn Ignition Ventilation Idle/Nominal Prelubr pump In synchronism ECU PwrRelay Ready for load Stand-by ready Operational Ready Not Ready CranckProcedure Starting Idle run Running ForwardSynchro ReverseSynchro Warming Soft load Loaded Soft unld Cooling Stopping Crancking PeakShaveAct
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Binary input: ManualLdRecon

Related FW	3.0
Description	This input is used for manual reconnection of the last disconnected part of the

	<p>load, if the load has dropped below the setpoint Ld recon level.</p> <p>This input works only if automatic reconnection is disabled, i.e. the setpoint AutoLd recon is set to DISABLED.</p>
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Binary input: FaultResButton

Related FW	3.0
Description	<p>This input is used for an external FAULT RESET button mounted on the switchboard. The function of the input is identical as function of the fault reset button on the controller front panel.</p> <p>The input is enabled only if the setpoint Local Button is set to position EXTBUTTONS or BOTH.</p>

Binary input: HornResButton

Related FW	3.0
Description	<p>This input is used for an external HORN RESET button mounted on the switchboard. The function of the input is identical as function of the horn reset button on the controller front panel.</p> <p>The input is enabled only if the setpoint Local Button is set to position EXTBUTTONS or BOTH.</p>

Binary input: StopButton

Related FW	3.0
Description	<p>This input is used for an external STOP button mounted on the switchboard. The function of the input is identical as function of the stop button on the controller front panel.</p> <p>The input is enabled only if the setpoint Local Button is set to position EXTBUTTONS or BOTH.</p>

Binary input: StartButton

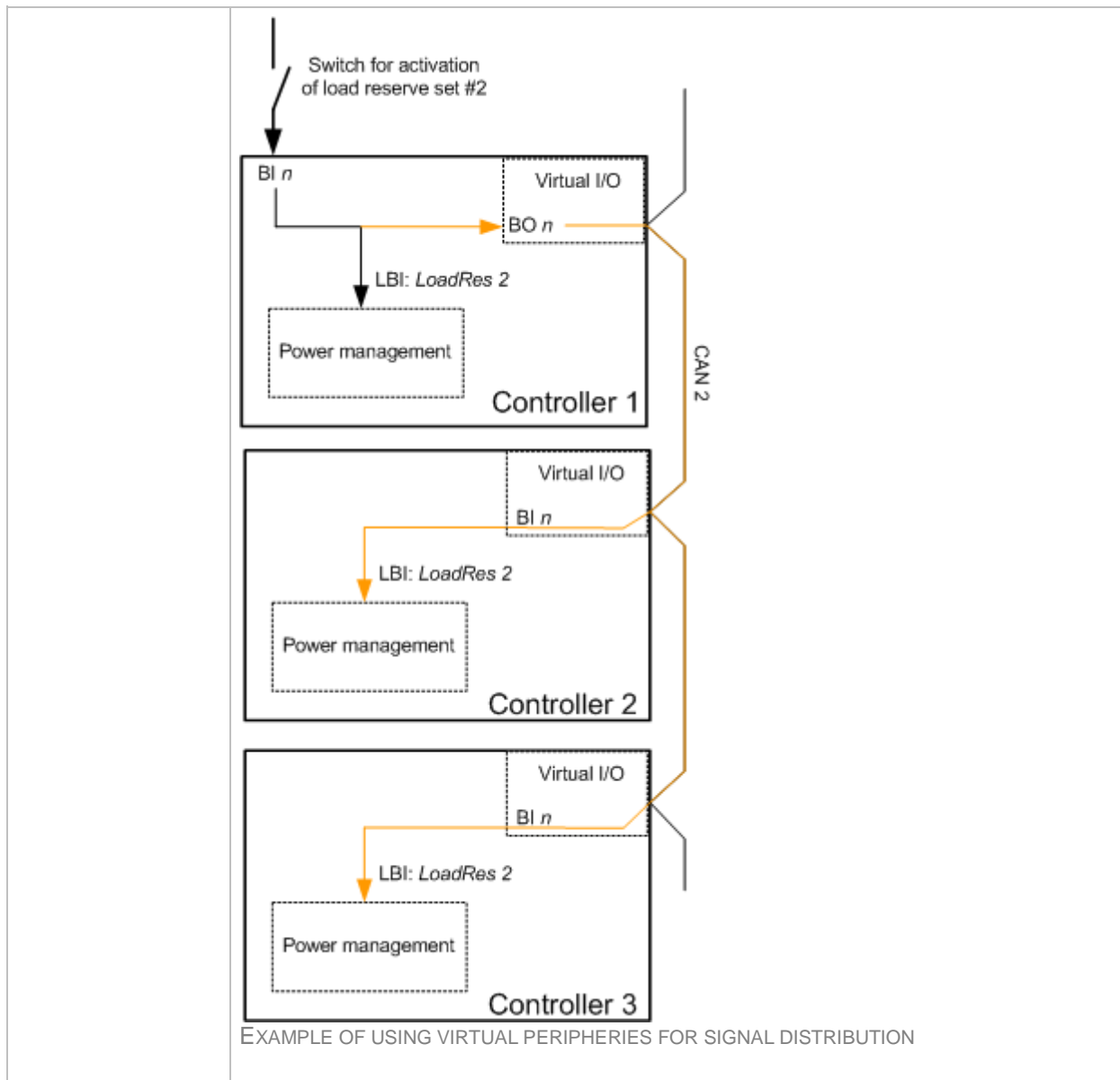
Related FW	3.0
Description	<p>This input is used for an external START button mounted on the switchboard. The function of the input is identical as function of the start button on the controller front panel.</p> <p>The input is enabled only if the setpoint Local Button is set to position EXTBUTTONS or BOTH.</p>

Binary input: GCBButton

Related FW	3.0
Description	<p>This input is used for an external GCB button mounted on the switchboard. The function of the input is identical as function of the GCB button on the controller front panel.</p> <p>The input is enabled only if the setpoint Local Button is set to position EXTBUTTONS or BOTH.</p>

Binary input: Load res 2

Related FW	3.0
Description	<p>This input is used to activate the load reserve set #2 instead of the set #1, which is active by default. The set #2 is adjusted by setpoints:</p> <ul style="list-style-type: none"> • #LoadResStrt 2 and #LoadResStop 2 if the power management is switched to absolute mode • #%LdResStrt 2 and #%LdResStop 2 if the power management is switched to relative mode. <p>CAUTION! All controllers cooperating together in Power management must have the same load reserve set selected.</p> <p>NOTE: It is possible to use <i>virtual peripheries</i> for distribution of the binary signal from one physical switch connected to one controller to all other controllers over the CAN bus.</p>



Binary input: Load res 3

Related FW	3.0
Description	<p>This input is used to activate the load reserve set #3 instead of the set #1, which is active by default. The set #3 is adjusted by setpoints:</p> <ul style="list-style-type: none"> • #LoadResStrt 3 and #LoadResStop 3 if the power management is switched to absolute (kW-based) mode • #%LdResStrt 3 and #%LdResStop 3 if the power management is switched to relative (%Pnom-based) mode. <p>CAUTION! All controllers cooperating together in Power management must have the same load reserve set selected.</p> <p>NOTE: It is possible to use <i>virtual peripheries</i> for distribution of the binary signal from one physical switch connected to one controller to all other controllers over the CAN</p>

	bus. See example in the description of the input Load res 2 .
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Binary input: Load res 4

Related FW	3.0
Description	<p>This input is used to activate the load reserve set #4 instead of the set #1, which is active by default. The set #4 is adjusted by setpoints:</p> <ul style="list-style-type: none"> • #LoadResStrt 4 and #LoadResStop 4 if the power management is switched to absolute (kW-based) mode • #%LdResStrt 4 and #%LdResStop 4 if the power management is switched to relative (%Pnom-based) mode. <p>CAUTION! All controllers cooperating together in Power management must have the same load reserve set selected.</p> <p>NOTE: It is possible to use <i>virtual peripheries</i> for distribution of the binary signal from one physical switch connected to one controller to all other controllers over the CAN bus. See example in the description of the input Load res 2.</p>

Binary input: MinRun power 1

Related FW	3.0
Description	<p>This input is used to activate the function Minimal running power #1, which is adjusted by setpoint #MinRunPower 1.</p> <p>NOTE: The default value of minimal running power, which takes place while none of the inputs <i>MinRun power x</i>, is 0kW.</p> <p>NOTE: If more then one binary input for MinRunPower is activated, the one with the highest number is used (i.e. its corresponding value).</p> <p>CAUTION! All controllers cooperating together in Power management must have the same minimal running power selected.</p> <p>NOTE: It is possible to use <i>virtual peripheries</i> for distribution of the binary signal from one physical switch connected to one controller to all other controllers over the CAN bus. See the principal diagram of such distribution in the description of the input Load res 2.</p>

Binary input: MinRun power 2

Related FW	3.0
Description	This input is used to activate the function Minimal running power #2, which is

	<p>adjusted by setpoint #MinRunPower 2.</p> <p>NOTE: The default value of minimal running power, which takes place while none of the inputs <i>MinRun power x</i>, is 0kW.</p> <p>NOTE: If more then one binary input for MinRunPower is activated, the one with the highest number is used (i.e. its corresponding value).</p> <p>CAUTION! All controllers cooperating together in Power management must have the same minimal running power selected.</p> <p>NOTE: It is possible to use <i>virtual peripheries</i> for distribution of the binary signal from one physical switch connected to one controller to all other controllers over the CAN bus. See the principal diagram of such distribution in the description of the input Load res 2.</p>
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Binary input: MinRun power 3

Related FW	3.0
Description	<p>This input is used to activate the function Minimal running power #3, which is adjusted by setpoint #MinRunPower 3.</p> <p>NOTE: The default value of minimal running power, which takes place while none of the inputs <i>MinRun power x</i>, is 0kW.</p> <p>NOTE: If more then one binary input for MinRunPower is activated, the one with the highest number is used (i.e. its corresponding value).</p> <p>CAUTION! All controllers cooperating together in Power management must have the same minimal running power selected.</p> <p>NOTE: It is possible to use <i>virtual peripheries</i> for distribution of the binary signal from one physical switch connected to one controller to all other controllers over the CAN bus. See the principal diagram of such distribution in the description of the input Load res 2.</p>

Binary input: Priority sw A

Related FW	3.0										
Description	<p>This is one of four inputs Priority sw A, Priority sw B, Priority sw C and Priority sw D that can be used for selection of the power management priority externally. These inputs are optional and if not configured, the priority is then adjusted by the setpoint Priority.</p> <p>ENCODING TABLE</p> <table border="1" style="width: 100%; text-align: center;"> <thead> <tr> <th style="background-color: #cccccc;">PRIORITY</th> <th style="background-color: #cccccc;">INPUT A</th> <th style="background-color: #cccccc;">INPUT B</th> <th style="background-color: #cccccc;">INPUT C</th> <th style="background-color: #cccccc;">INPUT D</th> </tr> </thead> <tbody> <tr> <td style="background-color: #cccccc;"> </td> <td style="background-color: #cccccc;"> </td> <td style="background-color: #cccccc;"> </td> <td style="background-color: #cccccc;"> </td> <td style="background-color: #cccccc;"> </td> </tr> </tbody> </table>	PRIORITY	INPUT A	INPUT B	INPUT C	INPUT D					
PRIORITY	INPUT A	INPUT B	INPUT C	INPUT D							

Default	0	0	0	0
1	1	0	0	0
2	0	1	0	0
3	1	1	0	0
4	0	0	1	0
5	1	0	1	0
6	0	1	1	0
7	1	1	1	0
8	0	0	0	1
9	1	0	0	1
10	0	1	0	1
11	1	1	0	1
12	0	0	1	1
13	1	0	1	1
14	0	1	1	1
15	1	1	1	1

NOTE:
"0" in the table means the input is not active or not configured.

NOTE:
"Default" is the priority adjusted by the setpoint [Priority](#).

Binary input: Priority sw B

Related FW	3.0
Description	This is one of four inputs Priority sw A , Priority sw B , Priority sw C and Priority sw D that can be used for selection of the power management priority externally. These inputs are optional and if not configured, the priority is then adjusted by the setpoint Priority .
NOTE:	See encoding table in the description of the input Priority sw A .

Binary input: Priority sw C

Related FW	3.0
Description	This is one of four inputs Priority sw A , Priority sw B , Priority sw C and Priority sw D that can be used for selection of the power management priority externally. These inputs are optional and if not configured, the priority is then adjusted by the setpoint Priority .
NOTE:	

	See encoding table in the description of the input Priority sw A .
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Binary input: Priority sw D

Related FW	3.0
Description	<p>This is one of four inputs Priority sw A, Priority sw B, Priority sw C and Priority sw D that can be used for selection of the power management priority externally. These inputs are optional and if not configured, the priority is then adjusted by the setpoint Priority.</p> <p>NOTE: See encoding table in the description of the input Priority sw A.</p>

Binary input: ECUComFailBlck

Related FW	3.0
Description	The input disables issuing of the ECU communication failure alarm and all other alarms related to values that are being read from the ECU.

Binary input: GroupLink

Related FW	3.0
Description	<p>This input is used for logical connection and disconnection of the two gen-set groups selected by setpoints GroupLinkLeft and GroupLinkRight. If the input is active, then the two selected groups will perform power management, kW-sharing and kVAr-sharing together as one large group.</p> <p>For linking of one couple of groups use this input only at one controller, e.g. the nearest to the bus tie breaker which physically disconnects the groups, and connect the input to the BTB feedback contact.</p> <p>NOTE: This function is independent on the group which the particular controller belongs to, i.e. the controller can provide linking function e.g. for groups 3,4 although it self belongs to group 2.</p>

Binary input: PulseCounter 1

Related FW	3.0
Description	<p>This is the input of the <i>PulseCounter #1</i> module. The module counts pulses at the input and if the input pulses counter reaches value given by the setpoint ConvCoefPulse1, the counter value PulseCounter 1 (in the group <i>Statistic</i>) is increased by 1 and input pulses counter is reset to 0. Both counter value and input pulses counter are stored in the nonvolatile memory.</p> <p>The <i>PulseCounter</i> modules are intended e.g. for connecting external energy or fuel meters with pulse outputs.</p> <p>NOTE:</p>

	Minimal pulse width as well as minimal pause between two successive pulses is 100ms.
	NOTE: The counter value can be reset in the IntelliMonitor statistics window.

Binary input: PulseCounter 2

Related FW	3.0
Description	<p>This is the input of the <i>PulseCounter #2</i> module. The module counts pulses at the input and if the input pulses counter reaches value given by the setpoint ConvCoefPulse2, the counter value PulseCounter 2 (in the group <i>Statistic</i>) is increased by 1 and input pulses counter is reset to 0. Both counter value and input pulses counter are stored in the nonvolatile memory.</p> <p>The <i>PulseCounter</i> modules are intended e.g. for connecting external energy or fuel meters with pulse outputs.</p> <p>NOTE: Minimal pulse width as well as minimal pause between two successive pulses is 100ms.</p> <p>NOTE: The counter value can be reset in the IntelliMonitor statistics window.</p> <p>NOTE: Available in IS-NT only.</p>

Binary input: PulseCounter 3

Related FW	3.0
Description	<p>This is the input of the <i>PulseCounter #3</i> module. The module counts pulses at the input and if the input pulses counter reaches value given by the setpoint ConvCoefPulse3, the counter value PulseCounter 3 (in the group <i>Statistic</i>) is increased by 1 and input pulses counter is reset to 0. Both counter value and input pulses counter are stored in the nonvolatile memory.</p> <p>The <i>PulseCounter</i> modules are intended e.g. for connecting external energy or fuel meters with pulse outputs.</p> <p>NOTE: Minimal pulse width as well as minimal pause between two successive pulses is 100ms.</p> <p>NOTE: The counter value can be reset in the IntelliMonitor statistics window.</p> <p>NOTE: Available in IS-NT only.</p>

Binary input: PulseCounter 4

Related FW	3.0
Description	<p>This is the input of the <i>PulseCounter #4</i> module. The module counts pulses at the input and if the input pulses counter reaches value given by the setpoint ConvCoefPulse4, the counter value PulseCounter 4 (in the group <i>Statistic</i>) is increased by 1 and input pulses counter is reset to 0. Both counter value and input pulses counter are stored in the nonvolatile memory.</p> <p>The <i>PulseCounter</i> modules are intended e.g. for connecting external energy or fuel meters with pulse outputs.</p> <p>NOTE: Minimal pulse width as well as minimal pause between two successive pulses is 100ms.</p> <p>NOTE: The counter value can be reset in the IntelliMonitor statistics window.</p> <p>NOTE: Available in IS-NT only.</p>

Binary input: Timer block 1

Related FW	3.0
Description	<p>This input is used to disable temporarily the output from the <i>Timer channel #1</i>.</p> <p>NOTE: See also the setpoint TimerChannel 1 and output TimerAct 1-4.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Binary input: Timer block 2

Related FW	3.0
Description	<p>This input is used to disable temporarily the output from the <i>Timer channel #2</i>.</p> <p>NOTE: See also the setpoint TimerChannel 2 and output TimerAct 1-4.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Binary input: Timer block 3

Related FW	3.0
Description	<p>This input is used to disable temporarily the output from the <i>Timer channel #3</i>.</p> <p>NOTE: See also the setpoint TimerChannel 3 and output TimerAct 1-4.</p>

	<p>NOTE: See the chapter Timers for more details about timers.</p>
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Binary input: Timer block 4

Related FW	3.0
Description	<p>This input is used to disable temporarily the output from the <i>Timer channel #4</i>.</p> <p>NOTE: See also the setpoint TimerChannel 4 and output TimerAct 1-4.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Binary input: Timer block 5

Related FW	3.0
Description	<p>This input is used to disable temporarily the output from the <i>Timer channel #5</i>.</p> <p>NOTE: See also the setpoint TimerChannel 5 and output TimerAct 5-8.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Binary input: Timer block 6

Related FW	3.0
Description	<p>This input is used to disable temporarily the output from the <i>Timer channel #6</i>.</p> <p>NOTE: See also the setpoint TimerChannel 6 and output TimerAct 5-8.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Binary input: Timer block 7

Related FW	3.0
Description	<p>This input is used to disable temporarily the output from the <i>Timer channel #7</i>.</p> <p>NOTE: See also the setpoint TimerChannel 7 and output TimerAct 5-8.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Binary input: Timer block 8

Related FW	3.0
Description	<p>This input is used to disable temporarily the output from the <i>Timer channel #8</i>.</p> <p>NOTE: See also the setpoint TimerChannel 8 and output TimerAct 5-8.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Binary input: Timer block 9

Related FW	3.0
Description	<p>This input is used to disable temporarily the output from the <i>Timer channel #9</i>.</p> <p>NOTE: See also the setpoint TimerChannel 9 and output TimerAct 9-12.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Binary input: Timer block 10

Related FW	3.0
Description	<p>This input is used to disable temporarily the output from the <i>Timer channel #10</i>.</p> <p>NOTE: See also the setpoint TimerChannel 10 and output TimerAct 9-12.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Binary input: Timer block 11

Related FW	3.0
Description	<p>This input is used to disable temporarily the output from the <i>Timer channel #11</i>.</p> <p>NOTE: See also the setpoint TimerChannel 11 and output TimerAct 9-12.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Binary input: Timer block 12

Related FW	3.0
Description	<p>This input is used to disable temporarily the output from the <i>Timer channel #12</i>.</p>

	<p>NOTE: See also the setpoint TimerChannel 12 and output TimerAct 9-12.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>
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Binary input: Timer block 13

Related FW	3.0
Description	<p>This input is used to disable temporarily the output from the <i>Timer channel #13</i>.</p> <p>NOTE: See also the setpoint TimerChannel 13 and output TimerAct 13-16.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Binary input: Timer block 14

Related FW	3.0
Description	<p>This input is used to disable temporarily the output from the <i>Timer channel #14</i>.</p> <p>NOTE: See also the setpoint TimerChannel 14 and output TimerAct 13-16.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Binary input: Timer block 15

Related FW	3.0
Description	<p>This input is used to disable temporarily the output from the <i>Timer channel #15</i>.</p> <p>NOTE: See also the setpoint TimerChannel 15 and output TimerAct 13-16.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Binary input: Timer block 16

Related FW	3.0
Description	<p>This input is used to disable temporarily the output from the <i>Timer channel #16</i>.</p> <p>NOTE: See also the setpoint TimerChannel 16 and output TimerAct 13-16.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

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Binary input: ExtValue1 up

Related FW	3.0
Description	<p>For IS-NT only.</p> <p>While this input is active the value of <i>ExtValue 1</i> is contiously beeing increased at the rate of ExtValue1 rate until it reaches ExtValue1HiLim.</p> <p>NOTE: If this input is used (configured), the <i>ExtValue 1</i> can't be written remotely from a remote terminal using the command <i>ExtValue 1</i>.</p>

Binary input: ExtValue1 down

Related FW	3.0
Description	<p>IS-NT specific function</p> <p>While this input is active the value of <i>ExtValue 1</i> is contiously beeing decreased at the rate of ExtValue1 rate until it reaches ExtValue1LoLim.</p> <p>NOTE: If this input is used (configured), the <i>ExtValue 1</i> can't be written remotely from a remote terminal using the command <i>ExtValue 1</i>.</p>

Binary input: ExtValue2 up

Related FW	3.0
Description	<p>For IS-NT only.</p> <p>While this input is active the value of <i>ExtValue 2</i> is contiously beeing increased at the rate of ExtValue2 rate until it reaches ExtValue2HiLim.</p> <p>NOTE: If this input is used (configured), the <i>ExtValue 2</i> can't be written remotely from a remote terminal using the command <i>ExtValue 2</i>.</p>

Binary input: ExtValue2 down

Related FW	3.0
Description	<p>IS-NT specific function</p> <p>While this input is active the value of <i>ExtValue 2</i> is contiously beeing decreased at the rate of ExtValue2 rate until it reaches ExtValue2LoLim.</p> <p>NOTE: If this input is used (configured), the <i>ExtValue 2</i> can't be written remotely from a remote terminal using the command <i>ExtValue 2</i>.</p>

Binary input: ExtValue3 up

Related FW	3.0
Description	<p>For IS-NT only.</p> <p>While this input is active the value of <i>ExtValue 3</i> is continuously being increased at the rate of ExtValue3 rate until it reaches ExtValue3HiLim.</p> <p>NOTE: If this input is used (configured), the <i>ExtValue 3</i> can't be written remotely from a remote terminal using the command <i>ExtValue 3</i>.</p>

Binary input: ExtValue3 down

Related FW	3.0
Description	<p>IS-NT specific function</p> <p>While this input is active the value of <i>ExtValue 3</i> is continuously being decreased at the rate of ExtValue3 rate until it reaches ExtValue3LoLim.</p> <p>NOTE: If this input is used (configured), the <i>ExtValue 3</i> can't be written remotely from a remote terminal using the command <i>ExtValue 3</i>.</p>

Binary input: ExtValue4 up

Related FW	3.0
Description	<p>For IS-NT only.</p> <p>While this input is active the value of <i>ExtValue 4</i> is continuously being increased at the rate of ExtValue4 rate until it reaches ExtValue4HiLim.</p> <p>NOTE: If this input is used (configured), the <i>ExtValue 4</i> can't be written remotely from a remote terminal using the command <i>ExtValue 4</i>.</p>

Binary input: ExtValue4 down

Related FW	3.0
Description	<p>IS-NT specific function</p> <p>While this input is active the value of <i>ExtValue 4</i> is continuously being decreased at the rate of ExtValue4 rate until it reaches ExtValue4LoLim.</p> <p>NOTE: If this input is used (configured), the <i>ExtValue 4</i> can't be written remotely from a remote terminal using the command <i>ExtValue 4</i>.</p>

Binary input: ExtValue1reset

Related FW	3.0
Description	<p>The <i>ExtValue 1</i> is reset to it's default value when this input is activated and held there until the input is deactivated. The default value is given by the setpoint ExtValue1defft.</p> <p>While the reset input is active:</p> <ul style="list-style-type: none"> • The value does not respond to up and down inputs. • The value does not accept new data that are written remotely from a remote terminal using the <i>ExtValue</i> command. <p>NOTE: Configuring of the reset input does not block writing the ExtValue remotely, in comparison to the up and down inputs, which does. However, if the reset input is active, the remotely written data are not accepted.</p>

Binary input: ExtValue2reset

Related FW	3.0
Description	<p>The <i>ExtValue 2</i> is reset to it's default value when this input is activated and held there until the input is deactivated. The default value is given by the setpoint ExtValue2defft.</p> <p>While the reset input is active:</p> <ul style="list-style-type: none"> • The value does not respond to up and down inputs. • The value does not accept new data that are written remotely from a remote terminal using the <i>ExtValue</i> command. <p>NOTE: Configuring of the reset input does not block writing the ExtValue remotely, in comparison to the up and down inputs, which does. However, if the reset input is active, the remotely written data are not accepted.</p>

Binary input: ExtValue3reset

Related FW	3.0
Description	<p>The <i>ExtValue 3</i> is reset to it's default value when this input is activated and held there until the input is deactivated. The default value is given by the setpoint ExtValue3defft.</p> <p>While the reset input is active:</p> <ul style="list-style-type: none"> • The value does not respond to up and down inputs. • The value does not accept new data that are written remotely from a remote terminal using the <i>ExtValue</i> command. <p>NOTE: Configuring of the reset input does not block writing the ExtValue remotely, in comparison to the up and down inputs, which does. However, if the reset input is active, the remotely written data are not accepted.</p>

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Binary input: ExtValue4reset

Related FW	3.0
Description	<p>The <i>ExtValue 4</i> is reset to it's default value when this input is activated and held there until the input is deactivated. The default value is given by the setpoint ExtValue4deflt.</p> <p>While the reset input is active:</p> <ul style="list-style-type: none"> • The value does not respond to up and down inputs. • The value does not accept new data that are written remotely from a remote terminal using the <i>ExtValue</i> command. <p>NOTE: Configuring of the reset input does not block writing the ExtValue remotely, in comparison to the up and down inputs, which does. However, if the reset input is active, the remotely written data are not accepted.</p>

Binary input: RunIndication 1

Related FW	3.0
Description	<p>This input is one of three inputs used for indication, that the engine is running, and has following functions:</p> <ul style="list-style-type: none"> • If the input is active when the engine is expected to be stopped, then the <i>Stop fail</i> alarm is issued and start is blocked. • If the input becomes active while cranking, the engine is considered as started and the start-up procedure continues to the next phase (idle). <p>NOTE: Learn more in the separate chapter Starting sequence.</p>

Binary input: RunIndication 2

Related FW	3.0
Description	<p>This input is one of three inputs used for indication, that the engine is running, and has following functions:</p> <ul style="list-style-type: none"> • If the input is active when the engine is expected to be stopped, then the <i>Stop fail</i> alarm is issued and start is blocked. • If the input becomes active while cranking, the engine is considered as started and the start-up procedure continues to the next phase (idle). <p>NOTE: Learn more in the separate chapter Starting sequence.</p>

Binary input: RunIndication 3

Related FW	3.0
Description	<p>This input is one of three inputs used for indication, that the engine is running, and has following functions:</p> <ul style="list-style-type: none"> • If the input is active when the engine is expected to be stopped, then the <i>Stop fail</i> alarm is issued and start is blocked. • If the input becomes active while cranking, the engine is considered as started and the start-up procedure continues to the next phase (idle). <p>NOTE: Learn more in the separate chapter Starting sequence.</p>

Binary input: IssueActCallC1

Related FW	3.0
Description	<p>This input forces the controller to issue an active call/e-mail/SMS via the channel #1. Type of the channel is to be adjusted by the setpoint AcallCH1-Type.</p> <p>This input can be used to inform a remote user about a specific non-alarm situation, e.g. mains failure and/or mains return:</p> <ol style="list-style-type: none"> 1. Select a binary signal in the controller, which indicates, that the particular situation occurred, about which you want to be informed remotely. There are many predefined binary informations provided directly by the controller or use PLC functions to create the desired binary signal. 2. Configure an universal protection block to the binary signal mentioned above and select protection type <i>AL indication</i>. 3. Configure the binary signal mentioned above onto the logical binary input <i>IssueActCallC1</i>.

Binary input: IssueActCallC2

Related FW	3.0
Description	<p>This input forces the controller to issue an active call/e-mail/SMS via the channel #2. Type of the channel is to be adjusted by the setpoint AcallCH2-Type.</p> <p>This input can be used to inform a remote user about a specific non-alarm situation, e.g. mains failure and/or mains return:</p> <ol style="list-style-type: none"> 1. Select a binary signal in the controller, which indicates, that the particular situation occurred, about which you want to be informed remotely. There are many predefined binary informations provided directly by the controller or use PLC functions to create the desired binary signal. 2. Configure an universal protection block to the binary signal mentioned above and select protection type <i>AL indication</i>. 3. Configure the binary signal mentioned above onto the logical binary input <i>IssueActCallC2</i>.

Binary input: IssueActCallC3

Related FW	3.0
Description	<p>This input forces the controller to issue an active call/e-mail/SMS via the channel #3. Type of the channel is to be adjusted by the setpoint AcallCH3-Type.</p> <p>This input can be used to inform a remote user about a specific non-alarm situation, e.g. mains failure and/or mains return:</p> <ol style="list-style-type: none"> 1. Select a binary signal in the controller, which indicates, that the particular situation occurred, about which you want to be informed remotely. There are many predefined binary informations provided directly by the controller or use PLC functions to create the desired binary signal. 2. Configure an universal protection block to the binary signal mentioned above and select protection type <i>AL indication</i>. 3. Configure the binary signal mentioned above onto the logical binary input <i>IssueActCallC3</i>.

Binary input: IssueActCallC4

Related FW	3.0
Description	<p>This input forces the controller to issue an active call/e-mail/SMS via the channel #4. Type of the channel is to be adjusted by the setpoint AcallCH4-Type.</p> <p>This input can be used to inform a remote user about a specific non-alarm situation, e.g. mains failure and/or mains return:</p> <ol style="list-style-type: none"> 1. Select a binary signal in the controller, which indicates, that the particular situation occurred, about which you want to be informed remotely. There are many predefined binary informations provided directly by the controller or use PLC functions to create the desired binary signal. 2. Configure an universal protection block to the binary signal mentioned above and select protection type <i>AL indication</i>. 3. Configure the binary signal mentioned above onto the logical binary input <i>IssueActCallC4</i>.

Binary input: IssueActCallC5

Related FW	3.0
Description	<p>This input forces the controller to issue an active call/e-mail/SMS via the channel #5. Type of the channel is to be adjusted by the setpoint AcallCH4-Addr.</p> <p>This input can be used to inform a remote user about a specific non-alarm situation, e.g. mains failure and/or mains return:</p> <ol style="list-style-type: none"> 1. Select a binary signal in the controller, which indicates, that the particular situation occurred, about which you want to be informed remotely. There are many predefined binary informations provided directly by the controller or use PLC functions to create the desired binary signal. 2. Configure an universal protection block to the binary signal mentioned above and select protection type <i>AL indication</i>. 3. Configure the binary signal mentioned above onto the logical binary input

	<i>IssueActCallC5.</i>
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Binary input: AccessLock D#2

Related FW	3.0
Description	<p>This input forces the external local terminal or IntelliVision (display) #2 into monitoring mode.</p> <p>NOTE: Local display means that it is connected to dedicated RS485. There is possibility to connect up to 2 external displays in IG-NT-BB or 1 in IG-NT. It is possible to connect up to 3 external displays in IS-NT-BB and in IS-NT.</p> <ul style="list-style-type: none"> • Setpoints changes are disabled. • Using control buttons on the panel is disabled even if the controller is in MAN mode. • Change of controller mode is disabled.

Binary input: AccessLock D#3

Related FW	3.0
Description	<p>NOTE: For IS-NT and IS-NT-BB only.</p> <p>This input forces the external local terminal or IntelliVision (display) #3 into monitoring mode.</p> <p>NOTE: Local display means that it is connected to dedicated RS485. There is possibility to connect up to 2 external displays in IG-NT-BB or 1 in IG-NT. It is possible to connect up to 3 external displays in IS-NT-BB and in IS-NT.</p> <ul style="list-style-type: none"> • Setpoints changes are disabled. • Using control buttons on the panel is disabled even if the controller is in MAN mode. • Change of controller mode is disabled.

Binary input: NeutralCB fdb

Related FW	3.0
Description	<p>This input is used for connection of the normally open feedback contact from the Neutral contactor. If the input is active, the controller will consider the neutral contactor as closed and vice versa. See also description of the setpoint #Neutral cont.</p>

Binary input: CylDifEvalBlk

Related FW	3.0
Description	<p>This input is used to disable temporarily evaluation of the alarms caused by cylinder temperatures deviations.</p> <p>NOTE: For IS-NT only.</p>

Binary input: ECU StoppedEng

Related FW	3.0
Description	<p>When this input is activated, the genset will be stopped immediately without unloading and cooling phase, however no alarm will be issued.</p> <p>This input is intended for situations, where the genset is controlled by an ECU or other device which also includes engine protections and can stop the engine itself. In such case the controller would issue an <i>Underspeed</i> alarm. Connecting this input to an appropriate ECU output, which provides information, that the engine has been stopped by the ECU, prevents the controller from issuing the underspeed alarm.</p>

Binary input: CtrlHBeat sens

Related FW	3.0
Description	<p>This input is used at a redundant controller to sense the "heart beat" from the main controller. The input is to be connected to the output CtrlHeartBeat of the main controller.</p> <p>If the redundant controller does not sense the heart beat from the main one, it will activate the binary output CtrlHBeat FD, which has to be wired such a way, that it disconnects the dead main controller from the genset, connects the redundant controller instead and activates it.</p> <p>NOTE: Learn more about redundancy in separate chapter Redundant controllers.</p>

Binary input: Nominal speed

Related FW	3.0
Description	<p>Use this input to bypass the idle phase of the start-up procedure.</p> <p>NOTE: The input is especially designed for shortening of the start-up procedure when the gen-set is starting to an AMF operation.</p>

Binary input: ForceValueIn 1

Related FW	3.0
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Description

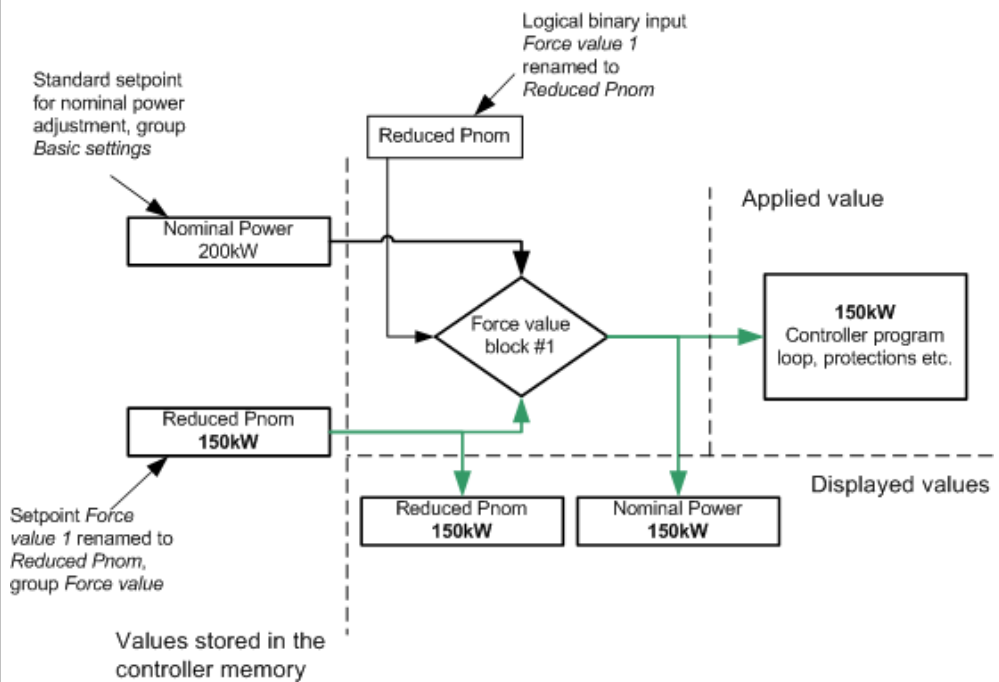
This input activates the *Force value #1* block. If the input is active, the value of the setpoint, to which the *Force value #1* block is configured, will be overridden by value of the alternative setpoint assigned to the *Force value #1* block.

NOTE:

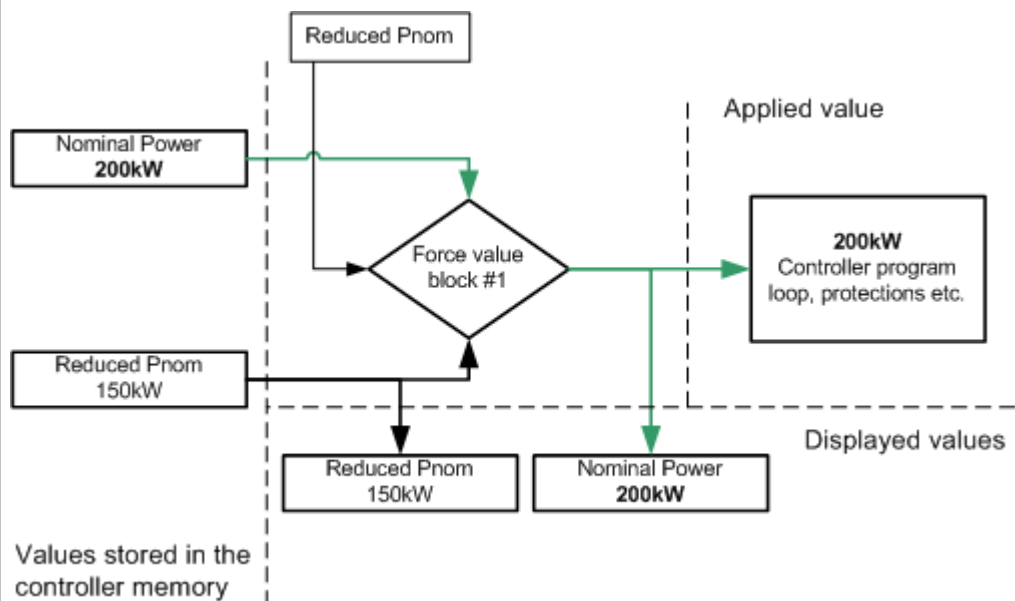
If there are more than one force value blocks configured onto one setpoint then the highest priority has the block with the lowest index (i.e. the first active block according to the list displayed in GenConfig in the **Force value** window at the related setpoint).

NOTE:

Watch a training video about force value function here:
<http://www.comap.cz/support/training/training-videos/>.



EXAMPLE OF AN ACTIVE FORCE VALUE BLOCK



EXAMPLE OF AN INACTIVE FORCE VALUE BLOCK

Binary input: ForceValueIn 2

Related FW	3.0
Description	<p>This input activates the <i>Force value #2</i> block. If the input is active, the value of the setpoint, to which the Force value #2 block is configured, will be overridden by value of the alternative setpoint assigned to the Force value #2 block.</p> <p>NOTE: If there are more than one force value blocks configured onto one setpoint then the highest priority has the block with the lowest index (i.e. the first active block according to the list displayed in GenConfig in the Force value window at the related setpoint).</p> <p>NOTE: Watch a training video about force value function here: http://www.comap.cz/support/training/training-videos/.</p> <p>NOTE: See an example in the description of the binary input Force value 1.</p>

Binary input: ForceValueIn 3

Related FW	3.0
Description	<p>This input activates the <i>Force value #3</i> block. If the input is active, the value of the setpoint, to which the Force value #3 block is configured, will be overridden by value of the alternative setpoint assigned to the Force value #3 block.</p> <p>NOTE: If there are more than one force value blocks configured onto one setpoint then the highest priority has the block with the lowest index (i.e. the first active block according to the list displayed in GenConfig in the Force value window at the related setpoint).</p> <p>NOTE: Watch a training video about force value function here: http://www.comap.cz/support/training/training-videos/.</p> <p>NOTE: See an example in the description of the binary input Force value 1.</p>

Binary input: ForceValueIn 4

Related FW	3.0
Description	<p>This input activates the <i>Force value #4</i> block. If the input is active, the value of the setpoint, to which the Force value #4 block is configured, will be overridden by value of the alternative setpoint assigned to the Force value #4 block.</p> <p>NOTE: If there are more than one force value blocks configured onto one setpoint then the highest priority has the block with the lowest index (i.e. the first active block according to the list displayed in GenConfig in the Force value window at the related setpoint).</p>

	<p>NOTE: Watch a training video about force value function here: http://www.comap.cz/support/training/training-videos/.</p> <p>NOTE: See an example in the description of the binary input Force value 1.</p>
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Binary input: ForceValueIn 5

Related FW	3.0
Description	<p>This input activates the <i>Force value #5</i> block. If the input is active, the value of the setpoint, to which the Force value #5 block is configured, will be overridden by value of the alternative setpoint assigned to the Force value #5 block.</p> <p>NOTE: If there are more than one force value blocks configured onto one setpoint then the highest priority has the block with the lowest index (i.e. the first active block according to the list displayed in GenConfig in the Force value window at the related setpoint).</p> <p>NOTE: Watch a training video about force value function here: http://www.comap.cz/support/training/training-videos/.</p> <p>NOTE: See an example in the description of the binary input Force value 1.</p>

Binary input: ForceValueIn 6

Related FW	3.0
Description	<p>This input activates the <i>Force value #6</i> block. If the input is active, the value of the setpoint, to which the Force value #6 block is configured, will be overridden by value of the alternative setpoint assigned to the Force value #6 block.</p> <p>NOTE: If there are more than one force value blocks configured onto one setpoint then the highest priority has the block with the lowest index (i.e. the first active block according to the list displayed in GenConfig in the Force value window at the related setpoint).</p> <p>NOTE: Watch a training video about force value function here: http://www.comap.cz/support/training/training-videos/.</p> <p>NOTE: See an example in the description of the binary input Force value 1.</p>

Binary input: ForceValueIn 7

Related FW	3.0
Description	This input activates the <i>Force value #7</i> block. If the input is active, the value of the

	<p>setpoint, to which the Force value #7 block is configured, will be overridden by value of the alternative setpoint assigned to the Force value #7 block.</p> <p>NOTE: If there are more than one force value blocks configured onto one setpoint then the highest priority has the block with the lowest index (i.e. the first active block according to the list displayed in GenConfig in the Force value window at the related setpoint).</p> <p>NOTE: Watch a training video about force value function here: http://www.comap.cz/support/training/training-videos/.</p> <p>NOTE: See an example in the description of the binary input Force value 1.</p>
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Binary input: ForceValueIn 8

Related FW	3.0
Description	<p>This input activates the <i>Force value #8</i> block. If the input is active, the value of the setpoint, to which the Force value #8 block is configured, will be overridden by value of the alternative setpoint assigned to the Force value #8 block.</p> <p>NOTE: If there are more than one force value blocks configured onto one setpoint then the highest priority has the block with the lowest index (i.e. the first active block according to the list displayed in GenConfig in the Force value window at the related setpoint).</p> <p>NOTE: Watch a training video about force value function here: http://www.comap.cz/support/training/training-videos/.</p> <p>NOTE: See an example in the description of the binary input Force value 1.</p>

Binary input: ForceValueIn 9

Related FW	3.0
Description	<p>This input activates the <i>Force value #9</i> block. If the input is active, the value of the setpoint, to which the Force value #9 block is configured, will be overridden by value of the alternative setpoint assigned to the Force value #9 block.</p> <p>NOTE: If there are more than one force value blocks configured onto one setpoint then the highest priority has the block with the lowest index (i.e. the first active block according to the list displayed in GenConfig in the Force value window at the related setpoint).</p> <p>NOTE: Watch a training video about force value function here: http://www.comap.cz/support/training/training-videos/.</p> <p>NOTE:</p>

	See an example in the description of the binary input Force value 1 .
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Binary input: ForceValueIn10

Related FW	3.0
Description	<p>This input activates the <i>Force value #10</i> block. If the input is active, the value of the setpoint, to which the Force value #10 block is configured, will be overridden by value of the alternative setpoint assigned to the Force value #10 block.</p> <p>NOTE: If there are more than one force value blocks configured onto one setpoint then the highest priority has the block with the lowest index (i.e. the first active block according to the list displayed in GenConfig in the Force value window at the related setpoint).</p> <p>NOTE: Watch a training video about force value function here: http://www.comap.cz/support/training/training-videos/.</p> <p>NOTE: See an example in the description of the binary input Force value 1.</p>

Binary input: ForceValueIn11

Related FW	3.0
Description	<p>This input activates the <i>Force value #11</i> block. If the input is active, the value of the setpoint, to which the Force value #11 block is configured, will be overridden by value of the alternative setpoint assigned to the Force value #11 block.</p> <p>NOTE: If there are more than one force value blocks configured onto one setpoint then the highest priority has the block with the lowest index (i.e. the first active block according to the list displayed in GenConfig in the Force value window at the related setpoint).</p> <p>NOTE: Watch a training video about force value function here: http://www.comap.cz/support/training/training-videos/.</p> <p>NOTE: See an example in the description of the binary input Force value 1.</p>

Binary input: ForceValueIn12

Related FW	3.0
Description	<p>This input activates the <i>Force value #12</i> block. If the input is active, the value of the setpoint, to which the Force value #12 block is configured, will be overridden by value of the alternative setpoint assigned to the Force value #12 block.</p> <p>NOTE: If there are more than one force value blocks configured onto one setpoint then the highest priority has the block with the lowest index (i.e. the first active block</p>

	<p>according to the list displayed in GenConfig in the Force value window at the related setpoint).</p> <p>NOTE: Watch a training video about force value function here: http://www.comap.cz/support/training/training-videos/.</p> <p>NOTE: See an example in the description of the binary input Force value 1.</p>
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Binary input: ForceValueIn13

Related FW	3.0
Description	<p>This input activates the <i>Force value #13</i> block. If the input is active, the value of the setpoint, to which the Force value #13 block is configured, will be overridden by value of the alternative setpoint assigned to the Force value #13 block.</p> <p>NOTE: If there are more than one force value blocks configured onto one setpoint then the highest priority has the block with the lowest index (i.e. the first active block according to the list displayed in GenConfig in the Force value window at the related setpoint).</p> <p>NOTE: Watch a training video about force value function here: http://www.comap.cz/support/training/training-videos/.</p> <p>NOTE: See an example in the description of the binary input Force value 1.</p>

Binary input: ForceValueIn14

Related FW	3.0
Description	<p>This input activates the <i>Force value #14</i> block. If the input is active, the value of the setpoint, to which the Force value #14 block is configured, will be overridden by value of the alternative setpoint assigned to the Force value #14 block.</p> <p>NOTE: If there are more than one force value blocks configured onto one setpoint then the highest priority has the block with the lowest index (i.e. the first active block according to the list displayed in GenConfig in the Force value window at the related setpoint).</p> <p>NOTE: Watch a training video about force value function here: http://www.comap.cz/support/training/training-videos/.</p> <p>NOTE: See an example in the description of the binary input Force value 1.</p>

Binary input: ForceValueIn15

Related FW	3.0
Description	<p>This input activates the <i>Force value #15</i> block. If the input is active, the value of the setpoint, to which the Force value #15 block is configured, will be overridden by value of the alternative setpoint assigned to the Force value #15 block.</p> <p>NOTE: If there are more than one force value blocks configured onto one setpoint then the highest priority has the block with the lowest index (i.e. the first active block according to the list displayed in GenConfig in the Force value window at the related setpoint).</p> <p>NOTE: Watch a training video about force value function here: http://www.comap.cz/support/training/training-videos/.</p> <p>NOTE: See an example in the description of the binary input Force value 1.</p>

Binary input: ForceValueIn16

Related FW	3.0
Description	<p>This input activates the <i>Force value #16</i> block. If the input is active, the value of the setpoint, to which the Force value #16 block is configured, will be overridden by value of the alternative setpoint assigned to the Force value #16 block.</p> <p>NOTE: If there are more than one force value blocks configured onto one setpoint then the highest priority has the block with the lowest index (i.e. the first active block according to the list displayed in GenConfig in the Force value window at the related setpoint).</p> <p>NOTE: Watch a training video about force value function here: http://www.comap.cz/support/training/training-videos/.</p> <p>NOTE: See an example in the description of the binary input Force value 1.</p>

Binary input: Force block 1

Related FW	3.0
Description	<p>This is one of three binary inputs used for user-defined blocking of protections. If the input is active, all the protections that have <i>Protection block type</i> configured as <i>Force block 1</i> block type are blocked (i.e. temporarily disabled).</p>

Binary input: Force block 2

Related FW	3.0
Description	<p>This is one of three binary inputs used for user-defined blocking of protections. If the input is active, all the protections that have <i>Protection block type</i> configured as</p>

	<i>Force block 2</i> block type are blocked (i.e. temporarily disabled).
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Binary input: Force block 3

Related FW	3.0
Description	This is one of three binary inputs used for user-defined blocking of protections. If the input is active, all the protections that have <i>Protection block type</i> configured as <i>Force block 3</i> block type are blocked (i.e. temporarily disabled).

Binary input: Lang sel int A

Related FW	3.0																																				
Description	<p>This is one of three binary inputs Lang sel int A, Lang sel int B, Lang sel int C, used for selecting language of the built-in IG-NT terminal (display). As the IS-NT does not have built-in terminal, this input is assigned to the terminal (display) #1, which is supposed to be directly attached to the controller or mounted close to it.</p> <p>NOTE: Using these inputs for language selection is an option only. If the inputs are not configured, the language can be selected using the menus on the terminal.</p> <p>ENCODING TABLE</p> <table border="1"> <thead> <tr> <th>LANGUAGE INDEX</th> <th>INPUT A</th> <th>INPUT B</th> <th>INPUT C</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>0</td> <td>0</td> </tr> <tr> <td>1</td> <td>1</td> <td>0</td> <td>0</td> </tr> <tr> <td>2</td> <td>0</td> <td>1</td> <td>0</td> </tr> <tr> <td>3</td> <td>1</td> <td>1</td> <td>0</td> </tr> <tr> <td>4</td> <td>0</td> <td>0</td> <td>1</td> </tr> <tr> <td>5</td> <td>1</td> <td>0</td> <td>1</td> </tr> <tr> <td>6</td> <td>0</td> <td>1</td> <td>1</td> </tr> <tr> <td>7</td> <td>1</td> <td>1</td> <td>1</td> </tr> </tbody> </table> <p>NOTE: "0" in the table means the input is not active or not configured.</p> <p>NOTE: Language index 0 selects the default language of the terminal, i.e. the language, which is adjusted in the terminal using it's menus.</p> <p>NOTE: The reaction on changes of these inputs is delayed about 1 sec to ensure the new combination is valid (e.g. if a rotary selector switch is used).</p> <p>CAUTION! Each language change causes the reinitialization of the display. Function of the controller is not influenced.</p>	LANGUAGE INDEX	INPUT A	INPUT B	INPUT C	0	0	0	0	1	1	0	0	2	0	1	0	3	1	1	0	4	0	0	1	5	1	0	1	6	0	1	1	7	1	1	1
LANGUAGE INDEX	INPUT A	INPUT B	INPUT C																																		
0	0	0	0																																		
1	1	0	0																																		
2	0	1	0																																		
3	1	1	0																																		
4	0	0	1																																		
5	1	0	1																																		
6	0	1	1																																		
7	1	1	1																																		

Binary input: Lang sel int B

Related FW	3.0																																				
Description	<p>This is one of three binary inputs Lang sel int A, Lang sel int B, Lang sel int C, used for selecting language of the built-in IG-NT terminal (display). As the IS-NT does not have built-in terminal, this input is assigned to the terminal (display) #1, which is supposed to be directly attached to the controller or mounted close to it.</p> <p>NOTE: Using these inputs for language selection is an option only. If the inputs are not configured, the language can be selected using the menus on the terminal.</p> <p>ENCODING TABLE</p> <table border="1"> <thead> <tr> <th>LANGUAGE INDEX</th> <th>INPUT A</th> <th>INPUT B</th> <th>INPUT C</th> </tr> </thead> <tbody> <tr><td>0</td><td>0</td><td>0</td><td>0</td></tr> <tr><td>1</td><td>1</td><td>0</td><td>0</td></tr> <tr><td>2</td><td>0</td><td>1</td><td>0</td></tr> <tr><td>3</td><td>1</td><td>1</td><td>0</td></tr> <tr><td>4</td><td>0</td><td>0</td><td>1</td></tr> <tr><td>5</td><td>1</td><td>0</td><td>1</td></tr> <tr><td>6</td><td>0</td><td>1</td><td>1</td></tr> <tr><td>7</td><td>1</td><td>1</td><td>1</td></tr> </tbody> </table> <p>NOTE: "0" in the table means the input is not active or not configured.</p> <p>NOTE: Language index 0 selects the default language of the terminal, i.e. the language, which is adjusted in the terminal using it's menus.</p> <p>NOTE: The reaction on changes of these inputs is delayed about 1 sec to ensure the new combination is valid (e.g. if a rotary selector switch is used).</p> <p>CAUTION! Each language change causes the reinitialization of the display. Function of the controller is not influenced.</p>	LANGUAGE INDEX	INPUT A	INPUT B	INPUT C	0	0	0	0	1	1	0	0	2	0	1	0	3	1	1	0	4	0	0	1	5	1	0	1	6	0	1	1	7	1	1	1
LANGUAGE INDEX	INPUT A	INPUT B	INPUT C																																		
0	0	0	0																																		
1	1	0	0																																		
2	0	1	0																																		
3	1	1	0																																		
4	0	0	1																																		
5	1	0	1																																		
6	0	1	1																																		
7	1	1	1																																		

Binary input: Lang sel int C

Related FW	3.0
Description	<p>This is one of three binary inputs Lang sel int A, Lang sel int B, Lang sel int C, used for selecting language of the built-in IG-NT terminal (display). As the IS-NT does not have built-in terminal, this input is assigned to the terminal (display) #1, which is supposed to be directly attached to the controller or mounted close to it.</p> <p>NOTE: Using these inputs for language selection is an option only. If the inputs are not configured, the language can be selected using the menus on the terminal.</p> <p>ENCODING TABLE</p>

LANGUAGE INDEX	INPUT A	INPUT B	INPUT C
0	0	0	0
1	1	0	0
2	0	1	0
3	1	1	0
4	0	0	1
5	1	0	1
6	0	1	1
7	1	1	1

NOTE:
"0" in the table means the input is not active or not configured.

NOTE:
Language index 0 selects the default language of the terminal, i.e. the language, which is adjusted in the terminal using it's menus.

NOTE:
The reaction on changes of these inputs is delayed about 1 sec to ensure the new combination is valid (e.g. if a rotary selector switch is used).

CAUTION!
Each language change causes the reinitialization of the display. Function of the controller is not influenced.

Binary input: Lang sel D#2 A

Related FW	3.0																																
Description	<p>This is one of three binary inputs Lang sel D#2 A, Lang sel D#2 B, Lang sel D#2 C, used for selecting language of the external local terminal #2.</p> <p>NOTE: Using these inputs for language selection is an option only. If the inputs are not configured, the language can be selected using the menus on the terminal.</p> <p>ENCODING TABLE</p> <table border="1"> <thead> <tr> <th>LANGUAGE INDEX</th> <th>INPUT A</th> <th>INPUT B</th> <th>INPUT C</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>0</td> <td>0</td> </tr> <tr> <td>1</td> <td>1</td> <td>0</td> <td>0</td> </tr> <tr> <td>2</td> <td>0</td> <td>1</td> <td>0</td> </tr> <tr> <td>3</td> <td>1</td> <td>1</td> <td>0</td> </tr> <tr> <td>4</td> <td>0</td> <td>0</td> <td>1</td> </tr> <tr> <td>5</td> <td>1</td> <td>0</td> <td>1</td> </tr> <tr> <td>6</td> <td>0</td> <td>1</td> <td>1</td> </tr> </tbody> </table>	LANGUAGE INDEX	INPUT A	INPUT B	INPUT C	0	0	0	0	1	1	0	0	2	0	1	0	3	1	1	0	4	0	0	1	5	1	0	1	6	0	1	1
LANGUAGE INDEX	INPUT A	INPUT B	INPUT C																														
0	0	0	0																														
1	1	0	0																														
2	0	1	0																														
3	1	1	0																														
4	0	0	1																														
5	1	0	1																														
6	0	1	1																														

	7	1	1	1
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NOTE:
"0" in the table means the input is not active or not configured.

NOTE:
Language index 0 selects the default language of the terminal, i.e. the language, which is adjusted in the terminal using it's menus.

NOTE:
The reaction on changes of these inputs is delayed about 1 sec to ensure the new combination is valid (e.g. if a rotary selector switch is used).

CAUTION!
Each language change causes the reinitialization of the display. Function of the controller is not influenced.

Binary input: Lang sel D#2 B

Related FW	3.0																																				
Description	<p>This is one of three binary inputs Lang sel D#2 A, Lang sel D#2 B, Lang sel D#2 C, used for selecting language of the external local terminal #2.</p> <p>NOTE: Using these inputs for language selection is an option only. If the inputs are not configured, the language can be selected using the menus on the terminal.</p> <p>ENCODING TABLE</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: left;">LANGUAGE INDEX</th> <th style="text-align: center;">INPUT A</th> <th style="text-align: center;">INPUT B</th> <th style="text-align: center;">INPUT C</th> </tr> </thead> <tbody> <tr><td>0</td><td style="text-align: center;">0</td><td style="text-align: center;">0</td><td style="text-align: center;">0</td></tr> <tr><td>1</td><td style="text-align: center;">1</td><td style="text-align: center;">0</td><td style="text-align: center;">0</td></tr> <tr><td>2</td><td style="text-align: center;">0</td><td style="text-align: center;">1</td><td style="text-align: center;">0</td></tr> <tr><td>3</td><td style="text-align: center;">1</td><td style="text-align: center;">1</td><td style="text-align: center;">0</td></tr> <tr><td>4</td><td style="text-align: center;">0</td><td style="text-align: center;">0</td><td style="text-align: center;">1</td></tr> <tr><td>5</td><td style="text-align: center;">1</td><td style="text-align: center;">0</td><td style="text-align: center;">1</td></tr> <tr><td>6</td><td style="text-align: center;">0</td><td style="text-align: center;">1</td><td style="text-align: center;">1</td></tr> <tr><td>7</td><td style="text-align: center;">1</td><td style="text-align: center;">1</td><td style="text-align: center;">1</td></tr> </tbody> </table> <p>NOTE: "0" in the table means the input is not active or not configured.</p> <p>NOTE: Language index 0 selects the default language of the terminal, i.e. the language, which is adjusted in the terminal using it's menus.</p> <p>NOTE: The reaction on changes of these inputs is delayed about 1 sec to ensure the new combination is valid (e.g. if a rotary selector switch is used).</p> <p>CAUTION!</p>	LANGUAGE INDEX	INPUT A	INPUT B	INPUT C	0	0	0	0	1	1	0	0	2	0	1	0	3	1	1	0	4	0	0	1	5	1	0	1	6	0	1	1	7	1	1	1
LANGUAGE INDEX	INPUT A	INPUT B	INPUT C																																		
0	0	0	0																																		
1	1	0	0																																		
2	0	1	0																																		
3	1	1	0																																		
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5	1	0	1																																		
6	0	1	1																																		
7	1	1	1																																		

Each language change causes the reinitialization of the display. Function of the controller is not influenced.
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Binary input: Lang sel D#2 C

Related FW	3.0																																				
Description	<p>This is one of three binary inputs Lang sel D#2 A, Lang sel D#2 B, Lang sel D#2 C, used for selecting language of the external local terminal #2.</p> <p>NOTE: Using these inputs for language selection is an option only. If the inputs are not configured, the language can be selected using the menus on the terminal.</p> <p>ENCODING TABLE</p> <table border="1"> <thead> <tr> <th>LANGUAGE INDEX</th> <th>INPUT A</th> <th>INPUT B</th> <th>INPUT C</th> </tr> </thead> <tbody> <tr><td>0</td><td>0</td><td>0</td><td>0</td></tr> <tr><td>1</td><td>1</td><td>0</td><td>0</td></tr> <tr><td>2</td><td>0</td><td>1</td><td>0</td></tr> <tr><td>3</td><td>1</td><td>1</td><td>0</td></tr> <tr><td>4</td><td>0</td><td>0</td><td>1</td></tr> <tr><td>5</td><td>1</td><td>0</td><td>1</td></tr> <tr><td>6</td><td>0</td><td>1</td><td>1</td></tr> <tr><td>7</td><td>1</td><td>1</td><td>1</td></tr> </tbody> </table> <p>NOTE: "0" in the table means the input is not active or not configured.</p> <p>NOTE: Language index 0 selects the default language of the terminal, i.e. the language, which is adjusted in the terminal using it's menus.</p> <p>NOTE: The reaction on changes of these inputs is delayed about 1 sec to ensure the new combination is valid (e.g. if a rotary selector switch is used).</p> <p>CAUTION! Each language change causes the reinitialization of the display. Function of the controller is not influenced.</p>	LANGUAGE INDEX	INPUT A	INPUT B	INPUT C	0	0	0	0	1	1	0	0	2	0	1	0	3	1	1	0	4	0	0	1	5	1	0	1	6	0	1	1	7	1	1	1
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0	0	0	0																																		
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3	1	1	0																																		
4	0	0	1																																		
5	1	0	1																																		
6	0	1	1																																		
7	1	1	1																																		

Binary input: Lang sel D#3 A

Related FW	3.0
Description	<p>This is one of three binary inputs Lang sel D#3 A, Lang sel D#3 B, Lang sel D#3 C, used for selecting language of the external local terminal #3. The terminal #3 is available in IS-NT only.</p> <p>NOTE: Using these inputs for language selection is an option only. If the inputs are not</p>

configured, the language can be selected using the menus on the terminal.

ENCODING TABLE

LANGUAGE INDEX	INPUT A	INPUT B	INPUT C
0	0	0	0
1	1	0	0
2	0	1	0
3	1	1	0
4	0	0	1
5	1	0	1
6	0	1	1
7	1	1	1

NOTE:

"0" in the table means the input is not active or not configured.

NOTE:

Language index 0 selects the default language of the terminal, i.e. the language, which is adjusted in the terminal using its menus.

NOTE:

The reaction on changes of these inputs is delayed about 1 sec to ensure the new combination is valid (e.g. if a rotary selector switch is used).

CAUTION!

Each language change causes the reinitialization of the display. Function of the controller is not influenced.

Binary input: Lang sel D#3 B

Related FW	3.0																								
Description	<p>This is one of three binary inputs Lang sel D#3 A, Lang sel D#3 B, Lang sel D#3 C, used for selecting language of the external local terminal #3. The terminal #3 is available in IS-NT only.</p> <p>NOTE: Using these inputs for language selection is an option only. If the inputs are not configured, the language can be selected using the menus on the terminal.</p> <p>ENCODING TABLE</p> <table border="1"> <thead> <tr> <th>LANGUAGE INDEX</th> <th>INPUT A</th> <th>INPUT B</th> <th>INPUT C</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>0</td> <td>0</td> </tr> <tr> <td>1</td> <td>1</td> <td>0</td> <td>0</td> </tr> <tr> <td>2</td> <td>0</td> <td>1</td> <td>0</td> </tr> <tr> <td>3</td> <td>1</td> <td>1</td> <td>0</td> </tr> <tr> <td>4</td> <td>0</td> <td>0</td> <td>1</td> </tr> </tbody> </table>	LANGUAGE INDEX	INPUT A	INPUT B	INPUT C	0	0	0	0	1	1	0	0	2	0	1	0	3	1	1	0	4	0	0	1
LANGUAGE INDEX	INPUT A	INPUT B	INPUT C																						
0	0	0	0																						
1	1	0	0																						
2	0	1	0																						
3	1	1	0																						
4	0	0	1																						

5	1	0	1
6	0	1	1
7	1	1	1

NOTE:
"0" in the table means the input is not active or not configured.

NOTE:
Language index 0 selects the default language of the terminal, i.e. the language, which is adjusted in the terminal using it's menus.

NOTE:
The reaction on changes of these inputs is delayed about 1 sec to ensure the new combination is valid (e.g. if a rotary selector switch is used).

CAUTION!
Each language change causes the reinitialization of the display. Function of the controller is not influenced.

Binary input: Lang sel D#3 C

Related FW	3.0																																				
Description	<p>This is one of three binary inputs Lang sel D#3 A, Lang sel D#3 B, Lang sel D#3 C, used for selecting language of the external local terminal #3. The terminal #3 is available in IS-NT only.</p> <p>NOTE: Using these inputs for language selection is an option only. If the inputs are not configured, the language can be selected using the menus on the terminal.</p> <p>ENCODING TABLE</p> <table border="1"> <thead> <tr> <th>LANGUAGE INDEX</th> <th>INPUT A</th> <th>INPUT B</th> <th>INPUT C</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>0</td> <td>0</td> </tr> <tr> <td>1</td> <td>1</td> <td>0</td> <td>0</td> </tr> <tr> <td>2</td> <td>0</td> <td>1</td> <td>0</td> </tr> <tr> <td>3</td> <td>1</td> <td>1</td> <td>0</td> </tr> <tr> <td>4</td> <td>0</td> <td>0</td> <td>1</td> </tr> <tr> <td>5</td> <td>1</td> <td>0</td> <td>1</td> </tr> <tr> <td>6</td> <td>0</td> <td>1</td> <td>1</td> </tr> <tr> <td>7</td> <td>1</td> <td>1</td> <td>1</td> </tr> </tbody> </table> <p>NOTE: "0" in the table means the input is not active or not configured.</p> <p>NOTE: Language index 0 selects the default language of the terminal, i.e. the language, which is adjusted in the terminal using it's menus.</p>	LANGUAGE INDEX	INPUT A	INPUT B	INPUT C	0	0	0	0	1	1	0	0	2	0	1	0	3	1	1	0	4	0	0	1	5	1	0	1	6	0	1	1	7	1	1	1
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5	1	0	1																																		
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<p>NOTE: The reaction on changes of these inputs is delayed about 1 sec to ensure the new combination is valid (e.g. if a rotary selector switch is used).</p>
<p>CAUTION! Each language change causes the reinitialization of the display. Function of the controller is not influenced.</p>

Binary input: User mask 1

Related FW	3.0						
Description	<p>This input allows user to activate chosen function in ScreenEditor (tool for GenConfig) for particular screen instrument. User may choose from the following functions:</p> <table border="1" data-bbox="438 757 1364 1108"> <thead> <tr> <th>NONE</th> <th>SHOW</th> <th>HIDE</th> </tr> </thead> <tbody> <tr> <td>No action regarding this screen instrument is taken.</td> <td>By default the screen instrument is hidden. If any of mask inputs (User mask 1, User mask 2, User mask 3, User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is shown.</td> <td>By default the screen instrument is shown. If any of mask inputs (User mask 1, User mask 2, User mask 3, User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is hidden.</td> </tr> </tbody> </table> <p>E.g. this function can be used to "swap" between two different screen instruments when certain conditions are fulfilled. Logical binary inputs Mask 1..4 can be used to define any custom condition for this "swapping" function.</p>	NONE	SHOW	HIDE	No action regarding this screen instrument is taken.	By default the screen instrument is hidden. If any of mask inputs (User mask 1 , User mask 2 , User mask 3 , User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is shown.	By default the screen instrument is shown. If any of mask inputs (User mask 1 , User mask 2 , User mask 3 , User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is hidden.
NONE	SHOW	HIDE					
No action regarding this screen instrument is taken.	By default the screen instrument is hidden. If any of mask inputs (User mask 1 , User mask 2 , User mask 3 , User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is shown.	By default the screen instrument is shown. If any of mask inputs (User mask 1 , User mask 2 , User mask 3 , User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is hidden.					

Binary input: User mask 2

Related FW	3.0						
Description	<p>This input allows user to activate chosen function in ScreenEditor (tool for GenConfig) for particular screen instrument. User may choose from the following functions:</p> <table border="1" data-bbox="438 1585 1364 1937"> <thead> <tr> <th>NONE</th> <th>SHOW</th> <th>HIDE</th> </tr> </thead> <tbody> <tr> <td>No action regarding this screen instrument is taken.</td> <td>By default the screen instrument is hidden. If any of mask inputs (User mask 1, User mask 2, User mask 3, User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is shown.</td> <td>By default the screen instrument is shown. If any of mask inputs (User mask 1, User mask 2, User mask 3, User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is hidden.</td> </tr> </tbody> </table> <p>E.g. this function can be used to "swap" between two different screen instruments</p>	NONE	SHOW	HIDE	No action regarding this screen instrument is taken.	By default the screen instrument is hidden. If any of mask inputs (User mask 1 , User mask 2 , User mask 3 , User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is shown.	By default the screen instrument is shown. If any of mask inputs (User mask 1 , User mask 2 , User mask 3 , User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is hidden.
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No action regarding this screen instrument is taken.	By default the screen instrument is hidden. If any of mask inputs (User mask 1 , User mask 2 , User mask 3 , User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is shown.	By default the screen instrument is shown. If any of mask inputs (User mask 1 , User mask 2 , User mask 3 , User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is hidden.					

	when certain conditions are fulfilled. Logical binary inputs Mask 1..4 can be used to define any custom condition for this "swapping" function.
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Binary input: User mask 3

Related FW	3.0						
Description	<p>This input allows user to activate chosen function in ScreenEditor (tool for GenConfig) for particular screen instrument. User may choose from the following functions:</p> <table border="1"> <thead> <tr> <th>NONE</th> <th>SHOW</th> <th>HIDE</th> </tr> </thead> <tbody> <tr> <td>No action regarding this screen instrument is taken.</td> <td>By default the screen instrument is hidden. If any of mask inputs (User mask 1, User mask 2, User mask 3, User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is shown.</td> <td>By default the screen instrument is shown. If any of mask inputs (User mask 1, User mask 2, User mask 3, User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is hidden.</td> </tr> </tbody> </table> <p>E.g. this function can be used to "swap" between two different screen instruments when certain conditions are fulfilled. Logical binary inputs Mask 1..4 can be used to define any custom condition for this "swapping" function.</p>	NONE	SHOW	HIDE	No action regarding this screen instrument is taken.	By default the screen instrument is hidden. If any of mask inputs (User mask 1 , User mask 2 , User mask 3 , User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is shown.	By default the screen instrument is shown. If any of mask inputs (User mask 1 , User mask 2 , User mask 3 , User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is hidden.
NONE	SHOW	HIDE					
No action regarding this screen instrument is taken.	By default the screen instrument is hidden. If any of mask inputs (User mask 1 , User mask 2 , User mask 3 , User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is shown.	By default the screen instrument is shown. If any of mask inputs (User mask 1 , User mask 2 , User mask 3 , User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is hidden.					

Binary input: User mask 4

Related FW	3.0						
Description	<p>This input allows user to activate chosen function in ScreenEditor (tool for GenConfig) for particular screen instrument. User may choose from the following functions:</p> <table border="1"> <thead> <tr> <th>NONE</th> <th>SHOW</th> <th>HIDE</th> </tr> </thead> <tbody> <tr> <td>No action regarding this screen instrument is taken.</td> <td>By default the screen instrument is hidden. If any of mask inputs (User mask 1, User mask 2, User mask 3, User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is shown.</td> <td>By default the screen instrument is shown. If any of mask inputs (User mask 1, User mask 2, User mask 3, User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is hidden.</td> </tr> </tbody> </table> <p>E.g. this function can be used to "swap" between two different screen instruments when certain conditions are fulfilled. Logical binary inputs Mask 1..4 can be used to define any custom condition for this "swapping" function.</p>	NONE	SHOW	HIDE	No action regarding this screen instrument is taken.	By default the screen instrument is hidden. If any of mask inputs (User mask 1 , User mask 2 , User mask 3 , User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is shown.	By default the screen instrument is shown. If any of mask inputs (User mask 1 , User mask 2 , User mask 3 , User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is hidden.
NONE	SHOW	HIDE					
No action regarding this screen instrument is taken.	By default the screen instrument is hidden. If any of mask inputs (User mask 1 , User mask 2 , User mask 3 , User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is shown.	By default the screen instrument is shown. If any of mask inputs (User mask 1 , User mask 2 , User mask 3 , User mask 4 or other switches) connected to this particular screen instrument is activated, this screen instrument is hidden.					

Table of analog input functions

Analog input: LCD brightness

Related FW	3.0
Description	This functional input is used to adjust the backlight intensity of the IG-NT built-in terminal (display) by an analog input (e.g. a potentiometer). If this input is configured to a physical analog input or other value, the brightness adjusted by buttons at the terminal is overridden by this analog input.

Analog input: RPM pick-up

Related FW	3.0
Description	This functional input is used for reading of the gen-set speed from other source than pickup or generator frequency. This source is typically an ECU unit, which provides the speed at the communication bus.

Analog input: Oil press

Related FW	3.0
Description	This functional input is used as an additional information whether the engine is running or not. If you want to use this additional feature configure this input onto the physical analog input where the oil pressure sensor is connected and adjust the setpoint Starting POil to cca 50% of typical engine oil pressure at idle speed. NOTE: See also the chapter Running engine detection .

Analog input: Warming temp

Related FW	3.0
Description	This functional input is used for <i>engine warming</i> . See also the setpoint Warming load .

Analog input: Fuel level

Related FW	3.0
Description	This logical analog input is used for evaluation of the <i>Fuel theft</i> alarm. Learn more in the description of the setpoint MaxLevelDrop .

Analog input: PowerDerating1

Related FW	3.0
Description	This is the input into the <i>Power derating</i> block #1. See details about the function in the chapter Power derating .

Analog input: PowerDerating2

Related FW	3.0
Description	This is the input into the <i>Power derating</i> block #2. See details about the function in the chapter Power derating .

Analog input: MLC:AnExSysBld

Related FW	3.0
Description	<p>This functional input is used for requesting the system baseload externally by an analog input. The setpoint SysBaseLdMode must be set to EXTERNAL to read the system baseload from this input.</p> <p>NOTE: This logical analog input must be configured at each gen-set to the identical source. The <i>shared peripheral modules</i> can be used to distribute the value over the controllers via the CAN2 bus. See the note in the description of the setpoint SysBaseLdMode.</p>

Analog input: MPF:AnExSysBPF

Related FW	3.0
Description	<p>This functional input is used for requesting the system power factor externally by an analog input. The setpoint SysBasePFMode must be set to EXTERNAL to read the requested system power factor from this input.</p> <p>NOTE: This logical analog input must be configured at each gen-set to the identical source. The <i>shared peripheral modules</i> can be used to distribute the value over the controllers via the CAN2 bus. See the note in the description of the setpoint SysBaseLdMode.</p>

Analog input: Cyl temp 1

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #1. Used for computing of values I Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 2

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #2. Used for computing of values I Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

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Analog input: Cyl temp 3

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #3. Used for computing of values I Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 4

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #4. Used for computing of values I Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 5

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #5. Used for computing of values I Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 6

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #6. Used for computing of values I Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 7

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #7. Used for computing of values I Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 8

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #8. Used for computing of values T Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 9

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #9. Used for computing of values T Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 10

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #10. Used for computing of values T Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 11

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #11. Used for computing of values T Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 12

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #12. Used for computing of values T Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 13

Related FW	3.0
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Description	Logical analog input for cylinder temperature #13. Used for computing of values I Cyl aver , T Cyl max , T Cyl min .
	NOTE: Available in IS-NT only.

Analog input: Cyl temp 14

Related FW	3.0
Description	Logical analog input for cylinder temperature #14. Used for computing of values I Cyl aver , T Cyl max , T Cyl min .
	NOTE: Available in IS-NT only.

Analog input: Cyl temp 15

Related FW	3.0
Description	Logical analog input for cylinder temperature #15. Used for computing of values I Cyl aver , T Cyl max , T Cyl min .
	NOTE: Available in IS-NT only.

Analog input: Cyl temp 16

Related FW	3.0
Description	Logical analog input for cylinder temperature #16. Used for computing of values I Cyl aver , T Cyl max , T Cyl min .
	NOTE: Available in IS-NT only.

Analog input: Cyl temp 17

Related FW	3.0
Description	Logical analog input for cylinder temperature #17. Used for computing of values I Cyl aver , T Cyl max , T Cyl min .
	NOTE: Available in IS-NT only.

Analog input: Cyl temp 18

Related FW	3.0
Description	Logical analog input for cylinder temperature #18. Used for computing of values I

	Cyl aver , T Cyl max , T Cyl min .
	NOTE: Available in IS-NT only.

Analog input: Cyl temp 19

Related FW	3.0
Description	Logical analog input for cylinder temperature #19. Used for computing of values T Cyl aver , T Cyl max , T Cyl min .
	NOTE: Available in IS-NT only.

Analog input: Cyl temp 20

Related FW	3.0
Description	Logical analog input for cylinder temperature #20. Used for computing of values T Cyl aver , T Cyl max , T Cyl min .
	NOTE: Available in IS-NT only.

Analog input: Cyl temp 21

Related FW	3.0
Description	Logical analog input for cylinder temperature #21. Used for computing of values T Cyl aver , T Cyl max , T Cyl min .
	NOTE: Available in IS-NT only.

Analog input: Cyl temp 22

Related FW	3.0
Description	Logical analog input for cylinder temperature #22. Used for computing of values T Cyl aver , T Cyl max , T Cyl min .
	NOTE: Available in IS-NT only.

Analog input: Cyl temp 23

Related FW	3.0
Description	Logical analog input for cylinder temperature #23. Used for computing of values T Cyl aver , T Cyl max , T Cyl min .

	<p>NOTE: Available in IS-NT only.</p>
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Analog input: Cyl temp 24

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #24. Used for computing of values T Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 25

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #25. Used for computing of values T Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 26

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #26. Used for computing of values T Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 27

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #27. Used for computing of values T Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 28

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #28. Used for computing of values T Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

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Analog input: Cyl temp 29

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #29. Used for computing of values T Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 30

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #30. Used for computing of values T Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 31

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #31. Used for computing of values T Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cyl temp 32

Related FW	3.0
Description	<p>Logical analog input for cylinder temperature #32. Used for computing of values T Cyl aver, T Cyl max, T Cyl min.</p> <p>NOTE: Available in IS-NT only.</p>

Analog input: Cold temp 1

Related FW	3.0
Description	<p>If there is an additional terminal board between a thermocouple and the IS-AIN8 module and there is a significant temperature difference between this terminal board and the module, it is necessary to measure the temperature at this terminal board and use this temperature for the thermocouple compensation instead of the internal temperature of the module.</p> <p>This analog input is intended for measurement of this thermocouple compensation</p>

	<p>temperature for the IS-AIN8 module with index #1.</p> <p>NOTE: Thermocouples without internal compensation "Thermo(nc)..." must be used for this case.</p>
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Analog input: Cold temp 2

Related FW	3.0
Description	<p>If there is an additional terminal board between a thermocouple and the IS-AIN8 module and there is a significant temperature difference between this terminal board and the module, it is necessary to measure the temperature at this terminal board and use this temperature for the thermocouple compensation instead of the internal temperature of the module.</p> <p>This analog input is intended for measurement of this thermocouple compensation temperature for the IS-AIN8 module with index #2.</p> <p>NOTE: Thermocouples without internal compensation "Thermo(nc)..." must be used for this case.</p>

Analog input: Cold temp 3

Related FW	3.0
Description	<p>If there is an additional terminal board between a thermocouple and the IS-AIN8 module and there is a significant temperature difference between this terminal board and the module, it is necessary to measure the temperature at this terminal board and use this temperature for the thermocouple compensation instead of the internal temperature of the module.</p> <p>This analog input is intended for measurement of this thermocouple compensation temperature for the IS-AIN8 module with index #3.</p> <p>NOTE: Thermocouples without internal compensation "Thermo(nc)..." must be used for this case.</p>

Analog input: Cold temp 4

Related FW	3.0
Description	<p>If there is an additional terminal board between a thermocouple and the IS-AIN8 module and there is a significant temperature difference between this terminal board and the module, it is necessary to measure the temperature at this terminal board and use this temperature for the thermocouple compensation instead of the internal temperature of the module.</p> <p>This analog input is intended for measurement of this thermocouple compensation temperature for the IS-AIN8 module with index #4.</p> <p>NOTE: Thermocouples without internal compensation "Thermo(nc)..." must be used for</p>

	this case.
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Table of binary output functions

Binary output: Starter

Related FW	3.0
Description	<p>The output is used to energize the starter motor. The output closes at the beginning of start sequence after prestart has been completed and opens when the engine is started.</p> <p>NOTE: Learn more in the separate chapter Starting sequence.</p>

Binary output: Fuel Solenoid

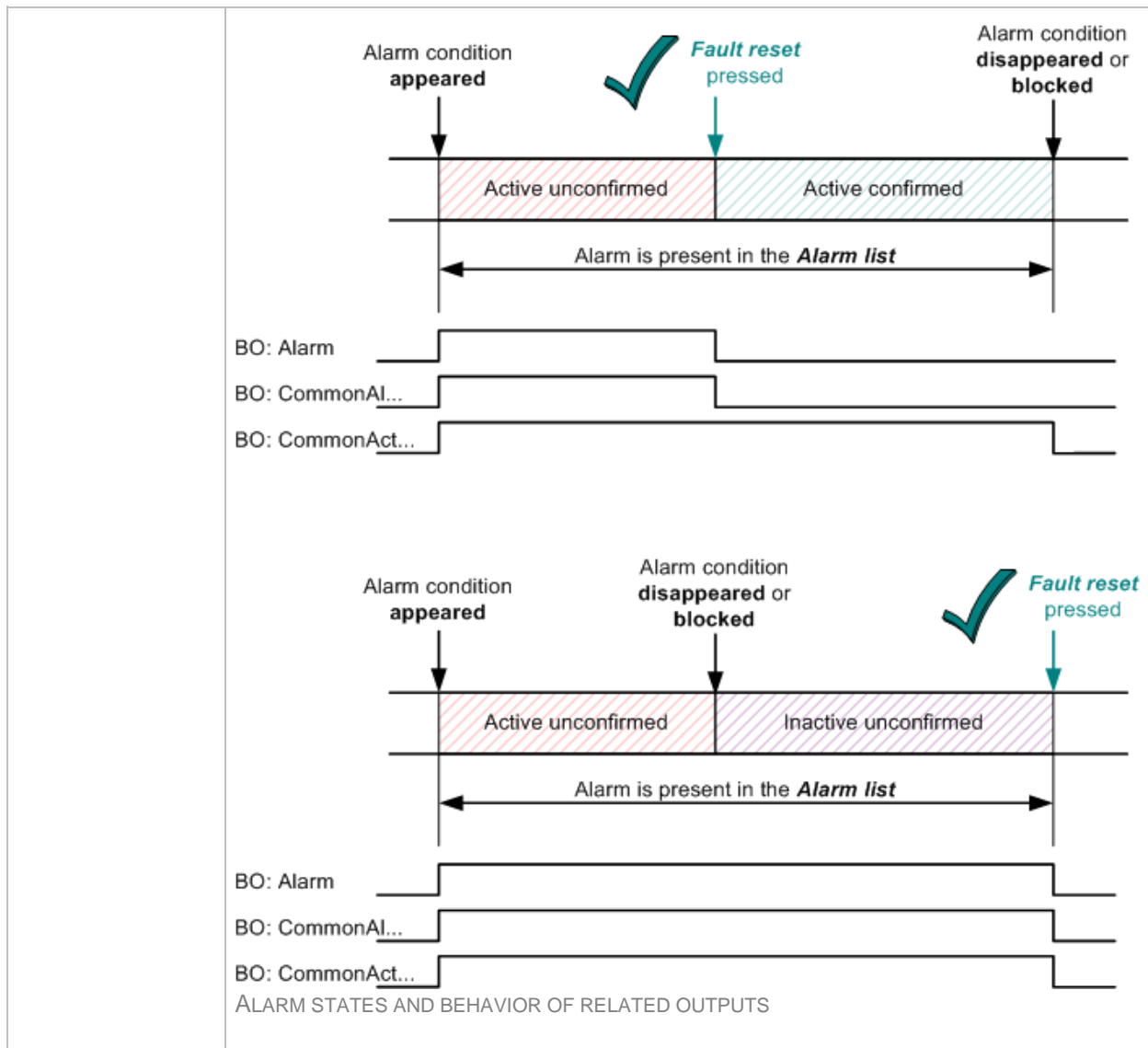
Related FW	3.0
Description	<p>This output is used for control of the engine fuel valve. The fuel valve can be either a fuel solenoid of diesel engine or a gas valve of gas engine. The behavior of this output is to be selected by the setpoint Fuel solenoid.</p> <p>NOTE: Learn more in the separate chapter Starting sequence.</p>

Binary output: Prestart

Related FW	3.0
Description	<p>This output can be used for control of any device, which has to be activated just before start, i.e. glow plugs. The output is closed for time period of Prestart time prior to activating of the starter motor and remains closed during cranking and also during pause between cranking attempts.</p> <p>NOTE: Learn more in the separate chapter Starting sequence.</p>

Binary output: Alarm

Related FW	3.0
Description	<p>The output is closed if there is at least one unconfirmed alarm in the alarm list.</p> <p>NOTE: Some alarm types as e.g. <i>Off load, History record, Low power, Mains protection</i> do not require confirmation, they disappear from the alarm list automatically when the alarm condition disappears. That means the <i>Alarm</i> output is not activated by alarms of these types.</p>



Binary output: Horn

Related FW	3.0
Description	The output closes together with the output Alarm . It opens when the output Alarm is opened or Horn reset button is pressed or Horn timeout has elapsed.

Binary output: CommonAlLev 1

Related FW	3.0
Description	This output is active if there is at least one unconfirmed 1st-level (yellow) alarm present in the alarm list. See the chapter Alarm management for more information.

Binary output: CommonAlLev 2

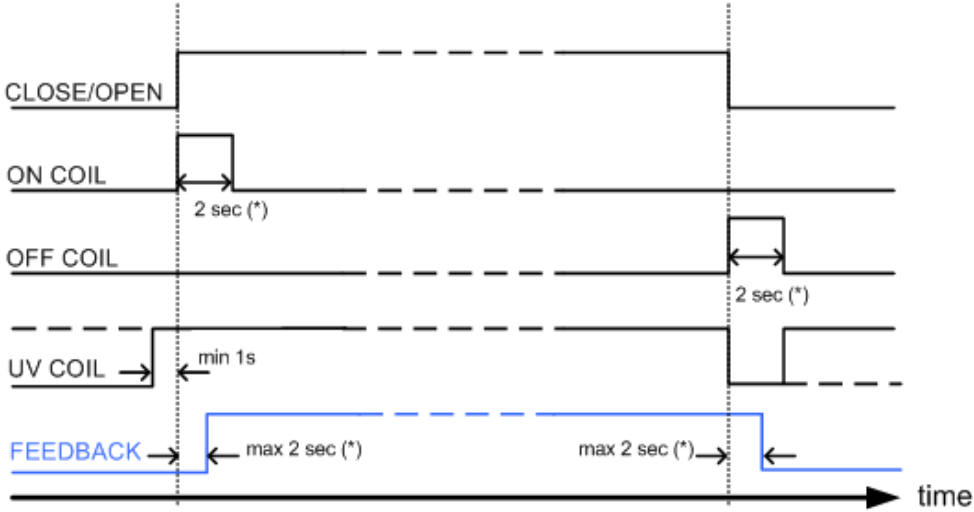
Related FW	3.0
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Description	This output is active if there is at least one unconfirmed 2nd-level (red) alarm present in the alarm list. See the chapter Alarm management for more information.
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Binary output: Cooling Pump

Related FW	3.0
Description	<p>This output is used for control of an external electric motor-driven cooling pump. The output closes when the gen-set is started (i.e. at the end of the <i>Starting</i> period) and opens at the end of the <i>Aftercooling</i> period, which takes place after the engine has been fully stopped. Duration of the aftercooling period is adjusted by the setpoint AfterCool time.</p> <p>The output opens immediately when Emergency stop is activated or if the controller is switched to OFF mode.</p>

Binary output: GCB Close/Open

Related FW	3.0
Description	<p>This output is intended for control of the GCB if a contactor is used as GCB. The output provides continuous signal while the GCB has to be closed.</p> <p>There are also other outputs available for GCB control:</p> <ul style="list-style-type: none"> • GCB ON coil • GCB OFF coil • GCB UV coil  <p>(*) 5 sec if synchronizing with the particular breaker is disabled. TIMING OF BREAKER CONTROL OUTPUTS</p>

Binary output: GCB ON Coil

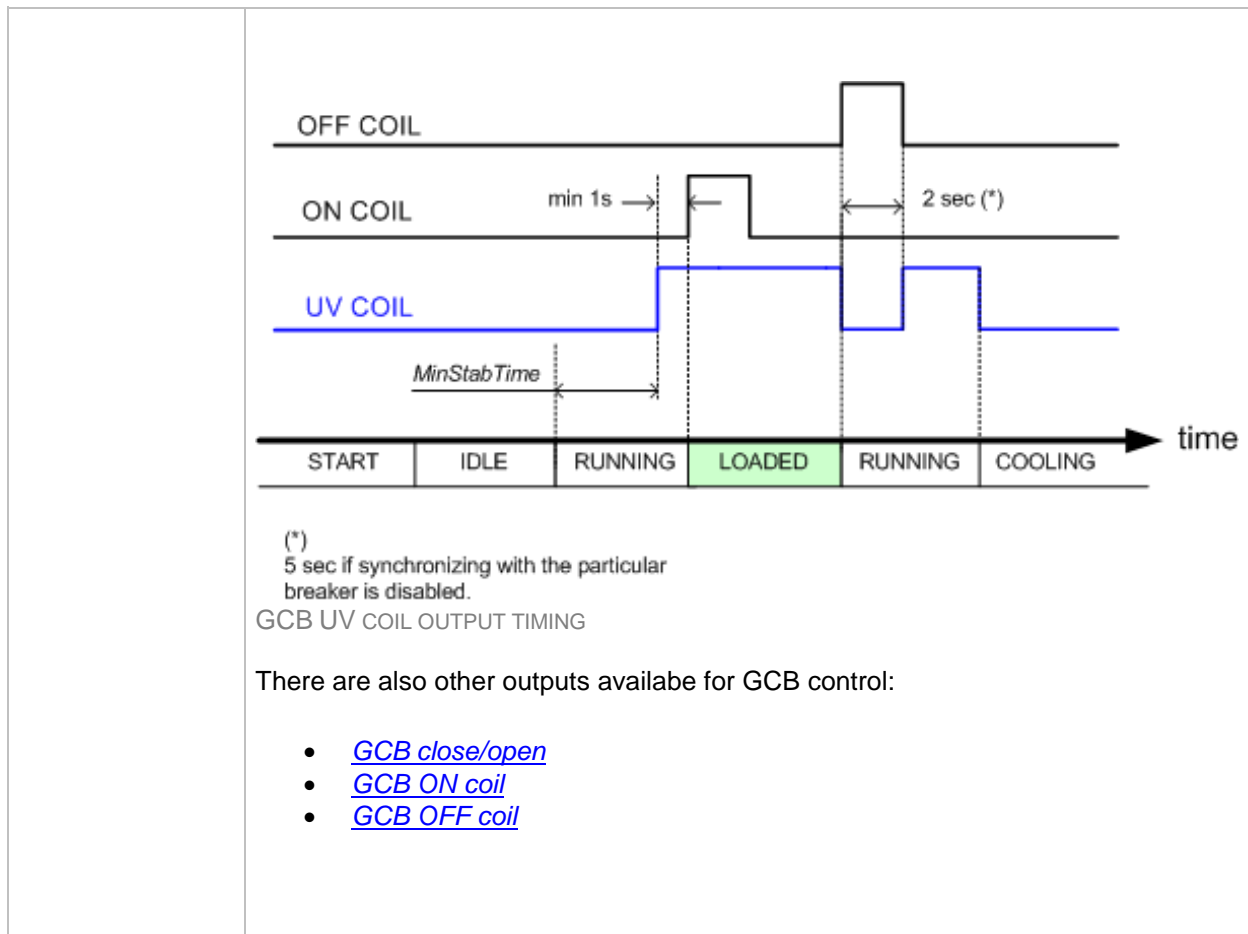
Related FW	3.0
Description	<p>This output is intended for closing of the GCB using ON coil if a circuit breaker is used as GCB. The output provides 2 sec pulse when the GCB has to close. If synchronizing is disabled with the particular breaker, the pulse length is extended to 5sec. See timing diagram of all available breaker control outputs in the description of the GCB close/open output.</p> <p>There are also other outputs available for GCB control:</p> <ul style="list-style-type: none"> • GCB close/open • GCB OFF coil • GCB UV coil

Binary output: GCB OFF Coil

Related FW	3.0
Description	<p>This output is intended for opening of the GCB using OFF coil if a circuit breaker is used as GCB. The output provides 2 sec pulse when the GCB has to open. If synchronizing is disabled with the particular breaker, the pulse length is extended to 5sec. See timing diagram of all available breaker control outputs in the description of the GCB close/open output.</p> <p>There are also other outputs available for GCB control:</p> <ul style="list-style-type: none"> • GCB close/open • GCB ON coil • GCB UV coil

Binary output: GCB UV Coil

Related FW	3.0
Description	<p>This output is intended for opening of the GCB using an undervoltage coil if a circuit breaker is used as GCB.</p> <ul style="list-style-type: none"> • The output is closed after the gen-set has been started, Min stab time has elapsed and the generator voltage and frequency has got into limits. GCB closing command is blocked for 1 sec after the UV coil has been closed to allow the breaker mechanical system getting ready for closing. • The output is opened for 2 sec when the GCB has to open. If synchronizing is disabled with the particular breaker, the length of the inverse pulse is extended to 5sec. • The output is closed again and remains closed while the generator voltage and frequency are in limits, if the <i>Running</i> phase follows after opening of the GCB (e.g. in MAN). • The output remains opened if the <i>Cooling</i> phase follows after opening of the GCB.



Binary output: Stop Solenoid

Related FW	3.0
Description	<p>This output is used at diesel engines equipped with fuel valve, which must be energized to stop the engine.</p> <p>The output is closed when the engine has to stop, remains closed while the engine is stopping and is opened back if the engine has successfully stopped and stop time elapsed.</p> <p>The total time this output is continuously active is never shorter than Stop time, i.e. if the gen-set stops quickly, the output may remain closed even though all symptoms indicate the engine is stopped.</p> <p>This output is also closed if the engine begins to rotate unexpectedly, i.e. if it is started manually directly on the engine. To allow the engine to be operated manually without intervention from the controller, switch the controller to the <i>emergency manual</i> mode using the input Emerg. manual.</p>

Binary output: Stop Pulse

Related FW	3.0
Description	<p>One second pulse is issued at this output when the engine is required to stop (i.e. this pulse does not commence stopping sequence but it is rather an actual command to engine physical stopping). The output is especially intended to be</p>

	used as stop command for ECU-controlled engines, which support stop command via the communication bus (e.g. J1939).
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Binary output: Syst res OK

Related FW	3.0
Description	The output is closed while the actual reserve is above the selected reserve for start.

Binary output: Syst res 1 OK

Related FW	3.0
Description	The output is closed while the actual reserve is above the reserve for start from the reserve set #1 .

Binary output: Syst res 2 OK

Related FW	3.0
Description	The output is closed while the actual reserve is above the reserve for start from the reserve set #2 .

Binary output: Syst res 3 OK

Related FW	3.0
Description	The output is closed while the actual reserve is above the reserve for start from the reserve set #3 .

Binary output: Syst res 4 OK

Related FW	3.0
Description	The output is closed while the actual reserve is above the reserve for start from the reserve set #4 .

Binary output: AllAvailGS run

Related FW	3.0
Description	The output is closed while all gen-sets in the group, which participate in the power management , are running and loaded.

Binary output: Speed up

Related FW	3.0
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Description	<p>This output together with the complementary output Speed dn are designed for speed and power control at gen-sets where the speed governor does not support analogue control.</p> <p>NOTE: The governor is recommended to be configured for droop function when these outputs are used for power control.</p> <p>NOTE: The alarm <i>Wrn SpdRegLim</i> is disabled when this output is used (configured onto any controller terminal or virtual output).</p>
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Binary output: Speed dn

Related FW	3.0
Description	<p>This output together with the complementary output Speed up are designed for speed and power control at gen-sets where the speed governor does not support analogue control.</p> <p>NOTE: The governor is recommended to be configured for droop function when these outputs are used for power control.</p> <p>NOTE: The alarm <i>Wrn SpdRegLim</i> is disabled when this output is used (configured onto any controller terminal or virtual output).</p>

Binary output: AVR up

Related FW	3.0
Description	<p>This output together with the complementary output AVR dn are designed for voltage and power factor control at gen-sets where the AVR does not support analogue control.</p> <p>NOTE: The AVR is recommended to be configured for droop function when these outputs are used for power factor control.</p> <p>NOTE: The alarm <i>Wrn VoltRegLim</i> is disabled when this output is used (configured onto any controller terminal or virtual output).</p>

Binary output: AVR dn

Related FW	3.0
Description	<p>This output together with the complementary output AVR up are designed for voltage and power factor control at gen-sets where the AVR does not support analogue control.</p> <p>NOTE: The AVR is recommended to be configured for droop function when these outputs are used for power factor control.</p>

	<p>NOTE: The alarm <i>Wrn VoltRegLim</i> is disabled when this output is used (configured onto any controller terminal or virtual output).</p>
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Binary output: Vgen <>

Related FW	3.0
Description	The output is closed while the <i>generator over/under voltage</i> alarm is present in the alarm list.

Binary output: Vbus <>

Related FW	3.0
Description	The output is closed while the <i>bus over/under voltage</i> alarm is present in the alarm list.

Binary output: Overcurrent

Related FW	3.0
Description	The output is closed while there is either the <i>Generator IDMT Overcurrent</i> or <i>Generator Short current</i> alarms present in the alarm list.

Binary output: Common Wrn

Related FW	3.0
Description	The output is closed while there is at least one alarm of the <i>Warning</i> type present in the alarm list. The alarm can be in any state, i.e. active unconfirmed, active confirmed or inactive unconfirmed. See the chapter Alarm management for more information.

Binary output: Common Sd

Related FW	3.0
Description	The output is closed while there is at least one alarm of the <i>Shutdown</i> type present in the alarm list. The alarm can be in any state, i.e. active unconfirmed, active confirmed or inactive unconfirmed. See the chapter Alarm management for more information.

Binary output: Common SdOvr

Related FW	3.0
Description	Common output that closes with 2s delay if any Shutdown override-type protection becomes active. If it is already active and another protection of that type becomes

	active, the output is deactivated for 2 seconds and then reactivated again to inform on this new alarm.
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Binary output: Common Stp

Related FW	3.0
Description	The output is closed while there is at least one alarm of the <i>Slow stop</i> type present in the alarm list. The alarm can be in any state, i.e. active unconfirmed, active confirmed or inactive unconfirmed. See the chapter Alarm management for more information.

Binary output: Common Fls

Related FW	3.0
Description	The output is closed while there is at least one alarm of the <i>Sensor fail</i> type present in the alarm list. The alarm can be in any state , i.e. active unconfirmed, active confirmed or inactive unconfirmed. See the chapter Alarm management for more information.

Binary output: Common LoP

Related FW	3.0
Description	This IS-NT specific function! The output is closed while there is at least one alarm of the <i>Low power</i> type present in the alarm list. See the chapter Alarm management for more information.

Binary output: Common OfL

Related FW	3.0
Description	The output is closed while there is at least one alarm of the <i>Off load</i> type present in the alarm list. See the chapter Alarm management for more information.

Binary output: Common BOC

Related FW	3.0
Description	The output is closed while there is at least one alarm of the <i>Breaker open&Cool-down</i> type present in the alarm list. The alarm can be in any state, i.e. active unconfirmed, active confirmed or inactive unconfirmed. See the chapter Alarm management for more information.

Binary output: Common AI

Related FW	3.0
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Description	The output is closed while there is at least one alarm of the <i>Alarm only</i> type present in the alarm list. The alarm can be in any state, i.e. active unconfirmed, active confirmed or inactive unconfirmed. See the chapter Alarm management for more information.
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Binary output: Common Hst

Related FW	3.0
Description	The output is closed for 1s when any alarm of <i>History record</i> type appears. See the chapter Alarm management for more information.

Binary output: CommonActLev 1

Related FW	3.0
Description	The output is closed while there is at least one 1st level (yellow) alarm present in the alarm list. The alarm can be in any state , i.e. active unconfirmed, active confirmed or inactive unconfirmed. See the chapter Alarm management for more information.

Binary output: CommonActLev 2

Related FW	3.0
Description	The output is closed while there is at least one 2nd level (red) alarm present in the alarm list. The alarm can be in any state , i.e. active unconfirmed, active confirmed or inactive unconfirmed. See the chapter Alarm management for more information.

Binary output: Alarm flashing

Related FW	3.0
Description	This is the flashing alternative of the output Alarm , i.e. the output flashes with period 1s/1s while the output Alarm is closed.

Binary output: Horn flashing

Related FW	3.0
Description	This is the flashing alternative of the output Horn , i.e. the output flashes with period 1s/1s while the output Horn is closed.

Binary output: T cyl differ

Related FW	3.0
Description	IS-NT specific function! The output is closed while the alarm <i>cylinder temperature difference</i> alarm is

	active.
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Binary output: Ignition

Related FW	3.0
Description	<p>The output is used for control of an ignition module on gas engines. The output is closed when the engine speed exceeds 30 RPM and opens when the engine is fully stopped regardless of the reason of the stop, i.e. whether it is an operational stop or shutdown stop. The only exception is activation of the input Emergency stop, when the ignition output is opened immediately after the input is activated.</p> <p>NOTE: Learn more in the separate chapter Starting sequence.</p>

Binary output: Ventilation

Related FW	3.0
Description	<p>The output is intended for control of an engine room ventilation fan or engine container ventilation fan. Intended for the engine ventilator control. The output is closed at the beginning of the start procedure together with Prestart output and opens together with Stop Solenoid after the engine is fully stopped.</p> <p>The output opens immediately when Emergency stop is activated or if the controller is switched to OFF mode.</p>

Binary output: Idle/Nominal

Related FW	3.0
Description	<p>This output is intended for switching of the speed governor reference from idle to nominal speed and vice versa. The output is opened when the engine is required to run at idle speed and it is closed when the engine is required to run at nominal speed.</p> <ul style="list-style-type: none"> • The output is opened while the engine is not running and also during start. • The output is closed after the engine has been started when the timer Idle time elapses. • The output remains closed while the engine is running. • The output is opened while stopping either at the beginning or at the end of the cooling phase. This is selectable by the setpoint Cooling speed. <p>NOTE: Some governors do not support speed reference switching.</p>

Binary output: Prelubr pump

Related FW	3.0
Description	<p>This output can be used for periodic lubrication of the engine while the engine is not running. The output is periodically closed for Prelubr time and then opened for</p>

	<p><u>Prelubr pause.</u></p> <p>The output opens immediately when <u>Emergency stop</u> is activated or if the controller is switched to OFF mode.</p> <p>NOTE: The engine must be equipped with an external electric motor-driven oil pump to allow this function.</p>
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Binary output: FltResButnEcho

Related FW	3.0
Description	<p>This output provides 1s pulse when:</p> <ul style="list-style-type: none"> • <i>Fault reset</i> button is pressed on the controller front panel or • <i>Fault reset</i> button is pressed on any of external local/remote terminals or • <i>fault reset</i> command is received via communication line or • the input <u>FaultResButton</u> is activated.

Binary output: HrnResButnEcho

Related FW	3.0
Description	<p>This output provides 1s pulse when:</p> <ul style="list-style-type: none"> • <i>Horn reset</i> button is pressed on the controller front panel or • <i>Horn reset</i> button is pressed on any of external local/remote terminals or • <i>horn reset</i> command is received via communication line or • the input <u>HornResButton</u> is activated.

Binary output: StartButnEcho

Related FW	3.0
Description	<p>This output provides 1s pulse when:</p> <ul style="list-style-type: none"> • <i>Start</i> button is pressed on the controller front panel or • <i>Start</i> button is pressed on any of external local/remote terminals or • <i>start</i> command is received via communication line or • the input <u>StartButton</u> is activated.

Binary output: StopButnEcho

Related FW	3.0
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Description	<p>This output provides 1s pulse when:</p> <ul style="list-style-type: none"> • <i>Stop</i> button is pressed on the controller front panel or • <i>Stop</i> button is pressed on any of external local/remote terminals or • <i>stop</i> command is received via communication line or • the input StopButton is activated.
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Binary output: GCBButnEcho

Related FW	3.0
Description	<p>This output provides 1s pulse when:</p> <ul style="list-style-type: none"> • <i>GCB</i> button is pressed on the controller front panel or • <i>GCB</i> button is pressed on any of external local/remote terminals or • <i>GCB close/open</i> command is received via communication line or • the input GCBButton is activated.

Binary output: GCB status

Related FW	3.0
Description	<p>This output indicates the GCB position, how it is internally considered in the controller. The position is based on GCB feedback input and optionally also on the GCB fdb neg input.</p> <ul style="list-style-type: none"> • If only the positive feedback input is used the output mirrors the feedback. • If both feedbacks are used and they match each other the output indicates the GCB position according to the feedbacks. • If both feedbacks are used, however they do not match each other, the output remains in previous position when they matched. <p>The output can be used for indication of the GCB position.</p>

Binary output: MCB status

Related FW	3.0
Description	<p>This output indicates the MCB position, how it is internally considered in the controller. The position is based on MCB feedback input and optionally also on the MCB fdb neg input.</p> <ul style="list-style-type: none"> • If only the positive feedback input is used the output mirrors the feedback. • If both feedbacks are used and they match each other the output indicates the MCB position according to the feedbacks. • If both feedbacks are used, however they do not match each other, the

	<p>output remains in previous position when they matched.</p> <p>The output can be used for indication of the MCB position.</p>
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Binary output: Gen params OK

Related FW	3.0
Description	<p>This output indicates that the generator actually provides proper voltage and frequency. The output is closed while the gen-set is running (regardless of whether GCB is closed or not) and all generator electrical parameters are in limits.</p> <p>NOTE: This output combined with a PLC block <i>Delay</i> can be used for switching on/off of some auxiliary devices (e.g. cooling pump), that are supplied directly from generator (before GCB). The delay is recommended to allow the generator getting stable and avoid unnecessary switching the auxiliary device on and off just after start.</p>

Binary output: Bus Params OK

Related FW	3.0
Description	<p>This output indicates that the bus is healthy. The output is closed while all bus electrical parameters are in limits.</p>

Binary output: kWh pulse

Related FW	3.0
Description	<p>This output generates 100ms pulse always when the internal kWh counter incremented.</p>

Binary output: In synchronism

Related FW	3.0
Description	<p>This output is closed during synchronization when all synchro conditions have been fulfilled. The output is opened either when:</p> <ul style="list-style-type: none"> • the synchro conditions are lost or • the corresponding breaker has been closed or • the synchronizing was interrupted or timed out. <p>Synchro conditions are following:</p> <ul style="list-style-type: none"> • Phase shift between generator and mains (bus) voltage must be within range of \pmPhase window for period longer than Dwell time.

	<ul style="list-style-type: none"> Voltage difference between generator and mains (bus) voltage (in all phases) must be lower or equal to Voltage window for period longer than Dwell time. <p>The output is intended for manual synchronization. Automatic closing of GCB must be disabled for this case. Use the input GCB disable.</p>
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Binary output: InMainsParal

Related FW	3.0
Description	<p>This LBO indicates that controller (or logical group, which the controller is member of) is connected to the mains. It means that there exists a way across MCB (IM-NT-MCB application) or MCB+MGCB (IM-NT-MGCB application) to the controller. It is possible to configure this signal as MCB feedback of the controller, what can be useful for complicated applications with higher amount of mains.</p> <p>NOTE: This signal works correctly only if IM-NT is used as the MCB/MGCB control device.</p>

Binary output: Derating 1 act

Related FW	3.0
Description	<p>IS-NT specific funtion!</p> <p>This output is closed when level 1 derating is active. For more information on power derating see chapter Power derating.</p>

Binary output: Derating 2 act

Related FW	3.0
Description	<p>IS-NT specific funtion!</p> <p>This output is closed when level 2 derating is active. For more information on power derating see chapter Power derating.</p>

Binary output: Engines swapped

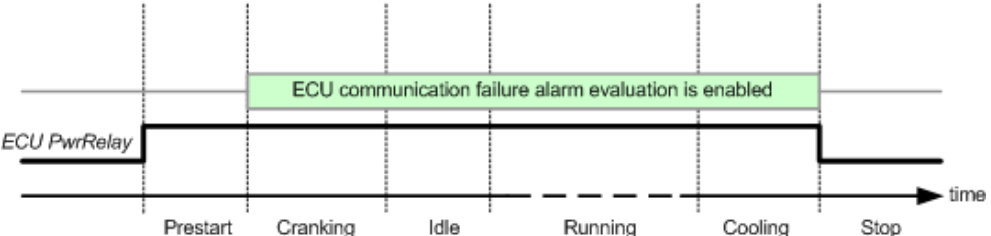
Related FW	3.0
Description	<p>This output is activated by the master controller for 100 ms pulse when the priority of two gen-sets was swapped by the Running hours equalization function.</p>

Binary output: Neutral CB C/O

Related FW	3.0
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Description	<p>This output is intended for control of the neutral contactor. The output provides continuous signal while the neutral contactor has to be closed. Use the input NeutralCB fdb for the neutral contactor feedback.</p> <p>Response time of the contactor must be less than 400ms. If the contactor does not respond to an open or close command within this time, the alarm <i>Wrn NCB fail</i> is issued.</p> <p>NOTE: Learn more about neutral contactor in the description of the setpoint #Neutral cont.</p>
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Binary output: ECU PwrRelay

Related FW	3.0
Description	<p>This output is used for control of the "Keyswitch" ECU input. The output is closed at the beginning of the prestart phase, remains closed while the engine is running, and is opened when the engine has to be stopped. The keyswitch input may be also labeled as "15" according to cable numbering convention used in vehicles.</p> <ul style="list-style-type: none"> If this input is used (configured), the evaluation of ECU communication fault alarm and other ECU-related alarms is enabled only while the engine is being started or is running. The reason is that most of ECUs go to sleep mode and do not communicate while the keyswitch input is deactivated.  <p>ECU ALARMS EVALUATION PERIOD WHEN THE ECU PWRRELAY IS USED</p> <p>NOTE: It is recommended to adjust the Prestart time to at least 3 sec to allow the ECU to wake-up and begin the communication prior to the ECU communication fault alarm is enabled.</p> <ul style="list-style-type: none"> If this input is not configured the evaluation of ECU-related alarms is enabled all the time. <p>NOTE: If your ECU does not have the keyswitch input, however you want the ECU-related alarms to be disabled while the engine is not running, configure the output onto a virtual IO module (VPIO).</p> <p>CAUTION! This output should not be used for disconnecting of main power supply from the ECU. Disconnecting of the main power supply while the engine is running might cause the ECU will not be able to record eventual trouble codes into it's nonvolatile memory.</p>

Binary output: ECU Comm Error

Related FW	3.0
Description	The output is closed while there is an error in the communication with ECU, i.e. while there is the alarm <i>ECU comm error</i> present in the alarm list.

Binary output: PeriphCommErr

Related FW	3.0
Description	The output is closed while there is an error in the communication with any peripheral unit (e.g. IS-AIN8, IGS-PTM, ...).

Binary output: CtrlHeartBeat

Related FW	3.0
Description	<p>The output provides alternating signal with rate 500ms active / 500ms inactive while the controller is operational, i.e. it has passed all checks after startup and no failure was detected.</p> <p>If the output does not provide the alternating signal it may indicate following:</p> <ul style="list-style-type: none"> • controller is switched off or • controller is damaged or • incorrect/missing firmware and/or application or • corrupted setpoints <p>The output is intended for using in wired redundancy systems at the main controller. Learn more about redundancy in separate chapter Redundant controllers.</p>

Binary output: CtrlHBeat FD

Related FW	3.0
Description	<p>This output is used at a redundant controller to disconnect the main controller from the gen-set, connect the redundant one instead and activate it.</p> <p>The output is closed:</p> <ul style="list-style-type: none"> • If the input CtrlHBeat sens is configured onto any input terminal and the redundancy controller does not sense the "heart beat" signal from the main controller at that terminal. • If the redundant controller has not received two consequent messages from the main controller. The address of the main controller for the particular redundant one is selected by the the setpoint Watched Contr

	<p>NOTE: Learn more about redundancy in separate chapter Redundant controllers.</p>
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Binary output: LdShed stage 1

Related FW	3.0
Description	<p>This output is used for control of first load group. This is the group which is disconnected as first one when the load shedding function becomes active. Connect least important loads to this group.</p> <p>NOTE: Learn more about load shedding in the separate chapter Load shedding.</p>

Binary output: LdShed stage 2

Related FW	3.0
Description	<p>This output is used for control of second load group. This group is disconnected as second one when the first group is already disconnected and the condition for disconnecting of next group is still fulfilled.</p> <p>NOTE: Learn more about load shedding in the separate chapter Load shedding.</p>

Binary output: LdShed stage 3

Related FW	3.0
Description	<p>This output is used for control of third load group. This group is disconnected as last one when the first two groups are already disconnected and the condition for disconnecting of next group is still fulfilled.</p> <p>NOTE: Learn more about load shedding in the separate chapter Load shedding.</p>

Binary output: TimerAct 1-4

Related FW	3.0
Description	<p>This is combined output from timer channels 1-4. The output is closed if at least one of the channels is active.</p> <p>NOTE: See the chapter Timers for more details about timers.</p>

Binary output: TimerAct 5-8

Related FW	3.0
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Description	This is combined output from timer channels 5-8. The output is closed if at least one of the channels is active. NOTE: See the chapter Timers for more details about timers.
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Binary output: TimerAct 9-12

Related FW	3.0
Description	This is combined output from timer channels 9-12. The output is closed if at least one of the channels is active. NOTE: See the chapter Timers for more details about timers.

Binary output: TimerAct 13-16

Related FW	3.0
Description	This is combined output from timer channels 13-16. The output is closed if at least one of the channels is active. NOTE: See the chapter Timers for more details about timers.

Binary output: TimerActiveCom

Related FW	3.0
Description	This is combined output from all timer channels. The output is active if at least one timer channel is active.

Binary output: MODES: Off mode

Related FW	3.0
Description	The output is closed while the controller is currently in OFF mode (either switched by the mode selector on the front panel or by the input Remote OFF).

Binary output: MODES: Man mode

Related FW	3.0
Description	The output is closed while the controller is currently in MAN mode (either switched by the mode selector on the front panel or by the input Remote MAN).

Binary output: MODES: Sem mode

Related FW	3.0
Description	IS-NT specific function! The output is closed while the controller is currently in SEM mode. This output is

	available in IS-NT controllers only.
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Binary output: MODES: Aut mode

Related FW	3.0
Description	The output is closed while the controller is currently in AUT mode (either switched by the mode selector on the front panel or by the input Remote AUT).

Binary output: MODES: Test mode

Related FW	3.0
Description	The output is closed while the controller is currently in TEST mode (either switched by the mode selector on the front panel or by the input Remote TEST).

Binary output: MODES: Off mode

Related FW	3.0
Description	The output is closed while the controller is currently in OFF mode (either switched by the mode selector on the front panel or by the input Remote OFF).

Binary output: MODES: Man mode

Related FW	3.0
Description	The output is closed while the controller is currently in MAN mode (either switched by the mode selector on the front panel or by the input Remote MAN).

Binary output: MODES: Sem mode

Related FW	3.0
Description	IS-NT specific function! The output is closed while the controller is currently in SEM mode. This output is available in IS-NT controllers only.

Binary output: MODES: Aut mode

Related FW	3.0
Description	The output is closed while the controller is currently in AUT mode (either switched by the mode selector on the front panel or by the input Remote AUT).

Binary output: MODES: Test mode

Related FW	3.0
Description	The output is closed while the controller is currently in TEST mode (either switched by the mode selector on the front panel or by the input Remote TEST).

Binary output: MODES: Off mode

Related FW	3.0
Description	The output is closed while the controller is currently in OFF mode (either switched

	by the mode selector on the front panel or by the input Remote OFF).
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Binary output: MODES: Man mode

Related FW	3.0
Description	The output is closed while the controller is currently in MAN mode (either switched by the mode selector on the front panel or by the input Remote MAN).

Binary output: MODES: Sem mode

Related FW	3.0
Description	IS-NT specific function! The output is closed while the controller is currently in SEM mode. This output is available in IS-NT controllers only.

Binary output: MODES: Aut mode

Related FW	3.0
Description	The output is closed while the controller is currently in AUT mode (either switched by the mode selector on the front panel or by the input Remote AUT).

Binary output: MODES: Test mode

Related FW	3.0
Description	The output is closed while the controller is currently in TEST mode (either switched by the mode selector on the front panel or by the input Remote TEST).

Binary output: MODES: Off mode

Related FW	3.0
Description	The output is closed while the controller is currently in OFF mode (either switched by the mode selector on the front panel or by the input Remote OFF).

Binary output: MODES: Man mode

Related FW	3.0
Description	The output is closed while the controller is currently in MAN mode (either switched by the mode selector on the front panel or by the input Remote MAN).

Binary output: MODES: Sem mode

Related FW	3.0
Description	IS-NT specific function! The output is closed while the controller is currently in SEM mode. This output is available in IS-NT controllers only.

Binary output: MODES: Aut mode

Related FW	3.0
Description	The output is closed while the controller is currently in AUT mode (either switched

	by the mode selector on the front panel or by the input Remote AUT).
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Binary output: MODES: Test mode

Related FW	3.0
Description	The output is closed while the controller is currently in TEST mode (either switched by the mode selector on the front panel or by the input Remote TEST).

Binary output: SystReady

Related FW	3.0
Description	<p>The output is closed while the group of gen-sets has enough capacity to fulfil the requested power reserve. If this output is not closed it means the system has not enough capacity to fulfil the reserve even if all the gen-sets will run.</p> <p>NOTE: <i>Fulfilled</i> reserve means the actual reserve is above the requested reserve for start.</p> <p>NOTE: This output do not indicate the requested reserve has been already fulfilled. It only indicates whether the system is able to fulfil it or not.</p>

Binary output: Ready for Load

Related FW	3.0
Description	This output is closed while the gen-set is running, it's voltage and frequency are in limits and the GCB is able to be closed or is already closed.

Binary output: Gen-set active

Related FW	3.0
Description	<p>The output closes at the beginning of the prestart phase and opens after the gen-set has been fully stopped. If the gen-set fails to start the output opens after the last cranking attempt.</p> <p>NOTE: The output also closes if the engine begins to rotate spontaneously.</p>

Binary output: Operational

Related FW	3.0
Description	The output is closed when the gen-set is ready for operation or is currently in operation.

Binary output: Ready

Related FW	3.0
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Description	<p>The output is closed while the gen-set is not in operation at the moment, however it is ready to be put into operation. The output is closed while:</p> <ul style="list-style-type: none"> • the genset is not running and • the controller is not in OFF mode and • there isn't any alarm blocking start of the gen-set
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Binary output: Not ready

Related FW	3.0
Description	<p>The output is closed while the gen-set is not in operation, however it is not ready to be put into operation. The output is closed while:</p> <ul style="list-style-type: none"> • the genset is not running and • the controller is in OFF mode or • there is an alarm blocking start of the gen-set.

Binary output: CrankProcedure

Related FW	3.0
Description	<p>The output is closed while the engine is cranking and during pauses between crank attempts. The output is opened either when the gen-set is started or failed to start. See the diagram in the description of the output Cranking for differences between outputs CrankProcedure, Cranking and Starter.</p>

Binary output: Starting

Related FW	3.0
Description	<p>The output is closed at the beginning of the prestart phase and remains closed during prestart, cranking and starting phases. The output is opened either when the gen-set goes to running phase or when it failed to start. See the diagram in the description of the output Cranking for details.</p>

Binary output: Idle run

Related FW	3.0
Description	<p>This output is closed while the timer Idle time is counting down. This timer begins to count down when the engine is considered as started and the starter motor is deenergized. See also description of the output Starter.</p>

Binary output: Running

Related FW	3.0
Description	This output is closed at the end of the Idle phase when the output Idle/Nominal is closed to switch the gen-set to nominal speed. The output is opened when the gen-set goes to cooling phase or performs a shutdown.

Binary output: ForwardSynchro

Related FW	3.0
Description	The output is closed during forward synchronizing and opens when the output GCB status is activated (= GCB was closed). NOTE: The output can be used for control of an external synchronizing module.

Binary output: Warming

Related FW	3.0
Description	The output is closed during warming period. Learn more about warmin in the description of the setpoint Warming load .

Binary output: Soft load

Related FW	3.0
Description	The output is closed during gen-set soft loading period – i.e. it is closed when the gen-set has been synchronized to the mains/bus and GCB has been closed and opened again when the ramp of the gen-set power reached the required level. NOTE: The output is not closed during the warming period.

Binary output: Loaded

Related FW	3.0
Description	The output is closed while the gen-set is loaded and the load is beeing regulated according to selected mode (baseload, import/export, power management etc.) or is not beeing regulated in single island operation.

Binary output: Soft unld

Related FW	3.0
Description	The output is closed while the gen-set is beeing unloaded before opening GCB.

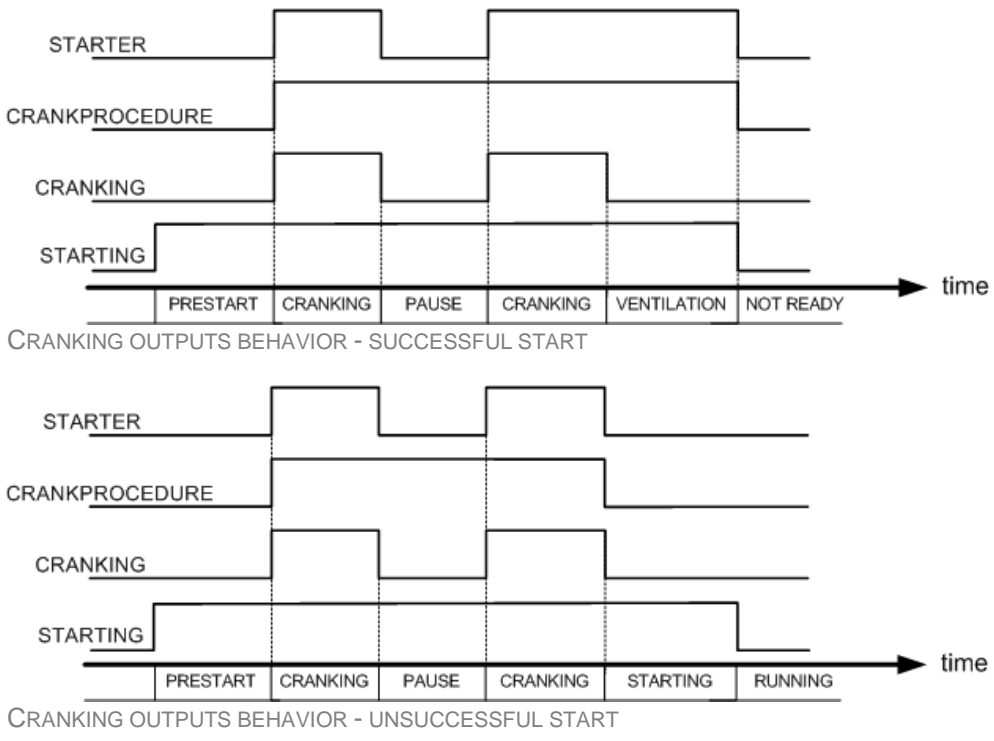
Binary output: Cooling

Related FW	3.0
Description	The output is closed during the <i>Cooling</i> phase, which takes place after GCB has been opened before the engine is stopped.

Binary output: Stopping

Related FW	3.0
Description	<p>The output closes when the command to stop the engine has been issued, i.e. the output Fuel Solenoid has been deactivated. It opens when the engine is fully stopped. The output also closes if the engine begins to rotate spontaneously.</p> <p>This output is closed for the whole time of the stopping sequence (regardless of the repeated opening of the Stop solenoid). It is deactivated immediately when the engine is considered stopped.</p>

Binary output: Cranking

Related FW	3.0
Description	<p>The output is closed while the engine is cranking. See the following diagrams for differences between outputs CrankProcedure, Cranking and Starter. The diagrams show situation for gas engine and two crank attempts.</p>  <p>The diagrams illustrate the timing of four binary outputs: STARTER, CRANKPROCEDURE, CRANKING, and STARTING over time. The time axis is divided into phases: PRESTART, CRANKING, PAUSE, CRANKING, VENTILATION, and NOT READY (for the successful start) or STARTING and RUNNING (for the unsuccessful start).</p> <p>CRANKING OUTPUTS BEHAVIOR - SUCCESSFUL START: In this scenario, the STARTING output is active during PRESTART and the first CRANKING phase. The STARTER output is active during both CRANKING phases. The CRANKPROCEDURE output is active from the start of the first CRANKING phase through the VENTILATION phase. The CRANKING output is active during both CRANKING phases. The engine starts successfully after the second CRANKING phase.</p> <p>CRANKING OUTPUTS BEHAVIOR - UNSUCCESSFUL START: In this scenario, the STARTING output is active during PRESTART and the first CRANKING phase. The STARTER output is active during both CRANKING phases. The CRANKPROCEDURE output is active from the start of the first CRANKING phase through the STARTING phase. The CRANKING output is active during both CRANKING phases. The engine does not start, and the STARTING output remains active through the RUNNING phase.</p>

Binary output: Logical 0

Related FW	3.0
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Description	This output is always opened. It may be used in functions (e.g. ECU outputs or PLC modules inputs) where a binary value is required, however it has to be continuously inactive.
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Binary output: Logical 1

Related FW	3.0
Description	This output is always closed. It may be used in functions (e.g. ECU outputs or PLC modules inputs) where continuously active binary value is required.

Binary output: Bin selector 1

Related FW	3.0
Description	Output is closed or opened according to the setpoint Bin selector 1 . NOTE: The output is intended for ECU-controlled engines to switch on/off some particular ECU function by a controller setpoint if the function can be controlled by a binary value over the J1939 bus.

Binary output: Bin selector 2

Related FW	3.0
Description	Output is closed or opened according to the setpoint Bin selector 2 . NOTE: The output is intended for ECU-controlled engines to switch on/off some particular ECU function by a controller setpoint if the function can be controlled by a binary value over the J1939 bus.

Binary output: Bin selector 3

Related FW	3.0
Description	Output is closed or opened according to the setpoint Bin selector 3 . NOTE: The output is intended for ECU-controlled engines to switch on/off some particular ECU function by a controller setpoint if the function can be controlled by a binary value over the J1939 bus.

Binary output: Bin selector 4

Related FW	3.0
Description	Output is closed or opened according to the setpoint Bin selector 4 . NOTE: The output is intended for ECU-controlled engines to switch on/off some particular

	ECU function by a controller setpoint if the function can be controlled by a binary value over the J1939 bus.
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Binary output: WrongPhSeq

Related FW	3.0
Description	Binary output WrongPhSeq is active when at least one of the following conditions is fulfilled: Generator/Mains/Bus phase is inverted or wrong generator/mains/bus phase sequence or opposed generator/mains/bus phase sequence is detected.

Binary output: User Button 1

Related FW	3.0								
Description	<p>This output can be specified for example on buttons on IV-5/8 or in SCADA diagram in IntelliMonitor. Its state depends on function assigned to the related button.</p> <p>It is possible to lock UserButton commands in configuration to specific user level. Buttons 1-8 and 9-16 are locked separately.</p> <table border="1" data-bbox="438 987 1366 1570"> <tr> <td>ON</td> <td>Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.</td> </tr> <tr> <td>OFF</td> <td>Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.</td> </tr> <tr> <td>ON/OFF</td> <td>Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).</td> </tr> <tr> <td>PULSE ON</td> <td>Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.</td> </tr> </table>	ON	Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.	OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.	ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).	PULSE ON	Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.
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ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).								
PULSE ON	Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.								

Binary output: User Button 2

Related FW	3.0
Description	<p>This output can be specified for example on buttons on IV-5/8 or in SCADA diagram in IntelliMonitor. Its state depends on function assigned to the related button.</p> <p>It is possible to lock UserButton commands in configuration to specific user level. Buttons 1-8 and 9-16 are locked separately.</p>

	ON	Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.
	OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.
	ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).
	PULSE ON	Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.

Binary output: User Button 3

Related FW	3.0								
Description	<p>This output can be specified for example on buttons on IV-5/8 or in SCADA diagram in IntelliMonitor. Its state depends on function assigned to the related button.</p> <p>It is possible to lock UserButton commands in configuration to specific user level. Buttons 1-8 and 9-16 are locked separately.</p>								
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ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).								
PULSE ON	Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.								

Binary output: User Button 4

Related FW	3.0
Description	This output can be specified for example on buttons on IV-5/8 or in SCADA diagram in IntelliMonitor. Its state depends on function assigned to the related

button.	
It is possible to lock UserButton commands in configuration to specific user level. Buttons 1-8 and 9-16 are locked separately.	
ON	Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.
OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.
ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).
PULSE ON	Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.

Binary output: User Button 5

Related FW	3.0								
Description	<p>This output can be specified for example on buttons on IV-5/8 or in SCADA diagram in InteliMonitor. Its state depends on function assigned to the related button.</p> <p>It is possible to lock UserButton commands in configuration to specific user level. Buttons 1-8 and 9-16 are locked separately.</p> <table border="1"> <tr> <td>ON</td> <td>Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.</td> </tr> <tr> <td>OFF</td> <td>Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.</td> </tr> <tr> <td>ON/OFF</td> <td>Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).</td> </tr> <tr> <td>PULSE ON</td> <td>Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.</td> </tr> </table>	ON	Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.	OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.	ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).	PULSE ON	Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.
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OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.								
ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).								
PULSE ON	Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.								

Binary output: User Button 6

Related FW	3.0								
Description	<p>This output can be specified for example on buttons on IV-5/8 or in SCADA diagram in IntelliMonitor. Its state depends on function assigned to the related button.</p> <p>It is possible to lock UserButton commands in configuration to specific user level. Buttons 1-8 and 9-16 are locked separately.</p> <table border="1"> <tr> <td>ON</td> <td>Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.</td> </tr> <tr> <td>OFF</td> <td>Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.</td> </tr> <tr> <td>ON/OFF</td> <td>Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).</td> </tr> <tr> <td>PULSE ON</td> <td>Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.</td> </tr> </table>	ON	Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.	OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.	ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).	PULSE ON	Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.
ON	Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.								
OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.								
ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).								
PULSE ON	Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.								

Binary output: User button 7

Related FW	3.0								
Description	<p>This output can be specified for example on buttons on IV-5/8 or in SCADA diagram in IntelliMonitor. Its state depends on function assigned to the related button.</p> <p>It is possible to lock UserButton commands in configuration to specific user level. Buttons 1-8 and 9-16 are locked separately.</p> <table border="1"> <tr> <td>ON</td> <td>Pressing the button changes the state of log. binary output User button X to closed. When the output is closed and the button is pressed state is not changed.</td> </tr> <tr> <td>OFF</td> <td>Pressing the button changes the state of log. binary output User button X to opened. When the output is opened and the button is pressed state is not changed.</td> </tr> <tr> <td>ON/OFF</td> <td>Pressing the button changes the state of log. binary output User button X to opened or closed depending on previous state (it is changed to the opposite state).</td> </tr> <tr> <td>PULSE ON</td> <td>Pressing the button issues log. binary output User button X to close for one second. NOTE: Repeated pressing of button during the closed period (one</td> </tr> </table>	ON	Pressing the button changes the state of log. binary output User button X to closed. When the output is closed and the button is pressed state is not changed.	OFF	Pressing the button changes the state of log. binary output User button X to opened. When the output is opened and the button is pressed state is not changed.	ON/OFF	Pressing the button changes the state of log. binary output User button X to opened or closed depending on previous state (it is changed to the opposite state).	PULSE ON	Pressing the button issues log. binary output User button X to close for one second. NOTE: Repeated pressing of button during the closed period (one
ON	Pressing the button changes the state of log. binary output User button X to closed. When the output is closed and the button is pressed state is not changed.								
OFF	Pressing the button changes the state of log. binary output User button X to opened. When the output is opened and the button is pressed state is not changed.								
ON/OFF	Pressing the button changes the state of log. binary output User button X to opened or closed depending on previous state (it is changed to the opposite state).								
PULSE ON	Pressing the button issues log. binary output User button X to close for one second. NOTE: Repeated pressing of button during the closed period (one								

	second) causes issuing another puls of length of one second to be generated from the moment of button pushing.
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Binary output: User Button 8

Related FW	3.0								
Description	<p>This output can be specified for example on buttons on IV-5/8 or in SCADA diagram in IntelliMonitor. Its state depends on function assigned to the related button.</p> <p>It is possible to lock UserButton commands in configuration to specific user level. Buttons 1-8 and 9-16 are locked separately.</p>								
	<table border="1" style="width: 100%;"> <tr> <td style="background-color: #444; color: white; text-align: center;">ON</td> <td>Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.</td> </tr> <tr> <td style="background-color: #444; color: white; text-align: center;">OFF</td> <td>Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.</td> </tr> <tr> <td style="background-color: #444; color: white; text-align: center;">ON/OFF</td> <td>Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).</td> </tr> <tr> <td style="background-color: #444; color: white; text-align: center;">PULSE ON</td> <td>Pressing the button issues log. binary output User Button X to close for one second.</td> </tr> </table>	ON	Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.	OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.	ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).	PULSE ON	Pressing the button issues log. binary output User Button X to close for one second.
	ON	Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.							
	OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.							
	ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).							
PULSE ON	Pressing the button issues log. binary output User Button X to close for one second.								
<p>NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.</p>									

Binary output: User Button 9

Related FW	3.0						
Description	<p>This output can be specified for example on buttons on IV-5/8 or in SCADA diagram in IntelliMonitor. Its state depends on function assigned to the related button.</p> <p>It is possible to lock UserButton commands in configuration to specific user level. Buttons 1-8 and 9-16 are locked separately.</p>						
	<table border="1" style="width: 100%;"> <tr> <td style="background-color: #444; color: white; text-align: center;">ON</td> <td>Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.</td> </tr> <tr> <td style="background-color: #444; color: white; text-align: center;">OFF</td> <td>Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.</td> </tr> <tr> <td style="background-color: #444; color: white; text-align: center;">ON/OFF</td> <td>Pressing the button changes the state of log. binary output User</td> </tr> </table>	ON	Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.	OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.	ON/OFF	Pressing the button changes the state of log. binary output User
	ON	Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.					
	OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.					
ON/OFF	Pressing the button changes the state of log. binary output User						

	<p>Button X to opened or closed depending on previous state (it is changed to the opposite state).</p>
PULSE ON	<p>Pressing the button issues log. binary output User Button X to close for one second.</p> <p>NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.</p>

Binary output: User Button 10

Related FW	3.0
Description	<p>This output can be specified for example on buttons on IV-5/8 or in SCADA diagram in IntelliMonitor. Its state depends on function assigned to the related button.</p> <p>It is possible to lock UserButton commands in configuration to specific user level. Buttons 1-8 and 9-16 are locked separately.</p>
ON	<p>Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.</p>
OFF	<p>Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.</p>
ON/OFF	<p>Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).</p>
PULSE ON	<p>Pressing the button issues log. binary output User Button X to close for one second.</p> <p>NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.</p>

Binary output: User Button 11

Related FW	3.0
Description	<p>This output can be specified for example on buttons on IV-5/8 or in SCADA diagram in IntelliMonitor. Its state depends on function assigned to the related button.</p> <p>It is possible to lock UserButton commands in configuration to specific user level. Buttons 1-8 and 9-16 are locked separately.</p>
ON	<p>Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is</p>

		pressed state is not changed.
	OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.
	ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).
	PULSE ON	Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.

Binary output: User Button 12

Related FW	3.0								
Description	<p>This output can be specified for example on buttons on IV-5/8 or in SCADA diagram in IntelliMonitor. Its state depends on function assigned to the related button.</p> <p>It is possible to lock UserButton commands in configuration to specific user level. Buttons 1-8 and 9-16 are locked separately.</p> <table border="1" data-bbox="438 1120 1364 1691"> <tr> <td>ON</td> <td>Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.</td> </tr> <tr> <td>OFF</td> <td>Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.</td> </tr> <tr> <td>ON/OFF</td> <td>Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).</td> </tr> <tr> <td>PULSE ON</td> <td>Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.</td> </tr> </table>	ON	Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.	OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.	ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).	PULSE ON	Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.
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OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.								
ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).								
PULSE ON	Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.								

Binary output: User Button 13

Related FW	3.0
Description	<p>This output can be specified for example on buttons on IV-5/8 or in SCADA diagram in IntelliMonitor. Its state depends on function assigned to the related button.</p>

<p>It is possible to lock UserButton commands in configuration to specific user level. Buttons 1-8 and 9-16 are locked separately.</p>	
ON	Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.
OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.
ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).
PULSE ON	<p>Pressing the button issues log. binary output User Button X to close for one second.</p> <p>NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.</p>

Binary output: User Button 14

Related FW	3.0
Description	<p>This output can be specified for example on buttons on IV-5/8 or in SCADA diagram in IntelliMonitor. Its state depends on function assigned to the related button.</p> <p>It is possible to lock UserButton commands in configuration to specific user level. Buttons 1-8 and 9-16 are locked separately.</p>
ON	Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.
OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.
ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).
PULSE ON	<p>Pressing the button issues log. binary output User Button X to close for one second.</p> <p>NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.</p>

Binary output: User Button 15

Related FW	3.0								
Description	<p>This output can be specified for example on buttons on IV-5/8 or in SCADA diagram in IntelliMonitor. Its state depends on function assigned to the related button.</p> <p>It is possible to lock UserButton commands in configuration to specific user level. Buttons 1-8 and 9-16 are locked separately.</p> <table border="1"> <tr> <td>ON</td> <td>Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.</td> </tr> <tr> <td>OFF</td> <td>Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.</td> </tr> <tr> <td>ON/OFF</td> <td>Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).</td> </tr> <tr> <td>PULSE ON</td> <td>Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.</td> </tr> </table>	ON	Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.	OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.	ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).	PULSE ON	Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.
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OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.								
ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).								
PULSE ON	Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one second) causes issuing another puls of length of one second to be generated from the moment of button pushing.								

Binary output: User Button 16

Related FW	3.0								
Description	<p>This output can be specified for example on buttons on IV-5/8 or in SCADA diagram in IntelliMonitor. Its state depends on function assigned to the related button.</p> <p>It is possible to lock UserButton commands in configuration to specific user level. Buttons 1-8 and 9-16 are locked separately.</p> <table border="1"> <tr> <td>ON</td> <td>Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.</td> </tr> <tr> <td>OFF</td> <td>Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.</td> </tr> <tr> <td>ON/OFF</td> <td>Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).</td> </tr> <tr> <td>PULSE ON</td> <td>Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one</td> </tr> </table>	ON	Pressing the button changes the state of log. binary output User Button X to closed. When the output is closed and the button is pressed state is not changed.	OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.	ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).	PULSE ON	Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one
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OFF	Pressing the button changes the state of log. binary output User Button X to opened. When the output is opened and the button is pressed state is not changed.								
ON/OFF	Pressing the button changes the state of log. binary output User Button X to opened or closed depending on previous state (it is changed to the opposite state).								
PULSE ON	Pressing the button issues log. binary output User Button X to close for one second. NOTE: Repeated pressing of button during the closed period (one								

	<p>second) causes issuing another puls of length of one second to be generated from the moment of button pushing.</p>
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Binary output: RemoteControl1

Related FW	3.0
Description	<p>This is a general purpose output, which can be closed and opened remotely, e.g. from IntelliMonitor using the "Remote switches" tool or via MODBUS using the register #46361 and command #26.</p> <p>NOTE: See the <i>Remote switches</i> chapter in the IntelliMonitor help for details about how to control the output from IntelliMonitor and the Modbus chapter in the latest communication guide for information about control the output using Modbus.</p>

Binary output: RemoteControl2

Related FW	3.0
Description	<p>This is a general purpose output, which can be closed and opened remotely, e.g. from IntelliMonitor using the "Remote switches" tool or via MODBUS using the register #46361 and command #26.</p> <p>NOTE: See the <i>Remote switches</i> chapter in the IntelliMonitor help for details about how to control the output from IntelliMonitor and the Modbus chapter in the latest communication guide for information about control the output using Modbus.</p>

Binary output: RemoteControl3

Related FW	3.0
Description	<p>This is a general purpose output, which can be closed and opened remotely, e.g. from IntelliMonitor using the "Remote switches" tool or via MODBUS using the register #46361 and command #26.</p> <p>NOTE: See the <i>Remote switches</i> chapter in the IntelliMonitor help for details about how to control the output from IntelliMonitor and the Modbus chapter in the latest communication guide for information about control the output using Modbus.</p>

Binary output: RemoteControl4

Related FW	3.0
Description	<p>This is a general purpose output, which can be closed and opened remotely, e.g. from IntelliMonitor using the "Remote switches" tool or via MODBUS using the register #46361 and command #26.</p> <p>NOTE: See the <i>Remote switches</i> chapter in the IntelliMonitor help for details about how to</p>

	control the output from IntelliMonitor and the Modbus chapter in the latest communication guide for information about control the output using Modbus.
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Binary output: RemoteControl5

Related FW	3.0
Description	<p>This is a general purpose output, which can be closed and opened remotely, e.g. from IntelliMonitor using the "Remote switches" tool or via MODBUS using the register #46361 and command #26.</p> <p>NOTE: See the <i>Remote switches</i> chapter in the IntelliMonitor help for details about how to control the output from IntelliMonitor and the Modbus chapter in the latest communication guide for information about control the output using Modbus.</p>

Binary output: RemoteControl6

Related FW	3.0
Description	<p>This is a general purpose output, which can be closed and opened remotely, e.g. from IntelliMonitor using the "Remote switches" tool or via MODBUS using the register #46361 and command #26.</p> <p>NOTE: See the <i>Remote switches</i> chapter in the IntelliMonitor help for details about how to control the output from IntelliMonitor and the Modbus chapter in the latest communication guide for information about control the output using Modbus.</p>

Binary output: RemoteControl7

Related FW	3.0
Description	<p>This is a general purpose output, which can be closed and opened remotely, e.g. from IntelliMonitor using the "Remote switches" tool or via MODBUS using the register #46361 and command #26.</p> <p>NOTE: See the <i>Remote switches</i> chapter in the IntelliMonitor help for details about how to control the output from IntelliMonitor and the Modbus chapter in the latest communication guide for information about control the output using Modbus.</p>

Binary output: RemoteControl8

Related FW	3.0
Description	<p>This is a general purpose output, which can be closed and opened remotely, e.g. from IntelliMonitor using the "Remote switches" tool or via MODBUS using the register #46361 and command #26.</p> <p>NOTE: See the <i>Remote switches</i> chapter in the IntelliMonitor help for details about how to control the output from IntelliMonitor and the Modbus chapter in the latest</p>

	communication guide for information about control the output using Modbus.
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Alarm output: Not lubricated

Related FW	3.0
Description	<p>The output is closed while there is the message <i>Not lubricated</i> present in the alarm list, i.e. while the first lubrication cycle haven't been completed yet. The first cycle occurs when the controller is switched on, when it is switched from OFF mode to another mode or when the input Emergency stop is released and confirmed.</p> <p>NOTE: If the setpoint Prelubr time is set to 0 (OFF), the prelubrication function is switched off.</p>

Alarm output: CAN2 bus empty

Related FW	3.0
Description	<p>The output is closed while there is the alarm <i>CAN2 bus empty</i> present in the alarm list, i.e. if the controller doesn't detect any other controller on the CAN2 bus. This alarm can be disabled by the setpoint CAN2emptDetect.</p>

Alarm output: Bus meas error

Related FW	3.0
Description	<p>The output closes when bus measurement protection is activated according to description of Gener protect: BusMeasError setpoint.</p>

Alarm output: ECU

Related FW	3.0
Description	<p>The output is closed while there is the <i>ECU</i> alarm present in the alarm list, i.e. if an ECU unit is configured and it does not communicate with the controller although it is required to communicate.</p>

Alarm output: SHBinCfgErr

Related FW	3.0
Description	<p>The output is closed while there is the <i>SHBinCfgErr</i> alarm present in the alarm list, i.e. if there is more than one controller on the CAN2 bus, which has configured the SHBOUT peripheral module with the same index.</p>

Alarm output: SHAINCfgErr

Related FW	3.0
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Description	The output is closed while there is the <i>SHAINCfgErr</i> alarm present in the alarm list, i.e. if there is more than one controller on the CAN2 bus, which has configured the SHAIN peripheral module with the same index .
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Alarm output: ECUDiagBlocked

Related FW	3.0
Description	The output is active when receiving of diagnostic messages from the ECU is disabled (<i>ECU diag</i> = DISABLED).

Alarm output: WrongConfig

Related FW	3.0
Description	This output is closed while there is the <i>WrongConfig</i> alarm present in the alarm list. The wrong configuration is indicated if the controller configuration contains a PLC program, which exceeds limits of the current controller hardware. Typically this situation can occur when a miniCHP archive is used in a controller without mCHP dongle inserted.

Alarm output: Dongle incomp

Related FW	3.0
Description	<p>This output is closed while there is the <i>Dongle incomp</i> alarm present in the alarm list. The incompatible dongle is indicated when a function is switched on, which requires dongle, however the dongle is not inserted or does not contain the appropriate feature.</p> <p>Typical situations are:</p> <ul style="list-style-type: none"> • Power management is enabled and there is not any dongle with "PMS" feature inserted in the controller. • The controller is in situation, when the load sharing should beeing performed, however there is not any dongle with "LS" feature inserted in the controller.

Alarm output: Emergency stop

Related FW	3.0
Description	This output is closed while the <i>Emergency stop</i> alarm is present in the alarm list. The emergency stop alarm is activated by the input Emergency stop .

Alarm output: WrnServiceT1+2

Related FW	3.0
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Description	This output is closed while the <i>WrnServiceT1+2</i> alarm is present in the alarm list. This alarm occurs when the counter Service time 1 or Service time 2 has reached zero value. Both timers must be reset to a nonzero value to get rid of this alarm.
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Alarm output: *WrnServiceT3+4*

Related FW	3.0
Description	This output is closed while the <i>WrnServiceT3+4</i> alarm is present in the alarm list. This alarm occurs when the counter Service time 3 or Service time 4 has reached zero value. Both timers must be reset to a nonzero value to get rid of this alarm.

Alarm output: *Overspeed*

Related FW	3.0
Description	This output is closed while the <i>Overspeed</i> alarm is present in the alarm list.

Alarm output: *Underspeed*

Related FW	3.0
Description	This output is closed while the <i>Underspeed</i> alarm is present in the alarm list.

Alarm output: *Start fail*

Related FW	3.0
Description	This output is closed while the <i>Start fail</i> alarm is present in the alarm list. See the diagram in the description of the Starter output for information when the start fail alarm is indicated.

Alarm output: *Sd Stop fail*

Related FW	3.0
Description	<p>This output is closed while the <i>Sd Stop fail</i> alarm is present in the alarm list. This alarm appears when the gen-set indicates that it is rotating although it has to be stopped. This situation can occur:</p> <ul style="list-style-type: none"> • when the gen-set starts to rotate spontaneously (from the controller point of view) or • when the gen-set does not stop after the stop command has been issued. See the timing diagram in the description of the output Stop Solenoid.

Alarm output: ChrgAlternFail

Related FW	3.0
Description	<p>This output is closed while the <i>ChrgAlternFail</i> alarm is present in the alarm list. This alarm appears when the voltage at the controller D+ terminal drops below 90% of the controller supply voltage for more than 2s.</p> <p>NOTE: Function of the D+ terminal is selected by the setpoint D+ Function.</p>

Alarm output: Pickup fail

Related FW	3.0
Description	<p>This output is closed while the <i>ChrgAlternFail</i> alarm is present in the alarm list. This alarm appears when the engine is running (there is at least one "running symptom" active), however zero speed is detected.</p> <p>NOTE: Pickup fail can be indicated even if the speed is actually measured from the generator frequency.</p> <p>The "running symptoms" are listed in the description of the output Starter.</p>

Alarm output: Sd ExtBattFlat

Related FW	3.0
Description	<p>This output is closed while the <i>Sd Battery flat</i> alarm is present in the alarm list.</p> <p>This alarm appears when reset of the controller occurs while the gen-set is actually cranking. Such a situation is considered as a reset caused by a drop of the supply voltage due to starter motor current when the gen-set starting battery is in bad condition.</p>

Alarm output: Stp GCB fail

Related FW	3.0
Description	This output is closed while the <i>GCB fail</i> alarm is present in the alarm list.

Alarm output: BOC NCB fail

Related FW	3.0
Description	This output is closed while the <i>NCB fail</i> alarm (neutral circuit breaker) is present in the alarm list.

Alarm output: Stp Sync fail

Related FW	3.0
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Description	This output is closed while the <i>Stp Sync fail</i> alarm is present in the alarm list, i.e. if the last synchronization process was not successful and ended by timeout.
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Alarm output: *WrnSpdRegLim*

Related FW	3.0
Description	<p>This output is closed while the <i>WrnSpdRegLimit</i> alarm is present in the alarm list, i.e. while the analog output for speed governor is near minimum or maximum position (out of the range SpeedGovLowLim + 0.2V to SpeedGovHiLim - 0.2V for more than 2s).</p> <p>NOTE: This alarm is disabled when speed governing via binary outputs Speed up and Speed dn is used (i.e. at least one of these outputs is configured onto a physical or virtual output terminal).</p>

Alarm output: *WrnVoltRegLim*

Related FW	3.0
Description	<p>This output is closed while the <i>WrnVoltRegLim</i> alarm is present in the alarm list, i.e. while the analog output for AVR is near minimum or maximum position (out of the range 2% to 98% for more than 2s).</p> <p>NOTE: This alarm is disabled when AVR control via binary outputs AVR up and AVR dn is used (i.e. at least one of these outputs is configured onto a physical or virtual output terminal).</p>

Alarm output: *Sd Oil press B*

Related FW	3.0
Description	This output is closed while the <i>Sd Oil press B</i> alarm is present in the alarm list, i.e. while there is a mismatch between gen-set state (running/stopped) and position of the input Oil press .

Alarm output: *OfL StartBlck*

Related FW	3.0
Description	This output is closed while message <i>OfL StartBlck</i> is present in the alarm list. The message indicates that the setpoints Island enable , ParallelEnable and Synchro enable are adjusted in such a way, that the genset is not allowed to operate in current conditions, for example if mains breaker is opened and however island operation is disabled.

Alarm output: *Start blocking*

Related FW	3.0
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Description	The output is closed while there is the message <i>Start blocking</i> in the alarm list, i.e. while the input Startblocking is closed.
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Alarm output: Fuel theft

Related FW	3.0
Description	This output is closed while the <i>Fuel theft</i> alarm is present in the alarm list. This alarm occurs when the fuel level value measured at the analog input Fuel level drops faster than is the limit adjusted by setpoint MaxFuelDrop .

Alarm output: PLC State 1

Related FW	3.0
Description	The output is closed while the alarm generated by the PLC block <i>Force prot 1</i> is present in the alarm list. NOTE: The actual text, which appears in the alarm list, can be changed in GenConfig.

Alarm output: PLC State 2

Related FW	3.0
Description	The output is closed while the alarm generated by the PLC block <i>Force prot 2</i> is present in the alarm list. NOTE: The actual text, which appears in the alarm list, can be changed in GenConfig.

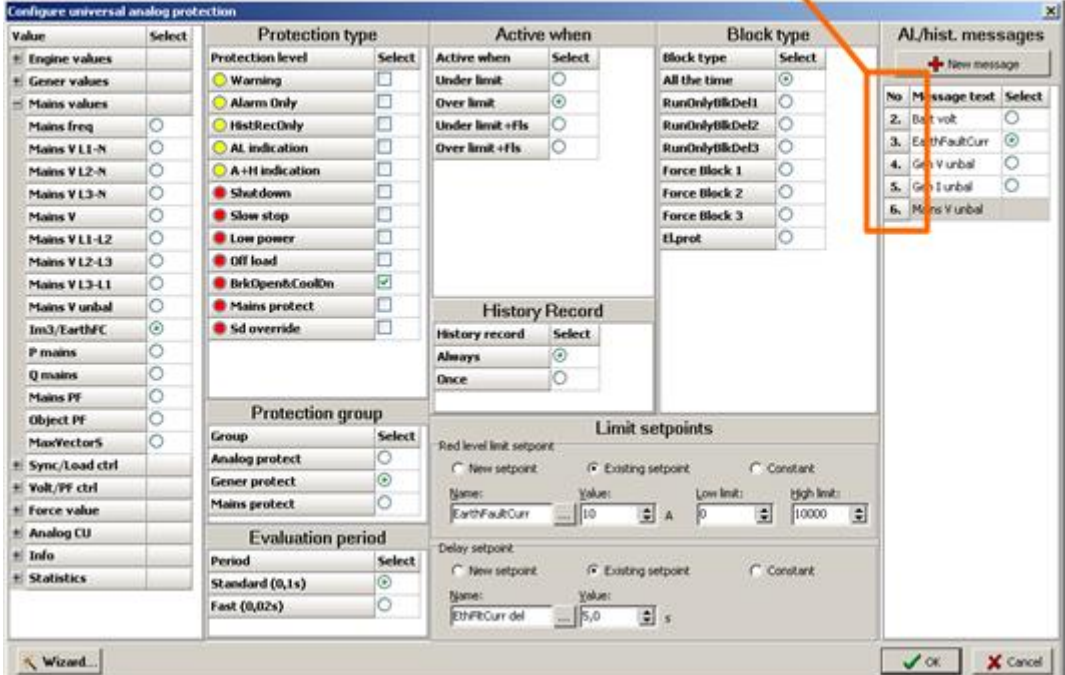
Alarm output: PLC State 3

Related FW	3.0
Description	The output is closed while the alarm generated by the PLC block <i>Force prot 3</i> is present in the alarm list. NOTE: The actual text, which appears in the alarm list, can be changed in GenConfig.

Alarm output: PLC State 4

Related FW	3.0
Description	The output is closed while the alarm generated by the PLC block <i>Force prot 4</i> is present in the alarm list. NOTE: The actual text, which appears in the alarm list, can be changed in GenConfig.

Alarm output: UnivState 1

Related FW	3.0
Description	<p>The output is closed while the alarm generated by the <i>Universal analog protection</i>, where the Message #1 is used, is present in the alarm list.</p> <p>NOTE: The actual text of the message depends on configuration.</p> <div style="text-align: right; color: orange; font-weight: bold;">MESSAGE No. (#)</div>  <p>HOW TO FIND OUT THE MESSAGE NUMBER</p>

Alarm output: UnivState 2

Related FW	3.0
Description	<p>The output is closed while the alarm generated by the <i>Universal analog protection</i>, where the Message #2 is used, is present in the alarm list. See the UnivState 1 for picture how to find the message number.</p>

Alarm output: UnivState 3

Related FW	3.0
Description	<p>The output is closed while the alarm generated by the <i>Universal analog protection</i>, where the Message #3 is used, is present in the alarm list. See the UnivState 1 for picture how to find the message number.</p>

Alarm output: UnivState 4

Related FW	3.0
Description	The output is closed while the alarm generated by the <i>Universal analog protection</i> , where the Message #4 is used, is present in the alarm list. See the UnivState 1 for picture how to find the message number.

Alarm output: UnivState 5

Related FW	3.0
Description	The output is closed while the alarm generated by the <i>Universal analog protection</i> , where the Message #5 is used, is present in the alarm list. See the UnivState 1 for picture how to find the message number.

Alarm output: UnivState 6

Related FW	3.0
Description	The output is closed while the alarm generated by the <i>Universal analog protection</i> , where the Message #6 is used, is present in the alarm list. See the UnivState 1 for picture how to find the message number.

Alarm output: UnivState 7

Related FW	3.0
Description	The output is closed while the alarm generated by the <i>Universal analog protection</i> , where the Message #7 is used, is present in the alarm list. See the UnivState 1 for picture how to find the message number.

Alarm output: UnivState 8

Related FW	3.0
Description	The output is closed while the alarm generated by the <i>Universal analog protection</i> , where the Message #8 is used, is present in the alarm list. See the UnivState 1 for picture how to find the message number.

Alarm output: UnivState 9

Related FW	3.0
Description	The output is closed while the alarm generated by the <i>Universal analog protection</i> , where the Message #9 is used, is present in the alarm list. See the UnivState 1 for picture how to find the message number.

Alarm output: UnivState 10

Related FW	3.0
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Description	The output is closed while the alarm generated by the <i>Universal analog protection</i> , where the Message #10 is used, is present in the alarm list. See the UnivState 1 for picture how to find the message number.
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Alarm output: UnivState 11

Related FW	3.0
Description	The output is closed while the alarm generated by the <i>Universal analog protection</i> , where the Message #11 is used, is present in the alarm list. See the UnivState 1 for picture how to find the message number.

Alarm output: UnivState 12

Related FW	3.0
Description	The output is closed while the alarm generated by the <i>Universal analog protection</i> , where the Message #12 is used, is present in the alarm list. See the UnivState 1 for picture how to find the message number.

Alarm output: UnivState 13

Related FW	3.0
Description	The output is closed while the alarm generated by the <i>Universal analog protection</i> , where the Message #13 is used, is present in the alarm list. See the UnivState 1 for picture how to find the message number.

Alarm output: UnivState 14

Related FW	3.0
Description	The output is closed while the alarm generated by the <i>Universal analog protection</i> , where the Message #14 is used, is present in the alarm list. See the UnivState 1 for picture how to find the message number.

Alarm output: UnivState 15

Related FW	3.0
Description	The output is closed while the alarm generated by the <i>Universal analog protection</i> , where the Message #15 is used, is present in the alarm list. See the UnivState 1 for picture how to find the message number.